

# Signals and Communication Theory

## Discrete-time System Implementation

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- 1 Introduction
- 2 First Order Systems
- 3 Second Order Systems
- 4 High Order Systems
  - Cascade Forms
  - Parallel Forms

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# Introduction

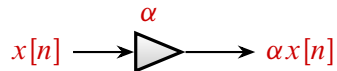
Now we focus on the implementation of discrete-time systems.

Hardware options for implementing discrete-time systems can be

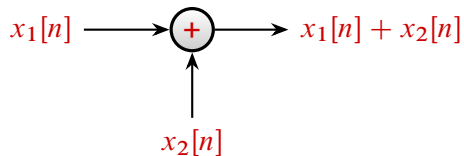
- Special-purpose (custom) chips such as application-specific integrated circuit (**ASICs**),
- Field-programmable gate arrays (**FPGAs**),
- General-purpose microprocessors or microcontrollers ( $\mu\mathbf{P}/\mu\mathbf{C}$ ),
- Digital signal processors (**DSP**) with application-specific hardware (HW) accelerators.

# Basic Building Blocks

## Multiplier



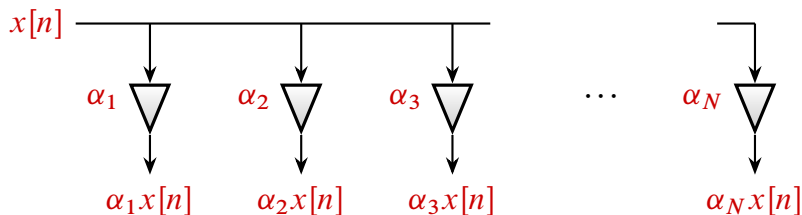
## Adder



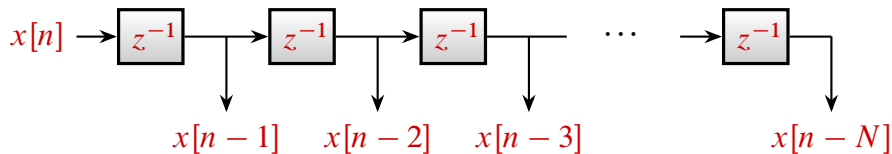
## Delay



# Basic Structures: **Multiple Constant Multiplication** (MCM)



## Basic Structures: **Delay Line**



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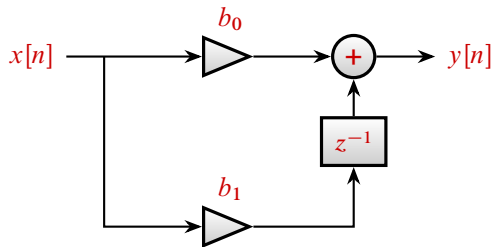
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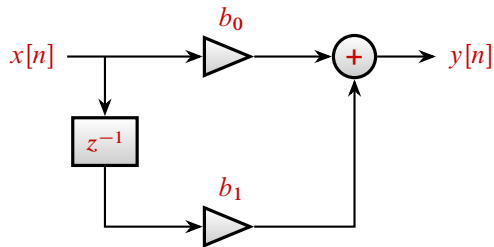
# First Order FIR System

