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# TensorFlow

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**TF 1.X**  
2015



`tf.session`  
`tf.contrib.layers`  
`tf.layers`

`tf.keras`  
`tf.data.Datasets`  
`@tf.function`



**TF 2**  
2019



# TensorFlow

## Tensor

Um tensor pode ser visto como a generalização de um vetor ou matriz em  $n$  dimensões

Escalar



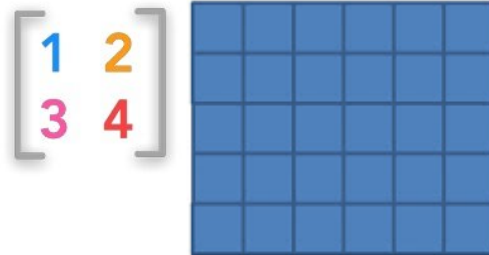
0 dimensão

Vetor



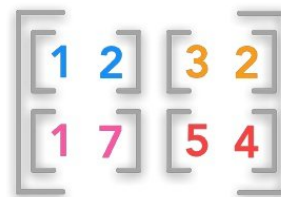
1 dimensão

Matriz



2 dimensões

Tensor



3 ou mais dimensões

## Constantes

```
n = np.array([[1., 2., 3., 4.], [5., 6., 7., 8.]])  
print(n)  
[[1. 2. 3. 4.]  
 [5. 6. 7. 8.]
```

```
t = tf.constant([[1., 2., 3., 4.], [5., 6., 7., 8.]])  
print(t)  
tf.Tensor(  
[[1. 2. 3. 4.]  
 [5. 6. 7. 8.]], shape=(2, 4), dtype=float32)
```

## Dimensões e tipos

```
print('shape:', n.shape)  
print('dtype:', n.dtype)
```

```
shape: (2,4)  
dtype: float64
```

```
print('shape:', t.shape)  
print('dtype:', t.dtype)
```

```
shape: (2,4)  
dtype: <dtype: 'float32'>
```

# TensorFlow

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## Operações

```
tf.square(t)  
np.square(n)
```

```
[[ 1.,  4.,  9., 16.],  
 [25., 36., 49., 64.]]
```

```
np.stack([n, n])  
Tf.stack([t, t])
```

```
[[[1., 2., 3., 4.],  
  [5., 6., 7., 8.]],
```

```
[[1., 2., 3., 4.],  
 [5., 6., 7., 8.]]]
```

```
np.reshape(n, (2,2,2))  
tf.reshape(t, (2,2,2))
```

```
[[[1., 2.],  
  [3., 4.]],
```

```
[[5., 6.],  
 [7., 8.]]]
```

## Operações

```
n.T  
tf.transpose(t)
```

```
[[1., 5.],  
 [2., 6.],  
 [3., 7.],  
 [4., 8.]]
```

```
n @ n.T  
t @ t.transpose(t)
```

```
[[ 30., 70.],  
 [ 70., 174.]]
```

```
np.sum(n, axis=1)  
tf.reduce_sum(t, axis=1)
```

```
[6., 15.]
```

```
np.mean(n, axis=0)  
tf.reduce_mean(t, axis=0)
```

```
[3., 4., 5., 6.]
```

## Operações

```
t + 10  
tf.add(t, 10., name='adicao')
```

```
t - 10  
tf.subtract(t, 10., name='subtracao')
```

```
t / 10  
tf.divide(t, 10., name='divisao')
```

```
t * 10  
tf.muliply(t, 10., name='multiplicacao')
```



## Conversões

```
a = tf.constant(6.)  
<tf.Tensor: shape=(), dtype=float32, numpy=6.0>
```

```
b = tf.constant(4)  
<tf.Tensor: shape=(), dtype=int32, numpy=4>
```

```
tf.cast(b, dtype=tf.float32)  
<tf.Tensor: shape=(), dtype=float32, numpy=4.0>
```

```
a + tf.cast(b, dtype=tf.float32)  
<tf.Tensor: shape=(), dtype=float32, numpy=10.0>
```

