

# Optimization and decision making

# Optimization and Decision Making

## **Objectives:**

- To understand the role of optimization in decision making
- To know the optimality conditions for linear and quadratic programming

## **Outline:**

1. The Kuhn-Tucker optimality conditions
2. Optimality conditions for quadratic programming problems
3. Optimality condition for linear programming problems
4. Dual of a linear programming problem
5. Standard form linear program
6. Economic interpretation of the dual problem
7. Dual of nonlinear programming problem
8. Application of optimization in decision making

# 1. The Kuhn-Tucker optimality conditions

The problem NLP (Non Linear Programming):

$$\text{minimize } f(x_1, x_2, x_3, \dots, x_n)$$

$$\text{subject to: } g_1(x_1, x_2, x_3, \dots, x_n) \leq b_1$$

$$g_2(x_1, x_2, x_3, \dots, x_n) \leq b_2$$

$$\vdots$$

$$g_m(x_1, x_2, x_3, \dots, x_n) \leq b_m$$

Note that

- o The number of variables is  $n$ , the number of constraints is  $m$
- o  **$\max f(x_1, x_2, x_3, \dots, x_n)$**  is equivalent to  **$-\min -f(x_1, x_2, x_3, \dots, x_n)$**
- o The constraint  **$g_k(x_1, x_2, x_3, \dots, x_n) \geq b_k$**  is equivalent to  
 **$-g_k(x_1, x_2, x_3, \dots, x_n) \leq -b_k$**

# The Kuhn-Tucker optimality conditions

The Kuhn-Tucker (KT) necessary conditions:

Suppose that the point  $\mathbf{x} = (x_1, x_2, x_3, \dots, x_n)$  is an optimal solution,  
then  $\mathbf{x} = (x_1, x_2, x_3, \dots, x_n)$  must satisfy all the constraints, that is,

$$g_1(x_1, x_2, x_3, \dots, x_n) \leq b_1$$

$$g_2(x_1, x_2, x_3, \dots, x_n) \leq b_2$$

.

.

$$g_m(x_1, x_2, x_3, \dots, x_n) \leq b_m$$

and there must exist multipliers  $\lambda_1, \lambda_2, \lambda_3, \dots, \lambda_m$  such that

$$\partial f(\mathbf{x}) / \partial x_j + \sum_{i=1}^m \lambda_i \partial g_i(\mathbf{x}) / \partial x_j = 0 \quad (j = 1, 2, \dots, n)$$

$$\lambda_i [b_i - g_i(\mathbf{x})] = 0 \quad (i = 1, 2, \dots, m) \quad \text{complementarity conditions}$$

$$\lambda_i \geq 0 \quad (i = 1, 2, \dots, m)$$

# The Kuhn-Tucker optimality conditions

The **complementarity conditions**:

$$\lambda_i [b_i - g_i(\mathbf{x})] = 0$$

imply

- If  $\lambda_i > 0$ ,  $b_i = g_i(\mathbf{x})$ , the  $i^{\text{th}}$  constraint is said to be binding
- If  $g_i(\mathbf{x}) < b_i$ , then  $\lambda_i = 0$ . In this case, the constraint is said to be non-binding.

**Partial derivative example:**

$$f(\mathbf{x}) = f(x_1, x_2, x_3) = -x_1(30 - x_1) - x_2(50 - 2x_2) + 3x_1 + 5x_2 + 10x_3$$

$$\partial f(\mathbf{x}) / \partial x_1 = -30 + 2x_1 + 3$$

$$\partial f(\mathbf{x}) / \partial x_2 = -50 + 4x_2 + 5$$

$$\partial f(\mathbf{x}) / \partial x_3 = 10$$



# The Kuhn-Tucker optimality conditions

KT sufficient conditions:

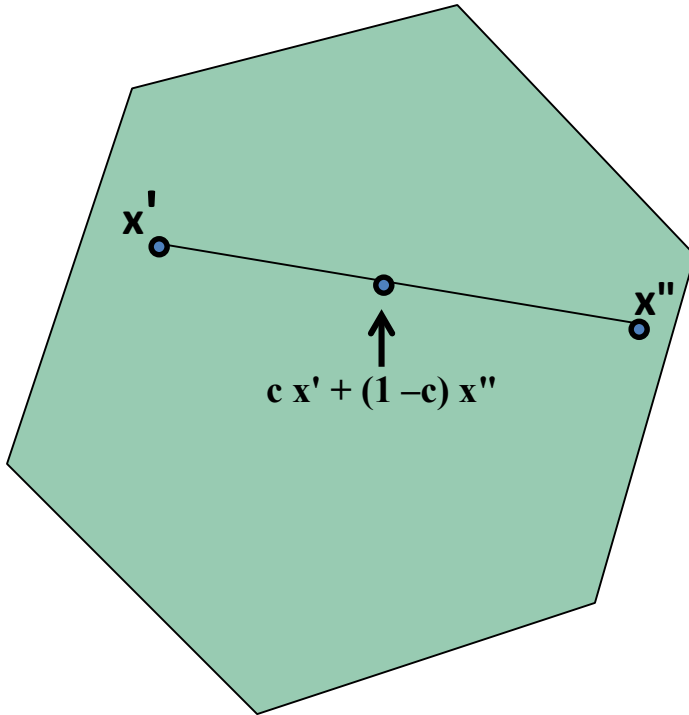
If  $f(x_1, x_2, x_3, \dots, x_n)$  is a convex function, and

$g_1(x_1, x_2, x_3, \dots, x_n)$ ,  $g_2(x_1, x_2, x_3, \dots, x_n)$ ,  $\dots$ ,  $g_m(x_1, x_2, x_3, \dots, x_n)$  are **convex** functions,

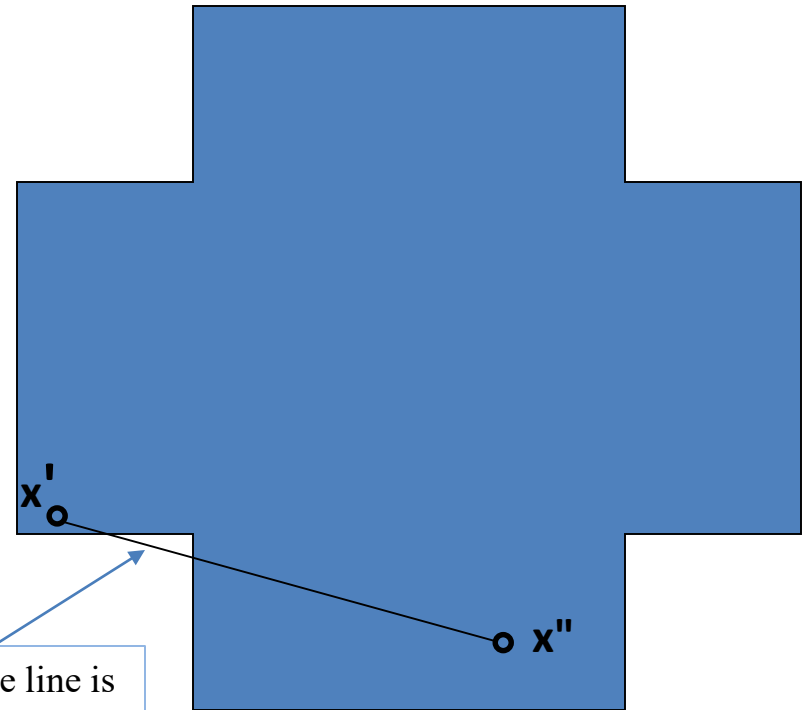
then any points  $\mathbf{x} = (x_1, x_2, x_3, \dots, x_n)$  that satisfies the KT necessary conditions is an optimal solution to the NLP.