$$H(z) = b_0 + b_1 z^{-1}$$

$$Y(z) = b_0 X(z) + b_1 z^{-1} X(z)$$



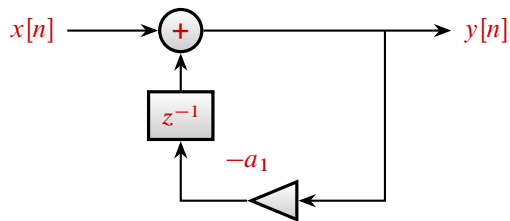
**Type F1A structure**



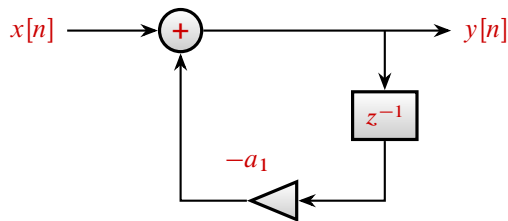
**Type F1B structure**

# First Order Allpole IIR System

$$H(z) = \frac{1}{1 + a_1 z^{-1}}$$
$$Y(z) = -a_1 z^{-1} Y(z) + X(z)$$



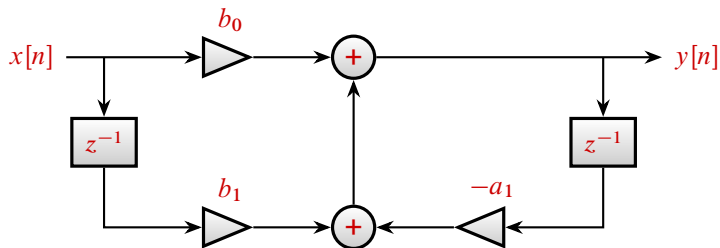
**Type I1A structure**



**Type I1B structure**

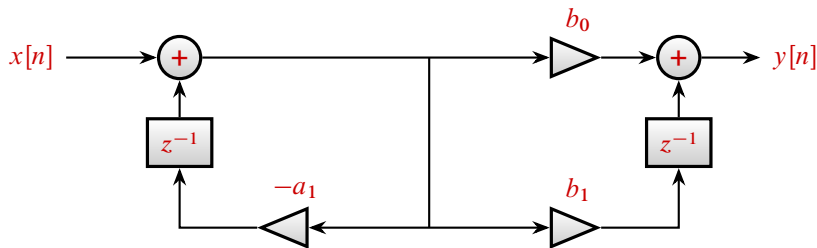
# First Order IIR System: Direct Form I Structure

$$\begin{aligned} H(z) &= \frac{b_0 + b_1 z^{-1}}{1 + a_1 z^{-1}} \\ &= \underbrace{(b_0 + b_1 z^{-1})}_{\text{Type F1B}} \underbrace{\frac{1}{1 + a_1 z^{-1}}}_{\text{Type I1B}} \end{aligned}$$



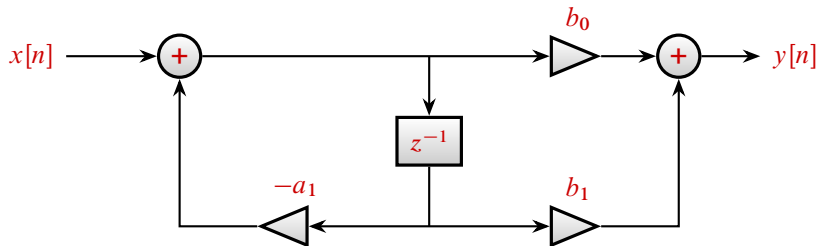
# First Order IIR System: Direct Form I<sub>t</sub> Structure

$$\begin{aligned} H(z) &= \frac{b_0 + b_1 z^{-1}}{1 + a_1 z^{-1}} \\ &= \underbrace{\frac{1}{1 + a_1 z^{-1}}}_{\text{Type I1A}} \underbrace{(b_0 + b_1 z^{-1})}_{\text{Type F1A}} \end{aligned}$$



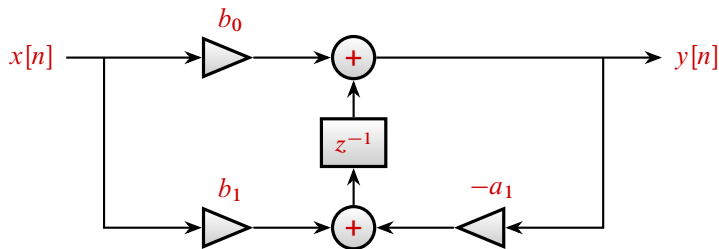
# First Order IIR System: Direct Form II Structure

$$\begin{aligned} H(z) &= \frac{b_0 + b_1 z^{-1}}{1 + a_1 z^{-1}} \\ &= \underbrace{\frac{1}{1 + a_1 z^{-1}}}_{\text{Type I1B}} \underbrace{(b_0 + b_1 z^{-1})}_{\text{Type F1B}} \end{aligned}$$



