
CIS 471/571 (Fall 2020): Introduction to Artificial Intelligence

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Lecture 7 <https://eduassistpro.github.io/>
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Thanh H. Nguyen

Source: <http://ai.berkeley.edu/home.html>

Reminders

- Project 2: Multi-agent Search
 - Deadline: Oct 27th, 2020
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- Homework 2: CSPs <https://eduassistpro.github.io/>
 - Deadline: Oct 24th, 2020 [Add WeChat](#) [edu_assist_pro](#)

Today

- Expectimax Search

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Uncertain Outcomes

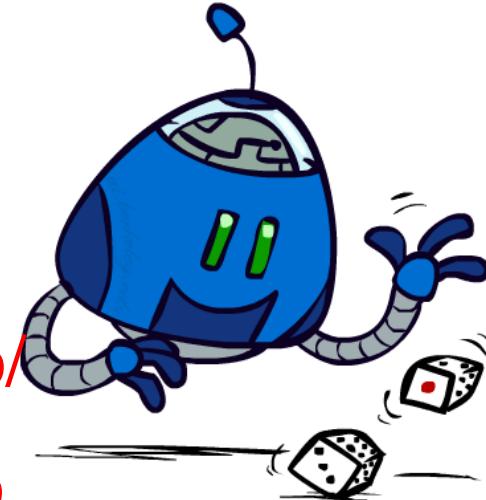
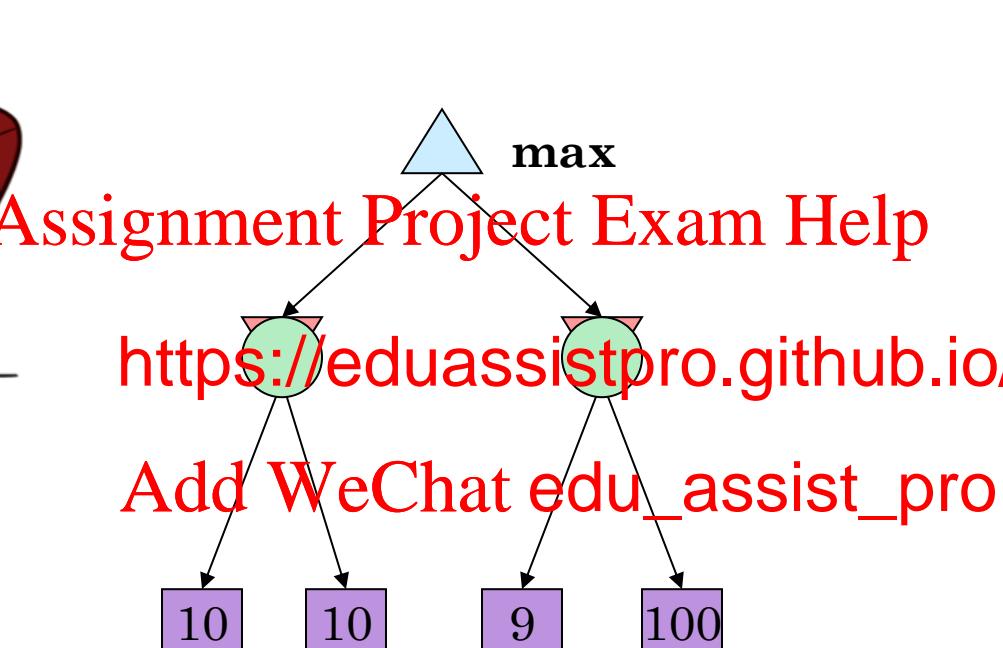
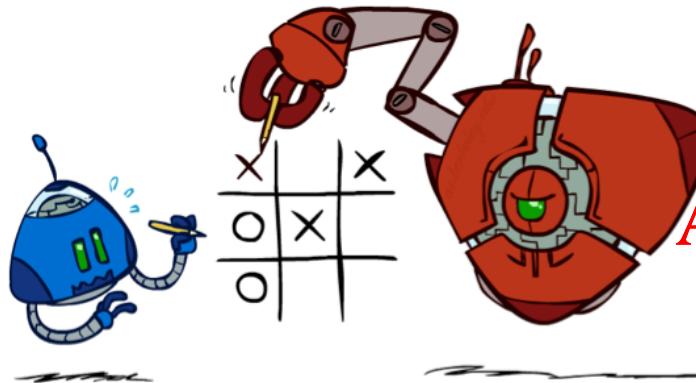
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Worst-Case vs. Average Case



Idea: Uncertain outcomes controlled by chance, not an adversary!



Expectimax Search

- Why wouldn't we know what the result of an action will be?

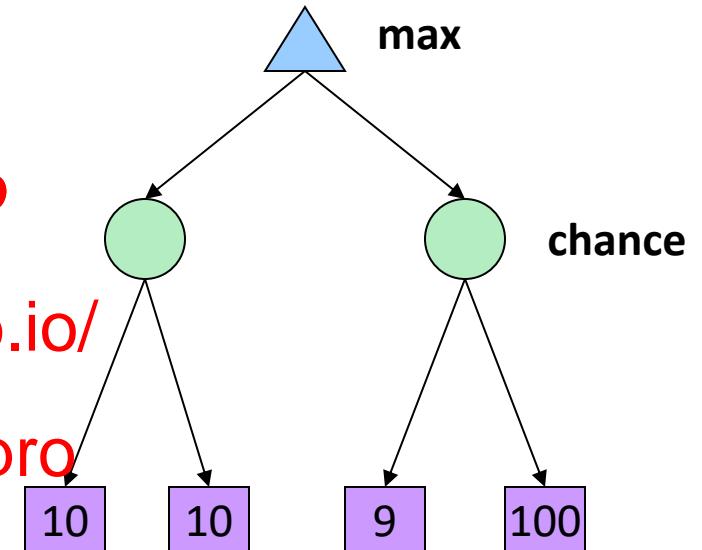
- Explicit randomness: rolling dice
 - Unpredictable opponents: the ghosts respond randomly
 - Actions can fail: when moving a robot, wheels might slip

