



Shadows & occlusion

- Shadow - occlusion duality
- Floor shadows
- Shadow buffer
- Soft shadows

Motivation

- **Visibility**
 - Most objects in a scene are hidden from any given view point
 - Rendering them wastes GPU cycles
 - Need efficient techniques for rejecting what is obviously hidden
 - Rejection tests can be exact, conservative (reject more), approximate
- **Shadows**
 - Objects in the shadow do not reflect direct illumination
 - Want to know which light sources illuminate an object
 - Need a quick test for being in the shadow
- **Visibility and shadows are defined in terms of occluders**
 - Surfaces or objects that may block the passage of light
 - When placed between the object and the viewer/light

Shadows provide depth clues

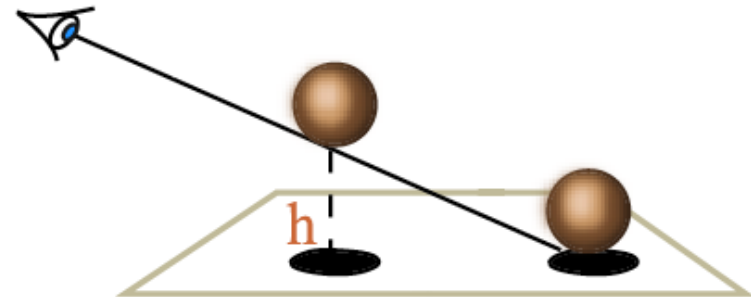
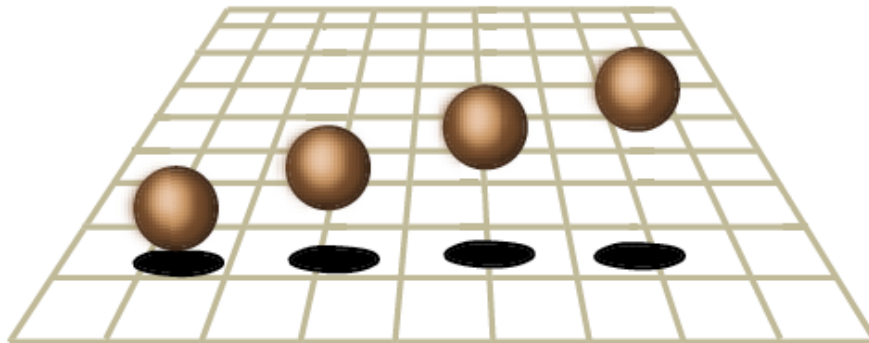
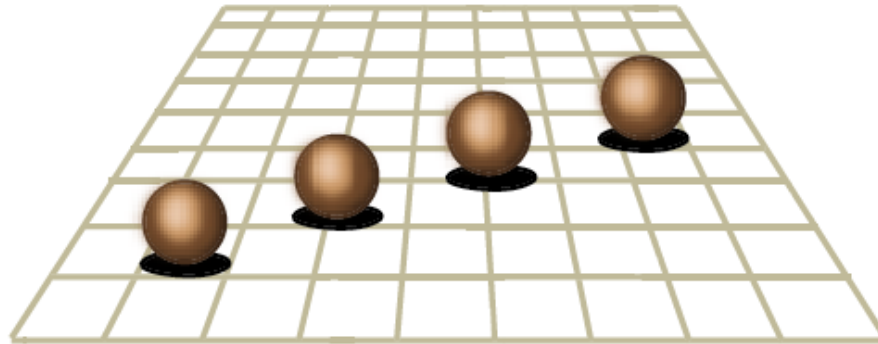


Image adapted from:

Palmer, Stephen E. *Vision Science: Photons to Phenomenology*. MIT Press. May 1999. ISBN: 0-262-16183-4.