# TensorFlow

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## Variáveis

```
t[1, 2].assign(30)
```

```
v = tf.Variable([[1., 2., 3.], [4., 5., 6.]])  
<tf.Variable 'Variable:0' shape=(2, 3) dtype=float32, numpy=  
array([[1., 2., 3.], [4., 5., 6.]], dtype=float32)>
```

```
v[1,2].assign(30)  
[[ 1.,  2.,  3.],  
 [ 4.,  5., 30.]]
```

# TensorFlow

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## Autodiff

```
def f(w1, w2):  
    return 3 * w1 ** 2 + 2 * w1 * w2
```

```
w1, w2 = tf.Variable(5.), tf.Variable(3.)  
with tf.GradientTape() as tape:  
    z = f(w1, w2)
```

```
gradients = tape.gradient(z, [w1, w2])  
[<tf.Tensor: shape=(), dtype=float32, numpy=36.0>,  
<tf.Tensor: shape=(), dtype=float32, numpy=10.0>]
```

$$3 \times w1^2 + 2 \times w1 \times w2$$

## Autodiff

```
def f(w1, w2):  
    return 3 * w1 ** 2 + 2 * w1 * w2
```

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w1, w2 = tf.Variable(5.), tf.Variable(3.)  
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```
gradients = tape.gradient(z, [w1, w2])  
[<tf.Tensor: shape=(), dtype=float32, numpy=36.0>,  
<tf.Tensor: shape=(), dtype=float32, numpy=10.0>]
```

**e se  $w_1$  e  $w_2$  fossem constantes?**

$$3 \times w_1^2 + 2 \times w_1 \times w_2$$

# TensorFlow

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## TF functions

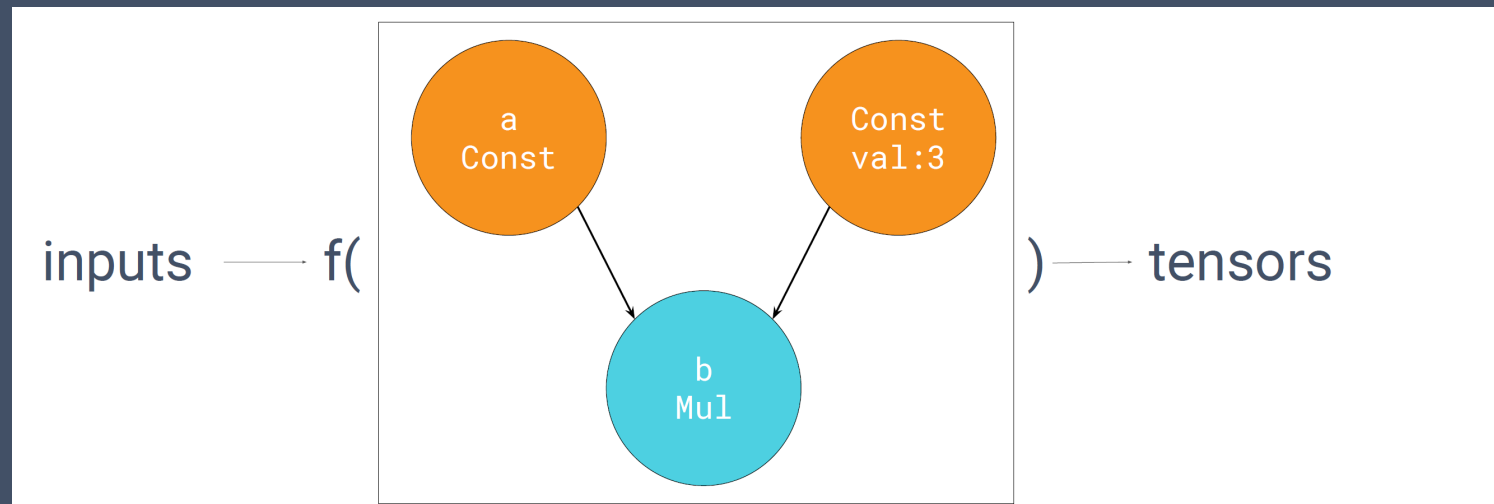
```
def cubo(x):  
    return x**3
```