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- Values should now reflect average outcomes, not worst-case (mini <https://eduassistpro.github.io/>)

- **Expectimax search:** compute the average score of optimal play
 - Max nodes as in minimax search
 - Chance nodes are like min nodes but the outcome is uncertain
 - Calculate their **expected utilities**
 - I.e. take weighted average (expectation) of children

- Later, we'll learn how to formalize the underlying uncertain-result problems as **Markov Decision Processes**



Expectimax Pseudocode

```
def value(state):
    if the state is a terminal state: return the state's utility
    if the next agent is MAX: return max-value(state)
    if the next
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        p-value(state)
```

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```
def max-value(state):
    initialize v = -∞
    for each successor of state:
        v = max(v, value(successor))
    return v
```

```
def exp-value(state):
    initialize v = 0
    for each successor of state:
        p = probability(successor)
        v += p * value(successor)
    return v
```



Expectimax Pseudocode

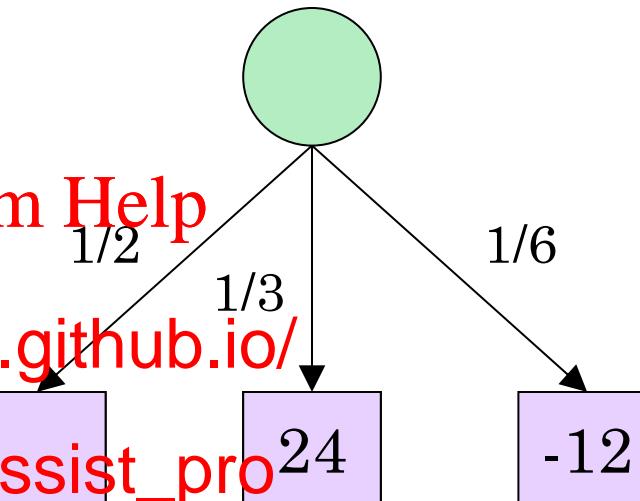
```
def exp-value(state):
    initialize v = 0
    for each successor s in state:
        p = probability(s)
        v += p * value(s)
    return v
```

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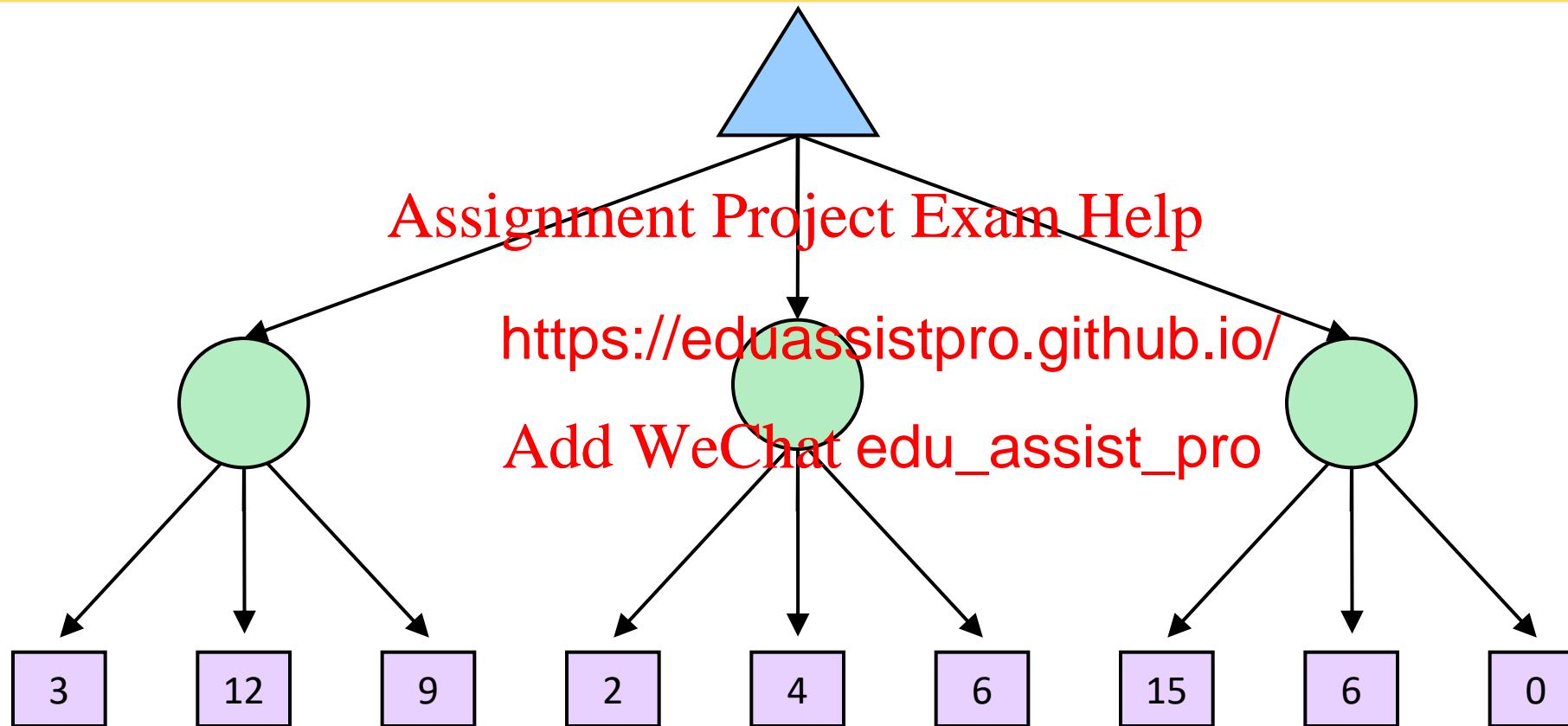
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-12

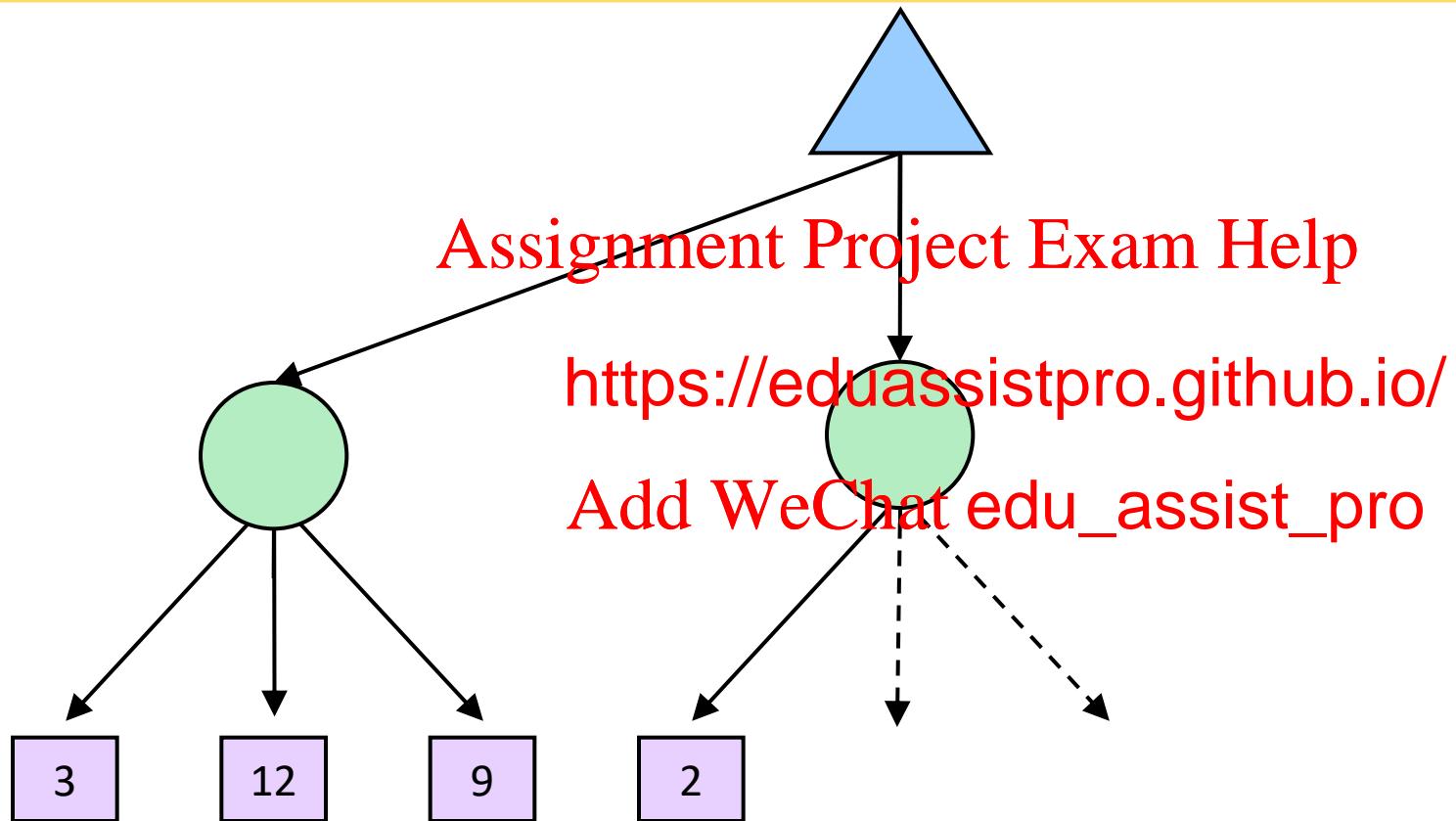
$$v = (1/2)(8) + (1/3)(24) + (1/6)(-12) = 10$$



