

Assignment Project Exam Help

Review of the Final

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Reminders/Comments

This is a final exam that means

- You should work on your own
- We will answer clarification questions but not debug your code
- No extensions

but it is o

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- We are happy to explain what error message
should isolate the line of code that generates t

On the first

- Structured like a homework; 3 questions, 6 p
- Sub-parts are structured as (i): do the coding, (ii) and (iii):
plot or comment on results.
- Happy to tell you what code should do, written responses are
up to you.

Question 1: Control Functionals

Reminder: control variate

■ Monte Carlo estimate if $X_i \sim \pi(\cdot)$

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has smaller variance if $\alpha = \text{cov}(g(X), h(X)) / \text{var}(h(X))$.

■ α ? Estimate from values of $g(X_i)$ and $h(X_i)$.

Example on Final

Part a: $X \sim N(0, 1)$, $g(x) = \sin(x + 0.1)$

Use $h(x) = -\frac{1}{2}e^x + \frac{1}{2}e^{-x}$ because $E[e^X] = e^{1/2}$.

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Comparisons

Parts b/c with antithetic sampling

Note: for $X \sim N(0, 1)$ ($X, -X$) are antithetic

We want to look at

1

—

2

3

\bar{N}

i

i

4

Both: $\frac{1}{N} \sum (g(X_i) + g(-X_i))/2$ — $/2$

For both, calculate alpha from values of
 $(h(X_i) + h(-X_i))/2$

Question about relative improvement are for you to think about.

Also bonus on using $g(x) = \sin(x)$ or $h(x) = x$.

Control Functionals

Part d taken from Oates, Girolami, Chopin, 2016

- Idea, if we can make $h_N(x)$ closer to $g(x)$ as $N \rightarrow \infty$ we will go better faster.
- Use $X_1, \dots, X_{N/2}$ to get a better $h_N(x)$, $X_{N/2+1}, \dots, X_N$ for

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$h_N(x) = \sum_{j=1}^{N/2} k_j(x)$
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d_j make $h_N(x)$ approximate $g(x)$ but we know

$$\int k_j(x) f(x) dx = 0$$

Control Functional Details

Need $E k_j(X) = 0$: modify a kernel function

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where $\phi(z; s)$ is normal density with standard deviation s
(dno

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Why?

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$$\begin{aligned}\int k_j(x) f(x) dx &= \int (\phi'(x - X_j; s) f(x)) dx \\ &= \int \frac{d}{dx} (\phi(x - X_j; s) f(x)) dx \\ &= \phi(\infty - X_j; s) f(\infty) - \phi(-\infty - X_j; s) f(-\infty) = 0\end{aligned}$$

Control Functional Implementation

- 1 Calculate matrix to store for $1, \dots, N/2$

$$K_{ij} = k_j(X_i) = \phi'(X_i; X_j; s) + \phi(X_i; X_j; s) f'(X_i) / f(X_j)$$

remember $\phi(z; s)$ is $N(0, s)$, $f(x)$ is $N(0, 1)$.

- 2

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- 3 Plug in $X_{N/2+1}, \dots, X_N$ to

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$$h_N(x) = \sum_{l=N/2+1}^N$$

(note that the X_j used to define k_j stay the same.

k_j : sort of kernel/sort of basis. No smoothing penalty because $g(X_i)$ has no error.

Example

Using $g(x) = \sin(x)$

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$N = 5$

$N = 50$

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Convergence Rates

Parts e/f: simulation based on control functionals Example is based on $g(x) = \sin(x)$, control variate $h(x) = x$ (more effective than parts a-c) Note: δ changes with N .

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End of Part f:

$$\sqrt{MSE} \approx CN^\alpha \rightarrow \log(\sqrt{MSE}) \approx \alpha \log(N) + \log(C)$$

looks like a linear model.

Question 2: Kernel Density Estimates

Kernel Density Estimation, given X_1, \dots, X_n :

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$$\hat{f}_s(x) = \frac{1}{n} \sum_{i=1}^n \phi(x - X_i; s)$$

$(\phi(z$ <https://eduassistpro.github.io>

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Cross Validation

Part b to choose s , we want to make the density on a *new* point as high as possible.

