

Texture and Other Mapping Techniques

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Intended Learning Outcomes

- Able to apply pixel order scanning for generating texture
- Describe and apply other advanced mapping methods

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Two methods of texture mapping

- Texture scanning : map texture pattern in (s, t) to pixel (x, y) . Left to right in Fig. below

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- pixel order scan to texture pattern in (s, t) . Right <https://eduassistpro.github.io/>

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Texture

- use : to add fine, realistic detail to a smooth surface
- A texture pattern is defined with a rectangular grid of intensity values in a texture space (s, t) . Surface positions in (u, v) coordinates. Pixel positions on the projection plane in (x, y) coordinates (Fig. 10-104).

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Pixel order scanning

- To simplify calculations, the mapping from texture space to object space is often specified with linear functions:

$$u = f_u(s, t) = a_u s + b_u t + c_u$$

$$v = f_v(s, t) = a_v s + b_v t + c_v$$

- The mapping from object space to image space consists of a concatenation of projective transformation followed by 2) projective transformation

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- Texture mapping is not used in practice. Pixel order scanning is used, together with antialiasing, as shown below:

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pyramid filter

Example: Pixel Order Scanning

- Map texture pattern in Fig. (a) to the cylindrical surface in Fig. (b).
- Parametric representation of the cylindrical surface:

Assignment Project Exam Help $X = r \cos u$

<https://eduassistpro.github.io/> $Y = r \sin u$

$Z = v$

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- Map the texture pattern to the surface by defining the following linear function

$$u = \frac{\pi}{2} s \quad (1)$$

$$v = t$$

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- The above is transformation M_T
- Suppose no g n and projection is orthographic with projection direction. Then Y-Z is the projection plane
- Viewing and projection transformation M_{VP} is

$$Y = r \sin u \quad (2)$$

$$Z = v$$

- For pixel order scanning, we need to compute the transformation $(Y, Z) \rightarrow (s, t)$
- First compute \mathbf{M}_{VP}^{-1} , or $(Y, Z) \rightarrow (u, v)$. From (2)

$$\begin{aligned} u &= \sin^{-1}\left(\frac{Y}{r}\right) \\ v &= Z \end{aligned} \tag{3}$$

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- Next compute \mathbf{M}_T^{-1} , or $(u, v) \rightarrow (s, t)$

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$$\begin{aligned} s &= \frac{2}{\pi} u \\ t &= v \end{aligned} \tag{4}$$

- Combining (3) and (4)

$$s = \frac{2}{\pi} \sin^{-1}\left(\frac{Y}{r}\right)$$

$$t = Z$$

- Using this transformation, the pixel area of a pixel (Y, Z) will be back-transformed into an area in the texture space (s, t). In a are averaged to obtain the pixel

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Bump Mapping

- Texture mapping can be used to add fine surface detail to smooth surface. However, it is not a good method for modelling rough surface e.g., oranges, strawberries, since the illumination detail in the texture pattern usually does not correspond to the direction in the scene.
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- Bump mapping is a method for representing surface bumpiness. A perturbation function is applied to the surface normal. The perturbed normal is used in the illumination model calculations.

$\mathbf{P}(u, v)$ position on a parametric surface

\mathbf{N} surface normal at (u, v)

$$\mathbf{N} = \mathbf{P}_u \times \mathbf{P}_v$$

where $\mathbf{P}_u = \frac{\partial \mathbf{P}}{\partial u}$ $\mathbf{P}_v = \frac{\partial \mathbf{P}}{\partial v}$

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$\mathbf{P}(u,v) + b(u,v)\mathbf{n}$ Add WeChat edu_assist_pro

where $\mathbf{n} = \mathbf{N} / |\mathbf{N}|$ is the unit (outward) surface normal

The normal $\mathbf{N} = \mathbf{P}_u \times \mathbf{P}_v$ is perturbed.

- The bump function $b(u, v)$ are usually obtained by table lookup. It can be setup using

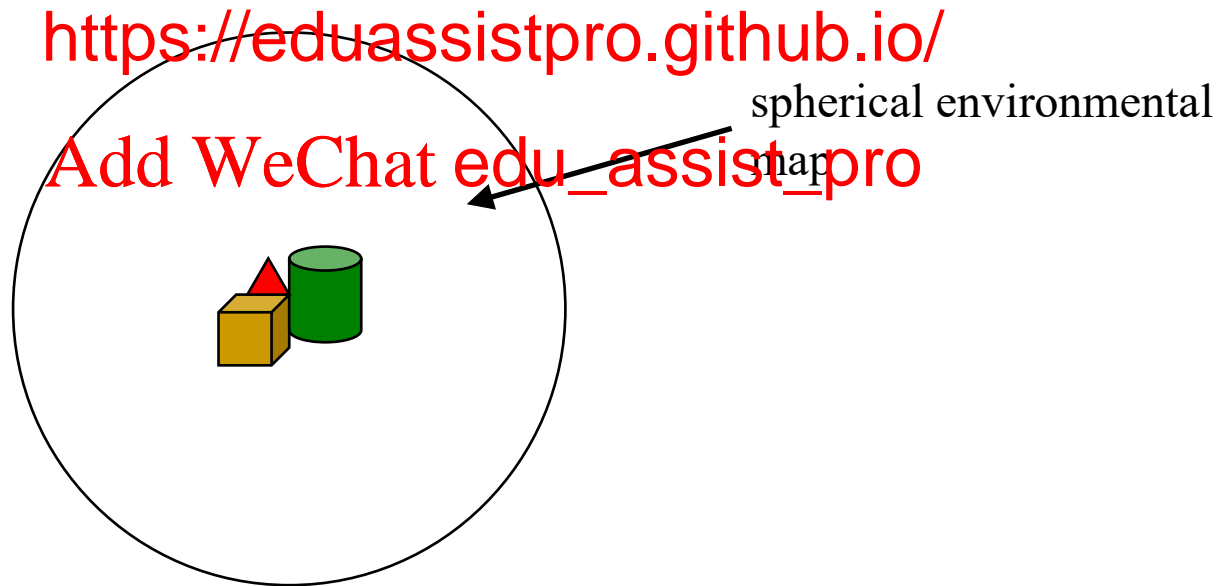
- 1) Random pattern to model irregular surfaces (e.g. raisin)
- 2) Repeating pattern to model regular surfaces (e.g. orang

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Environment Mapping

- A simplified ray tracing method that uses texture mapping concept.
- Environment map is defined over the surface of an enclosing universe. Information includes intensity values of light sources, the sky, or other background objects.



