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Logistic Regression and MaxEnt

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- Generative models:

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$$\Pr[y | \mathbf{x}] = \frac{\Pr[\mathbf{x} | y] \Pr[y]}{\Pr[\mathbf{x}]}$$

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- Example: Naive Bayes.
- Discriminative models:
 - Models $\Pr[y | \mathbf{x}]$ directly as $g(\mathbf{x})$
 - Example: Decision tree, Logistic Regre
- Instance-based Learning.
 - Example: k NN classifier.

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Figure: Linear Regres

Task

- Input: $(x^{(i)}, y^{(i)})$ pairs ($1 \leq i \leq n$)
- Preprocess: let $\mathbf{x}^{(i)} = [1 \quad x^{(i)}]^\top$
- Output: The best $\mathbf{w} = [w_0 \quad w_1]^\top$ such that $\hat{y} = \mathbf{w}^\top \mathbf{x}$ best explains the observations

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Find \mathbf{w} such that ℓ is minimized.

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Taylor Series of $f(x)$ at point a

$$f(x) = \sum_{n=0}^{+\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n$$

— $(x-a)^2$ (2)
a if it is

- close to x .
- If $f(x)$ has local minimum x^* then
 - $f'(x^*) = 0$, and
 - $f''(x^*) > 0$.

Minimum of the local minima is the global minimum if it is smaller than the function values at all the boundary points.

- Intuitively, $f(x)$ is almost $f(a) + \frac{f''(a)}{2}(x-a)^2$ if a is close to x^* .

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$$\frac{\partial \ell}{\partial w_j} = \sum_{i=1}^n 2 \epsilon_i \frac{\partial \epsilon_i}{\partial w_j} = \sum_{i=1}^n 2 \epsilon_i \frac{\partial \mathbf{w}^\top \mathbf{x}^{(i)}}{\partial w_j}$$

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By setting the above to 0, this essentially requires, f

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$$\sum_{i=1}^n \hat{y}^{(i)} x_j^{(i)} = \sum_{i=1}^n y^{(i)} x_j^{(i)}$$

what the model predicts

what the data says

Find the Least Square Fit for Linear Regression

In the simple 1D case, we have only two parameters in $\mathbf{w} = \begin{bmatrix} w_0 \\ w_1 \end{bmatrix}$

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$$\sum_{i=1}^n (w_0 + w_1 x_1^{(i)}) x_0^{(i)} = \sum_{i=1}^n y^{(i)} x_0^{(i)}$$

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Since $x_0^{(i)} = 1$, they are essentially

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$$\sum_{i=1}^n (w_0 + w_1 x_1^{(i)}) \cdot 1 =$$

$i=1$

$$\sum_{i=1}^n (w_0 + w_1 x_1^{(i)}) \cdot x_1^{(i)} = \sum_{i=1}^n y^{(i)} \cdot x_1^{(i)}$$

Example

Using the same example in [https://en.wikipedia.org/wiki/Linear_least_squares_\(mathematics\)](https://en.wikipedia.org/wiki/Linear_least_squares_(mathematics))

$$\mathbf{X} = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 6 \\ 5 \\ 7 \\ 10 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix} \begin{bmatrix} 6 \\ 5 \\ 7 \\ 10 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 1 & 4 \end{bmatrix} \begin{bmatrix} \hat{y}_3 \\ \hat{y}_4 \end{bmatrix}$$

- Easily generalizes to more than 2-dim:

$$\begin{matrix} 1 & x_1^{(1)} & \dots & x_m^{(1)} & & y^{(1)} \\ & 1 & \dots & \dots & w_0 & \vdots \\ & & & & & y^{(i)} \\ & & & & & \vdots \\ & & & & & y^{(n)} \end{matrix}$$

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- How to perform polynomial regression for x ?

$\hat{y} = w_0 + w_1 x + w_2 x^2 + \dots + w_m x^m$

- Let $x_j^{(i)} = (x_1^{(i)})^j \implies$ Polynomi

([http://mathworld.wolfram.com/](http://mathworld.wolfram.com/LeastSquaresFittingPolynomial.html)

[LeastSquaresFittingPolynomial.html](http://mathworld.wolfram.com/LeastSquaresFittingPolynomial.html))

High-level idea:

- Any \mathbf{w} is possible, but some \mathbf{w} is most likely.