# The Kuhn-Tucker optimality conditions

A set  $S$  is convex if  $x' \in S$  and  $x'' \in S$  imply that all points on the line segment joining  $x'$  and  $x''$  are members of  $S$ , that is  $c x' + (1 - c) x''$  is also in  $S$  for any  $0 \leq c \leq 1$ .



**Convex set**



Part of the line is outside the set

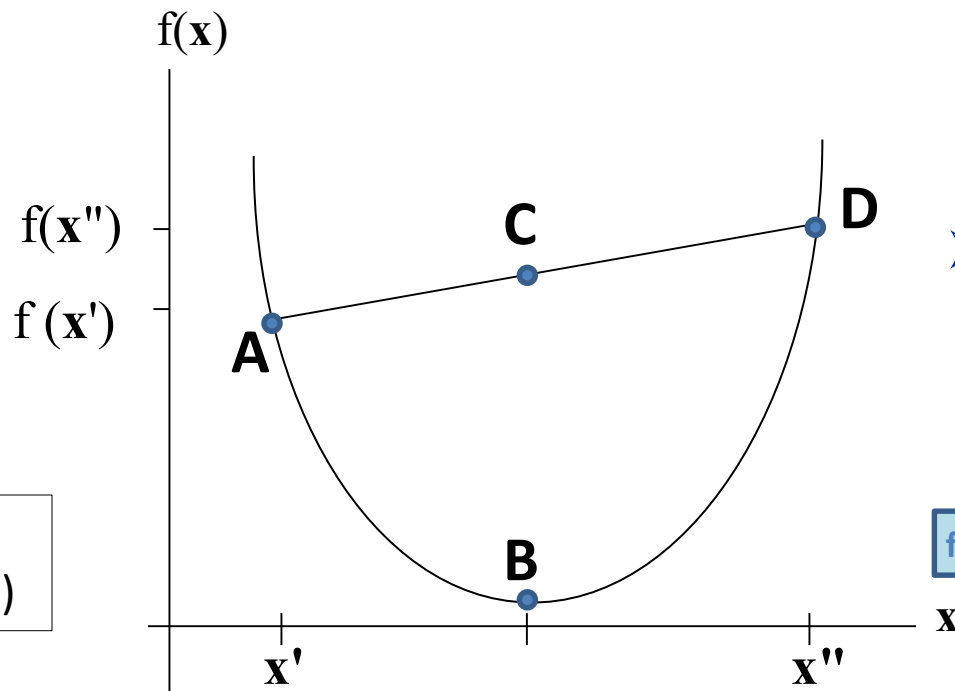
**Non-convex set**

# The Kuhn-Tucker optimality conditions

The function  $f(x_1, x_2, x_3, \dots, x_n)$  is a **convex function** on a convex set  $S$  if for any  $\mathbf{x}' \in S$  and  $\mathbf{x}'' \in S$

$$f(c \mathbf{x}' + (1 - c) \mathbf{x}'') \leq c f(\mathbf{x}') + (1 - c) f(\mathbf{x}'')$$

holds for  $0 \leq c \leq 1$



➤ X-coordinate:

$$B = (c \mathbf{x}' + (1 - c) \mathbf{x}'')$$

$$C = (c \mathbf{x}' + (1 - c) \mathbf{x}'')$$

➤ Y-coordinate:

$$B = f(c \mathbf{x}' + (1 - c) \mathbf{x}'')$$

$$C = c f(\mathbf{x}') + (1 - c) f(\mathbf{x}'')$$

$$f(c \mathbf{x}' + (1 - c) \mathbf{x}'') \leq c f(\mathbf{x}') + (1 - c) f(\mathbf{x}'')$$



# The Kuhn-Tucker optimality conditions

Example 1. Describe the optimal solution to

$$\max f(x)$$

$$\text{subject to } a \leq x \leq b$$

Answer:

$$- \min -f(x)$$

$$\text{subject to } -x \leq -a$$

$$x \leq b$$

Four possibilities:

1)  $\lambda_1 = \lambda_2 = 0$ , then  $f'(x) = 0$

2)  $\lambda_1 = 0, \lambda_2 > 0$ , then  $x = b, f'(b) = \lambda_2 > 0$

3)  $\lambda_1 > 0, \lambda_2 = 0$ , then  $x = a, f'(a) = -\lambda_1 < 0$

4)  $\lambda_1 > 0, \lambda_2 > 0$ , then  $x = a = b$ ,  
a contradiction, hence this case cannot occur

KT necessary conditions:

$$-f'(x) - \lambda_1 + \lambda_2 = 0$$

$$\lambda_1(a - x) = 0$$

$$\lambda_2(x - b) = 0$$

$$\lambda_1, \lambda_2 \geq 0$$

**If  $-f(x)$  is convex, a point that satisfies these 4 conditions is optimal since the constraints are linear**

# The Kuhn-Tucker optimality conditions

Example 1 (continued). Describe the optimal solution to

$$\begin{array}{ll}\max & -x^2 \\ \text{subject to} & 2 \leq x \leq 5\end{array}$$

Answer:

$$\begin{array}{ll}\min & x^2 \\ \text{subject to} & -x \leq -2 \\ & x \leq 5\end{array}$$

KT necessary conditions:

$$2x - \lambda_1 + \lambda_2 = 0$$

$$\lambda_1(2 - x) = 0$$

$$\lambda_2(x - 5) = 0$$

$$\lambda_1, \lambda_2 \geq 0$$

Here  $f(x) = -x^2$  and  $f'(x) = -2x$ . Four possibilities:

1)  $\lambda_1 = \lambda_2 = 0$ , then  $f'(x) = -2x = 0$

Not possible!

2.  $\lambda_1 = 0, \lambda_2 > 0$ , then  $x = b = 5$ ,  $2x - \lambda_1 + \lambda_2 > 0$ .

Not good!

3)  $\lambda_1 > 0, \lambda_2 = 0$ , then  $x = a = 2$  and  $2x - \lambda_1 + \lambda_2 = 0$  if we let  $\lambda_1 = 4$

**Solution:  $x = 2$  with maximum value of  $-x^2 = -4$**

# The Kuhn-Tucker optimality conditions

Example 2.

$$\min -x_1(30-x_1) - x_2(50-2x_2) + 3x_1 + 5x_2 + 10x_3$$

$$\text{subject to } x_1 + x_2 - x_3 \leq 0$$

$$x_3 \leq 17.25$$

KT necessary conditions:

$$-30 + 2x_1 + 3 + \lambda_1 = 0$$

$$-50 + 4x_2 + 5 + \lambda_1 = 0$$

$$10 - \lambda_1 + \lambda_2 = 0$$

$$\lambda_1(x_1 + x_2 - x_3) = 0$$

$$\lambda_2(x_3 - 17.25) = 0$$

$$\lambda_1, \lambda_2 \geq 0$$

Four possibilities:

- 1)  $\lambda_1 = \lambda_2 = 0$ , impossible ( $10 = 0$ )
- 2)  $\lambda_1 = 0, \lambda_2 > 0$ , impossible ( $\lambda_2 = -10$ )
- 3)  $\lambda_1 > 0, \lambda_2 = 0$ , then  $\lambda_1 = 10, x_1 = (30 - 3 - 10)/2 = 8.5, x_2 = (50 - 10 - 5)/4 = 8.75, x_3 = x_1 + x_2 = 17.25$
- 4)  $\lambda_1 > 0, \lambda_2 > 0$ , need not be considered as optimal solution is already found above.

