

Introduction to
Artificial Intelligence and Machine Learning
Homework 1 - Search

2018.9.26

Question 1~4 ~ Graph Search

- Motivation: By abstracting the problems, we can solve them using this **problem-independent** method.
- To abstract a problem, we define
 - the initial state
 - the goal state
 - the successors (or children) of each state
 - (optional) the cost of each action (i.e. state transition) of the problem.

Question 1~4 ~ Graph Search

- It is recommended that you begin with a function “graphSearch” defined by yourself
- def graphSearch(problem, search):


```
GRAPH-SEARCH(problem)
1  initialize the frontier using the initial state of problem
2  initialize the explored set to be empty
3  repeat
4      if the frontier is empty
5          return failure
6      choose a leaf node and remove it from the frontier.
7      if the node contains a goal state
8          return the corresponding solution
9      add the node to the explored set
10     expand the chosen node
11     if (not in the frontier) or (explored set)
12         add the resulting nodes to the frontier
```

Question 1~4 ~ Graph Search

- **graphSearch(problem, search):(in search.py)**

- Frontier.push(problem.getStartState())
- node = problem.getStartState()
- return ...(hint: return a list)

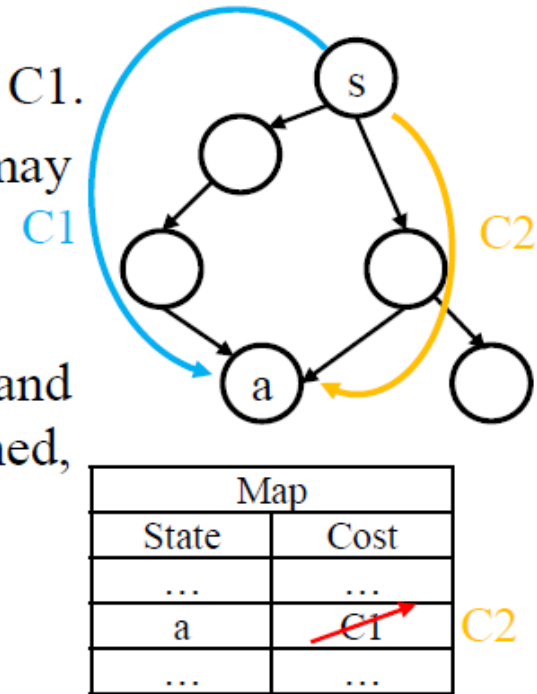
GRAPH-SEARCH(*problem*)



```
1 initialize the frontier using the initial state of problem
2 initialize the explored set to be empty
3 repeat
4     if the frontier is empty
5         return failure
6     choose a leaf node and remove it from the frontier.
7     if the node contains a goal state
8         return the corresponding solution
9     add the node to the explored set
10    expand the chosen node
11    if (not in the frontier) or (explored set)
12        add the resulting nodes to the frontier
```

Question 1~4 ~ Graph Search

- Question 1: DFS – Stack
- Question 2: BFS – Queue
- Question 3: UCS – Priority Queue, Tricky!
 - The first time when node “a” is explored, the cost is C1.
 - Since we are considering graph search, we may encounter “a” second time, with cost C2.
 - What if $C2 < C1$?
 - My method: A dict which remembers states and corresponding min cost. When lower cost confirmed, update the dict and push the node with new cost in.
 - Or define your PriorityQueue in *search.py*
 - Or any method you like.
- Question 4: A^* – with heuristic



Question 1~4 ~ Graph Search

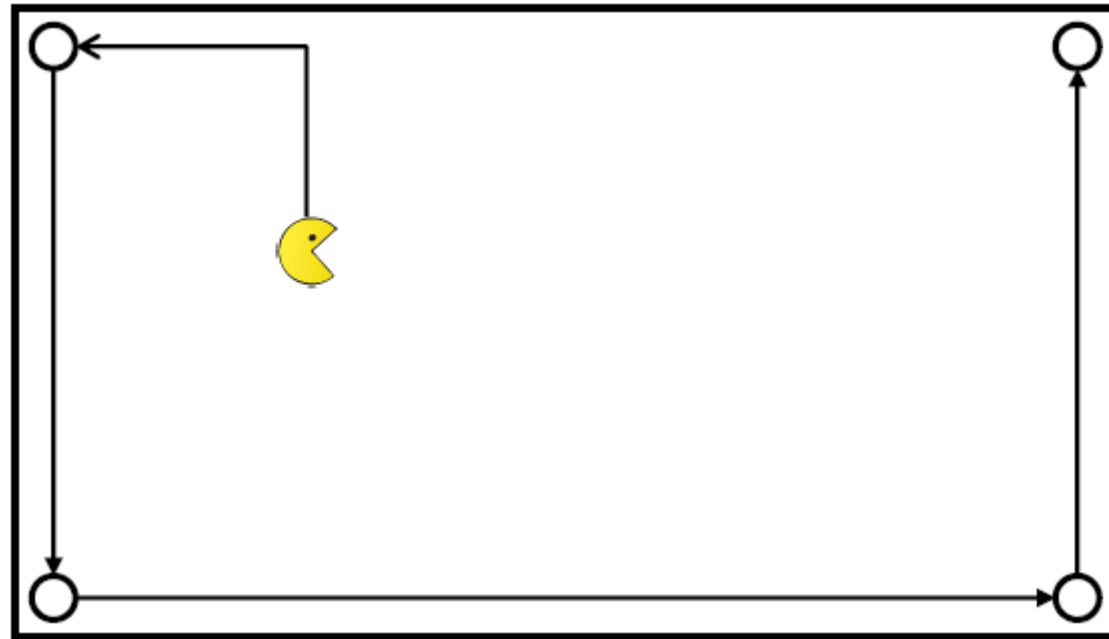
- Reminder: Please make sure your graph search program is *problem-independent*!
- –By testing “python eightpuzzle.py”