- $P(y^{(i)} | \hat{y}^{(i)}) = f_i(\mathbf{w})$

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- If we also incorporate some prior on
Maximum Posterior Estimation (MAP)

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- If we assume some Gaussian prior on \mathbf{w} , we can add a regularization term to the objective

- Many models and their variants can be deemed as different ways of estimating $P(y^{(i)} | \hat{y}^{(i)})$

Find \mathbf{w} such that $\|\mathbf{y} - \mathbf{X}\mathbf{w}\|_2$ is minimized.

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- What is $\mathbf{X}\mathbf{w}$ when \mathbf{X} is fixed?
 - It is the hyperplane spanned by the d column vectors of \mathbf{X} .

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column of \mathbf{X} as X_i)

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$$\left. \begin{array}{l} X_1^\top (\mathbf{y} - \mathbf{X}\mathbf{w}) = 0 \\ X_2^\top (\mathbf{y} - \mathbf{X}\mathbf{w}) = 0 \\ \dots\dots\dots \\ X_d^\top (\mathbf{y} - \mathbf{X}\mathbf{w}) = 0 \end{array} \right\} \implies \mathbf{X}^\top (\mathbf{y} - \mathbf{X}\mathbf{w}) = \mathbf{0}$$

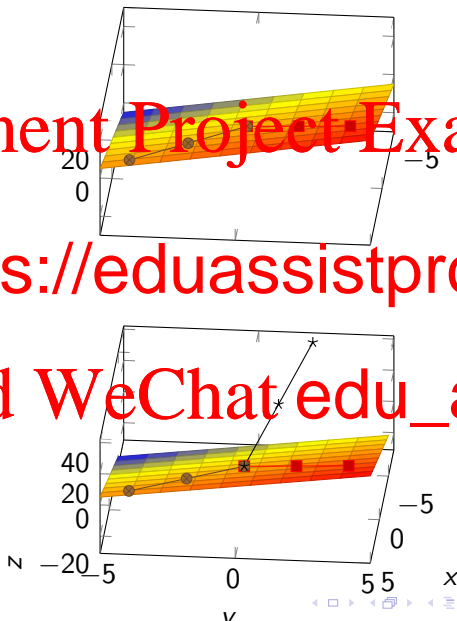
- $\mathbf{w} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y} = \mathbf{X}^+ \mathbf{y}$

(\mathbf{X}^+ : pseudo inverse of \mathbf{X})

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Special case: $y^{(i)} \in \{0, 1\}$.

- Not appropriate to directly regress $y^{(i)}$.
- Rather model $y^{(i)}$ as the observed outcome of a Bernoulli trial with an unknown parameter p_i .

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- What can we say about $p_{x+\epsilon}$ w
- Answer: we impose a linear relationship bet
 - What about a simple linear model
(Note: all points share the same parameter \mathbf{w})
 - Problem: mismatch of the domains: vs
 - Solution: mean function / inverse of link function:
 $g^{-1} : \mathbb{R} \rightarrow \text{params}$

- Solution: Link function $g(\text{parameters}) \rightarrow \mathbb{R}$

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$$\frac{1}{1 + e^{\mathbf{w}^\top \mathbf{x}}} \quad \frac{1}{1 + e^{-\mathbf{w}^\top \mathbf{x}}}$$

Where $\sigma(z) = \frac{1}{1 + \exp(-z)}$.
Recall that $p_{\mathbf{x}} = \mathbf{E}[y = 1 | \mathbf{x}]$.

- Decision boundary is $p \geq 0.5$.
 - Equivalent to whether $\mathbf{w}^\top \mathbf{x} \geq 0$. Hence, LR is a linear classifier.