## 2. Optimality conditions for quadratic programming problems

Any quadratic programming problem with linear constraints can be put in the following standard form:

$$\min \quad \frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{p}^t \mathbf{x}$$

$$\text{subject to } \mathbf{A} \mathbf{x} \leq \mathbf{a}$$

$$\mathbf{x} \geq 0$$

Where  $\mathbf{P}$  is an  $n$  by  $n$  matrix,  $\mathbf{p}$  is an  $n$ -dimensional vector,

$\mathbf{A}$  is an  $m$  by  $n$  matrix,  $\mathbf{a}$  is an  $m$ -dimensional vector

$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ \vdots \\ x_n \end{pmatrix} \text{ is an } n\text{-dimensional variable.}$$

# Optimality conditions for quadratic programming problems

$$\text{QP: } \min \frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{p}^t \mathbf{x}$$

$$\text{subject to } \mathbf{A} \mathbf{x} \leq \mathbf{a}$$

$$\mathbf{x} \geq 0$$

KT necessary conditions:

If  $\mathbf{x}$  is an optimal solution, then  $\mathbf{x}$  must satisfy the constraints  $\mathbf{A} \mathbf{x} \leq \mathbf{a}$ ,  $\mathbf{x} \geq 0$  and there must exist an  $n$ -dimensional vector  $\mathbf{v}$ , and an  $m$ -dimensional  $\mathbf{u}$ , such that

- $\mathbf{P} \mathbf{x} + \mathbf{p} + \mathbf{A}^t \mathbf{u} - \mathbf{v} = 0$  (note: there are  $n$  equations here)
- $\mathbf{u}^t (\mathbf{A} \mathbf{x} - \mathbf{a}) = 0$  (note: there are  $m$  complementarity conditions here)
- $\mathbf{v}^t \mathbf{x} = 0$  (note: there are  $n$  complementarity conditions here)
- $\mathbf{u} \geq 0$
- $\mathbf{v} \geq 0$

# Optimality conditions for quadratic programming problems

## A note on Complementarity condition $\mathbf{v}^t \mathbf{x} = 0$

- Since  $\mathbf{v} \geq 0$  and  $\mathbf{x} \geq 0$ ,

then if  $v_j > 0$ ,  $x_j$  must be 0 for the complementarity conditions to be satisfied.

Proof: Since  $\mathbf{x} \geq 0$ ,  $x_j$  cannot be negative. Suppose  $x_j > 0$ , then  $v_j x_j > 0$ , and

$$\mathbf{v}^t \mathbf{x} = v_1 x_1 + v_2 x_2 + \dots + v_j x_j + \dots + v_n x_n > 0. \text{ A contradiction.}$$

- Similarly, if  $x_j > 0$ , then  $v_j = 0$ , for all  $j = 1, 2, \dots, n$ .
- If  $x_j = 0$ , then  $v_j$  may be 0 or positive.
- Similarly if  $v_j = 0$ , then  $x_j$  may be 0 or positive.



# Optimality conditions for quadratic programming problems

$$\text{QP: } \min \frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{p}^t \mathbf{x}$$

$$\text{subject to } \mathbf{A} \mathbf{x} \leq \mathbf{a}$$

$$\mathbf{x} \geq 0$$

KT sufficient conditions: If  $\mathbf{x}$  is feasible and if there exist an  $n$ -dimensional vector  $\mathbf{v}$ , and an  $m$ -dimensional  $\mathbf{u}$ , such that

- $\mathbf{P} \mathbf{x} + \mathbf{p} + \mathbf{A}^t \mathbf{u} - \mathbf{v} = 0$  (note: there are  $n$  equations here)
- $\mathbf{u}^t (\mathbf{A} \mathbf{x} - \mathbf{a}) = 0$  (note: there are  $m$  complementarity conditions here)
- $\mathbf{v}^t \mathbf{x} = 0$  (note: there are  $n$  complementarity conditions here)
- $\mathbf{u} \geq 0$
- $\mathbf{v} \geq 0$

and if  $\frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{p}^t \mathbf{x}$  is convex, then  $\mathbf{x}$  solves QP

# Optimality conditions for quadratic programming problems

Example.  $\min -x_1 - x_2 + \frac{1}{2} (x_1)^2 + (x_2)^2 - x_1 x_2$

subject to  $x_1 + x_2 \leq 3$

$-2 x_1 - 3 x_2 \leq -6$

$x_1, x_2 \geq 0$

Show that  $x_1 = 9/5$ ,  $x_2 = 6/5$  is the solution.

KT conditions:

$$x_1 - 1 - x_2 + u_1 - 2u_2 - v_1 = 0$$

$$2x_2 - 1 - x_1 + u_1 - 3u_2 - v_2 = 0$$

$$(x_1 + x_2 - 3)u_1 = 0$$

$$(-2x_1 - 3x_2 + 6)u_2 = 0$$

$$v_1 x_1 = 0, v_2 x_2 = 0$$

$$x_1, x_2, u_1, u_2, v_1, v_2 \geq 0$$

Check feasibility:

✓  $x_1 + x_2 \leq 3$ ? Yes, and  $9/5 + 6/5 = 3$ , this constraint is binding.

✓  $-2x_1 - 3x_2 \leq -6$ ? Yes,  $-18/5 - 18/5 \leq -6$ , this constraint is not binding, hence  $u_2 = 0$

✓  $x_1, x_2 \geq 0$ ? Yes, these constraints are not binding, hence  $v_1 = v_2 = 0$

Can we find  $u_1 \geq 0$ ?

Yes,  $u_1 = 2/5$

All conditions are satisfied.

Since the objective function is also convex,

$x_1 = 9/5$ ,  $x_2 = 6/5$  is the solution.

# Optimality conditions for quadratic programming problems

$$f(x_1, x_2) = -x_1 - x_2 + \frac{1}{2} (x_1)^2 + (x_2)^2 - x_1 x_2$$

What is the matrix **P** and the vector **p**?

$$\bullet \partial f(x_1, x_2) / \partial x_1 = -1 + x_1 - x_2$$

$$\bullet \partial f(x_1, x_2) / \partial x_2 = -1 - x_1 + 2 x_2$$

$$\bullet \partial^2 f(x_1, x_2) / \partial x_1 \partial x_1 = 1$$

$$\bullet \partial^2 f(x_1, x_2) / \partial x_1 \partial x_2 = -1$$

$$\partial^2 f(x_1, x_2) / \partial x_2 \partial x_1 = -1$$

$$\partial^2 f(x_1, x_2) / \partial x_2 \partial x_2 = 2$$

$$\mathbf{P} = \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix}$$

$$\mathbf{p} = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$$

Note:

- the derivative of  $\frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{p}^t \mathbf{x}$  is  $\mathbf{P} \mathbf{x} + \mathbf{p}$
- the second derivative is **P**

Check that  $\frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{p}^t \mathbf{x} = -x_1 - x_2 + \frac{1}{2} (x_1)^2 + (x_2)^2 - x_1 x_2$

### 3. Optimality conditions for linear programming problems

If we just remove the matrix  $P$  from QP, we have the linear program

$$\text{LP: } \min \mathbf{c}^t \mathbf{x}$$

$$\text{subject to } \mathbf{Ax} \leq \mathbf{a}$$

$$\mathbf{x} \geq \mathbf{0}$$

Since the objective function and the constraints are all linear, the KT necessary and sufficient conditions: If the  $n$ -dimensional vector  $\mathbf{v}$  and the  $m$ -dimensional vector  $\mathbf{u}$  satisfy:

$$\mathbf{c} + \mathbf{A}^t \mathbf{u} - \mathbf{v} = \mathbf{0} \quad (\text{note: there are } n \text{ equations here})$$

$$\mathbf{u}^t (\mathbf{Ax} - \mathbf{a}) = \mathbf{0} \quad (\text{note: there are } m \text{ complementarity conditions here})$$

$$\mathbf{v}^t \mathbf{x} = \mathbf{0} \quad (\text{note: there are } n \text{ complementarity conditions here})$$

$$\mathbf{u} \geq \mathbf{0}$$

$$\mathbf{v} \geq \mathbf{0}$$

and  $\mathbf{x}$  satisfies the constraints of the LP, then  $\mathbf{x}$  is the solution of LP

