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COMP90038

Algorithms and Complexity

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Lecture 10: Devising a \sqrt{n} -by-a-Factor
(with thanks to Hara Ergaard)

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Decrease-and-Conquer

- **Last lecture:** to solve a problem of size n , try to express the solution in terms of a solution to the same problem of size $n-1$.
- A simple example was sorting: To sort an array of length n , just:
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 1. sort the first $n - 1$
 2. locate the cell $A[j]$ that should hold the last item, right-shift all elements to its right, then place the last element in $A[j]$.
- This led to an $O(n^2)$ algorithm called **insertion sort**. We can implement the idea either with recursion or iteration (we chose iteration).

Decrease-and-Conquer by-a-Factor

- We now look at better utilization of the approach, often leading to methods with logarithmic time behaviour or better!

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- **Decrease-by-a-c** is exemplified by binary search.

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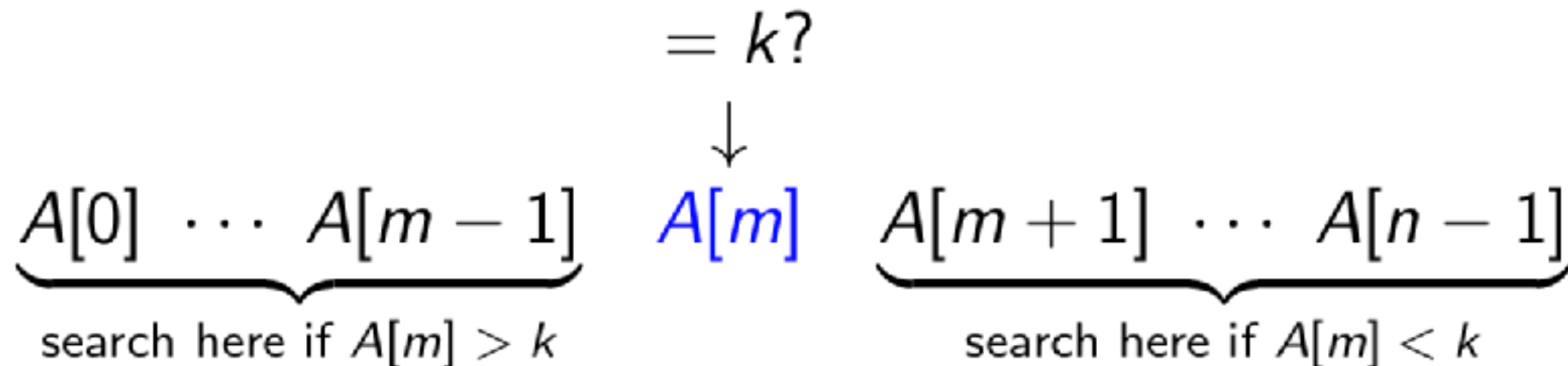
- **Decrease-by-a-variable-factor** is exemplified by interpolation search.
- Let us look at these and other instances.

Binary Search

- This is a well-known approach for searching for an element k in a sorted array.
- Start by comparing against the array's middle element $A[m]$. If $A[m] = k$ we are done.

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- If $A[m] > k$, search the sub-array $A[0] \dots A[m-1]$ recursively.
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- If $A[m] < k$, search the sub-array $A[m+1] \dots A[n-1]$ recursively.
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Binary Search

- We have already seen a recursive formulation in Lecture 4. Here is an iterative one.

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Example: Binary Search in Sorted Array



k: 41

lo: 0

hi: 6

m: 3

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A:

4	9	13	22	41	83	96
0	1	2	3	4	5	6

BinSearch(A,7,41)

Example: Binary Search in Sorted Array



k: 41

lo: 4

hi: 6

m: 3

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BinSearch(A,7,41)

Complexity of Binary Search



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- Worst-case input to binary search:
 - When k is not in the array
- In that case, its complexity is given by the following recursive equation:

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- A closed form is:
- In the worst case, searching for k in an array of size 1,000,000 requires 20 comparisons.
- The average-case time complexity is also $\Theta(\log n)$

Russian Peasant Multiplication



- A way of doing multiplication.

- For even n :

$$n \cdot m = \frac{n}{2} \cdot 2m$$

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- For odd n :

$$n \cdot m = \frac{n-1}{2} \cdot 2m + m$$

- Thus, ~halve n repeatedly, until $n = 1$. Add up all odd values of m

n	m	
81	92	92
40	184	
20	368	
10	736	
5	1472	1472
2	2944	
1	5888	5888
		<hr/>
		= 7452

Finding the Median

- Given an array, an important problem is how to find the **median**, that is, an array value which is no larger than half the elements and no smaller than half.

A:

9	23	3	41	22	8	46
0	1	2	3	4	5	6

- More generally, we would like to solve the problem of finding the kth smallest element. (e.g. w

A:

9	23	3	41			46
0	1	2	3	4	5	6

- If the array is sorted, the solution is straight-forward, so one approach is to start by sorting (as we'll soon see, this can be done in time $O(n \log n)$).

A:

3	8	9	22	23	41	46
0	1	2	3	4	5	6

- However, sorting the array seems like overkill.

A Detour via Partitioning

- Partitioning an array around some pivot element p means reorganizing the array so that all elements to the left of p are no greater than p , while those to the right are no smaller.

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A:

9	23					46
0	1	2	3	4	5	6

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Partitioning around the pivot 9

A:

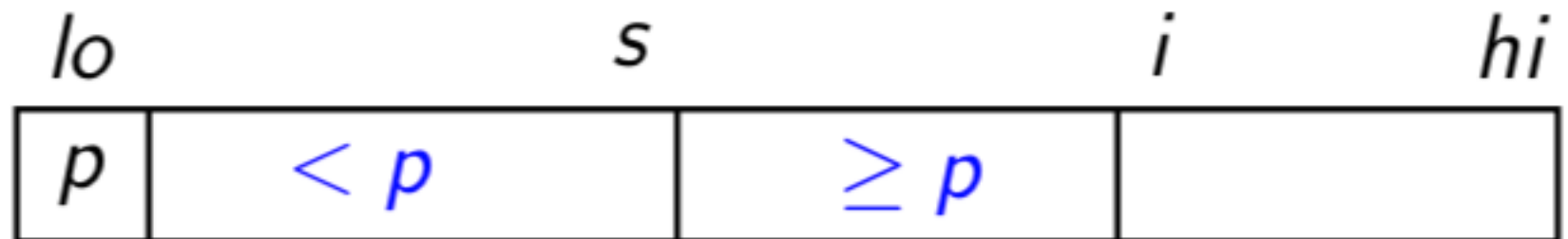
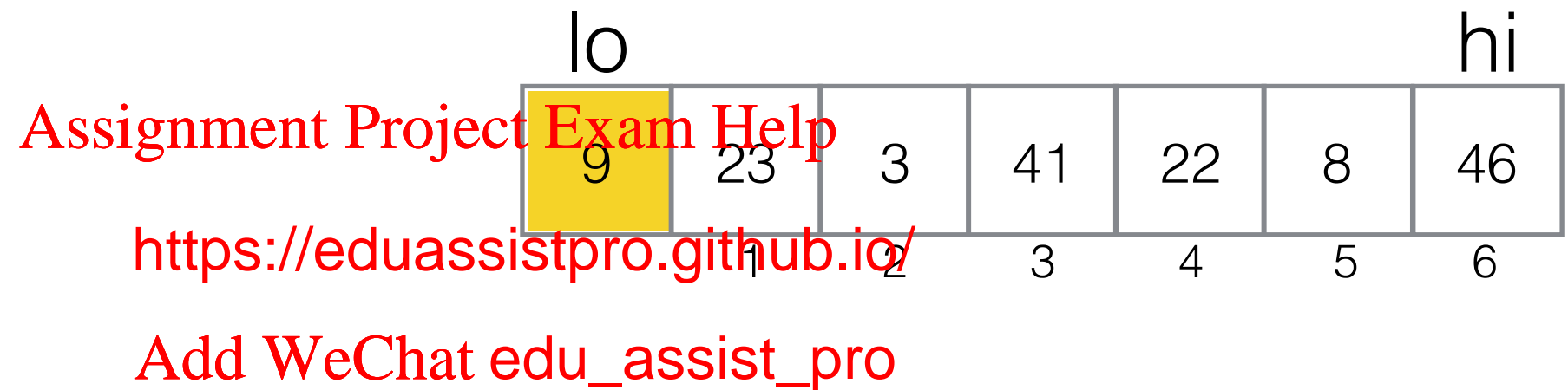
3	8	9	23	22	41	46
0	1	2	3	4	5	6