- Run “Example environment map”

- A surface is rendered by projecting the pixel area to the surface, then reflect onto the environment map. If the surface is transparent, also refract onto the map.
- **Pixel intensity** determined by averaging the intensity values within the **intersected region of the environment map**.

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armour (specular object) reflects the cathedral surrounding
Modelled using environmental map

OpenGL functions

glTexImage2D (*GL_TEXTURE_2D*, 0, *GL_RGBA*,
texWidth, *texHeight*, 0, *dataFormat*, *dataType*, *surfTexArray*);

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GL_RGBA Each colour of the texture pattern is specified
with (R, G, B, A) <https://eduassistpro.github.io/>

$A = 1.0 \Rightarrow$ compl

$A = 0.0 \Rightarrow$ opaque

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texWidth and *texHeight* is the width and height of the pattern

dataFormat and *dataType* specify the format and type of the
texture pattern e.g. *GL_RGBA* and *GL_UNSIGNED_BYTE*

*glTexParameterf (GL_TEXTURE_2D,
GL_TEXTURE_MAG_FILTER, GL_NEAREST)*

*glTexParameterf (GL_TEXTURE_2D,
GL_TEXTURE_MIN_FILTER, GL_NEAREST)*

Specify what to do if the texture is to be magnified (i.e.,
mag) or reduced

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<i>GL_NEAREST</i>	Assigns the nearest colour
<i>GL_LINEAR</i>	linear interpolate

glTexCoord2 (sCoord, tCoord);*

A texture pattern is normalized such that s and t are in [0, 1]

A coordinate position in 2-D texture space is selected with $0.0 \leq sCoord, tCoord$

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glEnable (GL_TEXTURE_2D)

glDisable (GL_TEXTURE_2D)

Enables / disables texture

Example: texture map a quadrilateral

```
GLubyte texArray [808][627][4];
```

```
glTexParameteri (GL_TEXTURE_2D, GL_TEXTURE_MAG_FILTER,  
GL_NEAREST);
```

```
glTexParameteri (GL_TEXTURE_2D, GL_TEXTURE_MIN_FILTER, GL_NEAREST);
```

```
glTexImage2D (GL_TEXTURE_2D, 0, GL_RGBA, 808, 627, 0, GL_RGBA,  
GL_UNSIGNED_BYTE, t
```

```
glEnable (GL_TEXTURE
```

```
// assign the full range of texture colors to a qu
```

```
glBegin (GL_QUADS);
```

```
    glTexCoord2f (0.0, 0.0);  glVertex3fv (vertex1);
```

```
    glTexCoord2f (1.0, 0.0);  glVertex3fv (vertex2);
```

```
    glTexCoord2f (1.0, 1.0);  glVertex3fv (vertex3);
```

```
    glTexCoord2f (0.0, 1.0);  glVertex3fv (vertex4);
```

```
glEnd ();
```

```
glDisable (GL_TEXTURE_2D);
```

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Simple example

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Use a large QUAD for the ground and texture map it

- To re-use the texture, we can assign a name to it

```
static GLuint texName;
```

```
glGenTextures (1, &texName); // generate 1 texture with name "texName"
```

```
glBindTexture (GL_TEXTURE_2D, texName);
```

```
glTexImage2D (GL_TEXTURE_2D, 0, GL_RGBA, 32, 32, 0, GL_RGBA,
```

```
GL_UNSIGNED_BYTE, texName);
```

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```
glBindTexture (GL_TEXTURE_2D, texName); // use it as current texture
```

- We can generate more than 1 name at a time. To generate 6 names:

```
static GLuint texNamesArray [6];  
glGenTextures (6, texNamesArray); // generate 6 texture names
```

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- To use *texNamesA*

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```
glBindTexture (GL_TEXTURE_2D, texN
```

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Texture mapping in Movie

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- Use texture map to blend graphics object into real movie production
- Double buffering is used
- Frame rate is unimportant as movie is produced off-line
- Human artist can optionally help with later stage production to make image more realistic

Light field (Lumigraph)

- An image based rendering (IBR) approach
- A “pre-computation” idea
- Stores intensities in all directions
- Uses data compression
- Adv.: Extremely fast
- Disadv.: High Pre-computational cost

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Application

- Light field camera

https://en.wikipedia.org/wiki/Light-field_camera

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- Capture instantly Do not nee

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References

- Text Ch. 18 on Texture
- Text Ch. 21-3 on Environment Mapping
- Light field: A. Watt, 3D Computer Graphics, 3rd Ed. (2000) pp. 463-65

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Implementation notes

- One may use OpenGL SOIL library or stb_image.h for reading in texture images
- Search the web with keyword “texture images”
- A .raw file is a file with no formatting and only consist of a sequence of numbers. The file into an array in C. `read_rawimage` to read a raw image into C. However, it is needed a suitable file converter that converts other file to raw file
- It is found that older graphics cards cannot display texture property if the source file is not in $2^n \times 2^m$