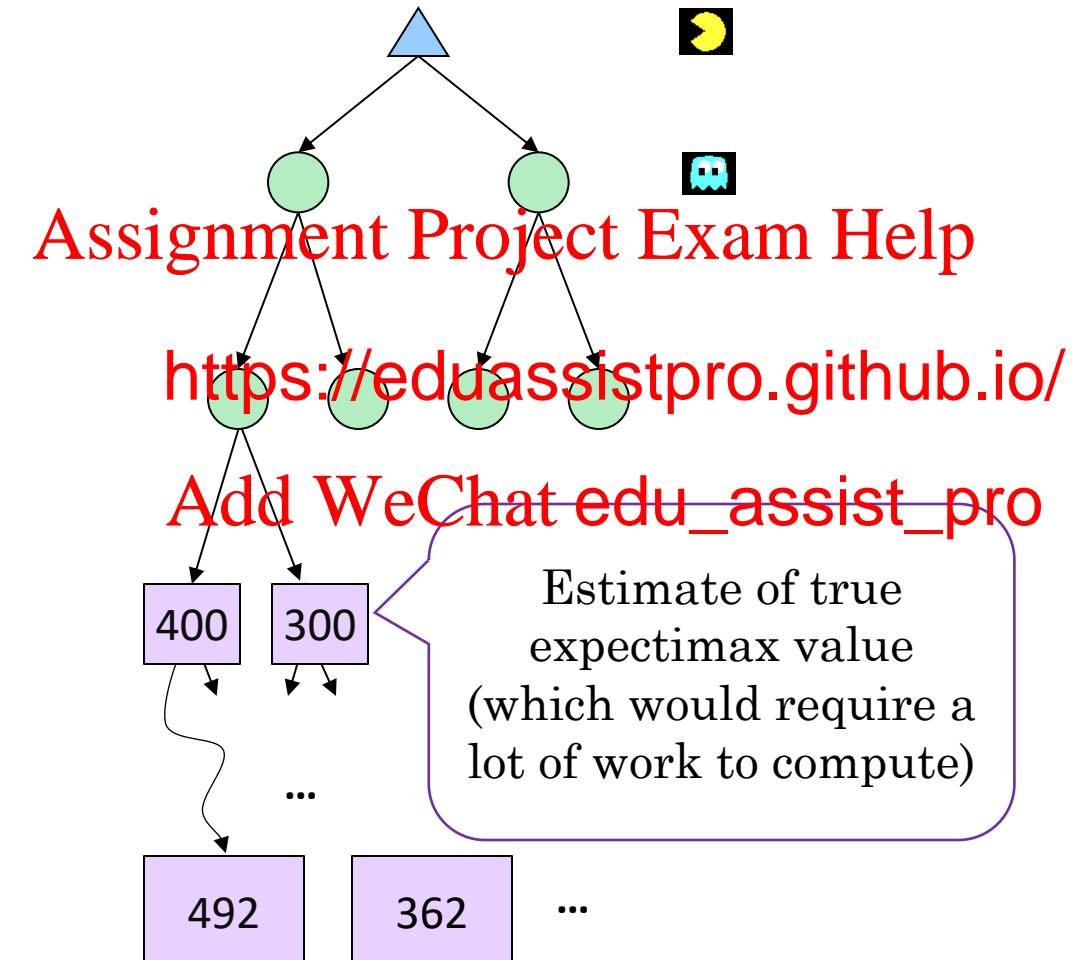
Expectimax Example



Expectimax Pruning?



Depth-Limited Expectimax



Probabilities

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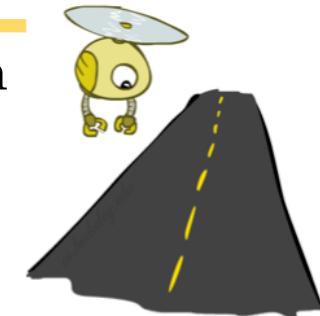
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Reminder: Probabilities

- A **random variable** represents an event whose outcome is unknown
- A **probability distribution** is an assignment of weights to outcomes



0.25

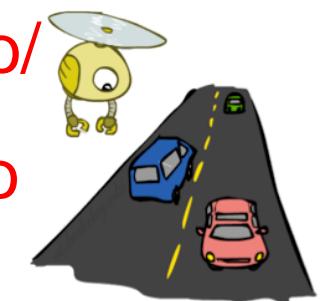
- Example: Traffic on freeway

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- Random variable: $T = \text{whether traffic is none, light, heavy}$
- Outcomes: $T \in \{\text{none, light, heavy}\}$
- Distribution: $P(T=\text{none}) = 0.25,$

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= 0.25



0.50

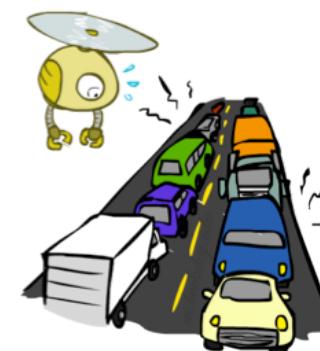
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- Some laws of probability (more later):

- Probabilities are always non-negative
- Probabilities over all possible outcomes sum to one

- As we get more evidence, probabilities may change:

- $P(T=\text{heavy}) = 0.25, P(T=\text{heavy} \mid \text{Hour}=8\text{am}) = 0.60$
- We'll talk about methods for reasoning and updating probabilities later



0.25



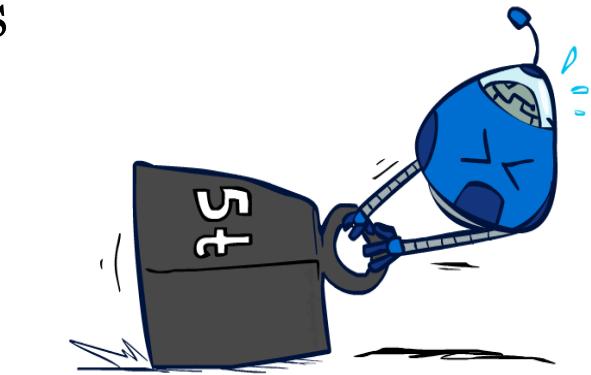
Reminder: Expectations

- The expected value of a function of a random variable is the average, weighted by the probability distribution over outcomes

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- Example: How long to get <https://eduassistpro.github.io/>

Time:	20 min	\times	30 min	\times	0 min