# Optimality conditions for linear programming problems

## **Example – LP formulation.**

- GW Inc. manufactures two types of wooden toys: soldiers and trains.
- A soldier sells for \$27 and uses \$10 worth of raw materials.
- Cost in labor for each soldier is \$14.
- A train sells for \$21 and uses \$9 worth of raw materials.
- Cost in labor for each train is \$10.
- A soldier requires 2 hours of finishing labor and 1 hour of carpentry labor.
- A train requires 1 hour of finishing and 1 hour of carpentry labor.
- Each week, GW can obtain all the needed labor but only 100 finishing hours and 80 carpentry hours.
- Only 40 soldiers per week can be sold.
- **Formulate an LP.**

# Optimality conditions for linear programming problems

## Example – LP formulation.

### 1. Decision variables:

$x_1$  = number of soldiers,  $x_2$  = number of trains produced per week

### 2. Objective function: maximize profit

- profit = revenue – cost
- revenue =  $27 x_1 + 21 x_2$
- cost =  $10 x_1 + 14 x_1 + 9 x_2 + 10 x_2$
- profit =  $27 x_1 + 21 x_2 - (10 x_1 + 14 x_1 + 9 x_2 + 10 x_2) = 3x_1 + 2 x_2$

### 3. Constraints:

- Each week, not more than 100 hours available for finishing:  $2 x_1 + x_2 \leq 100$
- Each week, not more than 80 hours available for carpentry:  $x_1 + x_2 \leq 80$
- Demand is limited to 40 soldiers per week:  $x_1 \leq 40$
- Non-negativity constraints:  $x_1, x_2 \geq 0$



# Optimality conditions for linear programming problems

## Graphical solution:

Dotted lines: isoprofit lines

Optimal solution:

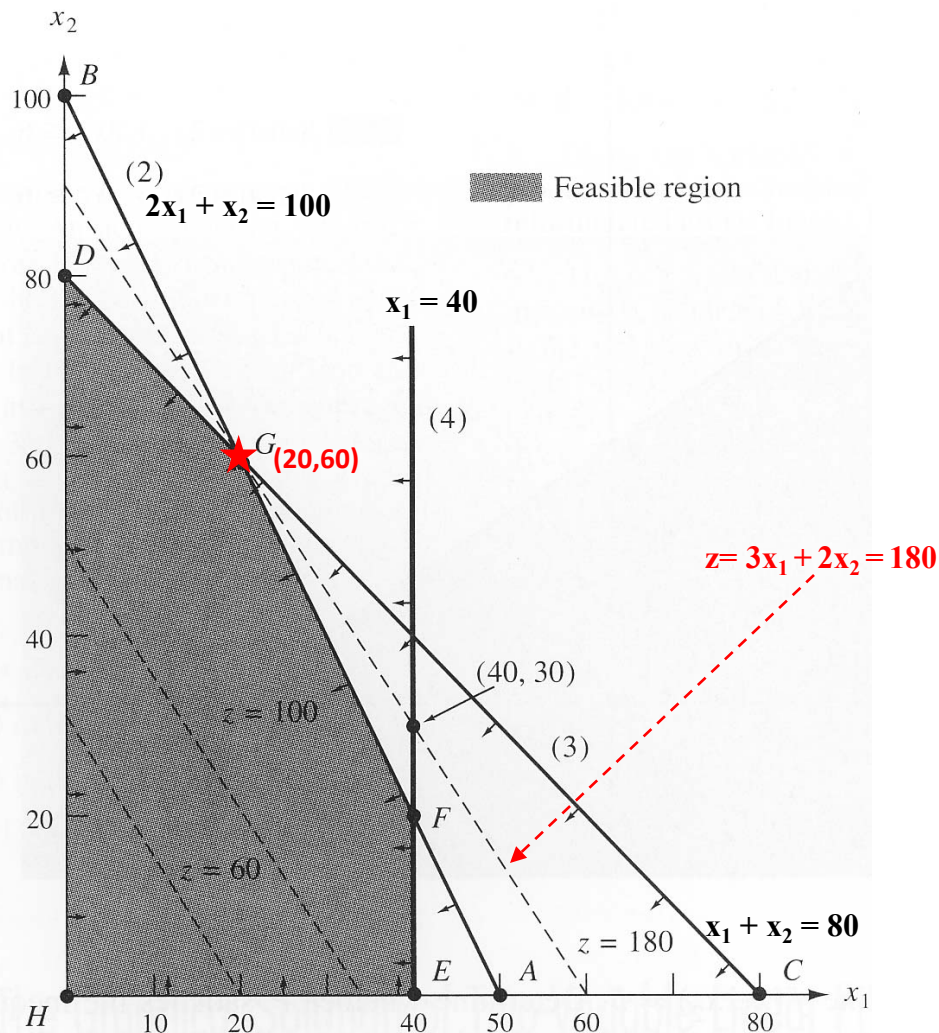
G where  $x_1 = 20$ ,  $x_2 = 60$

maximum profit =  $3(20) + 2(60) = 180$

**Feasible region:** the set of all points that satisfy the LP constraints

**Optimal solution:** a point in the feasible region with the best objective function value

If an LP has a solution, there must be a solution at an extreme point



# Optimality conditions for linear programming problems

## Linear Program:

$$\begin{aligned} & \text{-minimize } -3x_1 - 2x_2 \\ & \text{subject to: } 2x_1 + x_2 \leq 100 \quad \text{C1} \\ & \quad \quad \quad x_1 + x_2 \leq 80 \quad \text{C2} \\ & \quad \quad \quad x_1 \leq 40 \quad \text{C3} \\ & \quad \quad \quad x_1, x_2 \geq 0 \end{aligned}$$

## KT necessary and sufficient conditions:

$$\begin{aligned} -3 + 2u_1 + u_2 + u_3 - v_1 &= 0 \\ -2 + u_1 + u_2 - v_2 &= 0 \\ u_1 (2x_1 + x_2 - 100) &= 0 \\ u_2 (x_1 + x_2 - 80) &= 0 \\ u_3 (x_1 - 40) &= 0 \\ v_1 x_1 &= 0 \\ v_2 x_2 &= 0 \end{aligned}$$

**Optimal solution:  $x_1 = 20, x_2 = 60$**

Check all constraints, C1 and C2 are binding. C3 is not binding, hence  $u_3 = 0$ .