- Consider a training data point $\mathbf{x}^{(i)}$.
 - Recall that the conditional probability ($\Pr[y^{(i)} = 1 \mid \mathbf{x}^{(i)}]$) computed by the model is denoted by the shorthand notation $p(\mathbf{x}^{(i)})$, which is a function of \mathbf{w} and $\mathbf{x}^{(i)}$.
 - The likelihood of $\mathbf{x}^{(i)}$ is $p^{y^{(i)}}(\mathbf{x}^{(i)})$, if $y^{(i)} = 1$, or equivalently,

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$$L(\mathbf{w}) = \prod_{i=1}^n p(\mathbf{x}^{(i)})^{y^{(i)}} (1 - p(\mathbf{x}^{(i)}))^{1 - y^{(i)}}$$

- Log-likelihood is (assume $\log \triangleq \ln$)

$$\ell(\mathbf{w}) = \sum_{i=1}^n y^{(i)} \log p(\mathbf{x}^{(i)}) + (1 - y^{(i)}) \log (1 - p(\mathbf{x}^{(i)})) \quad (5)$$

- To maximize ℓ , notice that it is concave. So take its partial derivatives

$$\frac{\partial \ell(\mathbf{w})}{\partial \mathbf{w}_j} = \sum_{i=1}^n y^{(i)} \frac{1}{p(\mathbf{x}^{(i)})} \frac{\partial p(\mathbf{x}^{(i)})}{\partial \mathbf{w}_j} + \sum_{i=1}^n (1 - y^{(i)}) \frac{1}{1 - p(\mathbf{x}^{(i)})} \frac{\partial (1 - p(\mathbf{x}^{(i)}))}{\partial \mathbf{w}_j}$$

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- and set them to 0 essentially means, for all

$$\sum_{i=1}^n \hat{y}^{(i)} \cdot \mathbf{x}^{(i)}_j = \sum_{i=1}^n p(\mathbf{x}^{(i)}) \mathbf{x}^{(i)}_j = \sum_{i=1}^n y^{(i)} \cdot \mathbf{x}^{(i)}_j$$

what the model predicts

what the data says

- Consider one dimensional \mathbf{x} . The above condition is simplified to

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- training data in class $Y = 1$.
- The LHS says: if we use our learned model to assign probability (of belonging to the class) to the training data, the LHS is the expected sum of
- If this is still abstract, think of an example.

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- \mathbf{w} is initialized to some random value (e.g., $\mathbf{0}$).
- Since the gradient gives the *steepest* direction to increase a function's value, we move a small step towards that direction, i.e.,

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$i=1$

where α (learning rate) is usually a small value decreasing over the epochs.

- Stochastic version: using the gradient on a **randomly** selected training instance, i.e.,

$$w_j \leftarrow w_j + \alpha(y^{(i)} - p(\mathbf{x}^{(i)}))\mathbf{x}^{(i)}_j$$

- Gradient Ascent moves to the “right” direction a tiny step a time. Can we find a good step size?

- Consider 1D case **minimize** $f(x)$ and the current point is a .

- $f(x) = f(a) + f'(a)(x - a) + \frac{f''(a)}{2}(x - a)^2$ for x near a .

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- Can be applied to multiple dimension cases too \Rightarrow need to use ∇ (gradient) and Hess (Hessian).

- Regularization is another method to deal with **overfitting**.
 - It is designed to penalize large values of the model parameters.
 - Hence it *encourages* simpler models, which are less likely to overfit.
- Instead of optimizing for $\ell(\mathbf{w})$, we optimize $\ell(\mathbf{w}) + \lambda R(\mathbf{w})$.

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- Grid search: <http://sv-ml-learn.org/stab>
- There are alternative methods.
- $R(\mathbf{w})$ quantifies the “size” of the model parameters. Choices are:
 - L_2 regularization (**Ridge LR**) $R(\mathbf{w}) = \|\mathbf{w}\|_2$
 - L_1 regularization (**Lasso LR**) $R(\mathbf{w}) = \|\mathbf{w}\|_1$
 - L_1 regularization is more likely to result in sparse models.

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- LR can be generalized to multiple classes \Rightarrow MaxEnt.

$$\frac{\exp(\mathbf{c}^T \mathbf{x})}{Z}$$

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- Z is the normalization constant.
- Let \mathbf{c}^* be the last class in C , the
- Derive LR from MaxEnt. How?
- Both belong to *exponential* or *log*

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- Andrew Ng's note:

1.pdf

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- Tom Mitchell's book chapter: <http://www.cs.cmu.edu/~tom/mlboo>

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