# First Order IIR System: Direct Form II<sub>t</sub> Structure

$$\begin{aligned} H(z) &= \frac{b_0 + b_1 z^{-1}}{1 + a_1 z^{-1}} \\ &= \underbrace{(b_0 + b_1 z^{-1})}_{\text{Type F1A}} \underbrace{\frac{1}{1 + a_1 z^{-1}}}_{\text{Type I1A}} \end{aligned}$$



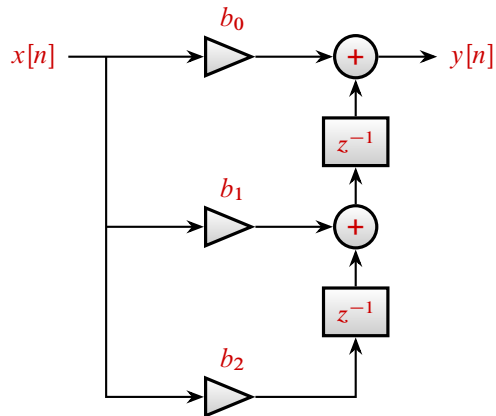
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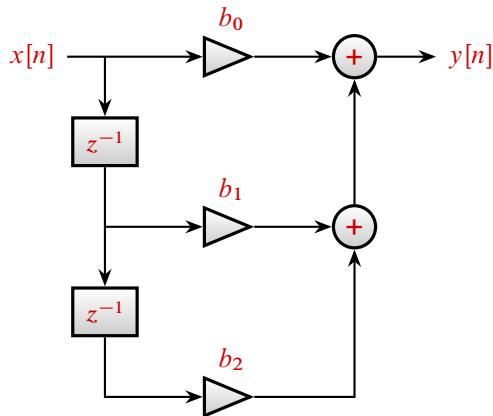
# Second Order FIR System