Lomuto Partitioning



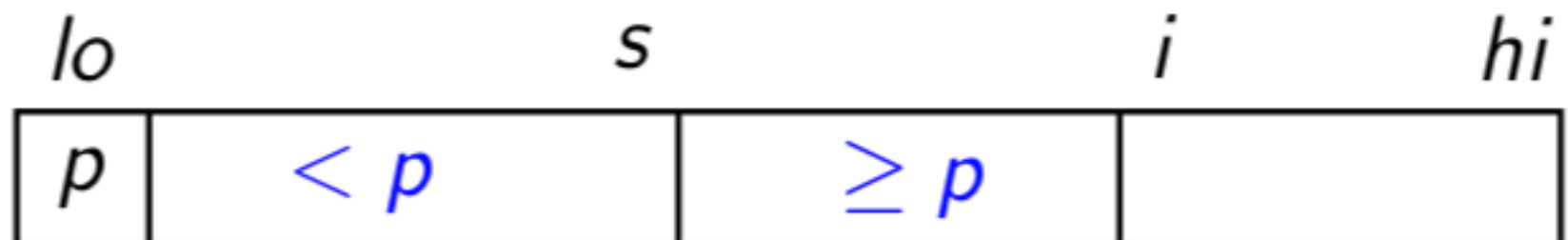
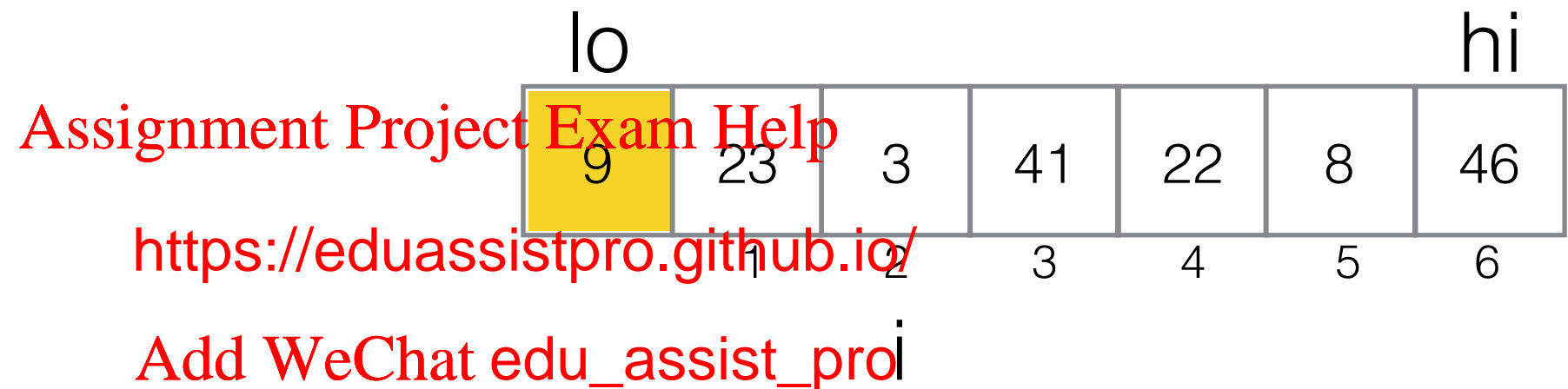
function LOMUTOPARTITION($A[\cdot]$, lo , hi)

...



Lomuto Partitioning

function LOMUTOPARTITION($A[\cdot]$, lo , hi)

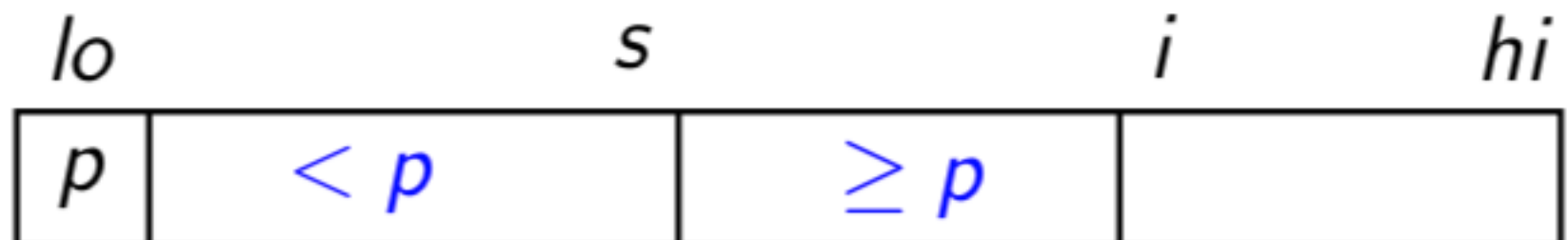
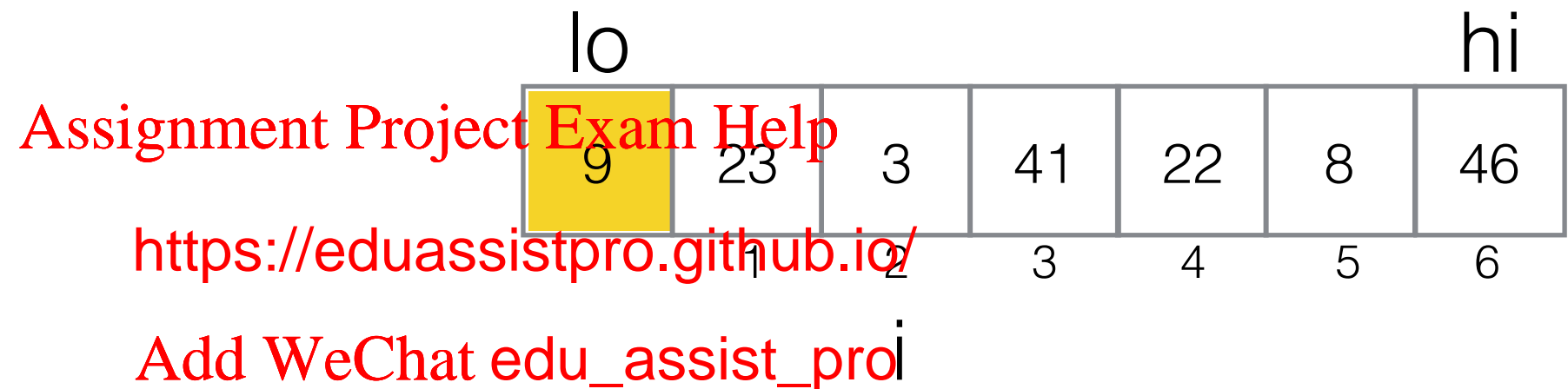