Also,  $x_1 > 0, x_2 > 0$ , hence  $v_1 = v_2 = 0$

Now find  $u_1 \geq 0$  and  $u_2 \geq 0$  so that all KT conditions are satisfied.

$$u_1 = 1, u_2 = 1$$

Note that the optimal objective function value:

$$3x_1 + 2x_2 = 3(20) + 2(60) =$$

$$100u_1 + 80u_2 + 40u_3 =$$

$$100(1) + 80(1) + 40(0) = 180$$

# 4. Dual of a linear programming problem

## Primal Linear Program:

$$\text{maximize } 3x_1 + 2x_2$$

$$\text{subject to: } 2x_1 + x_2 \leq 100$$

$$x_1 + x_2 \leq 80$$

$$x_1 \leq 40$$

$$x_1, x_2 \geq 0$$

## Dual linear program:

$$\text{minimize } 100u_1 + 80u_2 + 40u_3$$

$$\text{subject to: } 2u_1 + u_2 + u_3 \geq 3$$

$$u_1 + u_2 \geq 2$$

$$u_1, u_2, u_3 \geq 0$$

**Primal LP: Max  $c^t x$  st.  $Ax \leq b, x \geq 0$**

**Dual LP: Min  $b^t u$  st.  $A^t u \geq c, u \geq 0$**

$A =$

2	1
1	1
1	0

$A^t =$

2	1	1
1	1	0

# Dual of a linear programming problem

## Dual linear program:

$$\begin{aligned} &\text{minimize } 100 u_1 + 80 u_2 + 40 u_3 \\ &\text{subject to: } 2 u_1 + u_2 + u_3 \geq 3 \\ &\quad \quad \quad u_1 + u_2 \geq 2 \\ &\quad \quad \quad u_1, u_2, u_3 \geq 0 \end{aligned}$$

## KT necessary and sufficient conditions:

$$100 - 2x_1 - x_2 - w_1 = 0$$

$$80 - x_1 - x_2 - w_2 = 0$$

$$40 - x_1 - w_3 = 0$$

$$x_1(-2u_1 - u_2 - u_3 + 3) = 0$$

$$x_2(-u_1 - u_2 + 2) = 0$$

$$w_1 u_1 = 0, w_2 u_2 = 0, w_3 u_3 = 0$$

$$x_1 \geq 0, x_2 \geq 0, w_1 \geq 0, w_2 \geq 0, w_3 \geq 0$$

Show that the following values satisfy the KT conditions:

- $x_1 = 20, x_2 = 60$
- $u_1 = 1, u_2 = 1, u_3 = 0$
- $w_1 = 0, w_2 = 0, w_3 = 20$

(must also show that  $u_1, u_2, u_3$  satisfy the dual constraints to conclude that  $u_1, u_2, u_3$  is a solution of dual LP)

# 5. Standard form Linear Program

**Standard form LP**: an LP with only equality constraints and non-negative variables

Any LP can be easily converted to standard LP:

## Example 1.

Original LP: maximize  $3x_1 + 2x_2$

subject to:  $2x_1 + x_2 \leq 100$

$x_1 + x_2 \leq 80$

$x_1 \leq 40$

$x_1, x_2 \geq 0$

Standard LP: maximize  $3x_1 + 2x_2$

subject to:  $2x_1 + x_2 + s_1 = 100$

$x_1 + x_2 + s_2 = 80$

$x_1 + s_3 = 40$

$x_1, x_2, x_3, s_1, s_2, s_3 \geq 0$

$s_1, s_2, s_3$  are called slack variables

# Standard form Linear Program

## Example 2.

**Original LP:** minimize  $100 u_1 + 80 u_2 + 40 u_3$

subject to:  $2 u_1 + u_2 + u_3 \geq 3$

$u_1 + u_2 \geq 2$

$u_1, u_2 \geq 0$

$u_3$  unrestricted in sign

**Standard LP:** minimize  $100 u_1 + 80 u_2 + 40 (u_3' - u_3'')$

subject to:  $2 u_1 + u_2 + u_3' - u_3'' - s_1 = 3$

$u_1 + u_2 - s_2 = 2$

$u_1, u_2, u_3', u_3'', s_1, s_2 \geq 0$

$s_1, s_2$  are called surplus/excess variables

- Why need to convert LP into standard form? An algorithm for solving LP, the simplex algorithm requires that the LP is in standard form.
- How would you express the complementarity conditions in terms of the slack variables?

*Theorem of Complementary Slackness*



## 6. Economic interpretation of the dual problem

DF Company manufactures desks, tables, and chairs.

The resources are as follows:

Resource	Desk	Table	Chair	Available
Lumber	8 board ft	6 board ft	1 board ft	48 board ft
Finishing hour	4 hours	2 hours	1.5 hours	20 finishing hours
Carpentry hour	2 hours	1.5 hours	0.5 hours	8 carpentry hours

A desk sells for \$60, a table for \$30, a chair \$20.

Let  $x_1$ ,  $x_2$ ,  $x_3$  be the numbers of desks, tables, and chairs produced.

**Linear Program:** maximize  $60x_1 + 30x_2 + 20x_3$

subject to:  $8x_1 + 6x_2 + x_3 \leq 48$  (Lumber constraint)

$4x_1 + 2x_2 + 1.5x_3 \leq 20$  (Finishing constraint)

$2x_1 + 1.5x_2 + 0.5x_3 \leq 8$  (Carpentry constraint)

$x_1, x_2, x_3 \geq 0$

# Economic interpretation of the dual problem

**Primal LP:** maximize  $60x_1 + 30x_2 + 20x_3$

subject to:  $8x_1 + 6x_2 + x_3 \leq 48$  (Lumber constraint)

$4x_1 + 2x_2 + 1.5x_3 \leq 20$  (Finishing constraint)

$2x_1 + 1.5x_2 + 0.5x_3 \leq 8$  (Carpentry constraint)

$x_1, x_2, x_3 \geq 0$

**Dual LP:** minimize  $48u_1 + 20u_2 + 8u_3$

subject to:  $8u_1 + 4u_2 + 2u_3 \geq 60$

$6u_1 + 2u_2 + 1.5u_3 \geq 30$

$u_1 + 1.5u_2 + 0.5u_3 \geq 20$

$u_1, u_2, u_3 \geq 0$

## Solution:

**Primal:**  $x_1 = 2, x_2 = 0, x_3 = 8$

**Dual:**  $u_1 = 0, u_2 = 10, u_3 = 10$

**Objective function = 280**

# Economic interpretation of the dual problem

- $u_1$  = price paid for 1 board foot of lumber
- $u_2$  = price paid for 1 finishing hour
- $u_3$  = price paid for 1 carpentry hour
- Total price to be paid is  $48 u_1 + 20 u_2 + 8 u_3$
- A buyer must be willing to pay at least \$60 for the combination that includes 8 board ft of lumber, 4 finishing hours, and 2 carpentry hours. Why?

$$\text{Hence } 8u_1 + 4 u_2 + 2 u_3 \geq 60$$

- Similarly, the buyer must be willing to pay at least \$30 for the combination that includes 6 board ft of lumber, 2 finishing hours, and 1.5 carpentry hours.

$$\text{Hence } 6u_1 + 2 u_2 + 1.5 u_3 \geq 30$$

- Also,  $u_1 + 1.5u_2 + 0.5 u_3 \geq 20$

Objective function: minimize  $48 u_1 + 20 u_2 + 8 u_3$

# Economic interpretation of the dual problem

**Dual variables** are also referred to as **resource shadow prices**

Another interpretation of dual variables/shadow prices:

The shadow price of the  $i$ -th constraint is the amount by which the optimal objective function value is improved if we increase the corresponding right hand side by 1

**Primal LP:** maximize  $60x_1 + 30x_2 + 20x_3$   
subject to:  $8x_1 + 6x_2 + x_3 \leq 48$  (Lumber)  
 $4x_1 + 2x_2 + 1.5x_3 \leq 20$  (Finishing)  
 $2x_1 + 1.5x_2 + 0.5x_3 \leq 8$  (Carpentry)  
 $x_1, x_2, x_3 \geq 0$

## Solution:

**Primal:  $x_1 = 2, x_2 = 0, x_3 = 8$**

**Dual:  $u_1 = 0, u_2 = 10, u_3 = 10$**

**Objective function = 280**

One additional foot of lumber will not increase the revenue, because  $u_1 = 0$

If one additional hour of carpentry (now 9 hours are available), then the revenue would increase by  $u_3$  to  $(280 + 10) = 290$ . Optimal values for  $x_1, x_2, x_3$  would change.