4x4 matrix formulation (review)

u	0	0	0
0	v	0	0
0	0	w	0
0	0	0	1

$S(u,v,w)$

1	0	0	u
0	1	0	v
0	0	1	w
0	0	0	1

$T(u,v,w)$

U_x	V_x	W_x	0
U_y	V_y	W_y	0
U_z	V_z	W_z	0
0	0	0	1

$R(U,V,W)$

c	-s	0	0
s	c	0	0
0	0	1	0
0	0	0	1

$R_Z(a)$

U_x	V_x	W_x	u
U_y	V_y	W_y	v
U_z	V_z	W_z	w
0	0	0	1

$M \cdot P$

x
y
z
1

=

$U_x x + V_x y + W_x z + u$
$U_y x + V_y y + W_y z + v$
$U_z x + V_z y + W_z z + w$
1

Rotation matrix

- $\|U\|=\|V\|=1$
- $U \cdot V = 0$
- $W=U \times V$
- $R = \{ U \ V \ W \}$, 3x3 matrix
- $R' = \triangleleft R$, inverse = transpose
- Rotation to map Z to W
 - $U := Y \times W$ or $X \times W$
 - $U := U / \|U\|$
 - $V := W \times U$
 - $R_{ZtoW} = \{ U \ V \ W \}$
- Rotation to map W to Z axis
 - $\triangleleft R_{ZtoW}$

U_x	V_x	W_x	0
U_y	V_y	W_y	0
U_z	V_z	W_z	0
0	0	0	1

U_x	V_x	W_x
U_y	V_y	W_y
U_z	V_z	W_z

R

inverse

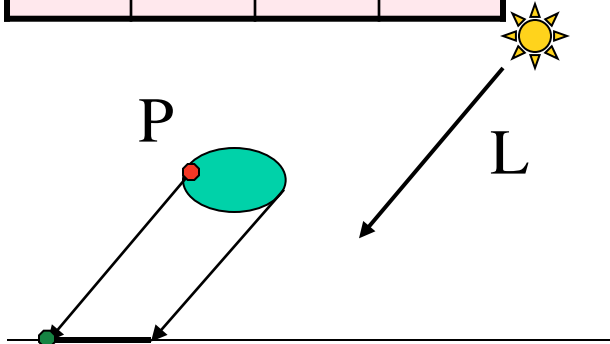
U_x	U_y	U_z
V_x	V_y	V_z
W_x	W_y	W_z

R'

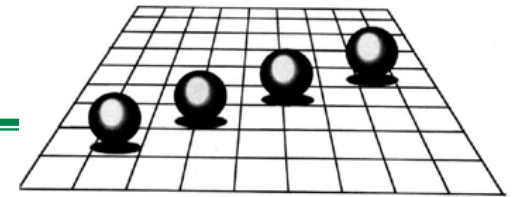
Floor shadows

- Depth cue, realism, light position
- Draw object twice
 - Second time: projected on the ground
- **Does not support self-shadows**

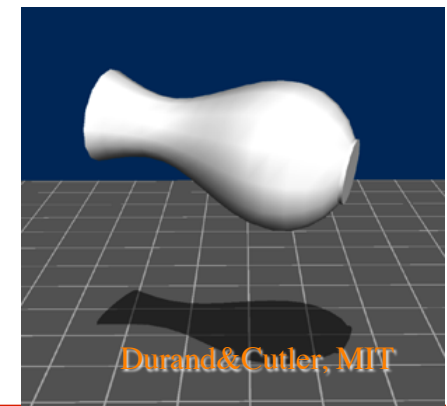
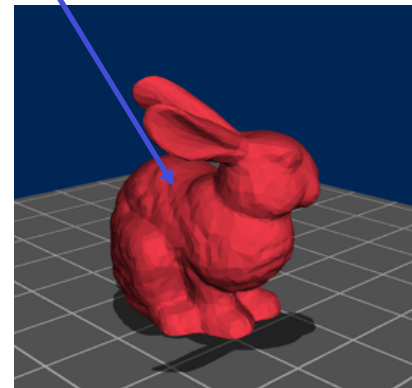
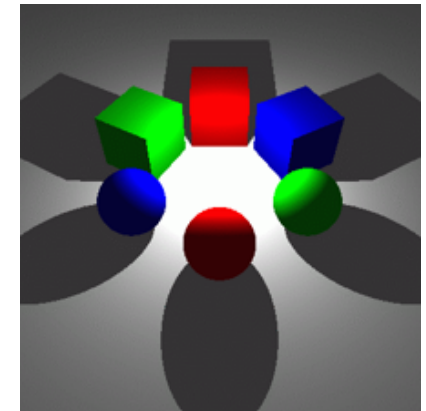
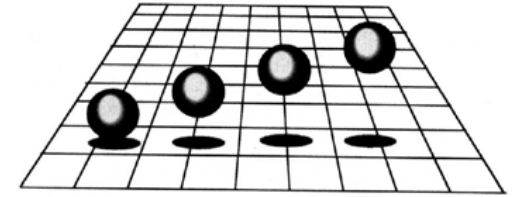
1	0	L_x/L_z	0
0	1	L_y/L_z	0
0	0	0	0
0	0	0	1