$$H(z) = b_0 + b_1z^{-1} + b_2z^{-2}$$

$$Y(z) = b_0X(z) + b_1z^{-1}X(z) + b_2z^{-2}X(z)$$



**Type F2A structure**



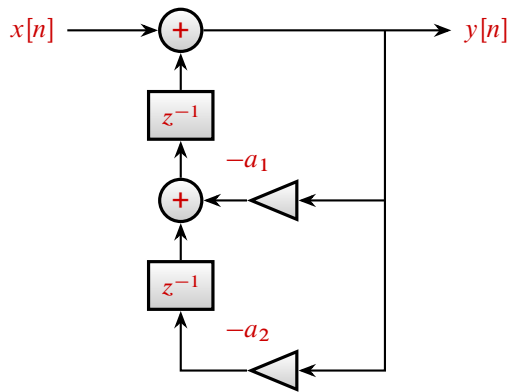
**Type F2B structure**



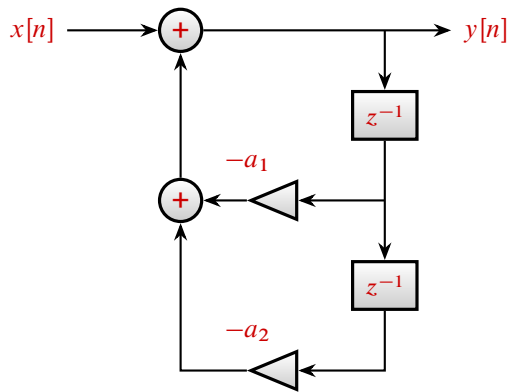
# Second Order Allpole IIR System

$$H(z) = \frac{1}{1 + a_1 z^{-1} + a_2 z^{-2}}$$

$$Y(z) = -a_1 z^{-1} Y(z) - a_2 z^{-2} Y(z) + X(z)$$



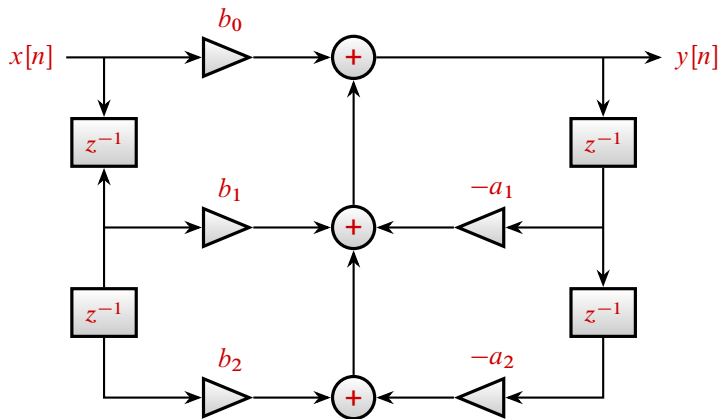
**Type I2A structure**



**Type I2B structure**

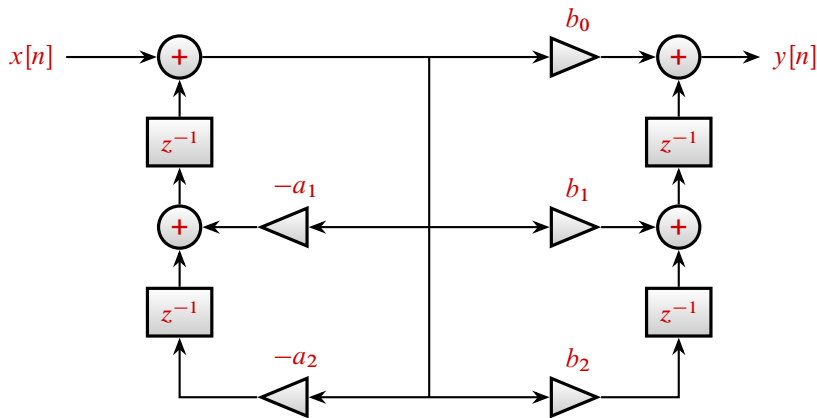
## Second Order IIR System: Direct Form I Structure

$$H(z) = \frac{b_0 + b_1z^{-1} + b_2z^{-2}}{1 + a_1z^{-1} + a_2z^{-2}} = \underbrace{(b_0 + b_1z^{-1} + b_2z^{-2})}_{\text{Type F2B}} \underbrace{\frac{1}{1 + a_1z^{-1} + a_2z^{-2}}}_{\text{Type I2B}}$$



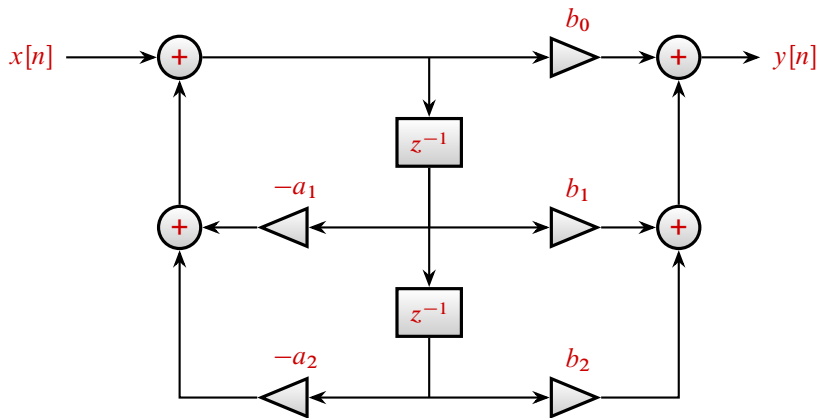
## Second Order IIR System: Direct Form I<sub>t</sub> Structure

$$H(z) = \frac{b_0 + b_1z^{-1} + b_2z^{-2}}{1 + a_1z^{-1} + a_2z^{-2}} = \underbrace{\frac{1}{1 + a_1z^{-1} + a_2z^{-2}}}_{\text{Type I2A}} \underbrace{(b_0 + b_1z^{-1} + b_2z^{-2})}_{\text{Type F2A}}$$