		+			
Probability:	0.25		0.50		0.25

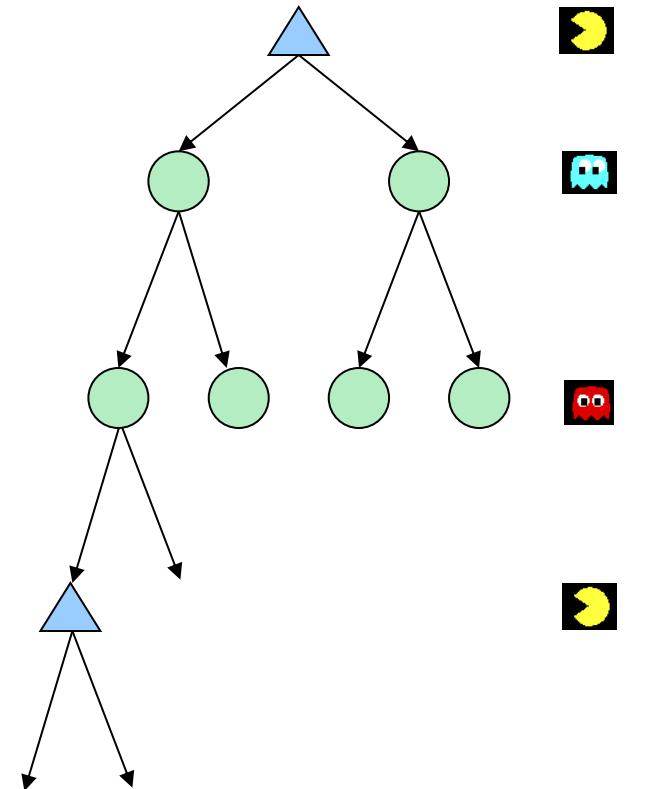


35
min



What Probabilities to Use?

- In expectimax search, we have a probabilistic model of how the opponent (or environment) will behave in any state
 - Model could be a simple uniform distribution (roll a die)
 - Model could be sophisticated a <https://eduassistpro.github.io/> of computation
 - We have a chance node for any outcome out of o control: opponent or environment
 - The model might say that adversarial actions are likely!
- For now, assume each chance node magically comes along with probabilities that specify the distribution over its outcomes

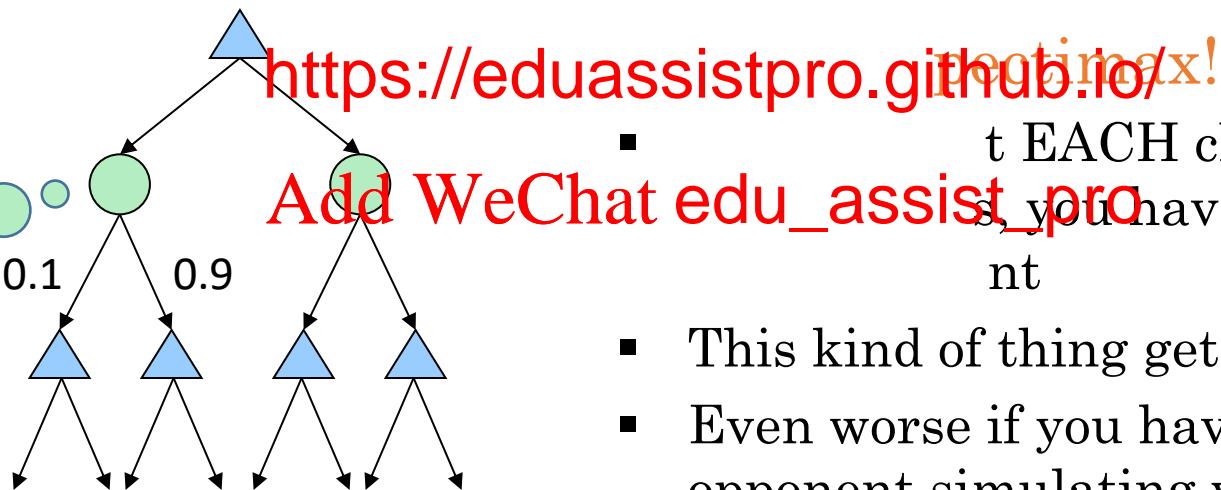
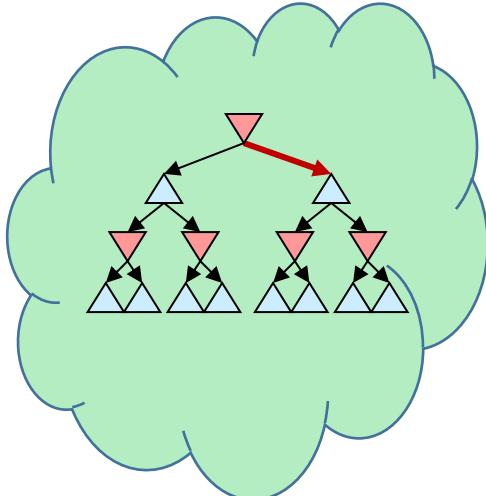


Having a probabilistic belief about another agent's action does not mean that the agent is flipping any coins!

Quiz: Informed Probabilities

- Let's say you know that your opponent is actually running a depth 2 minimax, using the result 80% of the time, and moving randomly otherwise
- Question: What tree search should you use?

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- t EACH chance node's
- s, you have to run a simulation of
- This kind of thing gets very slow very quickly
- Even worse if you have to simulate your opponent simulating you...
- ... except for minimax, which has the nice property that it all collapses into one game tree



Modeling Assumptions

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The Dangers of Optimism and Pessimism

Dangerous Optimism

Assuming chance when the world is adversarial

Dangerous Pessimism