```
cubo(np.array(2, 4))  
[8., 16.]
```

Recebe np.array, retorna np.array

## TF functions

@tf.function



# TensorFlow

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## TF functions

```
@tf.function  
def cubo(x):  
    return x**3
```

```
cubo(np.array(2, 4))  
<tf.Tensor: shape=(2,), dtype=int64,  
numpy=array([27, 64])>
```

=

```
def cubo(x):  
    return tf.power(x,3)
```

```
cubo(np.array(2, 4))  
<tf.Tensor: shape=(2,), dtype=int64,  
numpy=array([27, 64])>
```

# TensorFlow

## TF data API

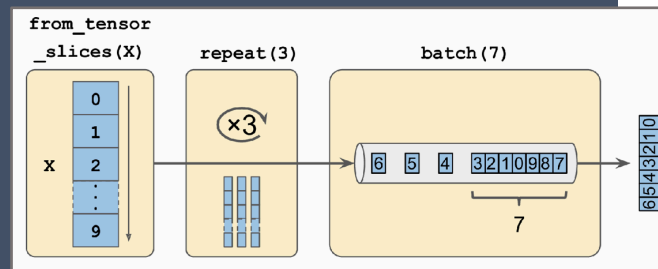
Na maior parte dos projetos de deep learning, o dataset não cabe interinamente na RAM

Tensorflow disponibiliza o data API para realizar pré-processamento, carregamento em batch, multithreading com o tf.keras

```
X = tf.range(10)
dataset = tf.data.Dataset.from_tensor_slices(X)
<TensorSliceDataset shapes: (), types: tf.int32>
```

```
ndataset = dataset.repeat(3).batch(7)
tf.Tensor([0 1 2 3 4 5 6], shape=(7,), dtype=int32)
tf.Tensor([7 8 9 0 1 2 3], shape=(7,), dtype=int32)
tf.Tensor([4 5 6 7 8 9 0], shape=(7,), dtype=int32)
tf.Tensor([1 2 3 4 5 6 7], shape=(7,), dtype=int32)
```