# 7. Dual of nonlinear programming problem

Consider the primal NLP

$$\text{minimize } f(x_1, x_2, x_3, \dots, x_n)$$

$$\text{subject to: } g_1(x_1, x_2, x_3, \dots, x_n) \leq b_1$$

$$g_2(x_1, x_2, x_3, \dots, x_n) \leq b_2$$

.....

$$g_m(x_1, x_2, x_3, \dots, x_n) \leq b_m$$

Its dual is:

$$\begin{aligned} \max \quad & f(x_1, x_2, x_3, \dots, x_n) + \lambda_1 [g_1(x_1, x_2, x_3, \dots, x_n) - b_1] + \lambda_2 [g_2(x_1, x_2, x_3, \dots, x_n) - b_2] \\ & + \dots + \lambda_m [g_m(x_1, x_2, x_3, \dots, x_n) - b_m] \end{aligned}$$

st:

$$\partial f(x_1, x_2, x_3, \dots, x_n) / \partial x_j + \sum_{i=1}^m \lambda_i \partial g_i(x_1, x_2, x_3, \dots, x_n) / \partial x_j = 0, \quad j = 1, 2, \dots, n$$

$$\lambda_i \geq 0, \quad i = 1, 2, \dots, m$$

# Dual of nonlinear programming problem

Consider the primal QP

$$\text{minimize } \frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{p}^t \mathbf{x}$$

$$\text{subject to } \mathbf{A} \mathbf{x} \leq \mathbf{a}$$

$$\mathbf{x} \geq \mathbf{0}$$

Its dual is:

$$\text{maximize } \frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{p}^t \mathbf{x} + \mathbf{u}^t (\mathbf{A} \mathbf{x} - \mathbf{a}) - \mathbf{v}^t \mathbf{x}$$

$$\text{st: } \mathbf{P} \mathbf{x} + \mathbf{p} + \mathbf{A}^t \mathbf{u} - \mathbf{v} = \mathbf{0}$$

$$\mathbf{u}, \mathbf{v} \geq \mathbf{0}$$

Multiply this constraint by  $\mathbf{x}$   
and then simplify the  
objective function

An equivalent formulation:

$$\text{- minimize } \frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{u}^t \mathbf{a}$$

$$\text{st: } \mathbf{P} \mathbf{x} + \mathbf{p} + \mathbf{A}^t \mathbf{u} \geq \mathbf{0}$$

$$\mathbf{u} \geq \mathbf{0}$$

$$\mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{x}^t \mathbf{p} + \mathbf{x}^t \mathbf{A}^t \mathbf{u} - \mathbf{x}^t \mathbf{v} = 0$$

$$-\mathbf{x}^t \mathbf{P} \mathbf{x} = \mathbf{p}^t \mathbf{x} + \mathbf{u}^t \mathbf{A} \mathbf{x} - \mathbf{v}^t \mathbf{x}$$

$$\frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{p}^t \mathbf{x} + \mathbf{u}^t (\mathbf{A} \mathbf{x} - \mathbf{a}) - \mathbf{v}^t \mathbf{x} =$$

$$\frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} - \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{u}^t (-\mathbf{a}) =$$

$$- \frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} - \mathbf{u}^t (\mathbf{a})$$



# Dual of nonlinear programming problem

Example

$$\begin{aligned} &\text{minimize } \frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{p}^t \mathbf{x} \\ &\text{subject to } \mathbf{A} \mathbf{x} \leq \mathbf{a} \\ &\quad \mathbf{x} \geq \mathbf{0} \end{aligned}$$

Dual:

$$\begin{aligned} &\text{- minimize } \frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{u}^t \mathbf{a} \\ &\text{st: } \mathbf{P} \mathbf{x} + \mathbf{p} + \mathbf{A}^t \mathbf{u} \geq \mathbf{0} \\ &\quad \mathbf{u} \geq \mathbf{0} \end{aligned}$$

$$\begin{aligned} \text{Primal: minimize } &x_1^2 + x_2^2 \\ \text{subject to: } &-x_1 - x_2 \leq -4 \\ &x_1 + 2x_2 \leq 8 \\ &x_1 \geq 0 \\ &x_2 \geq 0 \end{aligned}$$

Dual

$$\begin{aligned} &\text{- minimize } x_1^2 + x_2^2 - 4u_1 + 8u_2 \\ &\text{subject to: } 2x_1 - u_1 + u_2 \geq 0 \\ &\quad 2x_2 - u_1 + 2u_2 \geq 0 \\ &\quad u_1 \geq 0 \\ &\quad u_2 \geq 0 \end{aligned}$$

$$\frac{1}{2} \mathbf{x}^t \mathbf{P} \mathbf{x} + \mathbf{p}^t \mathbf{x} = x_1^2 + x_2^2$$

$$\mathbf{P} \mathbf{x} + \mathbf{p} = \begin{bmatrix} 2x_1 \\ 2x_2 \end{bmatrix}$$

$$\mathbf{P} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \quad \mathbf{p} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\mathbf{A} = \begin{bmatrix} -1 & -1 \\ 1 & 2 \end{bmatrix} \quad \mathbf{a} = \begin{bmatrix} -4 \\ 8 \end{bmatrix}$$

$$\mathbf{A}^t \mathbf{u} = \begin{bmatrix} -1 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} -u_1 + u_2 \\ -u_1 + 2u_2 \end{bmatrix}$$