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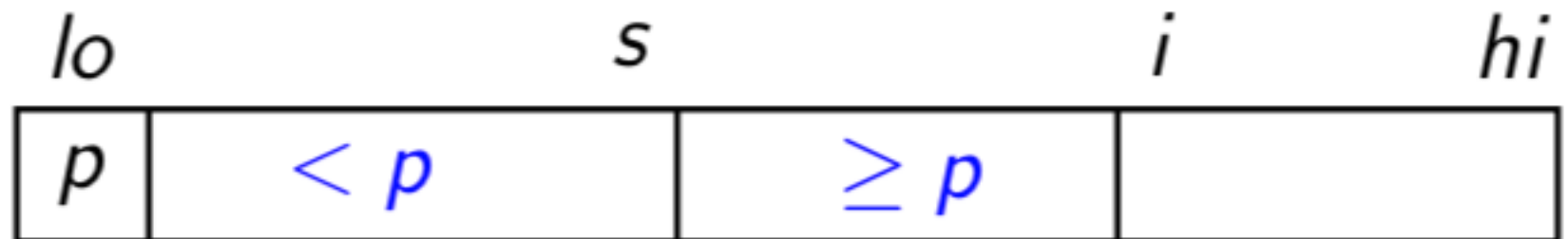
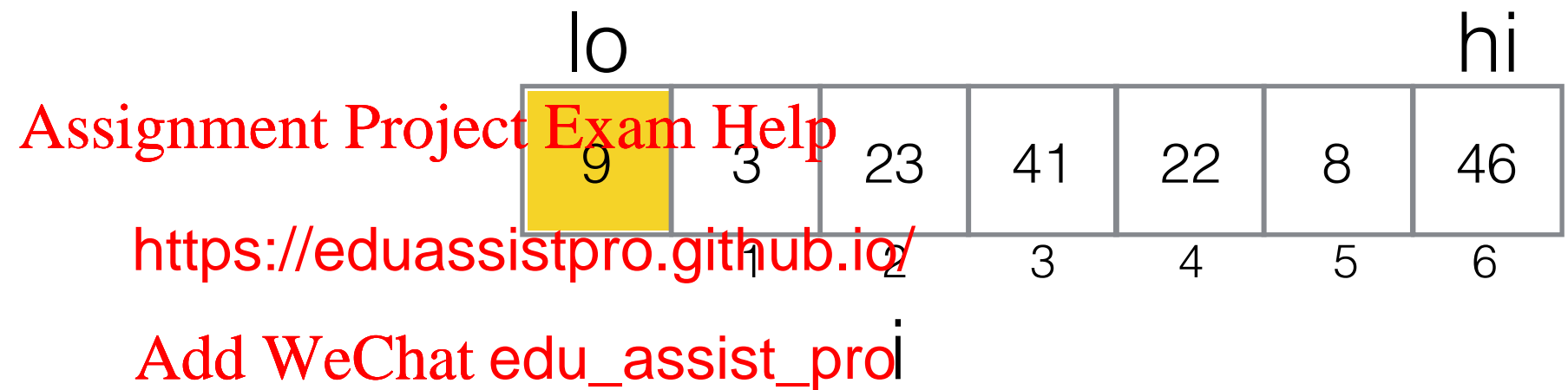


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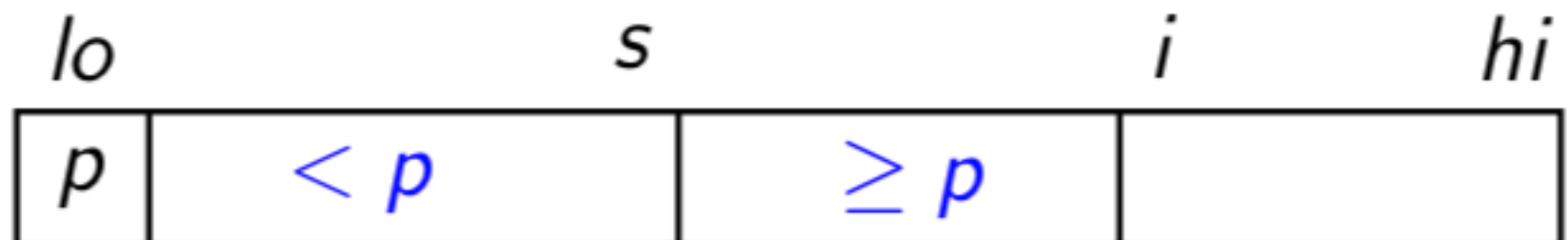
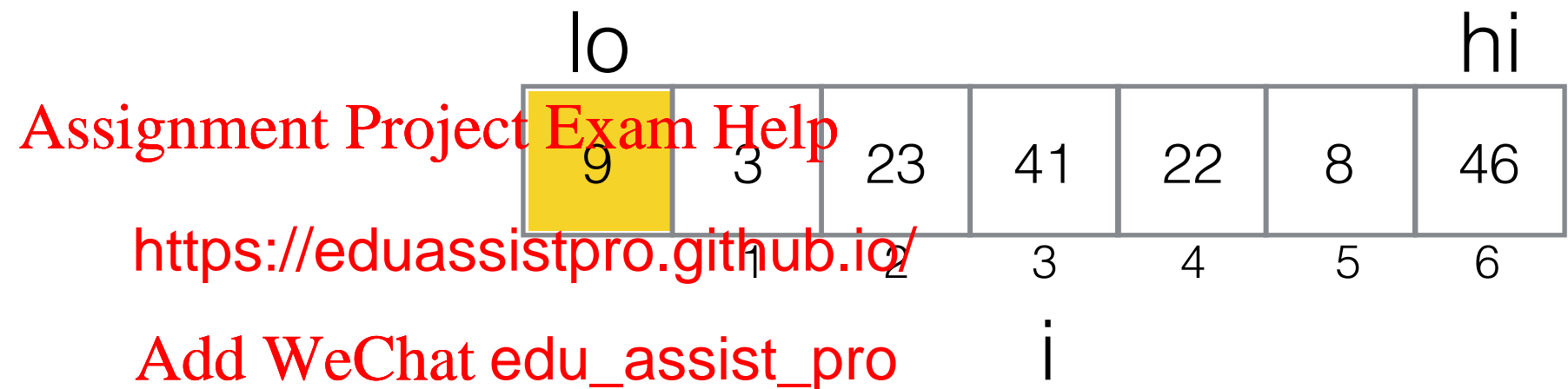
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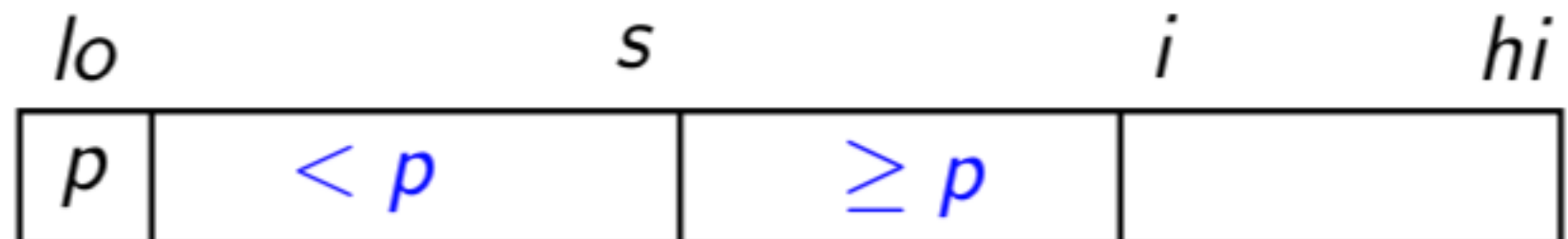
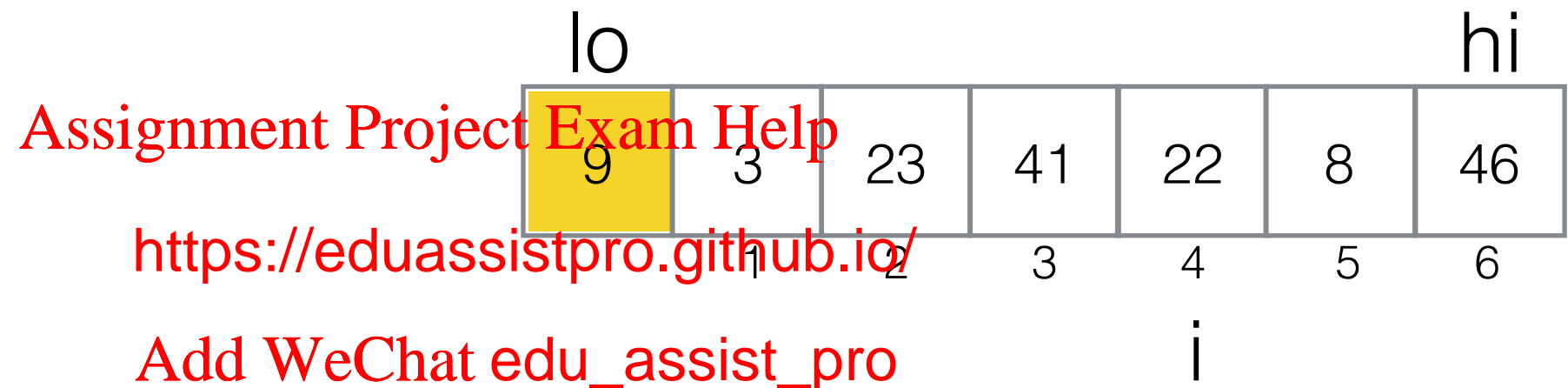