Question 5 – Defining Game States

- *searchAgents.py*
- Objective: Abstract the Corner Problem
 - There are four foods at each corner at the beginning.
 - Once the Pacman wanders to a corner with food, the food will be eaten and no longer exist.
 - The goal is the Pacman eating up all foods, which declares the end of the game.
- You don't need to change codes after line 459 in *searchAgents.py*

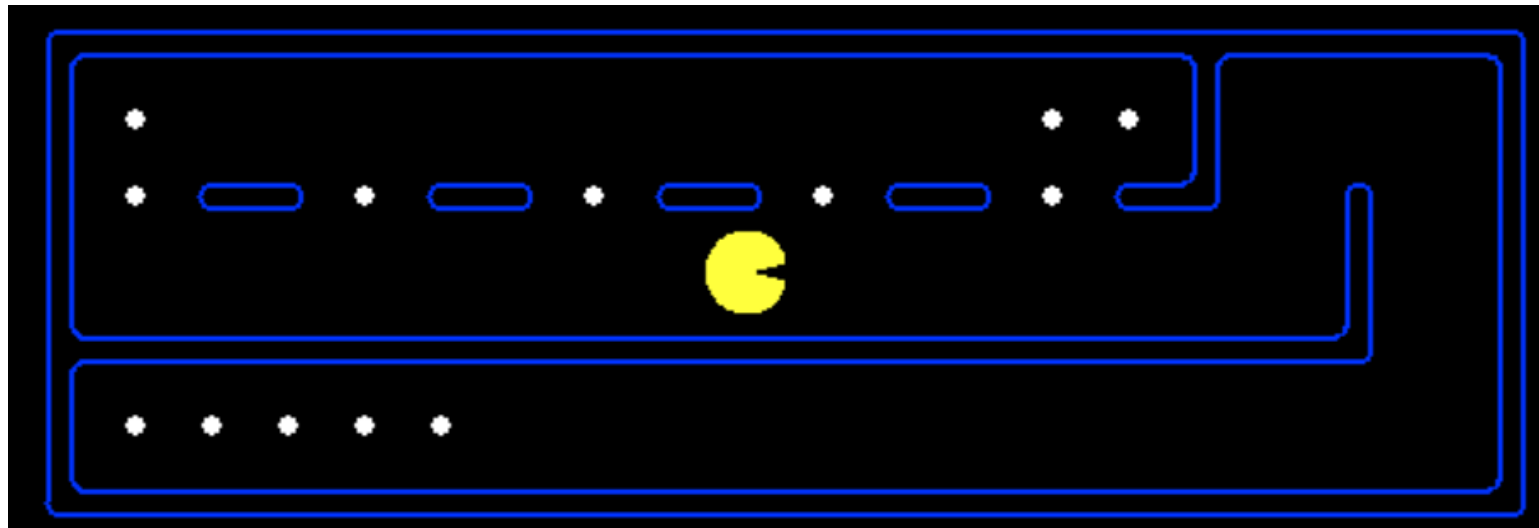
Question 6~7 – Designing a Heuristic

- Reminder: Design a consistent heuristic for the Corner Problem *for all possible game states*.
- Question: Is $\min\{\text{manh}(p, c1), \text{manh}(p, c2), \text{manh}(p, c3), \text{manh}(p, c4)\} + \text{manh}(c1, c2) + \text{manh}(c2, c3) + \text{manh}(c3, c4)$ consistent?



Question 6~7 – Designing a Heuristic

- For question 7, you may search the closest food first.
- However, if you only use it as your heuristic, your cost will be higher after you eat a food than not.
- `mazeDistance(point1, point2, gameState)` may be useful
- You may focus on this “tricky” search.



Deadline

- 2018/10/17 27:00 (2018/10/18 03:00)
- Allow late submission until 2018/10/24 27:00 (2018/10/25 03:00)