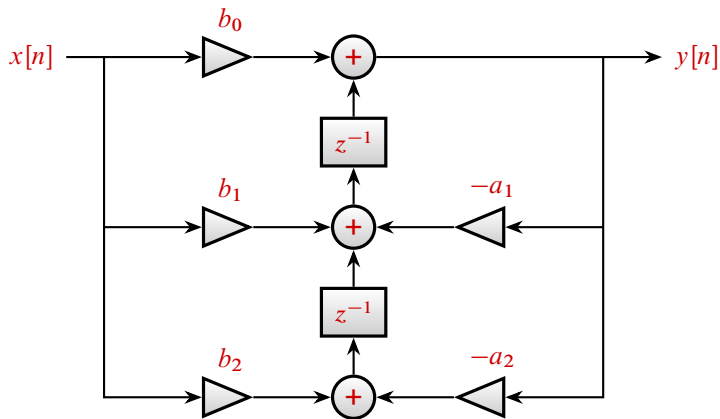
## Second Order IIR System: Direct Form II Structure

$$H(z) = \frac{b_0 + b_1z^{-1} + b_2z^{-2}}{1 + a_1z^{-1} + a_2z^{-2}} = \underbrace{\frac{1}{1 + a_1z^{-1} + a_2z^{-2}}}_{\text{Type I2B}} \underbrace{(b_0 + b_1z^{-1} + b_2z^{-2})}_{\text{Type F2B}}$$



## Second Order IIR System: Direct Form II<sub>t</sub> Structure

$$H(z) = \frac{b_0 + b_1z^{-1} + b_2z^{-2}}{1 + a_1z^{-1} + a_2z^{-2}} = \underbrace{(b_0 + b_1z^{-1} + b_2z^{-2})}_{\text{Type F2A}} \underbrace{\frac{1}{1 + a_1z^{-1} + a_2z^{-2}}}_{\text{Type I2A}}$$



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# Definition

A **cascade form** is obtained by expressing the numerator and denominator polynomials of the system function  $H(z)$  as a product of polynomials of first and second degree, i.e.,

$$H(z) = G \frac{\prod_{k=1}^K P_k(z)}{\prod_{m=1}^M D_m(z)},$$

where  $G$  is a gain constant and

$$\begin{aligned} P_k(z) &= 1 + \beta_{1,k}z^{-1} + \beta_{2,k}z^{-2}, \\ D_m(z) &= 1 + \alpha_{1,m}z^{-1} + \alpha_{2,m}z^{-2}. \end{aligned}$$



## Example 1

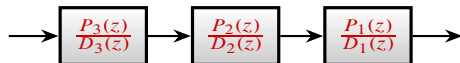
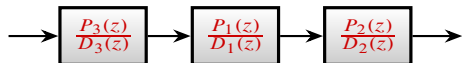
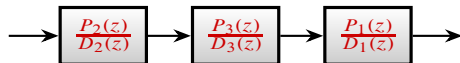
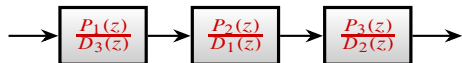
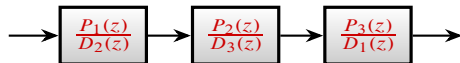
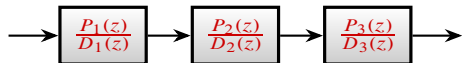
Consider the following system function

$$H(z) = \frac{P_1(z)P_2(z)P_3(z)}{D_1(z)D_2(z)D_3(z)}.$$

Different realizations can be obtained by different pole/zero polynomial pairings.

**In practice due to the finite wordlength effects, each such cascade realization behaves differently from others.**

# Example 1: Different Cascade Realizations



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# Definition

A **parallel form** can be obtained by making use of the partial fraction expansion.