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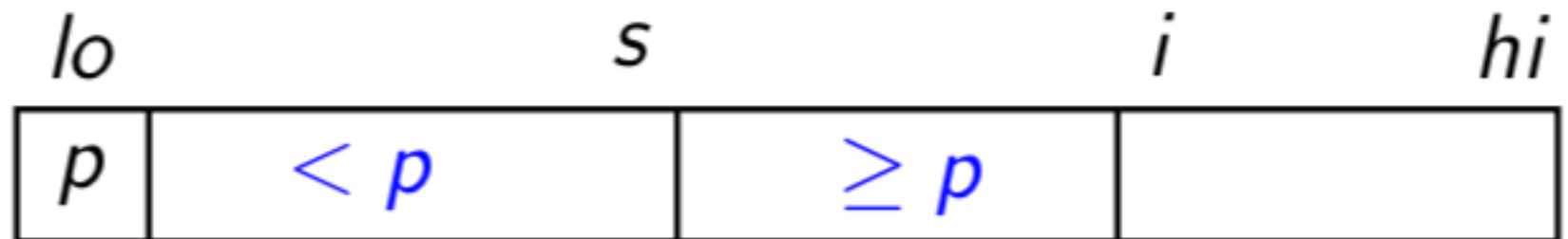
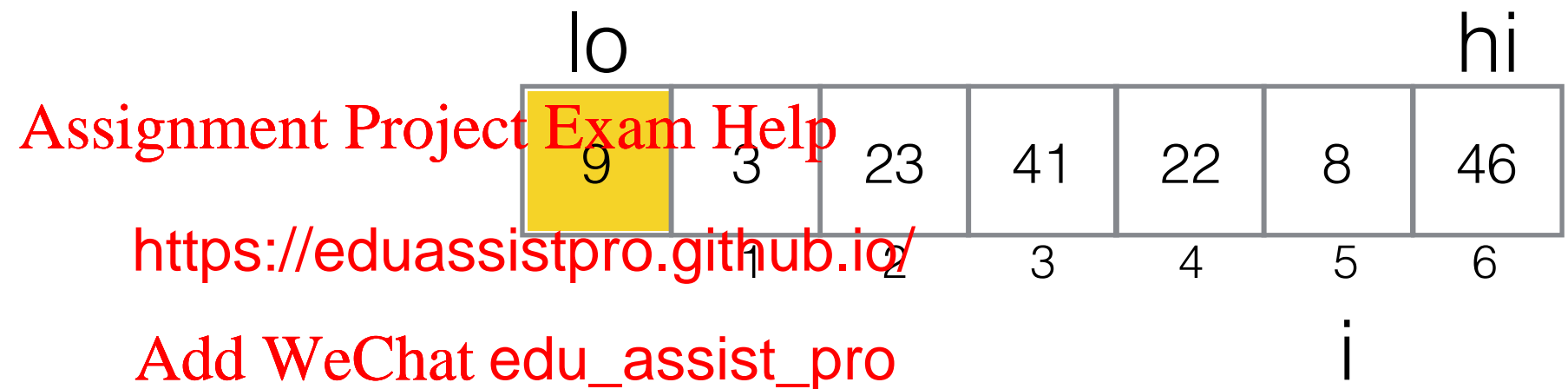


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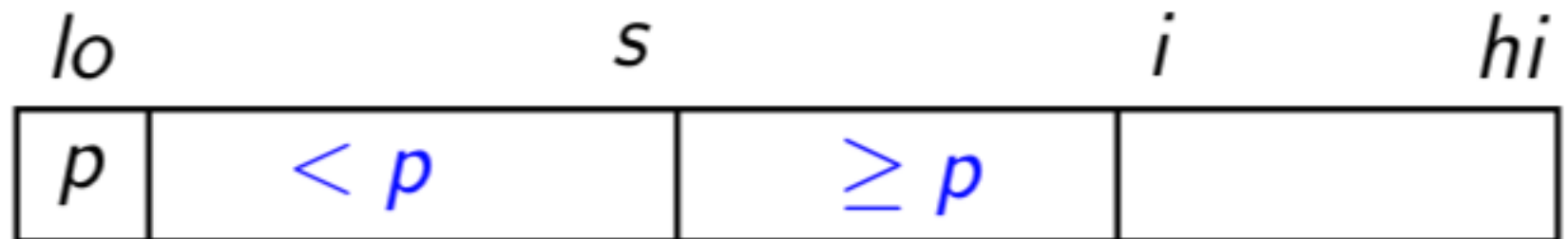
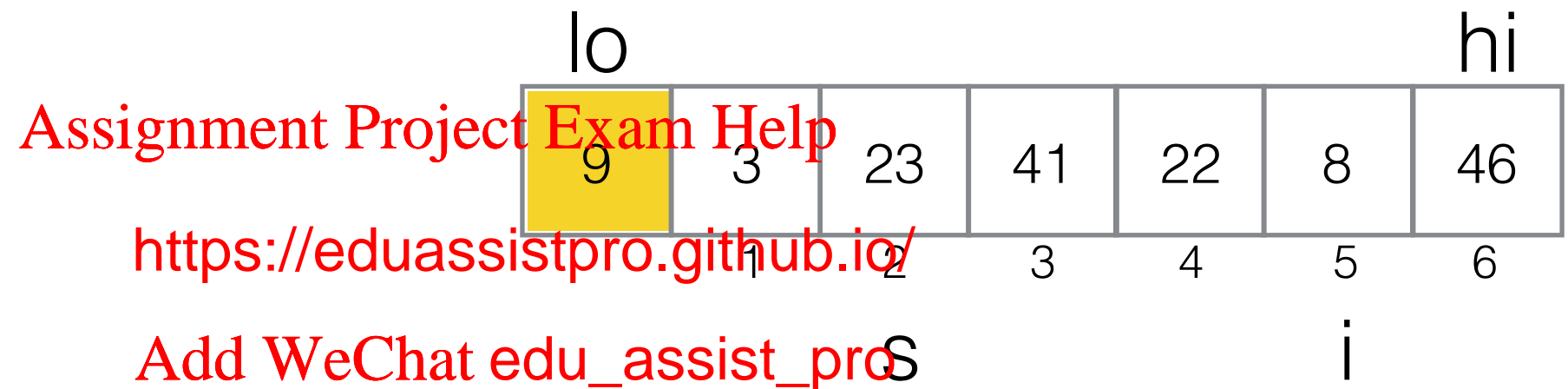