$$S = P + (P_z/L_z) L$$



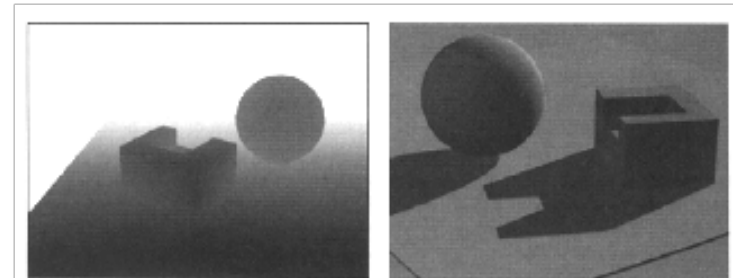
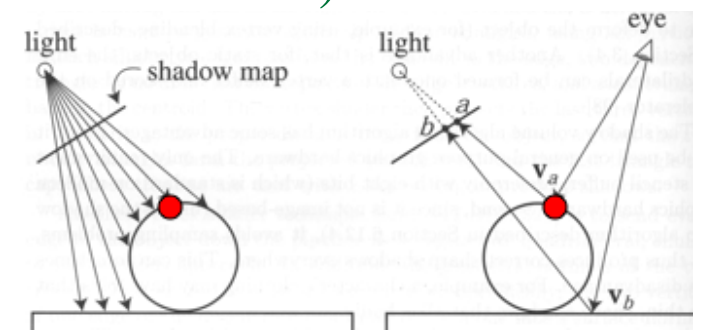
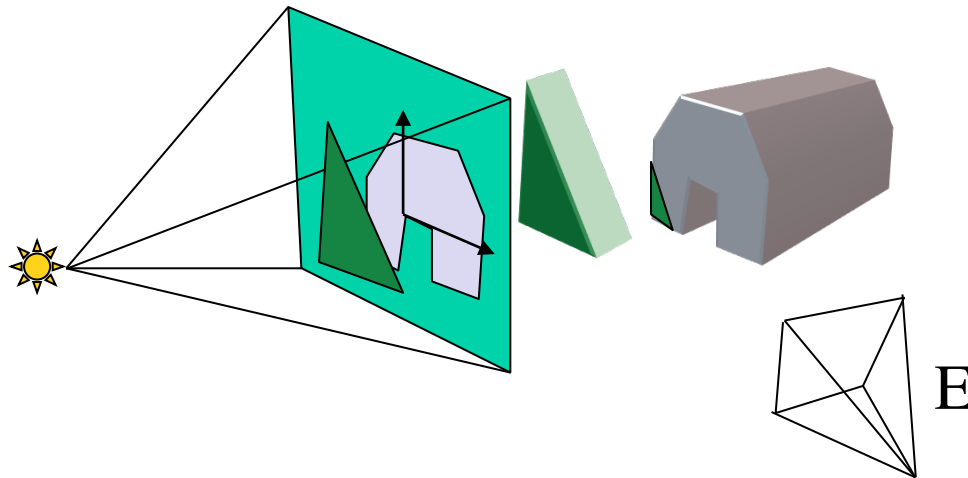
A



Shadow map (supports self-shadows)

