

Assignment Project Exam Help

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Dr. Liam O'Connor
University of Edinburgh LFCS
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Where we're at

- We refined the abstract M-Machine to a C-Machine, with explicit stacks

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- Function a

$$\frac{(\text{Apply } \langle \langle f, x, e \rangle \rangle \rangle) \triangleright \triangleleft \langle v \rangle \mapsto_C s}{(\text{Apply } \langle \langle f, x, e \rangle \rangle \rangle) \triangleright \triangleleft \langle v \rangle \mapsto_C s}$$

- We're going to extend our C-Machine to replace substitutions with an **environment**, giving us a new *E-Machine*

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Environments

Definition

An *environment* is a context containing equality assumptions about variables. It can be viewed like a *state* that maps variables to their values, except that a variable's value d

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• **Env** $x = v, \eta$ **Env**

We write $\eta(x)$ to indicate the leftmost value corresponding

Let's change our machine states to include an *environment*:

$$s \mid \eta \succ e \quad s \mid \eta \prec v$$

First Attempt

First, we'll add a rule for consulting the environment if we encounter a free variable:

Then, we just need to <https://eduassistpro.github.io/>

One broken attempt:

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$$\frac{}{(\text{Apply } \langle\langle f.x. e \rangle\rangle \square) \triangleright s \mid \eta \prec v \mapsto_E s \mid e}$$

We don't know when to remove the variables again!

Second Attempt

We will extend our **stacks** to allow us to **save** the old environment to it.

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s Stack η Env

Calling a function

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$$\frac{(\text{Apply } \langle\langle f.x. e \rangle\rangle \square) \triangleright s \mid \eta \prec v \mapsto_E \eta \triangleright}{\triangleright e}$$

When the function returns, we restore the old environment, **bindings**:

$$\frac{}{\eta \triangleright s \mid \eta' \prec v \mapsto_E s \mid \eta \prec v}$$

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Simple Example

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Seems

```

(Ap (□ (N 3)) ▷ ○ | •   γ {Ap (Fun (f.x. (Plus x (N 1)))) (N 3))
(Ap (□ (N 3)) ▷ ○ | •   γ {Fun (f.x. (Plus x (N 1)))}
(Ap «...» □ ▷ | •   γ «f.x. (Plus x (N 1))»
(Ap «...» □ ▷ | •   γ
•▷
(Plus □ (N 1)) ▷ •▷
(Plus □ (N 1)) ▷ •▷○ | x = 3, f = «...», •   γ 3
(Plus 3 □) ▷ •▷○ | x = 3, f = «...», •   γ (N 1)
(Plus 3 □) ▷ •▷○ | x = 3, f = «...», •   γ 2
•▷○ | x = 3, f = «...», •   γ 4
○ | •   γ 4

```

to work for **basic examples**, but is there some way to break it?

Closure Capture

○ | ● \succ (Ap (Ap (Fun ($f.x.$ (Fun ($g.y.$ x)))) (N 3)) (N 4))

\mapsto_E (Ap □ (N 4)) \triangleright ○ | ● \succ (Ap (Fun ($f.x.$ (Fun ($g.y.$ x)))) (N 3))

\mapsto_E (Ap □ (N 3)) \triangleright (Ap □ (N 4)) \triangleright ○ | ● \succ (Fun ($f.x.$ (Fun ($g.y.$ x))))

\mapsto_E (Ap □ (

\mapsto_E (Ap $\langle\langle f.$

\mapsto_E (Ap $\langle\langle f.$

\mapsto_E ● \triangleright (Ap □ (N 4)) \triangleright ○ | $x = 3, f = \langle\langle f \dots \rangle\rangle, \bullet \succ$

\mapsto_E ● \triangleright (Ap □ (N 4)) \triangleright ○ | $x = 3, f = \langle\langle f \dots \rangle\rangle, \bullet \prec$

\mapsto_E (Ap □ (N 4)) \triangleright ○ | ● $\prec \langle\langle g.y. x \rangle\rangle$

\mapsto_E (Ap $\langle\langle g.y. x \rangle\rangle$ □) \triangleright ○ | ● \succ (N 4)

\mapsto_E (Ap $\langle\langle g.y. x \rangle\rangle$ □) \triangleright ○ | ● $\prec 4$

\mapsto_E ● \triangleright ○ | $y = 4, g = \langle\langle g.y. x \rangle\rangle, \bullet \succ x$

Oh no! We're stuck!