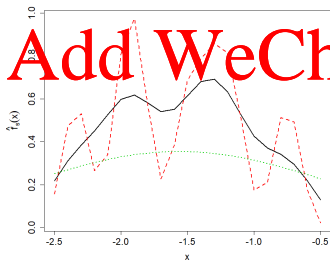
■ $\hat{f}_{-i}^{(s)}(x_j)$: density with bandwidth s evaluated at X_j estimated *without* using X_j .

■ density

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Possible Densities

CV Scores



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CV can be calculated efficiently

Simulation

Part c Form of density is like

$$Z|k \sim N(X_k, s), k \sim \text{Unif}(1, \dots, n)$$

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1 Choose an observation at random

2

Can all

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Hellinger Distance

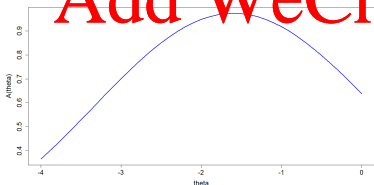
Part d Measure of distance between densities

$$\int (\sqrt{g(x)} - \sqrt{f(x)})^2 dx = 2 - 2 \int \sqrt{g(x)} \sqrt{f(x)} dx = 2 - 2A(f, g)$$

or use *affinity*

$$A(g, f) = \int \sqrt{g(x)f(x)} dx$$

Statistical use: find θ to maximize affinity



Here

and $f(x; \theta)$ is $N(\theta, 1)$:

$$A(\theta) = \frac{1}{N} \sum \sqrt{\frac{\phi(Z_j - \theta, 1)}{\hat{f}(Z_j)}}$$

Optimization and Robustness

To find $\max_{\theta} A(\theta)$ use optimize function between -10 and 10.

Part e Reason for Hellinger is *robustness* – adding a large value to data doesn't change estimate much

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- Add O to data (8 points instead of 7)
- Don't change s with value of O (yes this is cheating).
- Do simulate new Monte Carlo points with each value.

Hellinger's Posterior

Hooker and Vidyashankar, 2014 suggested finding a posterior based on

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Here we let $\pi(\theta)$ be $N(0, 10)$ and sample from $P(\theta)$ by MCMC

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For this question:

- Keep same MC samples with $A(\theta)$ for each θ .
- Experiment to get acceptance to around 30%; decide on thinning from visual inspection (don't work too hard).

Stochastic Objective Functions

Monte Carlo integration \Rightarrow evaluation of $A(\theta)$ random.

Using same samples makes problem smooth, still random.

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New Sample Each θ

10 samples same θ

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In MCMC, stochastic posteriors are ok, but decrease acceptance rate.

Mixed Effects Logistic Models

Example data

- 12 Subjects, each measured 7 times
- Record to nail health 1 time from treatment

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Logistic model (can use plogis)

$$P(Y_{ij} = 1|Z_j) = \frac{e^{\beta_0 + \beta_1 X_{ij} + Z_j}}{1 + e^{\beta_0 + \beta_1 X_{ij} + Z_j}}$$

X_{ij} = time of visit, Z_j = effect of subject j .

Generative Model

Don't get to see subject effects Z_j : model for a new data set is

1 Generate new Z_1, \dots, Z_{12} from $N(0, \sigma^2)$

2 Then generate Y_{ij} from $P(Y_{ij} = 1|Z_j)$

Since we don't see Z_j probability of observed data is

When

$$P(Y_1, \dots, Y_{7j}|z) = \prod_{i=1}^7 P(Y_{ij}|z)$$

$$= \prod_{i=1}^7 P(Y_{ij} = 1|z)^{Y_{ij}} (1 - P(Y_{ij} = 1|z))^{1 - Y_{ij}}$$

$$= \prod_{i=1}^7 [Y_{ij} P(Y_{ij} = 1|z) + (1 - Y_{ij})(1 - P(Y_{ij} = 1|z))]$$

Use most convenient form, or dbinom.