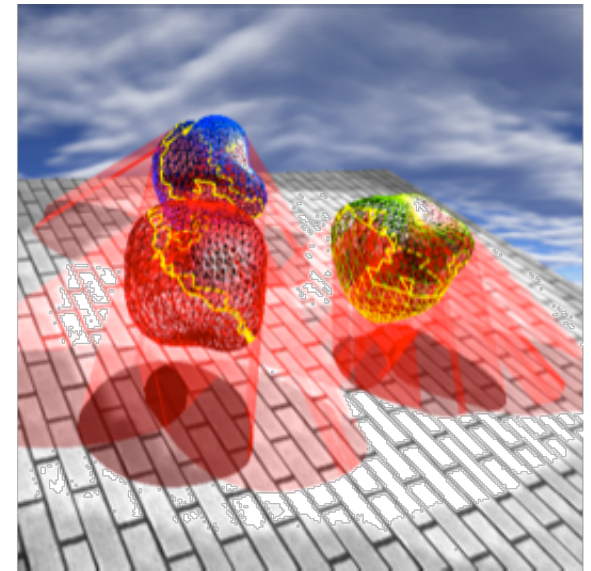
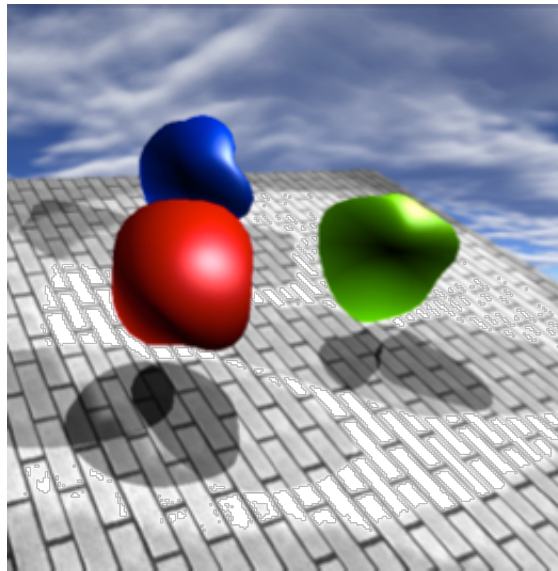
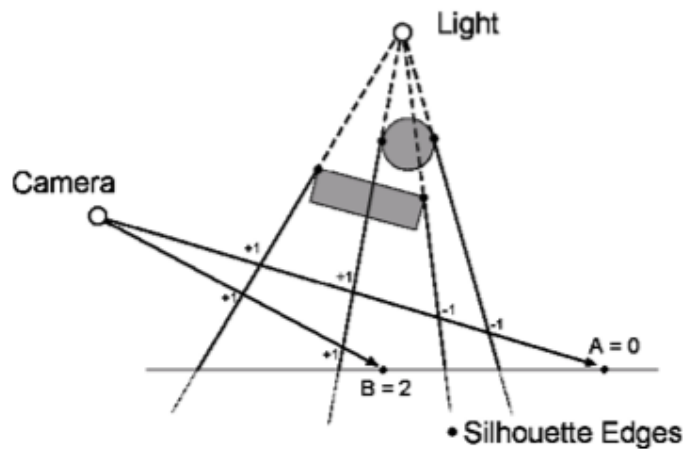
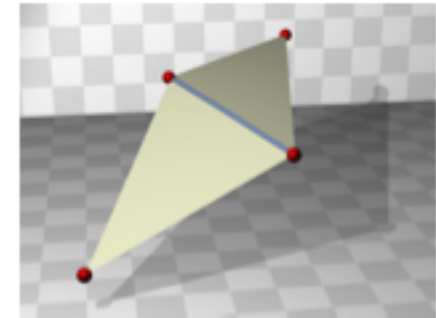
- Pre-render from light : store z-buffer as shadow map (texture)
- While rendering, check whether fragments are in shadow
 - Use GPU to perform the check (compare z to texture)