Assuming the worst case when it's not likely

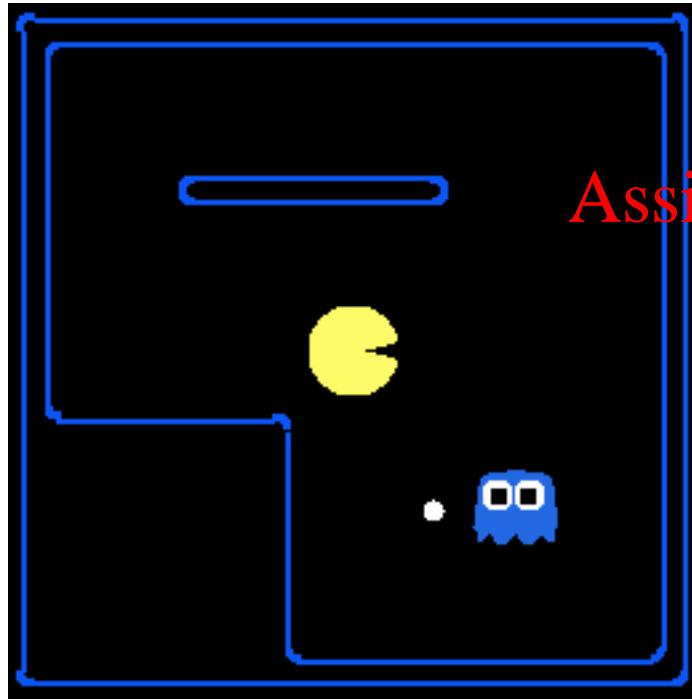
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Assumptions vs. Reality



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Expectimax
Pacman

Adversarial Ghost

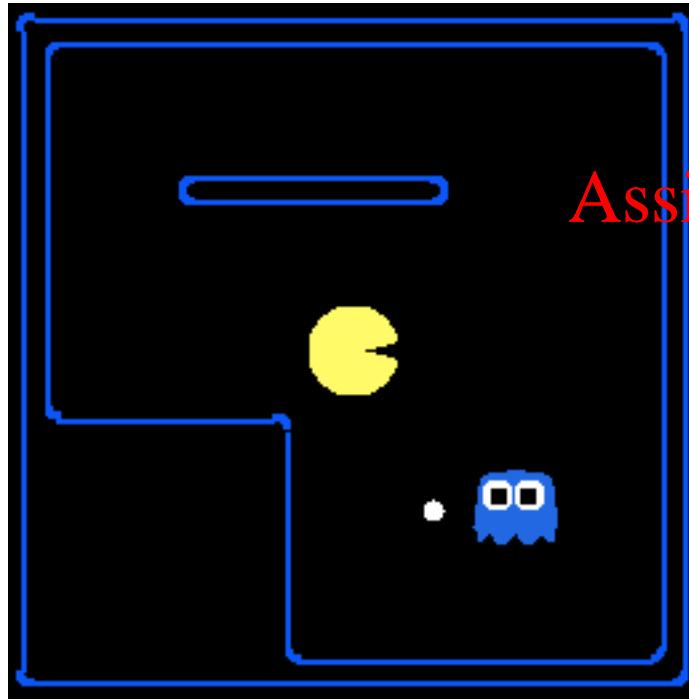
Random Ghost

Results from playing 5 games

Pacman used depth 4 search with an eval function that avoids trouble
Ghost used depth 2 search with an eval function that seeks Pacman



Assumptions vs. Reality



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Expectimax
Pacman

Adversarial Ghost

Won 5/5
Avg. Score: 483

Random Ghost

Won 5/5
Avg. Score: 493

Won 1/5
Avg. Score: -303

Results from playing 5 games

Pacman used depth 4 search with an eval function that avoids trouble
Ghost used depth 2 search with an eval function that seeks Pacman



Other Game Types

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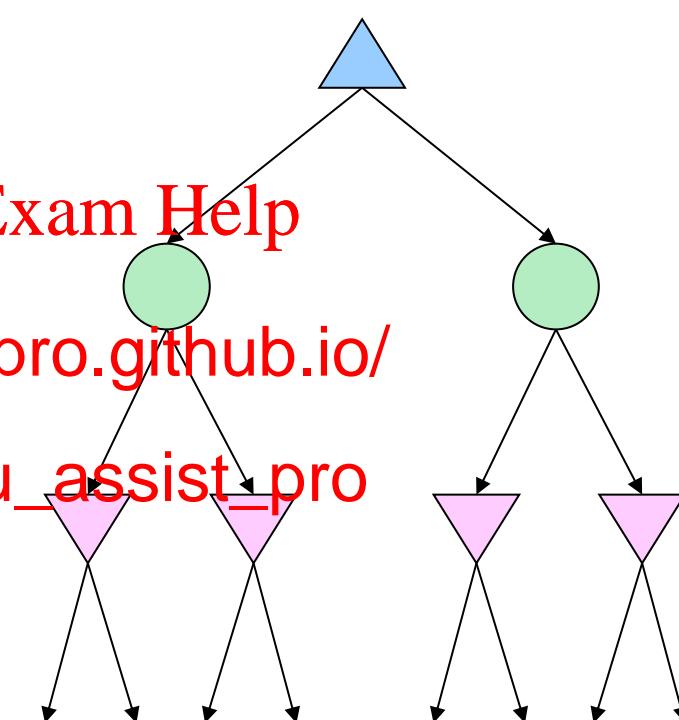
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Mixed Layer Types

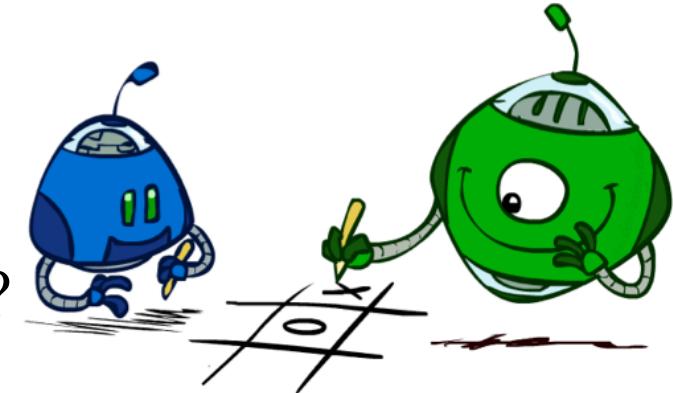
- E.g. Backgammon
- Expectiminimax
 - Environment is an extra “random agent” player that moves after each min/max agent
 - Each node computes the appropriate combination of its children

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Multi-Agent Utilities

- What if the game is not zero-sum, or has multiple players?



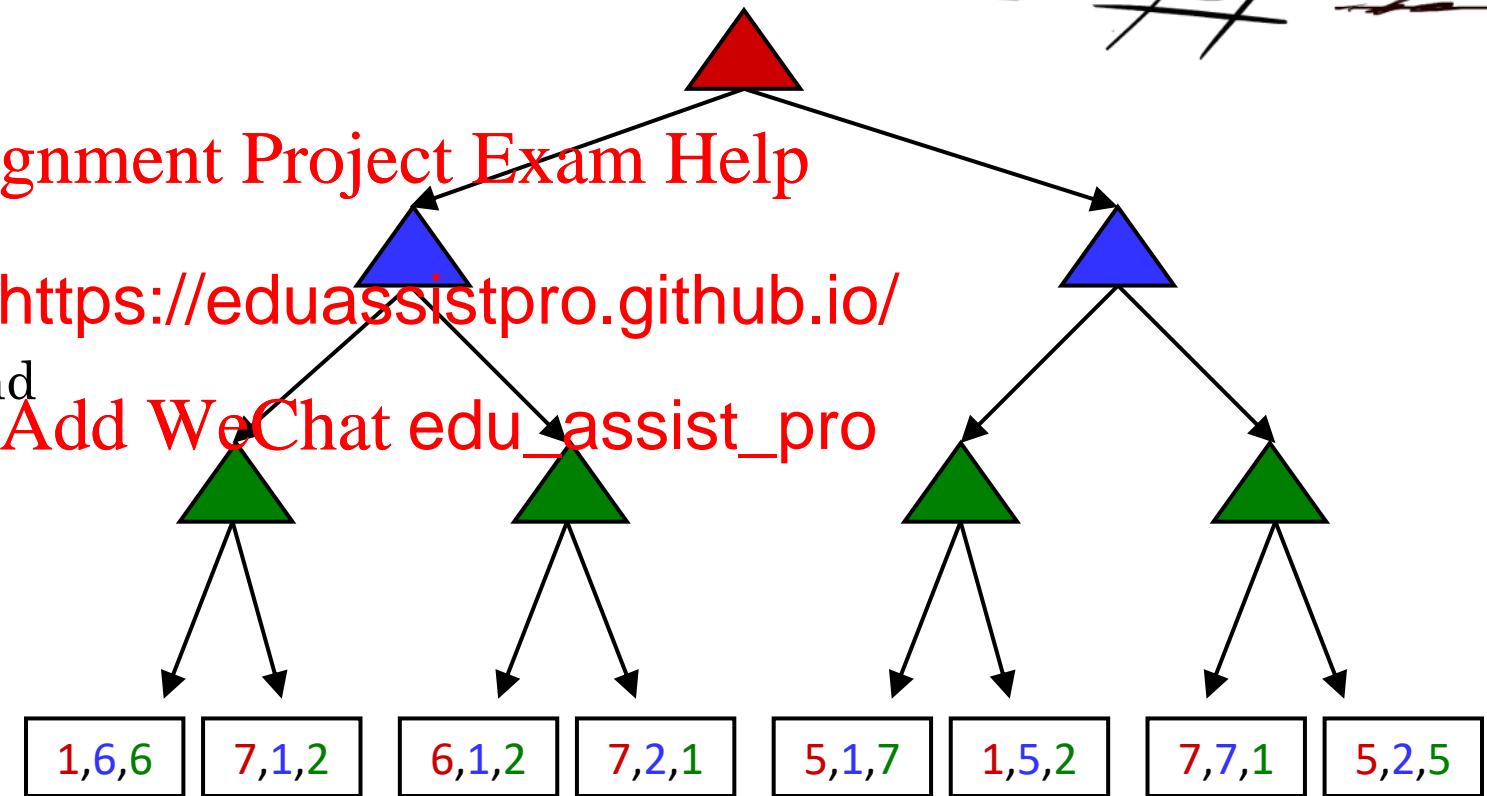
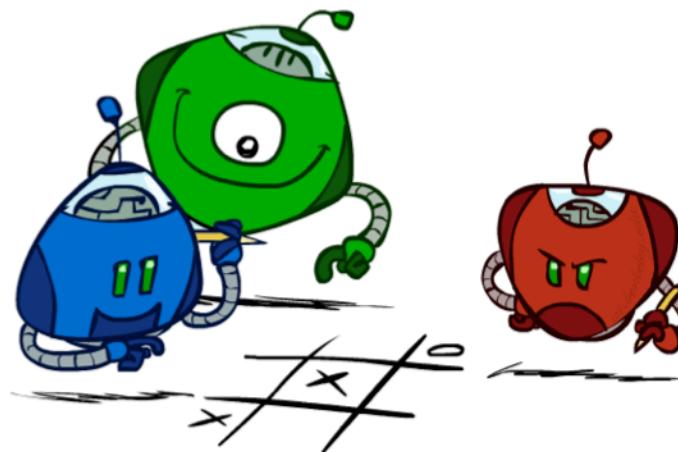
- Generalization of minimax:

- Terminals have utility tuples
- Node values are also utility tu