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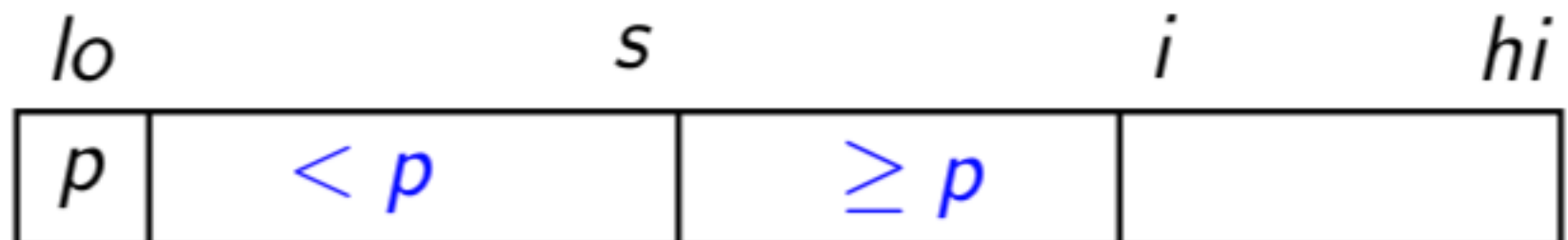
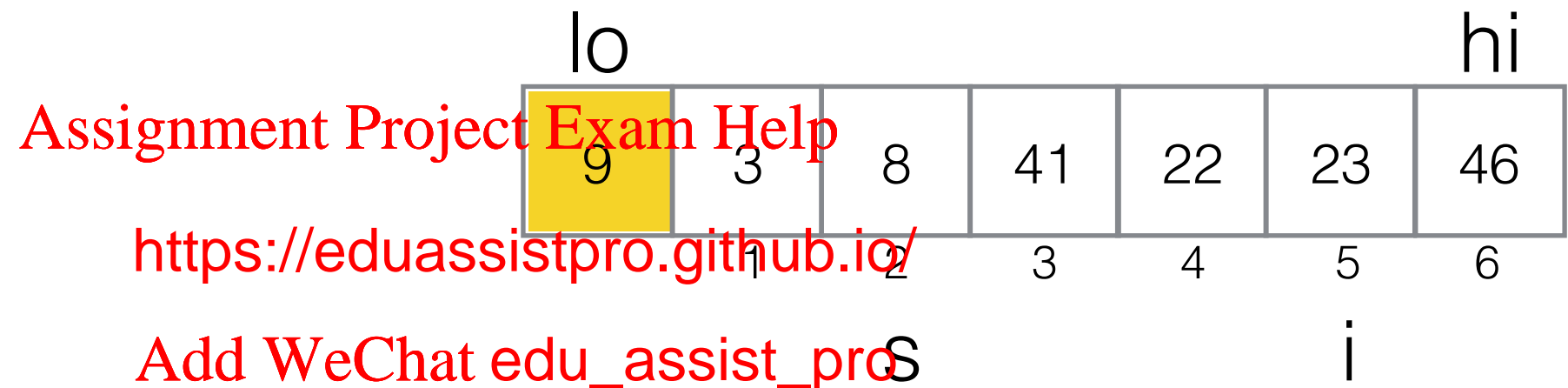


Lomuto Partitioning



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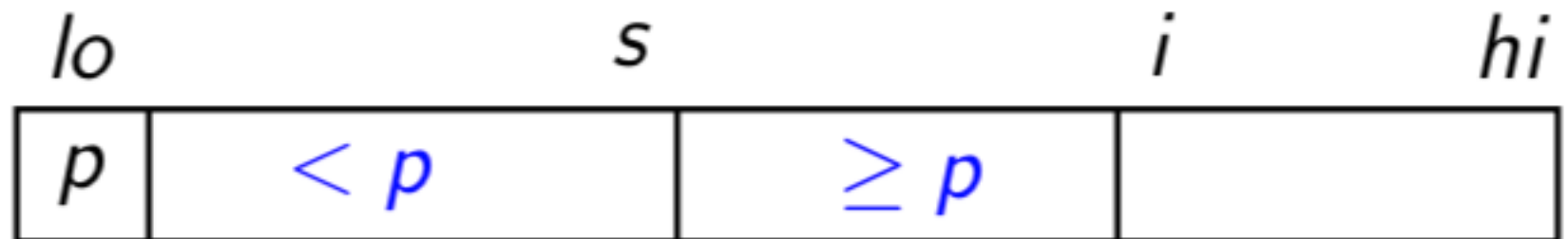
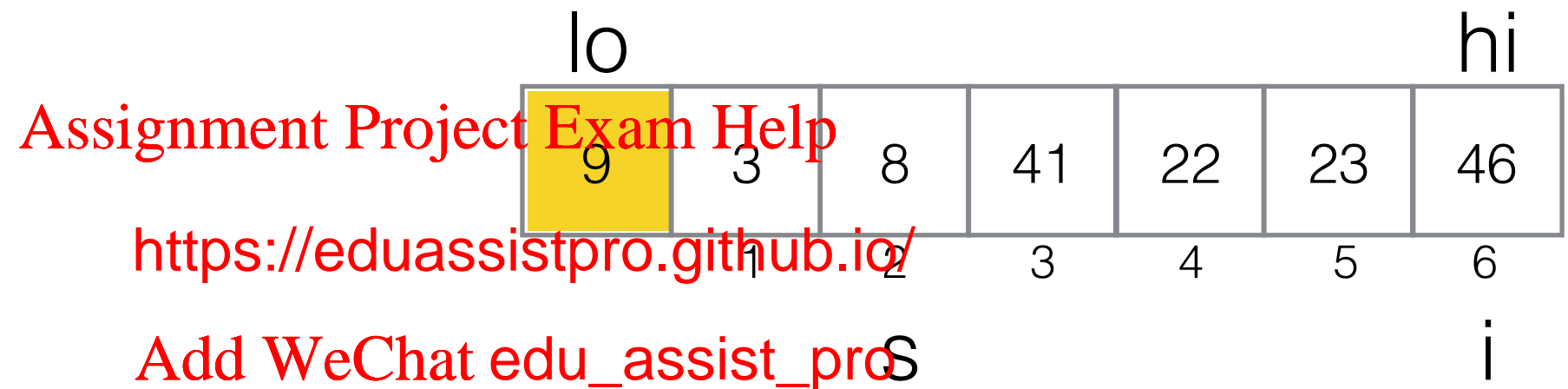


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function LOMUTOPARTITION($A[\cdot]$, lo , hi)

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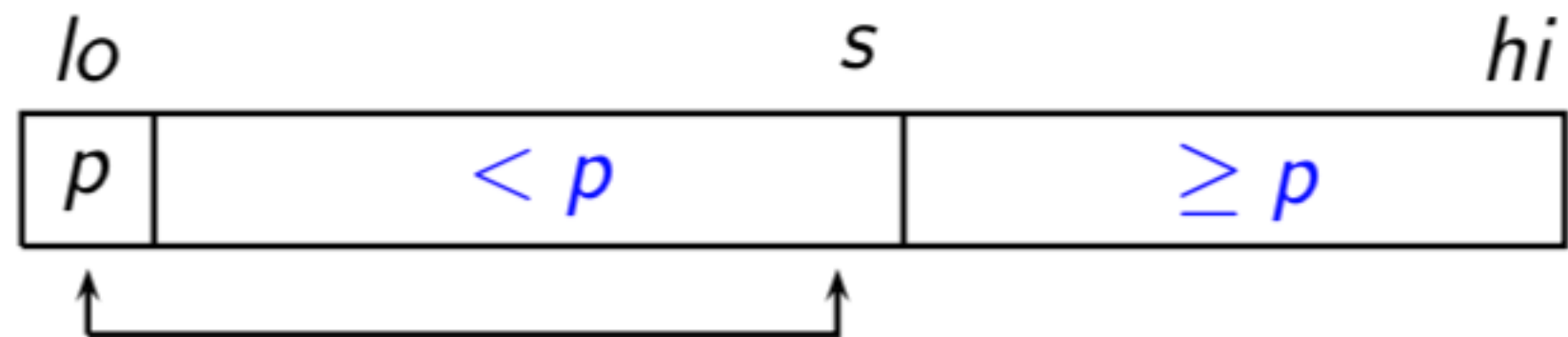
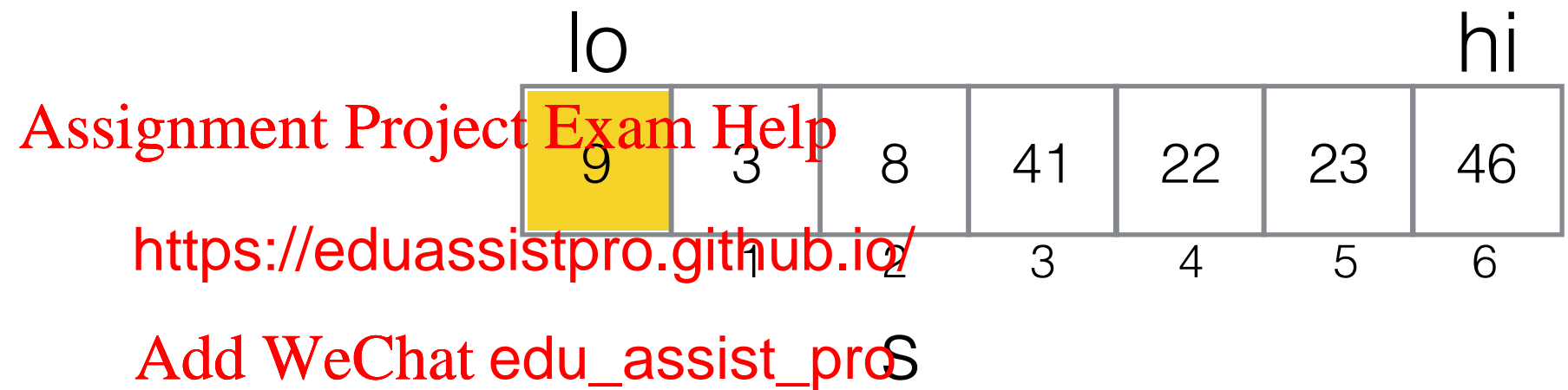