Shadow-casting
fragments must be in
light frustum



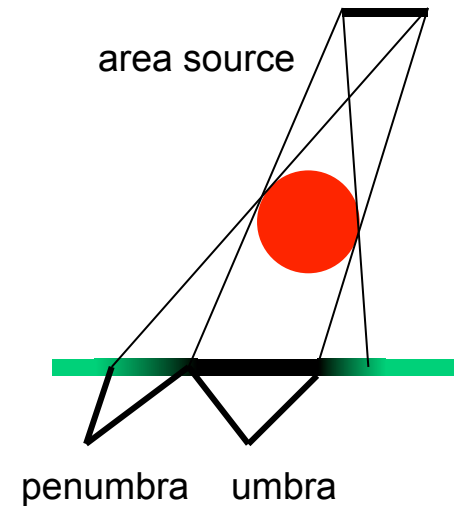
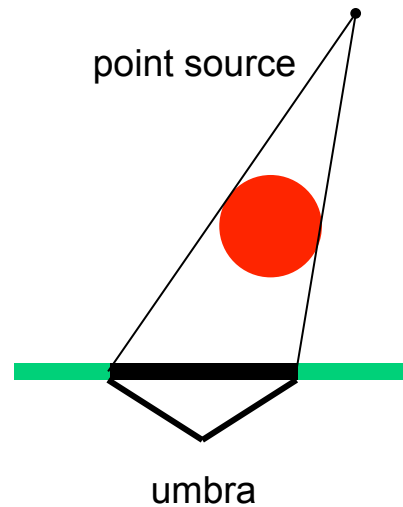
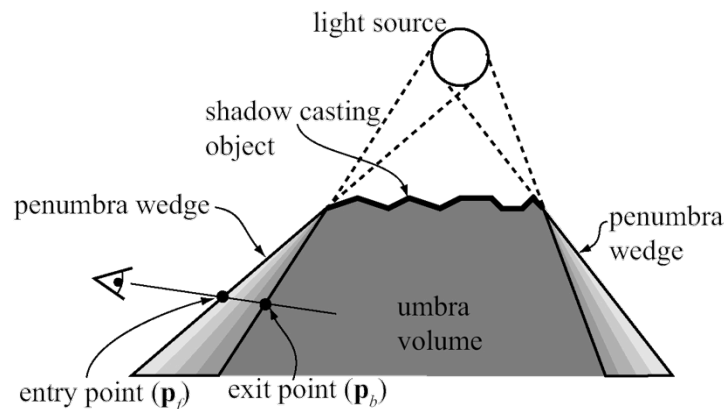
Shadow volumes on GPU

- Heidmann (IRIS Universe 1991), Everitt (nVidia 2002)
 - Shadow volume = triangles facing light + silhouette extrusions
- Brabec-Seidel (EUROGRAPHICS 2003)
 - Add silhouette identification in hardware



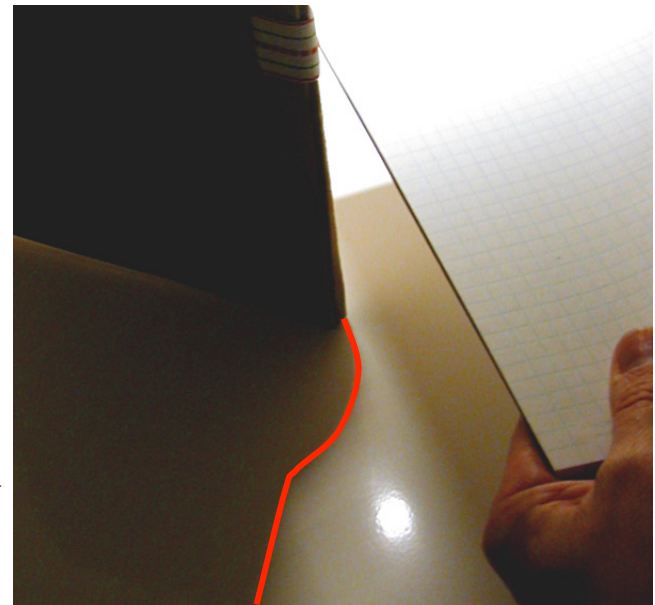
Soft shadows (area light sources)

- Polygonal area light source



Assarsson et al.

