

Assignment Project Exam Help

Spectral Clustering

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May 7, 2018

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- Let \mathbf{A} be some $n \times n$ matrix.
- What is \mathbf{Ax} ? What's the **type** of the output? What may \mathbf{x} represent?
- Some numeric assignment on all nodes in G .
 - E.g., what if $x_i \in \{0, 1\}$? $x_i \in [0, 1]$? $x_i \in \mathbb{R}$?

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- Let \mathbf{A} is the adjacency matrix of a “normal” (unweighted) undirected graph G . \mathbb{V} are the vertices of G and \mathbb{E} are the edges of G

- An edge between v_i and v_j is modelled as (i, j) and (j, i) , i.e.,
 $A_{ij} = A_{ji} = 1$.

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- $d_i = \deg(v_i)$

- What about $\mathbf{x}^T \mathbf{A} \mathbf{x}$?
- Now what about $2(\mathbf{x}^T \mathbf{D} \mathbf{x} - \mathbf{x}^T \mathbf{A} \mathbf{x})$?

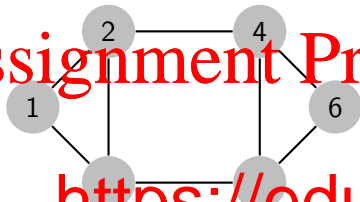
$$\mathbf{x}^\top \mathbf{L} \mathbf{x} = \frac{1}{2} \cdot \sum_{i,j \in \mathbb{V}} (x_i - x_j)^2, \text{ where } \mathbf{L} = \mathbf{D} - \mathbf{A}.$$

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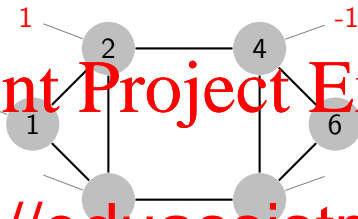


	n_1	n_2	n_3	n_4	n_5	n_6
n_1						
n_2						
n_3						

- $\mathbf{1}$ is the one vector.

- $\mathbf{L}\mathbf{1} = \mathbf{0}$ (NB: $\mathbf{L}^\top = \mathbf{L}$)

- $\mathbf{x}^\top \mathbf{L} \mathbf{x} =$



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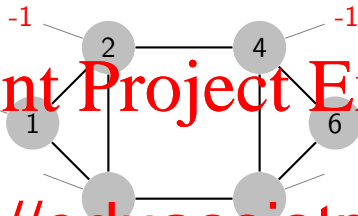
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- $\mathbf{x} =$

- $\mathbf{x}^\top \mathbf{L} \mathbf{x} =$

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- $\mathbf{x} =$

- $\mathbf{x}^T \mathbf{L} \mathbf{x} =$

- $\mathbf{x}^T \mathbf{F} \mathbf{x} =$

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- Min cuts are not *always* desirable.
 - **Biased** towards cutting small sets of isolated nodes.

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- Cut: $cut(A, B) = \sum_{v_i \in A, v_j \in B} w_{ij}$.
- Normalized cut:

$$ncut(A, B) = \frac{cut(A, B)}{vol(A)} + \frac{cut(A, B)}{vol(B)},$$

where $vol(A) = \sum_{v_i \in A} d_i = \sum_{v_i \in A, v_j \in V} w_{ij}$.

$$ncut(A, B) = cut(A, B) \left(\frac{1}{vol(A)} + \frac{1}{vol(B)} \right)$$

- Let $x_i = \frac{1}{vol(A)}$ if $v_i \in A$, and $= \frac{-1}{vol(B)}$ otherwise.

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$$\chi^T L \chi = \frac{1}{2} \sum_{i,j} w_{ij} (x_i - x_j)^2 = 0 + \sum_{v_i \in A, v_j \in B} \left(\frac{1}{vol(A)} + \frac{1}{vol(B)} \right)$$

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$$ncut(A, B) = \frac{1}{2} \sum_{i,j} w_{ij} (x_i - x_j)^2$$

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Minimize $ncut(A, B) = \frac{\mathbf{x}^T \mathbf{L} \mathbf{x}}{\mathbf{x}^T \mathbf{D} \mathbf{x}}$ Subject to $x_i \in \left\{ \frac{1}{\sqrt{d_i(\mathbf{A})}}, \frac{-1}{\sqrt{d_i(\mathbf{B})}} \right\}$

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- allow \mathbf{x} to be a real vector?

- Yes, but too large.

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- This gives the constraint: $\mathbf{x}^T \mathbf{D} \mathbf{x} = 1$
(You can verify this by plugging in any discrete vector.)

- Solution: the second smallest eigenvector of the generalized eigen value problem $\mathbf{L} \mathbf{x} = \lambda \mathbf{D} \mathbf{x}$.

- Normalized Laplacian:

$$\mathbf{L}' = \mathbf{D}^{-\frac{1}{2}}(\mathbf{D} - \mathbf{W})\mathbf{D}^{-\frac{1}{2}} = \mathbf{I} - \mathbf{D}^{-\frac{1}{2}}\mathbf{W}\mathbf{D}^{-\frac{1}{2}}$$

- Algorithm $SC_recursive_bin_cut(data, k)$

- Construct the weighted graph G
- Construct the d -dimensional graph laplacian L for G
- Compute the smallest non-zero eigenvector for L . This is the new representation of vertices in a new d -dimensional space

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are needed.

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- Algorithm $SC_k_way_cut(data, k)$
 - Construct the weighted graph G
 - Construct the k -graph laplacian L for G
 - Compute the smallest k non-zero eigenvector for L . This is the new representation of vertices in a new k -dimensional space

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- How to construct the weighted graph if only n objects are given?

- Be based on the similarity or distance among objects.

- E.g., $w_{ij} = \exp(-\frac{\|f(o_i) - f(o_j)\|^2}{2\sigma^2})$ where $f(o)$ is the feature vector of object o . One can also induce a sparse graph if one caps the

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 - Normalized graph laplacian $\mathbf{L} = \mathbf{D}^{-\frac{1}{2}}(\mathbf{D} - \mathbf{W})\mathbf{D}^{-\frac{1}{2}}$.

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- Pros:

- Usually better quality than other methods.
- Can be thought of (non-linear) dimensionality reduction or embedding.
- Freedom to construct a (sparse) G to preserve local

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case).

- Cons:

- Still need to determine k .
- Assumes clusters are of similar sizes.
- Does not scale well with large datasets; but more scalable variants exist.
- One of the relaxation of the original NP-hard problem – may not be the tightest relaxation.