



Graphics rasterization pipeline

- Light reflection model
- Conversion to screen coordinates
- Perspective transform
- Scan-conversion
- Performance issues
- Compare with raycasting

Rasterization (high level)

For each triangle T do

 Compute vertex colors (or triangle color)

 Clip to viewing frustum

 Compute perspective projection T'

 by projecting its vertices

 Interpolate vertex depth and color

 For each pixel p' in T'

 If (interpolated depth < stored depth)

 Update color and depth of p'



Graphic Pipeline

Model transforms

Vertex lighting

Viewing transform

Frustum clipping

Perspective transform

Slope computation

Scan-conversion

Approximate light reflection model

Reflected light: $k_a + (k_s(V \cdot R)^n + k_d(N \cdot L))I/r^2$

Ambient light

Ambient reflection coefficient: k_a

Distance attenuation of incident light: I/r^2

I = Intensity of point source at distance d in direction L

The attenuation effect is often softened to $\max(I/(ar^2 + br + c), I)$

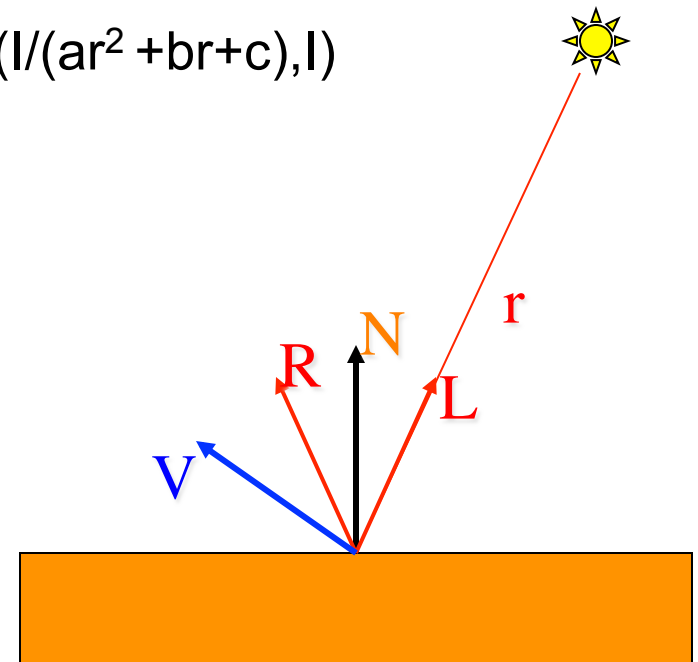
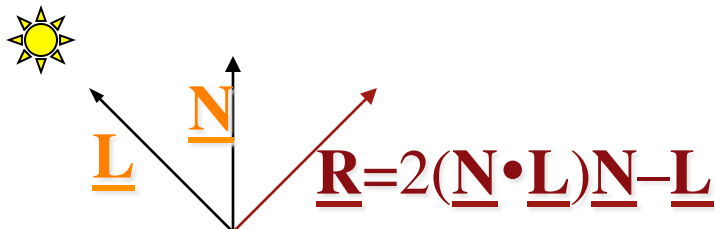
Diffuse (Lambertian) reflection: $k_d(N \cdot L)$

k_d = diffuse reflection coefficient

Specular (Phong) reflection: $k_s(V \cdot R)^n$

k_s = specular reflection coefficient

n = specular reflection exponent





Graphic Pipeline

Model transforms

Vertex lighting

Viewing transform

Frustum clipping

Perspective transform

Slope computation

Scan-conversion

Clipping

What does it do?

Trims each triangle to the window

Why?

To avoid processing out of window pixels

How?

Preprocessing stage

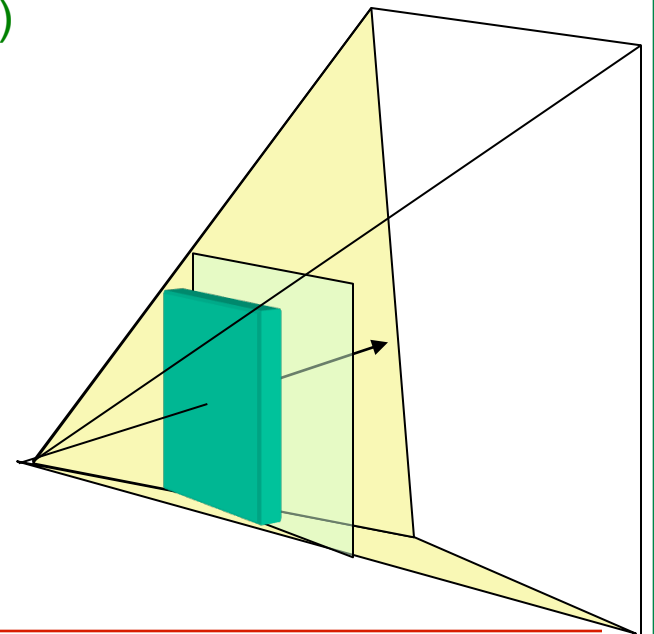
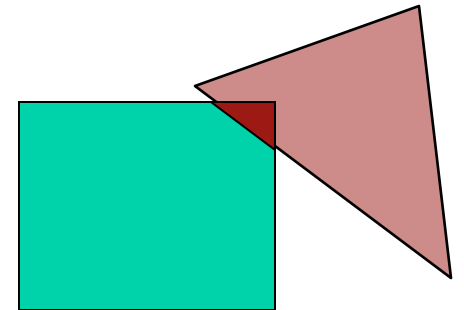
In model space (before perspective transform)