Gauss Hermite Approximation

Part a Package `ecoreg` function `GaussHermite(21)` produces z_q , w_q in columns `Points` and `Weights` so that

$$\int_{\mathbb{R}^n} P(Y_{11}, \dots, Y_{1j} | z) \phi(z; \sigma) dz \approx \sum w_q P(Y_{11}, \dots, Y_{1j} | \sigma z_q)$$

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log Likelihood

Parameter vector $\theta = (\beta_0, \beta_1, \sigma)$ has *negative* log likelihood

$$\ell(\theta) = -\sum_j \log P(Y_{1j}, \dots, Y_{7j} | \theta)$$

(Not

nota

Writ

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- Obtain $P(Y_{ij}|z_q, X_{ij}, \theta)$ from plog
- Evaluate $P(Y_{1j}, \dots, Y_{7j}|z_q, X_{\cdot j}, \theta)$
- Obtain

$$P(Y_{1j}, \dots, Y_{7j} | X_{1j}, \dots, X_{7j}, \theta) \approx \sum w_q P(Y_{1j}, \dots, Y_{7j} | z_q, X_{\cdot j}, \theta)$$

- negative log likelihood is minus sum of logs.

Maximizing and Alternatives

Maximum likelihood estimator minimizes negative log likelihood.

Use

```
optim(par=theta,fn=logistic.nll,data=toenail)
```

to get

Part

Replace Gauss-Hermite approximation with

$$\int P(Y_{i1}, \dots, Y_{ij} | z) \phi(z, \sigma) dz \approx \frac{1}{k} \sum_{k=1}^k$$

with $Z_1, \dots, Z_N \sim N(0, \sigma^2)$.

Possible to code so minimal changes from Part a.

Part c: MCMC

- Fix $\sigma = 1.2$ (MCMC techniques for variances are more fiddly).
- Set a prior $\beta_0 \sim N(0, 10)$, $\beta_1 \sim N(0, 10)$.
- Easiest to work with log posterior, log likelihood + log prior (remember log=TRUE in density functions)

Run

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Obtain mean values and quantiles from chain.

Part d: Extended MCMC

What if we also include Z_1, \dots, Z_{12} as values to be sampled?

Whole likelihood is

$$P(Y, Z, \theta) = \prod_{j=1}^J \left[P(Y_j | X_{ij}, Z_j, \theta) \right] P(Z_j | \sigma)^J \pi(\theta)$$

easier

For M

1 $\beta_0 \sim N(\beta_0, 0.25), \beta_1 \sim N(\beta_1, 0.05)$

2 $Z_j \sim N(0, 0.5)$

Z_1 chain gives $P(Z_1 | Y_1, \dots, Y_{11})$ (e

Part e: SMC

Alternative random number generation from $f(z)$:

1. Generate $Z_1, \dots, Z_N \sim g(z)$

2. Resample (with replacement) using probabilities

$$W_i = f(Z_i)/g(Z_i) \text{ to get } Z_i^*$$

samp

Our e

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$$Z_i \sim N(\mu, \sigma^2)$$
$$W_i = P(Y_{.1}|Z_i, X_{.1}, \theta)$$

$Y_{.1}, X_{.1}$ data from Subject 1, θ
from Part a estimate.

Bonus

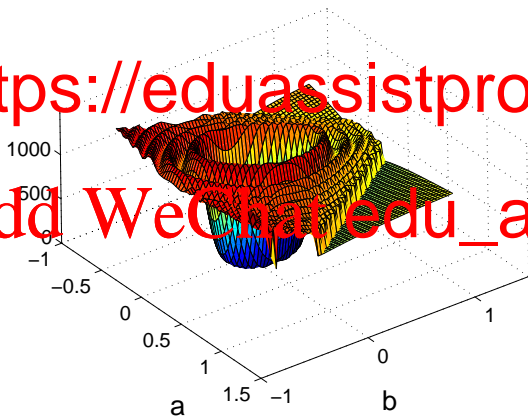
For a hard optimization problem:

- 1 Write squared error function
- 2 try function to avoid errors

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Wrap Up

BTRY/STSCI 4520: Many Topics Covered Briefly

- Computational considerations
 - Programming strategies + computational complexity
 - Numerical stability

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- Integration (numerical/Monte Carlo)

- Statistics

- Simulation

- Bootstraps and permutation
- Nonparametric smoothing
- Maximum likelihood and LASSO penalties
- MCMC

Many tools enable practical, modern statistics.