# Dual of nonlinear programming problem

Primal: minimize  $x_1^2 + x_2^2$

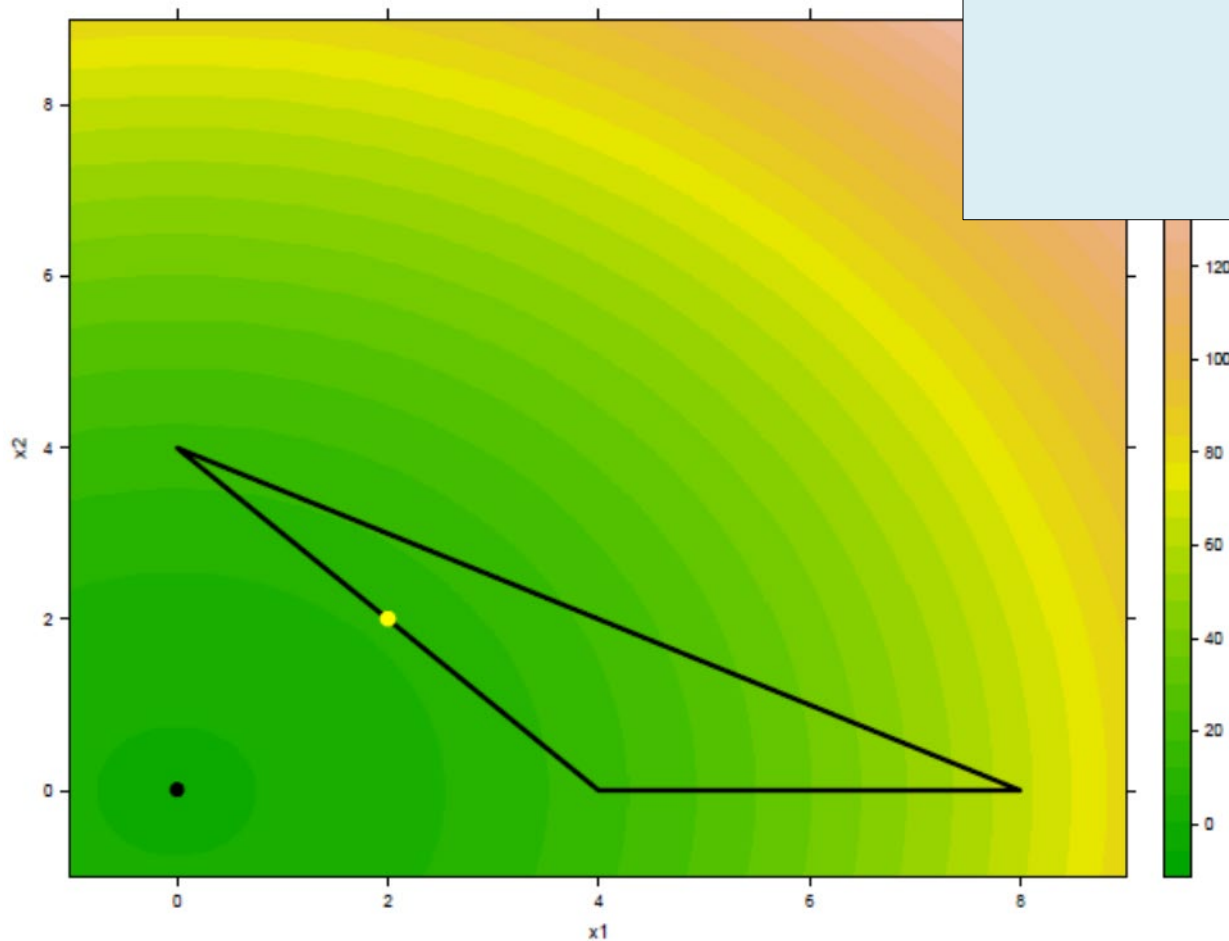
subject to:  $-x_1 - x_2 \leq -4$

$x_1 + 2x_2 \leq 8$

$x_1 \geq 0$

$x_2 \geq 0$

QP solutions, unconstrained at (0,0), constrained at (2,2)



# Dual of nonlinear programming problem

Primal: minimize  $x_1^2 + x_2^2$   
subject to:  $-x_1 - x_2 \leq -4$   
 $x_1 + 2x_2 \leq 8$   
 $x_1 \geq 0$   
 $x_2 \geq 0$

Dual

– minimize  $x_1^2 + x_2^2 - 4u_1 + 8u_2$   
subject to:  $2x_1 - u_1 + u_2 \geq 0$   
 $2x_2 - u_1 + 2u_2 \geq 0$   
 $u_1 \geq 0$   
 $u_2 \geq 0$

KT conditions:

$$2x_1 - u_1 + u_2 - v_1 = 0 \quad \clubsuit$$

$$2x_2 - u_1 + 2u_2 - v_2 = 0 \quad \clubsuit$$

$$u_1(-x_1 - x_2 + 4) = 0 \quad \diamond$$

$$u_2(x_1 + 2x_2 - 8) = 0 \quad \spadesuit$$

$$x_1 v_1 = 0, \quad x_2 v_2 = 0 \quad \spadesuit$$

**Solution:**

- $x_1$  and  $x_2$  cannot be both 0. Why?
- Suppose  $x_1 > 0$ ,  $x_2 > 0$ , and  $x_1 + 2x_2 < 8$
- Then  $v_1 = 0$ ,  $v_2 = 0$ ,  $u_2 = 0 \quad \spadesuit$
- Hence,  $u_1 = 2x_1 = 2x_2 > 0 \quad \clubsuit$
- And  $x_1 + x_2 = 4$ ,  $x_1 = x_2 = 2, \quad \diamond$
- Therefore,  $u_1 = 4$
- Dual objective function value  $= -(x_1^2 + x_2^2 - 4u_1 + 8u_2) = -(4 + 4 - 16 + 0) = 8$

# 8. Application of optimization in decision making

## The Multisurface Method (MSM)

MSM is a method based on linear program for finding a piece-wise linear discriminant function.

We first consider the case when the samples from the sets A and B are **linearly separable**.

The linear program is to find  $\mathbf{w}$ ,  $\alpha$  and  $\beta$  such that:

$$\text{(LP) max } \alpha - \beta$$

subject to

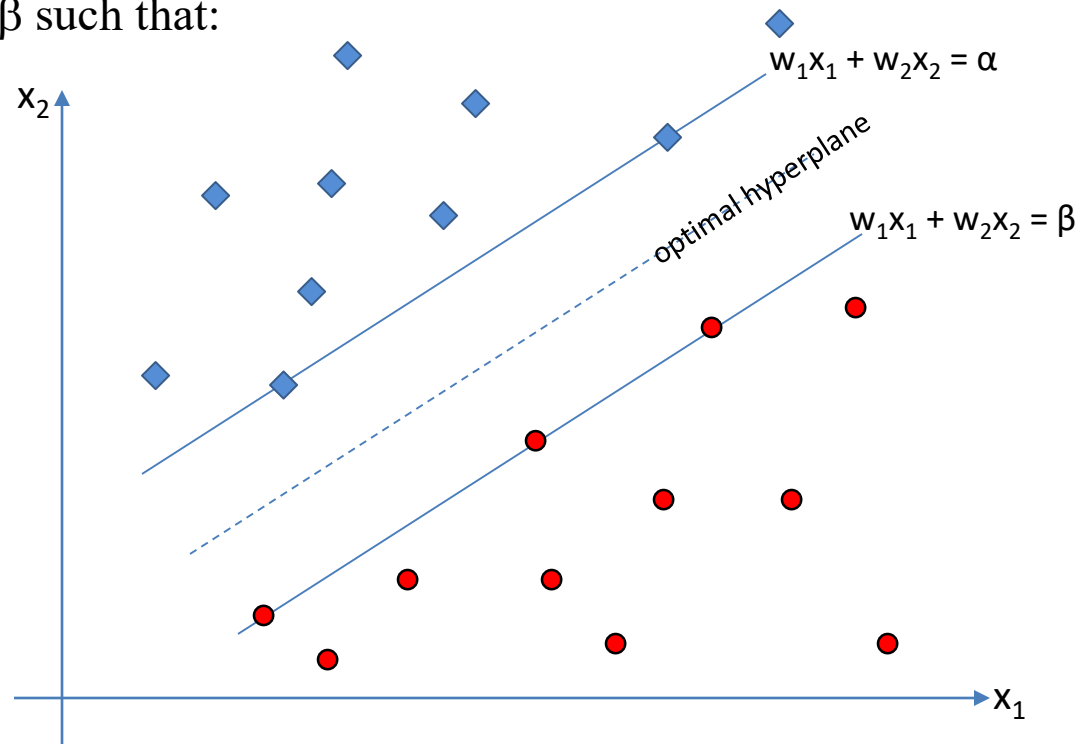
$$\mathbf{w}^T \mathbf{x}_i \geq \alpha \text{ for } \mathbf{x}_i \in A$$

$$\mathbf{w}^T \mathbf{x}_i \leq \beta \text{ for } \mathbf{x}_i \in B$$

$$-1 \leq \mathbf{w} \leq 1$$

The optimal hyperplane is

$$\mathbf{w}^T \mathbf{x} = (\alpha + \beta)/2$$



# 8. Application of optimization in decision making

## The Multisurface Method (MSM)

(LP) max  $\alpha - \beta$

subject to

$$\mathbf{w}^T \mathbf{x}_i \geq \alpha \text{ for } \mathbf{x}_i \in A$$

$$\mathbf{w}^T \mathbf{x}_i \leq \beta \text{ for } \mathbf{x}_i \in B$$

$$-1 \leq \mathbf{w} \leq 1$$

Without the constraint  $-1 \leq \mathbf{w} \leq 1$ , when the samples are linearly separable, the LP will be unbounded:

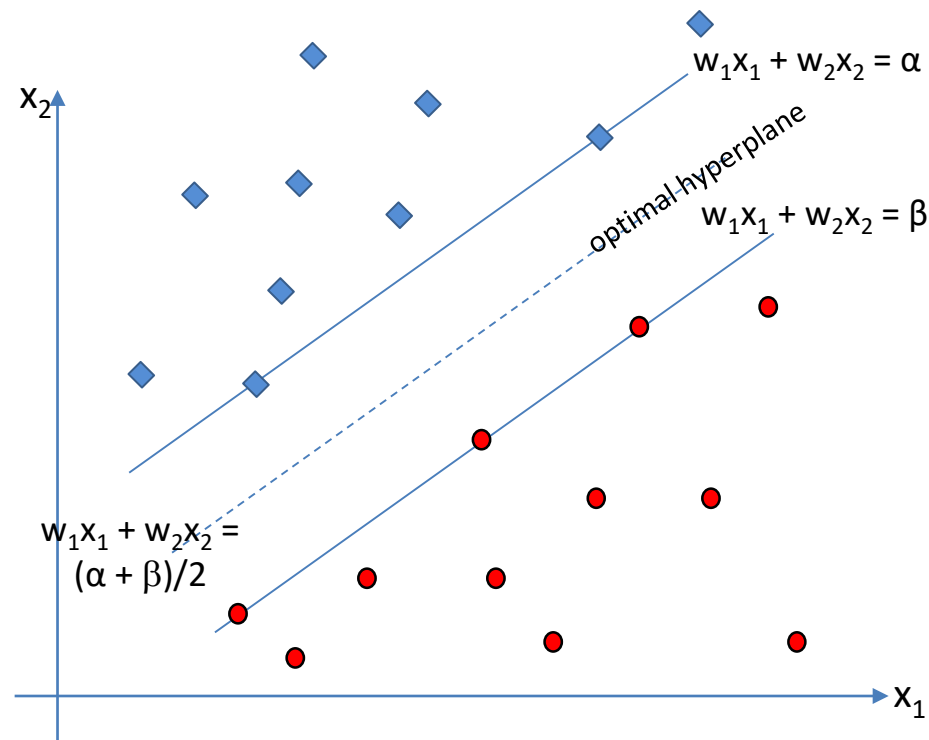
Let  $(\mathbf{w}^*, \alpha^*, \beta^*)$  be feasible for the LP and

$Z = \alpha^* - \beta^*$ , then for any  $k > 0$ ,

$(k\mathbf{w}^*, k\alpha^*, k\beta^*)$  is also feasible, and the

objective function value is  $k\alpha^* - k\beta^* = kZ$

can have arbitrarily large value.



# Application of optimization in decision making

## The Multisurface Method (MSM): Nonlinearly separable case

When the samples are linearly non-separable, a sequence of linear programs are solved.

The linear program at each iteration is:

$$\text{(LP)} \quad \max \alpha - \beta$$

subject to

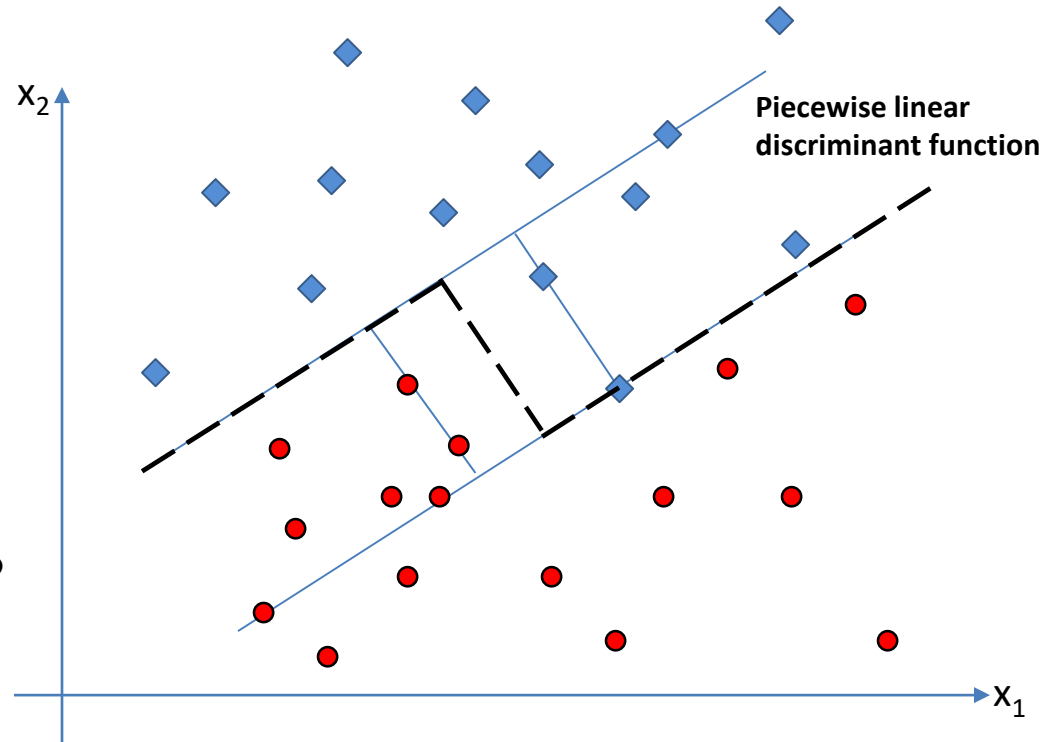
$$\mathbf{w}^T \mathbf{x}_i \geq \alpha \quad \text{for } \mathbf{x}_i \in A$$

$$\mathbf{w}^T \mathbf{x}_i \leq \beta \quad \text{for } \mathbf{x}_i \in B$$

$$-1 \leq \mathbf{w}_i \leq 1, i = 1, 2, \dots, N$$

$$w_d = 1 \text{ or } w_d = -1 \quad d = 1, 2, \dots, N$$

The constraint  $w_d = 1$  or  $w_d = -1$  is added to ensure that the solution of the LP is non-trivial ( $\mathbf{w} \neq 0$ ) when the samples are non-linearly separable.





# Application of optimization in decision making

## The Multisurface Method (MSM):

(Note: the method is for a 2 class problem,  $N$  =the dimensionality of the samples)

- Step 1. Let  $A$  be the whole sample set containing samples from set group 1, and  $B$  the set containing samples from group 2.
- Step 2: Solve linear program  $2*N$  linear programs LP.
- Step 3: Of the  $2N$  solutions (= hyperplanes), find one that gives the minimum total number of incorrectly classified samples.
- Step 4: If there are incorrectly classified samples, let  $A$  be the set of samples from group 1 that are incorrectly classified and  $B$  the set of samples from group 2 that are incorrectly classified. Go to Step 2.

(Note: The algorithm terminates when there are no more incorrectly classified samples, or when the number of minimum number of such samples is below a threshold, or if the maximum number of hyperplanes has been reached)

# References.

1. W.L. Winston, 3<sup>rd</sup> Edition, Sections 12.8, 12.9, 6.5, 6.6, 6.7, 3.1, 3.1  
or W.L. Winston, 4<sup>th</sup> Edition, Chapter 11 and Chapter 6.
2. O.L. Mangasarian, R. Setiono, W.H. Wolberg, Pattern recognition via linear programming: Theory and application to medical diagnosis, in Large Scale Numerical Optimization, 1989, T.F. Coleman and Y. Li Editors, SIAM Press, pages 22-30.

(This paper presents the method formally and describes its application in medical diagnosis. More information about the method and application is available at U Wisconsin-Madison <http://www.cs.wisc.edu/~olvi/uwmp/cancer.html>)

Data set: [https://archive.ics.uci.edu/ml/datasets/Breast+Cancer+Wisconsin+\(Original\)](https://archive.ics.uci.edu/ml/datasets/Breast+Cancer+Wisconsin+(Original))