- Each player maximizes its own utility
- Can give rise to cooperation and competition dynamically...

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Utilities

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Maximum Expected Utility

- Why should we average utilities? Why not minimax?

- Principle of maximum **Assignment Project Exam Help**

- A rational agent should choose its expected utility, given its knowledge <https://eduassistpro.github.io/>

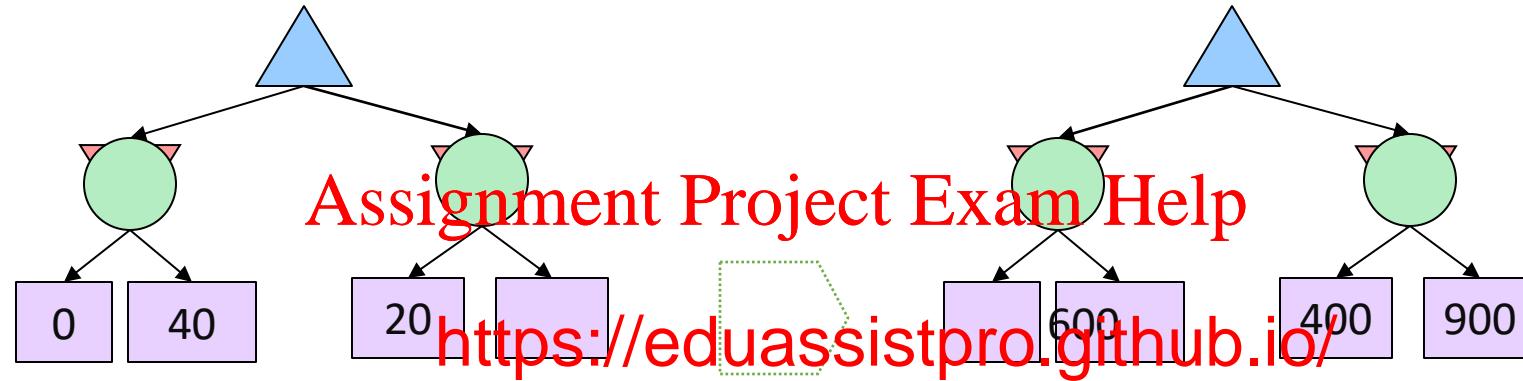
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- Questions:

- Where do utilities come from?
 - How do we know such utilities even exist?
 - How do we know that averaging even makes sense?
 - What if our behavior (preferences) can't be described by utilities?



What Utilities to Use?



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- For worst-case minimax reasoning, terminal function scale doesn't matter
 - We just want better states to have higher evaluations (get the ordering right)
 - We call this **insensitivity to monotonic transformations**
- For average-case expectimax reasoning, we need *magnitudes* to be meaningful



Utilities

- Utilities are functions from outcomes (states of the world) to real numbers that describe an agent's preferences

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- Where do utilities come from?
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- In a game, may be simple (+1/-1)
- Utilities summarize the agent's goals
- Theorem: any “rational” preferences can be summarized as a utility function



Utilities: Uncertain Outcomes