Lomuto Partitioning



function LOMUTOPARTITION($A[\cdot]$, lo , hi)

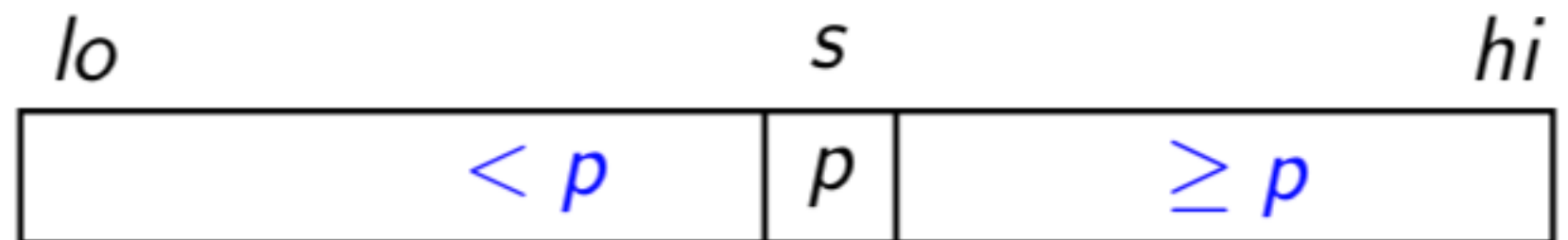
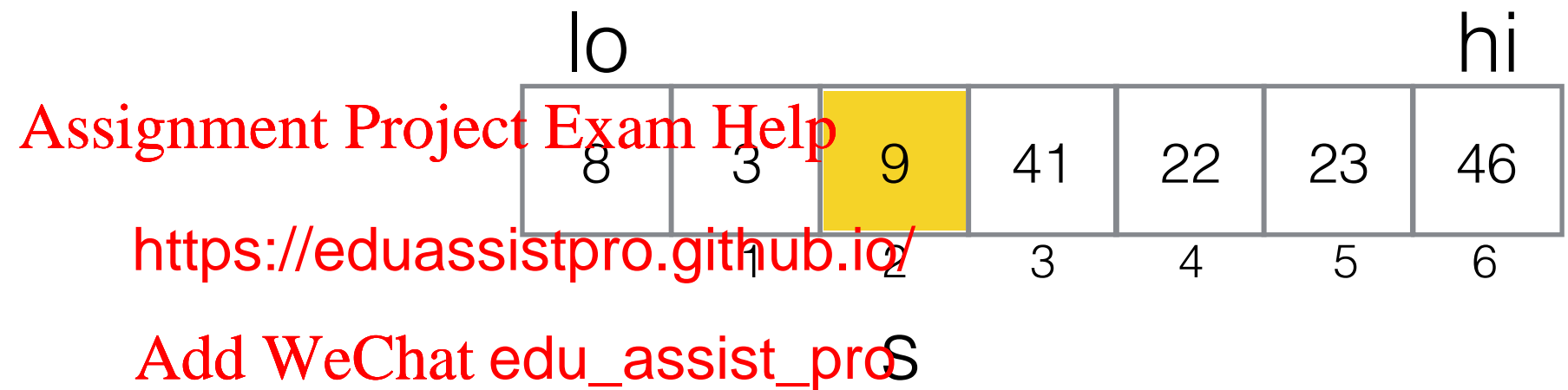
...



Lomuto Partitioning



```
function LOMUTOPARTITION( $A[\cdot]$ ,  $lo$ ,  $hi$ )  
    ...
```



Finding the k th-smallest Element



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lo			hi			
8	3	9	41	22	23	46
0	1	2	3	4	5	6
S						

Example: Find the Sixth Smallest Element

k: 6

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lo							hi	
9	23	3	41	22	8	46		
0	1	2	3	4	5	6		

Example: Find the Fifth Smallest Element

k: 6

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lo			hi			
8	3	9	41	22	23	46
0	1	2	3	4	5	6
S						

Example: Find the Fifth Smallest Element

k: 3

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lo			hi			
8	3	9	41	22	23	46
0	1	2	3	4	5	6

Example: Find the Fifth Smallest Element



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function LOMUTOPARTITION($A[\cdot]$, lo , hi)

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			lo				hi
8	3	9	41	22	23	46	
0	1	2	3	4	5	6	
			s	i			

Example: Find the Fifth Smallest Element



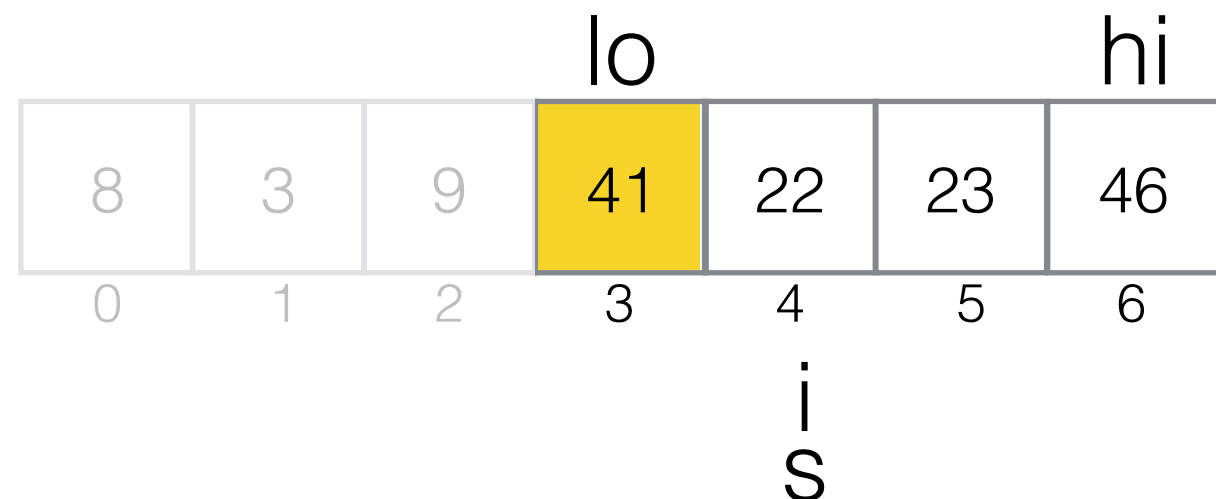
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function LOMUTOPARTITION($A[\cdot]$, lo , hi)

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Example: Find the Fifth Smallest Element



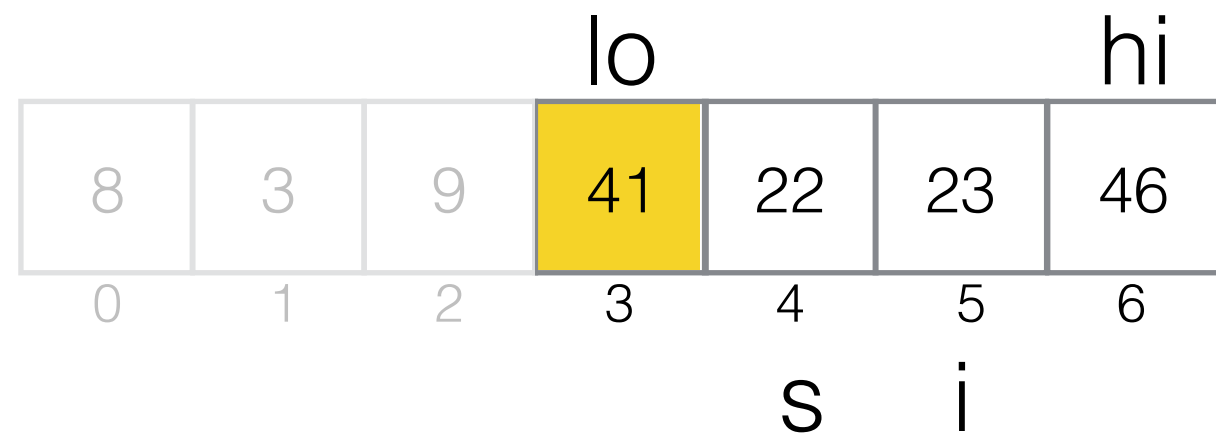
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...