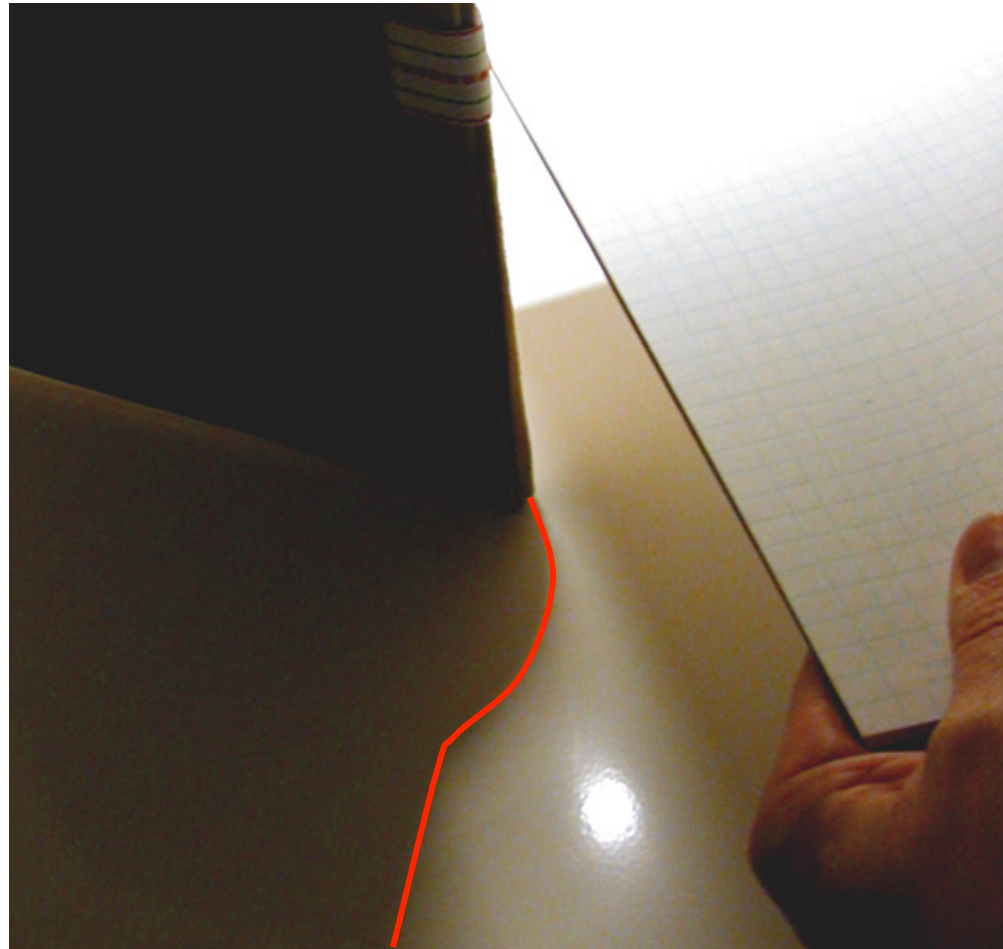
Polygons
cast curved
shadows



How can we compute (pen)umbras?

- Difficult because they involve cells of 3D space partition by planes and curved surfaces (even if the shape and light source is polygonal)

Polygons cast curved shadows!