```
ndataset.map()
```

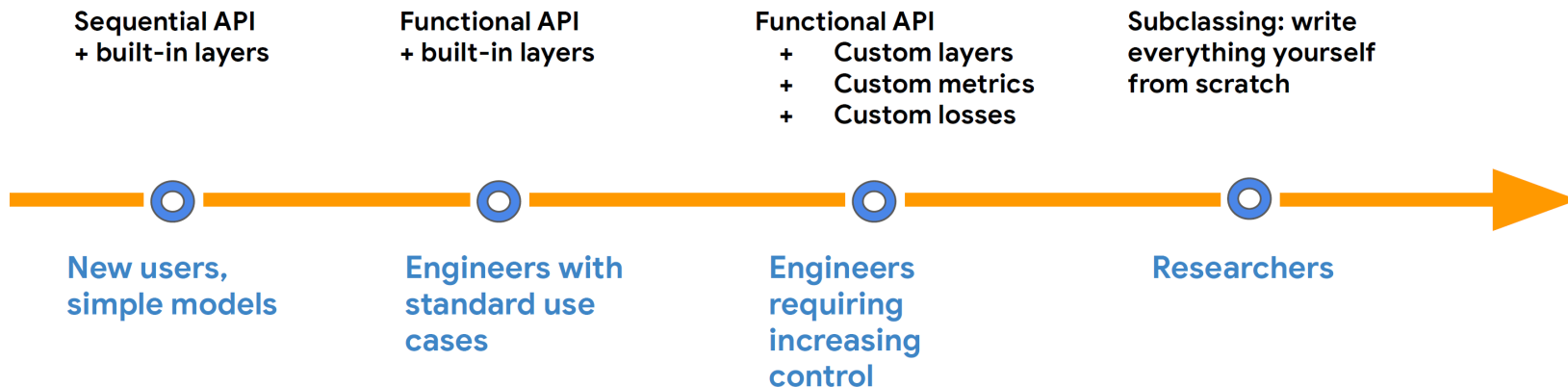




# TensorFlow

## Model building: from simple to arbitrarily flexible

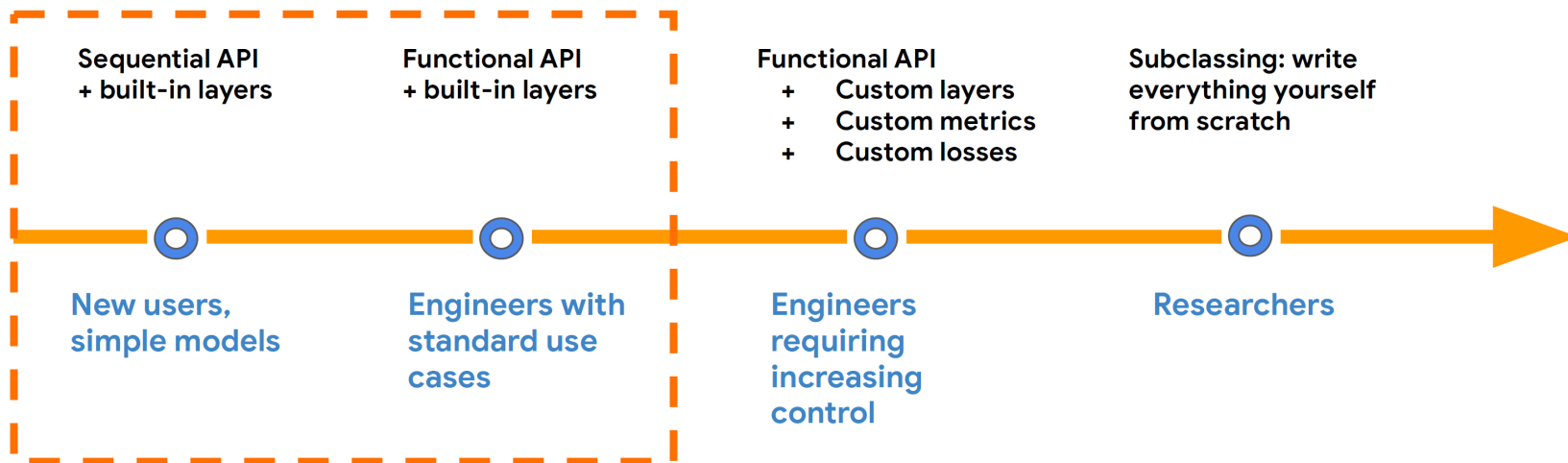
Progressive disclosure of complexity



# TensorFlow

## Model building: from simple to arbitrarily flexible

Progressive disclosure of complexity



## Sequential API

API simples para criação rápida de redes neurais "clássicas"