A partial fraction expansion of the system function in  $z^{-1}$  leads to the **Parallel Form I**, that is,

$$H(z) = \gamma_0 + \sum_k \frac{\gamma_{0,k} + \gamma_{1,k}z^{-1}}{1 + \alpha_{1,k}z^{-1} + \alpha_{2,k}z^{-2}}.$$

Similarly, a partial fraction expansion of the system function in  $z$  leads to the **Parallel Form II**, i.e.,

$$H(z) = \beta_0 + \sum_k \frac{\beta_{1,k}z^{-1} + \beta_{2,k}z^{-2}}{1 + \alpha_{1,k}z^{-1} + \alpha_{2,k}z^{-2}}.$$

## Example 2

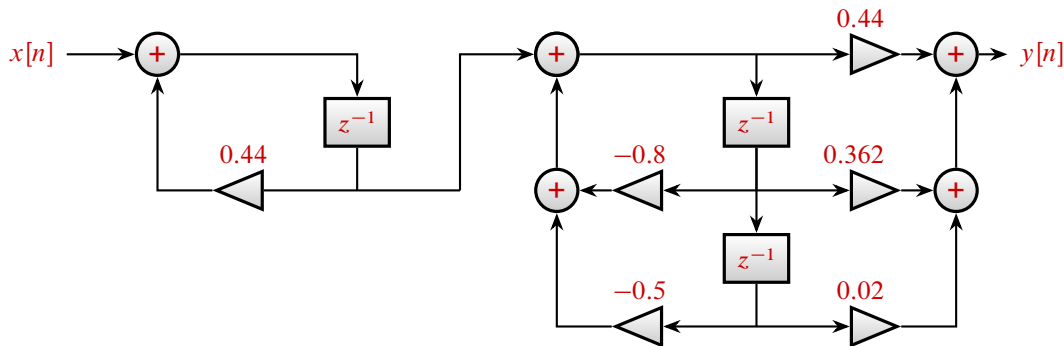
*Assume that the system function is given by*

$$\begin{aligned} H(z) &= \frac{0.44z^{-1} + 0.36z^{-2} + 0.02z^{-2}}{1 + 0.4z^{-1} + 0.18z^{-2} - 0.2z^{-3}} \\ &= \frac{0.44z^2 + 0.36z^1 + 0.02}{z^3 + 0.4z^2 + 0.18z - 0.2} \end{aligned}$$

*Develop the cascade and parallel forms.*

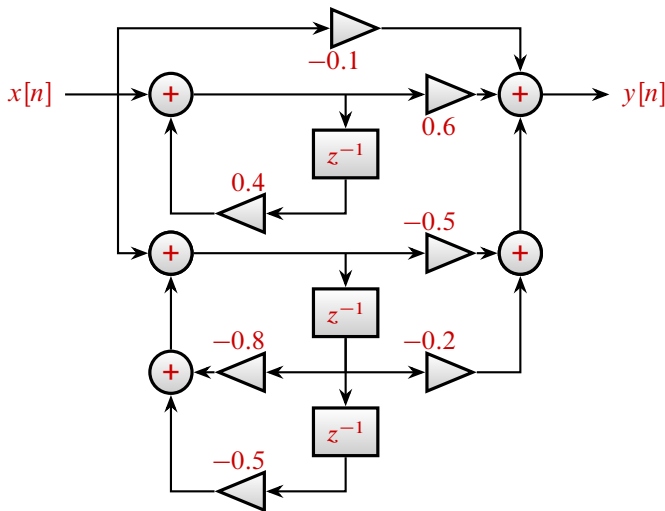
## Answer to Example 2: Cascade Form

$$H(z) = \left( \frac{z^{-1}}{1 - 0.4z^{-1}} \right) \left( \frac{0.44 + 0.362z^{-1} + 0.02z^{-2}}{1 + 0.8z^{-1} + 0.5z^{-2}} \right)$$



## Answer to Example 2: Parallel Form I

$$H(z) = -0.1 + \frac{0.6}{1 - 0.4z^{-1}} + \frac{-0.5 - 0.2z^{-1}}{1 + 0.8z^{-1} + 0.5z^{-2}}$$



# Homework

- From [9], Projects 6.1, 6.2

[9] S. K. Mitra , **Digital Signal Processing Laboratory Using MATLAB**, 1999, McGraw Hill (`labmanual.pdf`)