Soft Shadow volumes

- Using graphics hardware

Ulf Assarsson¹,
Michael Dougherty²,
Michael Mounier²,
and Tomas Akenine-Möller¹

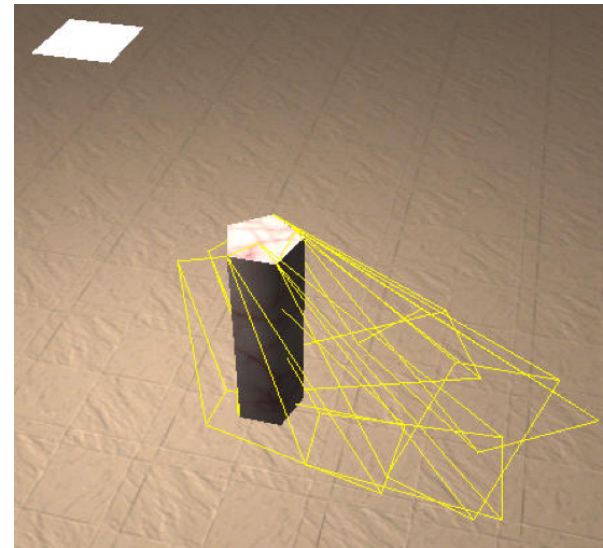
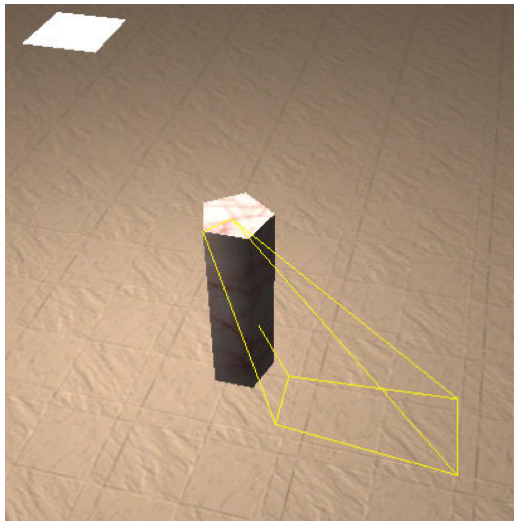
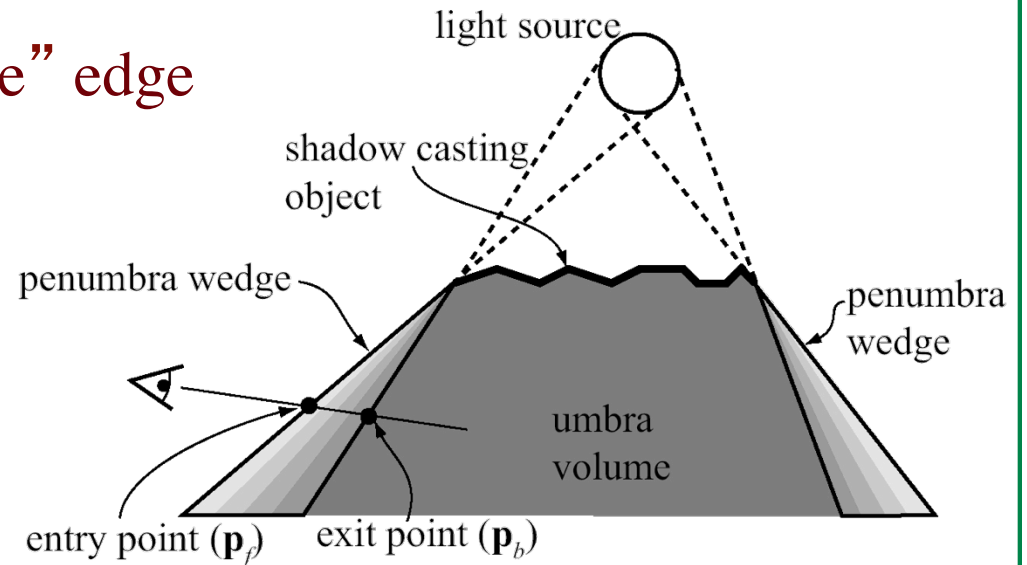
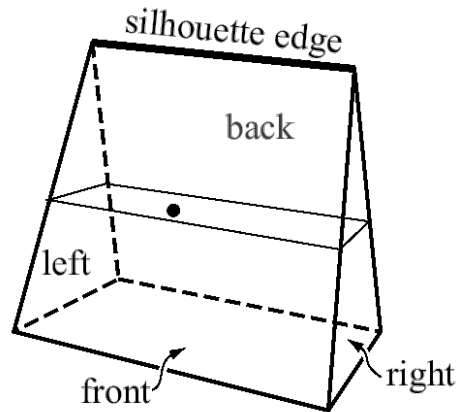