Intersect the triangle the viewing frustum

Intersection of 5 or 6 half-spaces

Or in image space (after perspective)

Using axis-aligned half-spaces





Graphic Pipeline

Model transforms

Vertex lighting

Viewing transform

Frustum clipping

Perspective transform

Slope computation

Scan-conversion

Perspective transform

Screen center O , is the closest point on the screen to the viewpoint V

Given S on screen and the screen normal \underline{K} , $O = V + d\underline{K}$, with $OS \cdot \underline{K} = 0$.
Hence, $OV \cdot \underline{K} + d\underline{K} \cdot \underline{K} = 0$ and $d = -OV \cdot \underline{K}$.

Compute the (x, y, z) screen coordinates of P

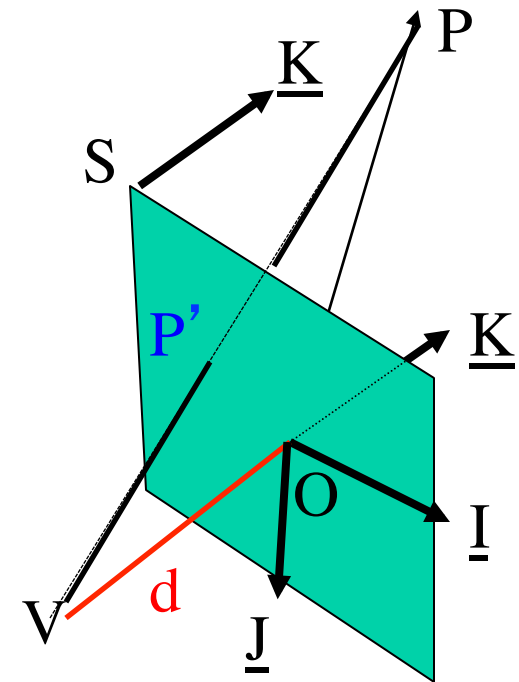
$$x = \underline{OP} \cdot \underline{I}, y = \underline{OP} \cdot \underline{J}, z = \underline{OP} \cdot \underline{K}$$

Compute perspective P' of P

$$P' = (x', y', z') = d/(d+z) P$$

P appears on screen at (x', y')

z' is stored at pixel containing (x', y')





Graphic Pipeline

Model transforms
Vertex lighting
Viewing transform
Frustum clipping
Perspective transform
Slope computation
Scan-conversion

Scan-conversion (rasterization)

Clear z-buffer $Z[*,*]$ and back frame buffer $I[*,*]$

For each triangle (A,B,C) do

Lit A, B, C using normals, surface attributes, lighting parameters

Transform vertices $\{A' = dA/(d+A.z); B' = dB/(d+B.z); C' = dC/(d+C.z)\}$

Compute slopes for c (color), z (depth), and leading/trailing edges

For each scanline L covered by triangle (A',B',C') do

Compute range [S..E] by interpolation on leading/trailing edges

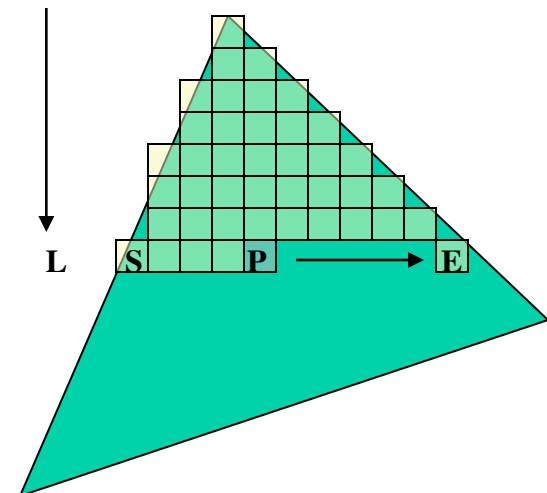
Compute initial z and c by interpolation along leading edge

For each pixel P in [S..E] do

Compute z and c using interpolation

If $z < Z[P,L]$ then $\{Z[P,L] := z; I[P,L] := c\}$

Swap frame buffers to show image



Rasterization costs

Per vertex

- Lighting calculations
- Perspective transform
- Slopes calculation

Per pixel

- Interpolations of z, c

 - Along leading edges (per triangle)**

 - Along scanline (per pixel)**

- Read, compare, right from/to (graphics) memory

 - Read is sequential along scanline

 - z-buffer (read and write)

 - Image buffer (write)

Ray-casting / scan-conversion

Scan-conversion:

For each triangle T do

For each pixel P **covered by the projection of T** do

Decide if the triangle is visible

Compute reflected color and store in the pixel

Ray-casting:

For each pixel P do

For each triangle T **projecting over P** do

Decide if the triangle is visible

Compute reflected color and store in the pixel

Why is scan-conversion faster

Ray casting consider all ray-triangle pairs.

Scan-conversion considers only pixels in projections

10,000 times less work if you have 10x10 pixel triangles

Ray-casting requires multiplications and divisions

for selecting which triangles cover a pixel and for computing the corresponding depth.

Scan-conversion uses mostly additions

to test which pixels are covered and to compute the color and depth for each pixel

And a few multiplications and division per triangle

to compute vertex projections and slopes),