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Example: Find the Fifth Smallest Element



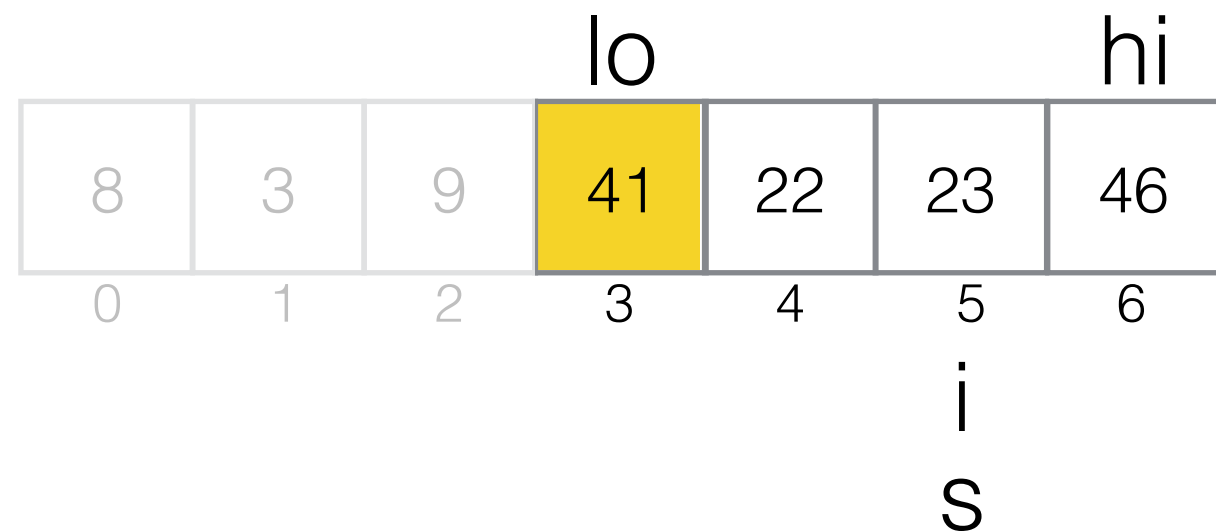
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Example: Find the Fifth Smallest Element



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function LOMUTOPARTITION($A[\cdot]$, lo , hi)

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			lo				hi
8	3	9	41	22	23	46	
0	1	2	3	4	5	6	
					s	i	

Example: Find the Fifth Smallest Element



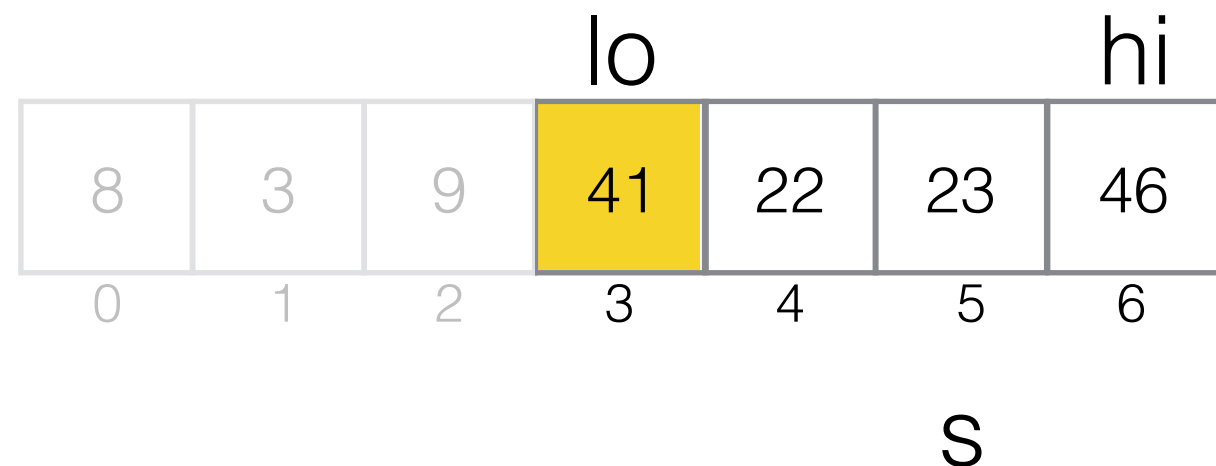
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Example: Find the Fifth Smallest Element



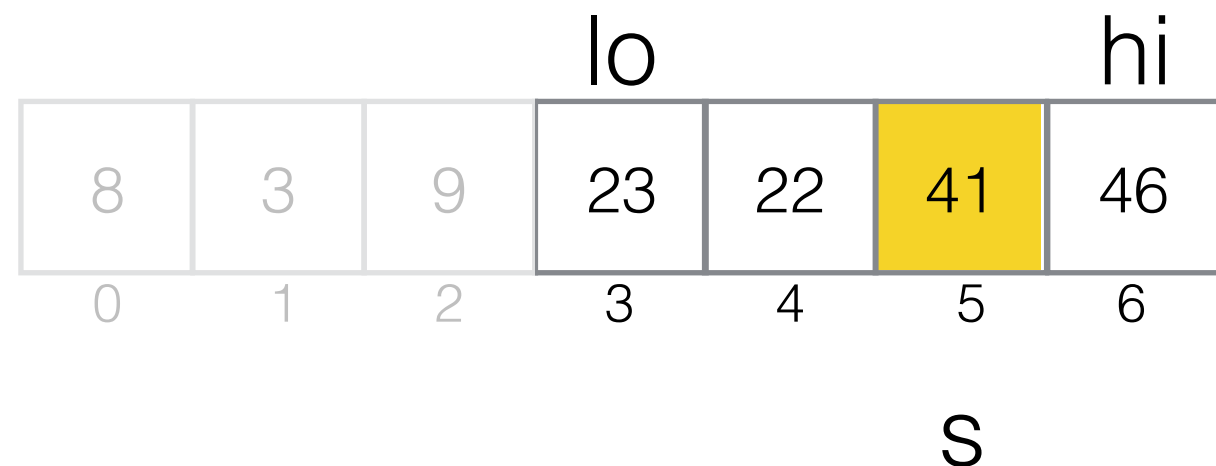
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...