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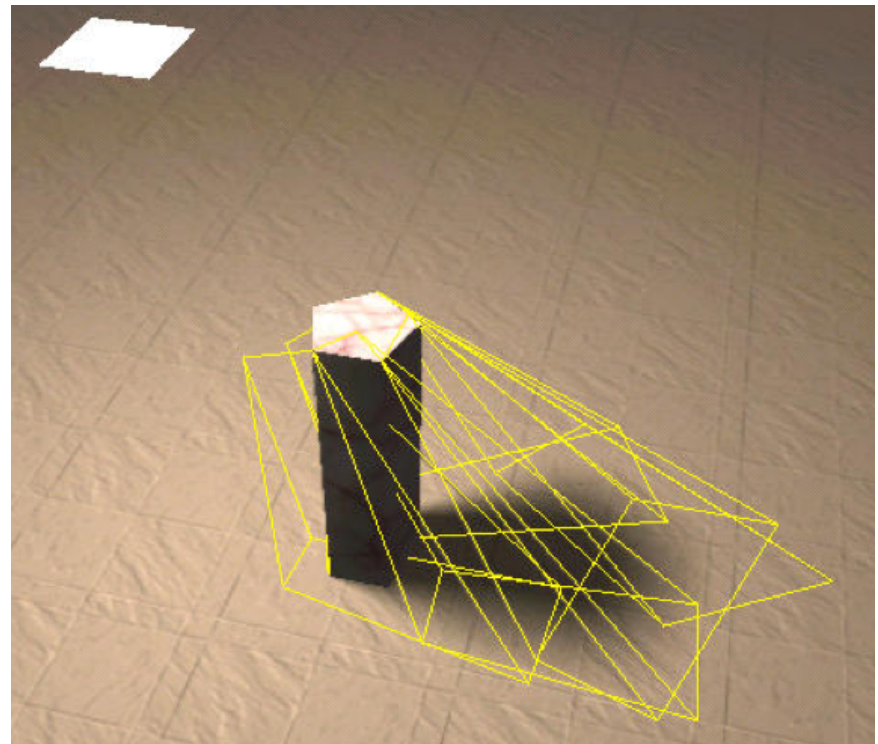
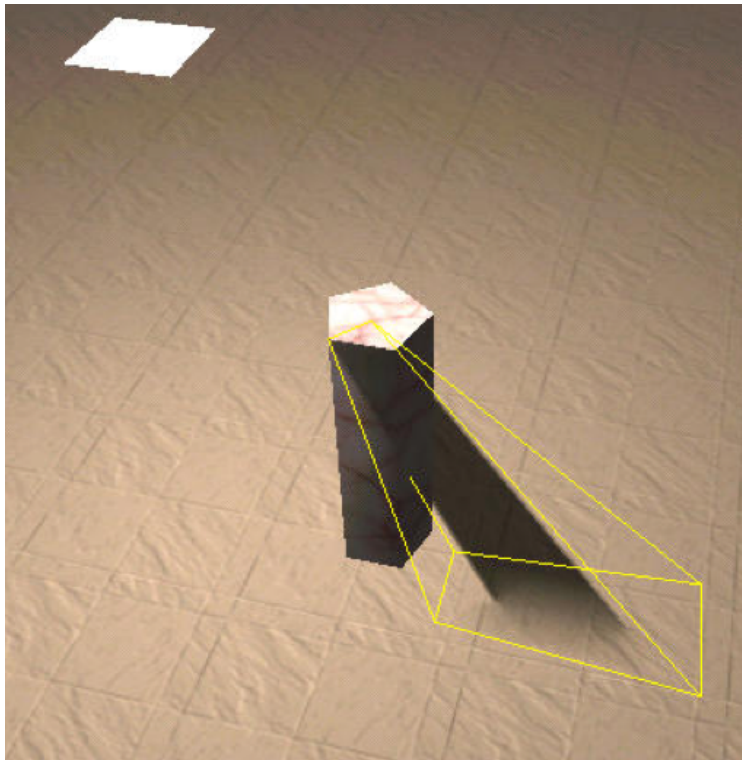


Shadow Volume

- A wedge for each “silhouette” edge



Rasterize the edges



Results

- www.ce.chalmers.se/staff/tomasm/soft/