Preferences

- An agent must have preferences among:
 - Prizes: A , B , etc.
 - Lotteries: situations with uncertain prizes

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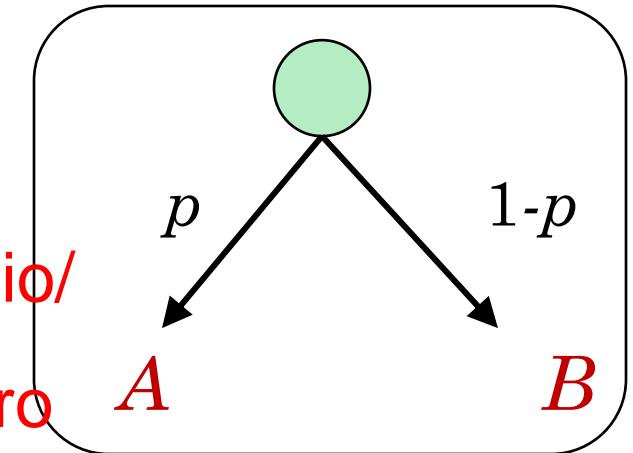
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A Prize



A Lottery



- Notation:

- Preference: $A \succ B$
- Indifference: $A \sim B$



Rationality

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Rational Preferences

- We want some constraints on preferences before we call them rational, such as:

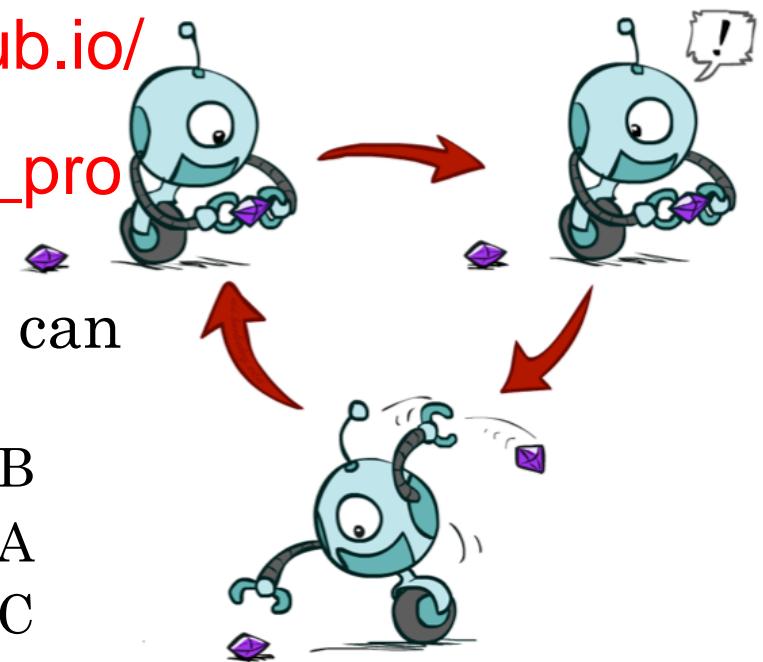
Axiom of Transitivity: $(A \succ B) \wedge (B \succ C) \Rightarrow (A \succ C)$

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- For example: an agent with **intransitive preferences** can be induced to give away all of its money

- If $B > C$, then an agent with C would pay (say) 1 cent to get B
- If $A > B$, then an agent with B would pay (say) 1 cent to get A
- If $C > A$, then an agent with A would pay (say) 1 cent to get C



Rational Preferences

The Axioms of Rationality

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Theorem: Rational preferences imply behavior describable as maximization of expected utility



MEU Principle

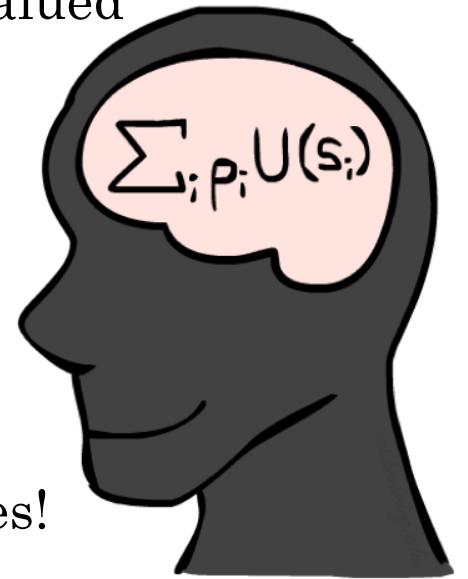
- Theorem [Ramsey, 1931; von Neumann & Morgenstern, 1944]
 - Given any preferences satisfying these constraints, there exists a real-valued function U such that:

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- I.e. values assigned by U preserve preferences of both prizes and lotteries!
- Maximum expected utility (MEU) principle:
 - Choose the action that maximizes expected utility



Human Utilities

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Human Utilities

- Utilities map states to real numbers. Which numbers?
- Standard approach to assessment (elicitation) of human utilities:
 - Compare a prize A to a standard lottery L_p between **Assignment Project Exam Help**
 - “best possible prize” u_+ with
 - “worst possible catastrophe” <https://eduassistpro.github.io/>
- Adjust lottery probability p
- Resulting p is a utility in $[0,1]$ **Add WeChat edu_assist_pro**



Human Utilities: Example

- A person is given the choice between 2 scenarios:
 - Guaranteed scenario: the person receives \$50
 - Uncertain scenario: a coin is flipped to decide the person receive \$100 or not.
- Which choice would that person make?
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Risk Aversion

- **Risk averse:** would accept the guaranteed payment of (less than) \$50 rather than take the gamble

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- **Risk neutral:** indifferent between the bet and the guaranteed \$50 payment

- **Risk seeking:** would accept the bet even when the guaranteed payment is more than \$50

Prospect Theory: Utility Function

- Risk aversion: convexity

- Risk averse regarding gain
- Risk seeking regarding loss

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- Loss aversion

- Losses are felt more strongly than gains

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- Endowment effect

- We value things we own more highly
- Reference point: differentiate gains and losses