Answers to EE5808 Assignment 2

On 1

a) Parallel projection: all the projection rays are parallel

Perspective projection: all the projection rays pass through the projection reference point (or point of projection)

b) α is the angle the projection rays make with the view plane/projection plane

Cavalier projection: $\alpha = tan^{-1}1$

Cabinet projection: $\alpha = tan^{-1}2$

c) Z = 2.

The equation is expressed in camera coordinates (or viewer coordinates)

d) gluLookA(100, 100, 100, 0, 100, 0, 100 o Project Exam Help

Qn 2

b) $M_{1\leftarrow 2} = T(-2, 10, 0)R_z(30^o)S(0.5, 0.5, 1.0)$

$$= \begin{pmatrix} 0.5\cos 30^{o} & -0.5\sin 30^{o} & 0 & -2\\ 0.5\sin 30^{o} & 0.5\cos 30^{o} & 0 & 10\\ 0 & 0 & 1 & 0\\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} \sqrt{3}/4 & -0.25 & 0 & -2\\ 0.25 & \sqrt{3}/4 & 0 & 10\\ 0 & 0 & 1 & 0\\ 0 & 0 & 0 & 1 \end{pmatrix}$$

c)

glTranslatef (10, 0, 0);

Part (); // Part 1 glTranslatef (-2, 10, 0); $// M_{1 \leftarrow 2}$ glRotatef (30, 0, 0, 1);

glScalef (0.5, 0.5, 1.0);

Part (); // Part 2

glTranslatef(0,10,0);glRotatef (30, 0, 0, 1);

glRotatef (45, 0, 1, 0);

// Part 3 *Part ();*

Assignment Project Exam Help d) refer to the underlined added code

 $// M_{2 \leftarrow 3}$

https://eduassistpro.github.io/ On 3

a) Add WeChat edu_assist_pro

VRP = (0.100, -100)VPN = (0,100,-100)VUP = (0,1,0);

$$Z_{VC} = (0, \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}})$$

$$VUP \times VPN = \begin{vmatrix} i & j & k \\ 0 & 1 & 0 \\ 0 & 100 & -100 \end{vmatrix} = (-100,0,0) \quad X_{VC} = (-1,0,0)$$

$$Y_{VC} = Z_{VC} \times X_{VC} = \begin{vmatrix} i & j & k \\ 0 & 1/\sqrt{2} & -1/\sqrt{2} \\ -1 & 0 & 0 \end{vmatrix} = (0, \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$$

$$M_{VC \leftarrow WC} = \begin{pmatrix} X_{VC} & -VRP \cdot X_{VC} \\ Y_{VC} & -VRP \cdot Y_{VC} \\ Z_{VC} & -VRP \cdot Z_{VC} \\ 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 1/\sqrt{2} & -1/\sqrt{2} & -200/\sqrt{2} \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

b)

$$1 = \frac{V_{pz}}{\sqrt{{V_{px}}^2 + {V_{py}}^2}}$$

$$\left(V_{px}, V_{py}\right) = (1,1)$$

$$V_{pz} = \sqrt{2}$$
 Assignment Project Exam Help $Z_{vp} = -5$

$$M_{parallel} = \begin{pmatrix} 1 & 0 & \text{https://eduassistpro_github.io/} \\ 0 & 1 & V_{py} & V_{py} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & - & - & - \\ 0 & 1 & - & - & - \\ 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 1 & - & - & - \\ 0 & 0 & 0 & 1 & - & - \\ 0 & 0 & 0 & 1 & - & - \\ 0 & 0 & 0 & 1 & - & - \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

c)

i)

Use method 2, P1 is the coordinate system.

The transformation is

$$T(60,0,-100)R_{y}(30^{o}) = \begin{pmatrix} \sqrt{3}/2 & 0 & 0.5 & 60\\ 0 & 1 & 0 & 0\\ -0.5 & 0 & \sqrt{3}/2 & -100\\ 0 & 0 & 0 & 1 \end{pmatrix}$$
(3 marks) (2 marks)
ii)

3

```
void draw_part2 (void)
      glPushMatrix();
      glTranslatef (60, 0, -100);
      glRotatef (30, 0, 1, 0);
      glRotatef (15, 1, 0, 0);
      Part_2 ( );
      glPopMatrix();
}
void object (void)
     glTranslatef (10, 10, 10);
     Assignment Project Exam Help
     glScalef (-1, 1 https://eduassistpro.github.io/
     draw_part2 ( );
}
               Add WeChat edu_assist_pro
iii)
```

The underlined code