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Something went wrong!

Returning functions as a result means that the function's body expression escapes the scope of bound variables that existed where it is defined.

The function value
when the function was defined.

Solution: Store the environment inside the function value

$$s \mid \eta \succ (\text{Recfun } (f.x. e)) \mapsto_E s \mid \eta \prec \langle\langle \eta, f.x. e \rangle\rangle$$

This type of function value is called a *closure*.

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$(\text{Apply } \langle\langle \eta', f.x. e \rangle\rangle \square) \triangleright s \mid \eta \prec v \mapsto_E \eta \triangleright s \mid (x = v, f = \langle\langle f.x. e \rangle\rangle, \eta') \succ e$

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Retrieve the new
env. from the closure

Our Example

○ | ● \succ (Ap (Ap (Fun (f.x. (Fun (g.y. x)))) (N 3)) (N 4))

(Ap □ (N 4)) ▷ ○ | ● \succ (Ap (Fun (f.x. (Fun (g.y. x)))) (N 3))

(Ap □ (N 3)) ▷ (Ap □ (N 4)) ▷ ○ | ● \succ (Fun (f.x. (Fun (g.y. x))))

(Ap □ (N 3)) ▷ (Ap (N 4)) ▷ , f.x. (Fun (g.y. x))

(Ap ⟨●, f...⟩

(Ap ⟨●, f...⟩

● ▷ (Ap □ (N 4)) ▷ ○ | x = 3, f = ⟨f...⟩, ● \succ (Fun (g.y. x))

● ▷ (Ap □ (N 4)) ▷ ○ | x = 3, f = ⟨f...⟩, ● \prec ⟨(x

(Ap □ (N 4)) ▷ ○ | ● \prec ⟨(x = 3, f = ...), g.y. x⟩

(Ap ⟨(x = 3, f = ...), g.y. x⟩ □) ▷ ○ | ● \succ (N

(Ap ⟨(x = 3, f = ...), g.y. x⟩ □) ▷ ○ | ● \prec 4

● ▷ ○ | y = 4, g = ⟨g.y. x⟩, x = 3, f = ... , ● \succ x

● ▷ ○ | y = 4, g = ⟨g.y. x⟩, x = 3, f = ... , ● \prec 3

○ | ● \prec 3

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Refinement

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- We already sketched the proof that shows that each C-machine execution has a corresponding E-machine execution.
- This means that we can prove about C-machine executions of the same program.
- Now we want to prove that each E-machine execution has a corresponding C-machine execution (and therefore a M-machine execution).

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Ingredients for Refinement

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Once again, we want the same ingredients to prove a simulation proof that we did in the previous refinement \mathcal{A} that converts E-mac

- Each initial state in the E-machine is mapped to an initial state in the C-machine.
- Each final state in the E-machine is mapped to a final state in the C-machine.
- For each transition from one state to another in the E-machine, there is a corresponding transition in the C-machine, or the two states are both final states.

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How to define \mathcal{A} ?

- Our abstraction function \mathcal{A} applies the environment γ as a substitution to the current expression, and to the stack, starting at the left.
- If any environment
- E-Machine environment inside closures as a substitution to the expression inside the closure.

With such a function definition, it is trivial to prove that each E-M has a corresponding transition in the C-Machine, as it is 1:1.

Except!

There is one rule which is not 1:1. Which one?