```
# Define um modelo Sequential com 3 camadas
model = tf.keras.Sequential([
    layers.Dense(2, activation="relu", name="layer1"),
    layers.Dense(3, activation="relu", name="layer2"),
    layers.Dense(4, name="layer3"),
])
```

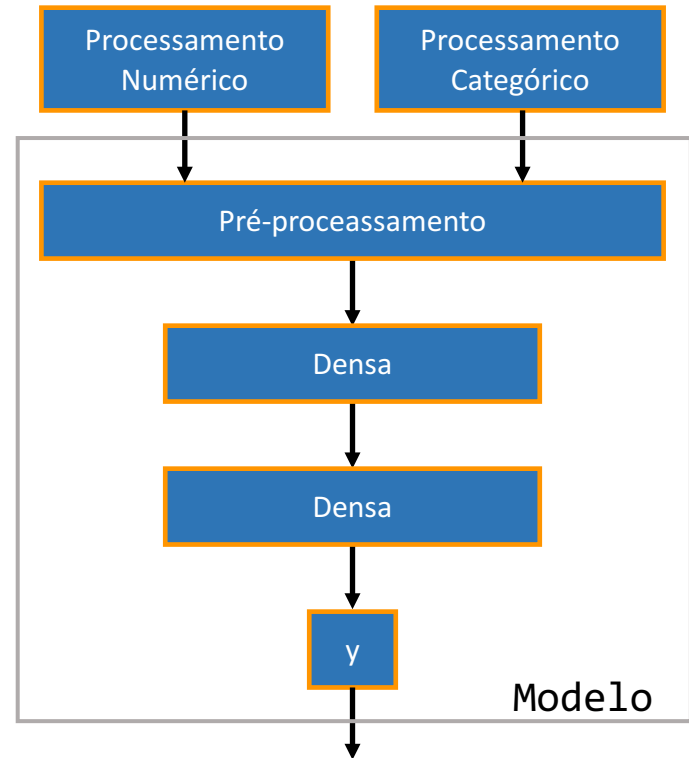
```
# Executa o modelo em em exemplo de teste
x = tf.ones((3, 3))
y = model(x)
```

# TensorFlow

## Sequential API

*notebook:* NNRegression.ipynb

Boston House Price



## Functional API

Permite maior maleabilidade do que o Sequential.  
Topologias não lineares, pesos compartilhados...

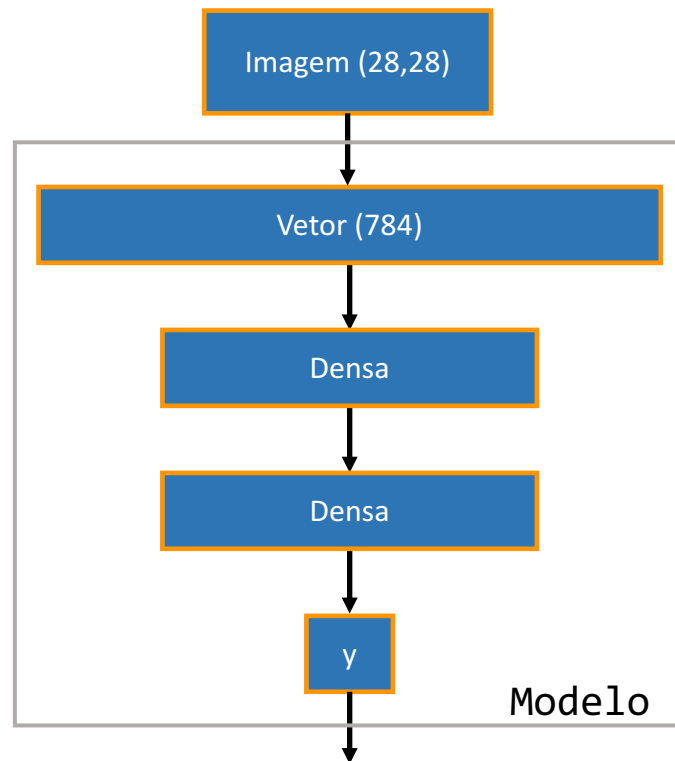
```
#define as dimensões do vetor de entrada
inputs = tf.keras.Input(shape=(3,))
x = tf.keras.layers.Dense(128, activation=tf.nn.relu)(inputs)
x = tf.keras.layers.Dense(128, activation=tf.nn.relu)(x)
outputs = tf.keras.layers.Dense(5, activation=tf.nn.softmax)(x)

#define o modelo com a camada de entrada e saída
model = tf.keras.Model(inputs=inputs, outputs=outputs)
```

## Functional API

*notebook:* `NNSimpleClassification.ipynb`

Fashion Mnist



**Obrigado!**