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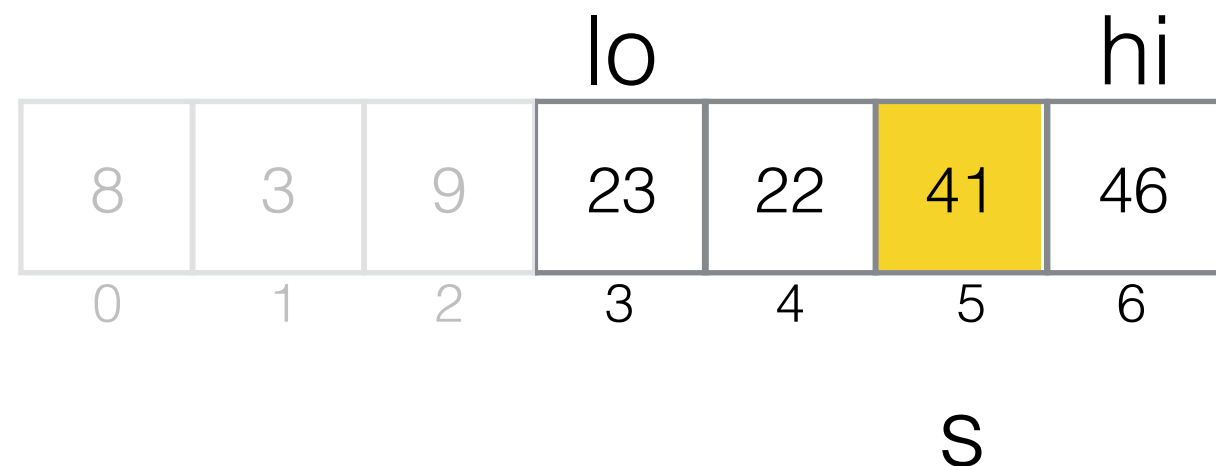
Example: Find the Fifth Smallest Element

k: 3

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Example: Find the Fifth Smallest Element

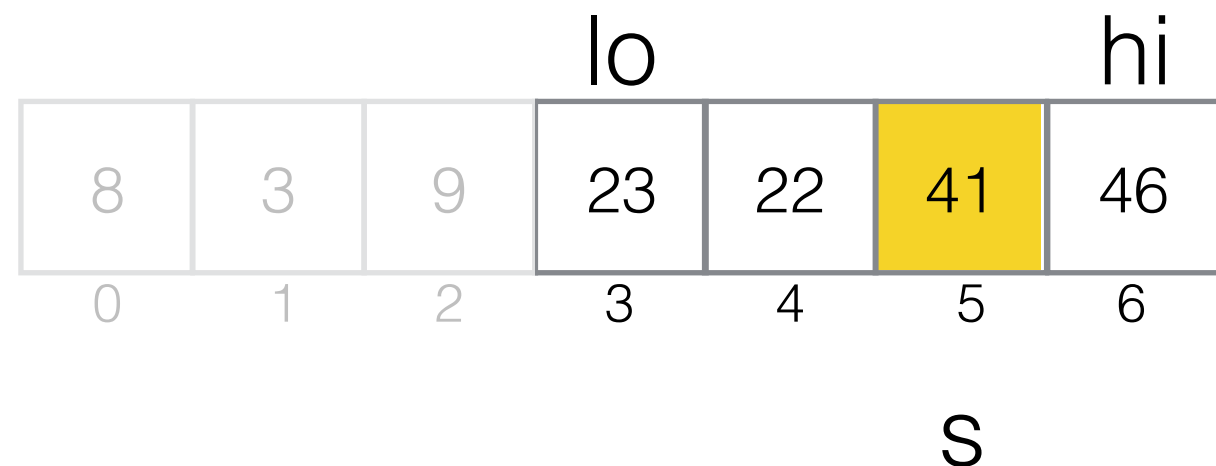
k: 3

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returns 41!



QuickSelect Complexity

- **Worst-case** complexity is quadratic,
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- **Average-case** complexity is linear.

Interpolation Search

- If the elements of a sorted array are distributed reasonably evenly, we can do better than binary search!
- Think about how you search for an entry in the telephone directory. If you know the name is 'Aobel', you make a rough estimate of its position. If you know it's close to the end of the directory, you make a probe—very close to the end of the directory.
- This is the idea in interpolation search.
- When searching for k in the array segment $A[lo]$ to $A[hi]$, take into account where k is, relative to $A[lo]$ and $A[hi]$.

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Interpolation Search



A:

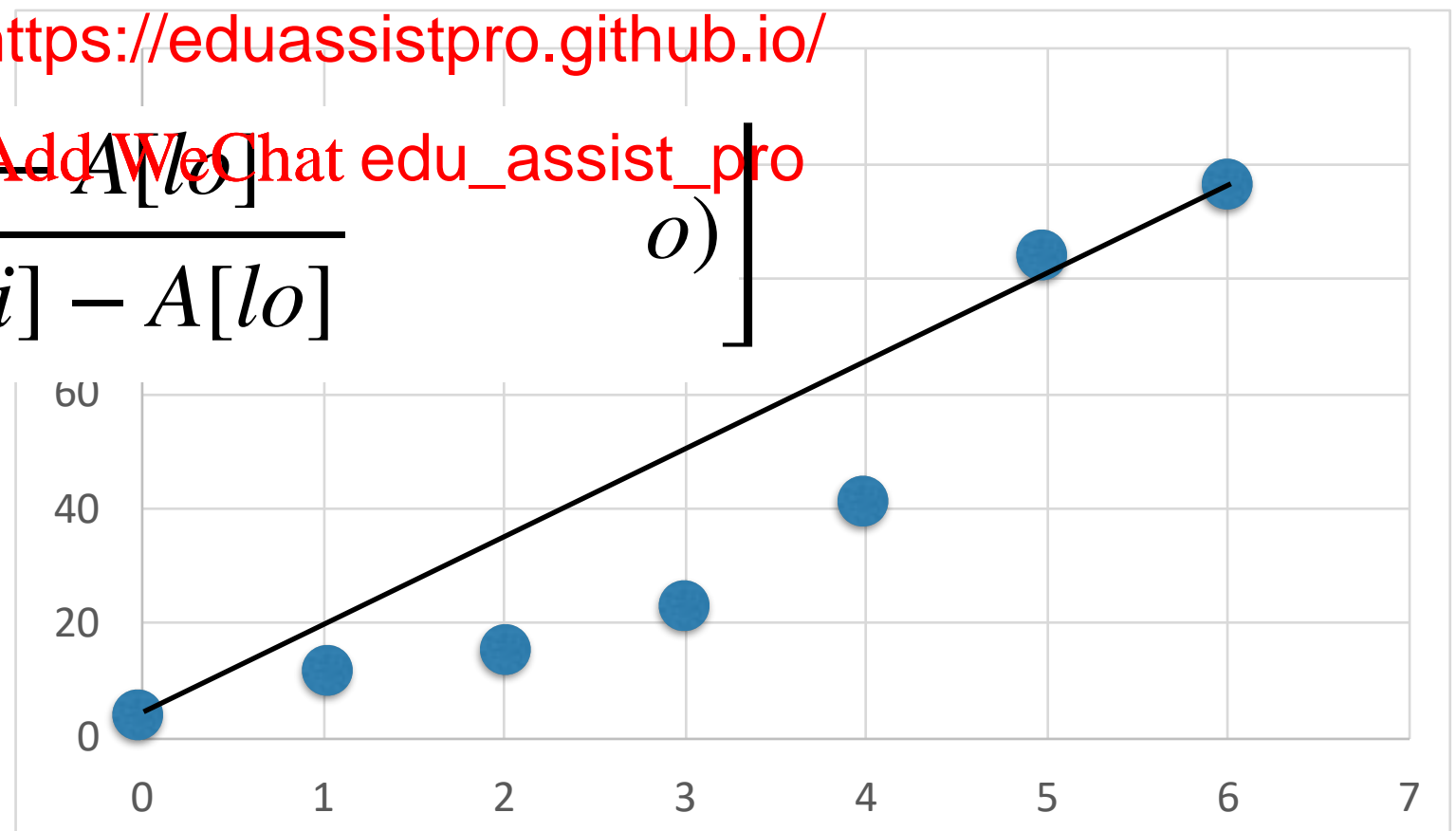
4	9	13	22	41	83	96
0	1	2	3	4	5	6

Suppose we are searching for $k = 83$

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$$mid = A[lo] + \left\lfloor \frac{k - A[lo]}{A[hi] - A[lo]} \right\rfloor$$



Interpolation Search

- Instead of computing the mid-point m as in binary search:

$$m \leftarrow \lfloor (lo + hi)/2 \rfloor$$

we instead perform linear interpolation between the points $(lo, A[lo])$ and $(hi, A[hi])$

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$$m \leftarrow lo + \left\lfloor \frac{(A[hi] - A[lo])}{(i - A[lo])} (i - lo) \right\rfloor$$

- Interpolation search has average complexity $O(\log \log n)$
- It is the right choice for large arrays when elements are **uniformly distributed**

Next Week

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- Learn to divide a <https://eduassistpro.github.io/>
- Read Levitin Chapter 5, but [Add WeChat edu_assist_pro](#).4.