

Software Requirements Specification

Mechtronics Enigeering

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Table 1: Revision History

Date	Developer(s)	Change
2022-10-04	Edward He, Erping Zhang Guangwei Tang, Peng Cui Peihua Jin	Revision 0

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1 Project Drivers

1.1 The Purpose of the Project

The purpose of the project is to build a mechatronics system called "Smart-Vault" that is able to assist user in finding their belongings in a given area.

1.2 The Purpose of the Document

This document is intended to provide detailed set of requirements project SmartVault. The documentation will cover the functionality of the system and the requirements that the system is expected to fulfill. In addition to the function requirements of software system, non-functional requirements will also be included in this document. Any additional useful information for building the system is also covered and written in details. This document is used as a reference and guideline for the development of the system and is to ensure that the built system is fulfilling the necessary requirements and meeting the desired goals.

1.3 The Stakeholders

1.3.1 The Client

- Dr. Spencer Smith, professor from McMaster university, Computing and Software department.

1.3.2 The Customers

- people who often can't find their belongings due to poor organization
- people who has bad memory

1.3.3 Other Stakeholders

N/A

2 Project Constraints

2.1 Mandated Constraints

2.2 Naming Conventions and Terminology

2.3 Relevant Facts and Assumptions

2.3.1 User Characteristics

The users of SmartVault are people who have trouble finding their belongings in their daily lives. It is preferred that the user to have general knowledge of what is presented in the designated area. Users should be familiar and comfortable with technology. At minimum, the users should be able to read, type and navigate on a webpage.

2.3.2 Reader Characteristics

The intended readers for this document are the developers responsible for developing SmartVault. Dr.Smith, a professor at McMaster University and his teaching team will also be the intended reader of this document. The document is written in a technical manner and requires the reader to possess both software and hardware knowledge. The reader should be familiar with image processing and the ability to understand the basic logic of object detection. The reader should also understand the software design cycle and the steps taken to develop a complete software program. In order to fully understand the document, it is suggested that the reader has the ability to read and comprehend the communication and control system between a software program and hardware device.

2.4 Assumptions and Dependencies

AD1: The user can perform simple computer operations.

Rationale: The user can type, moving mouse and clicking on the window.

AD2: The user can understand English.

AD3: The operation of the project should take place indoors with adequate lighting.

AD4: All objects can be seen by the product without hiding.

AD5: Every motion of the user can be seen by the device.

3 Functional Requirements

3.1 The Scope of the Work and the Product

3.1.1 The Context of the Work

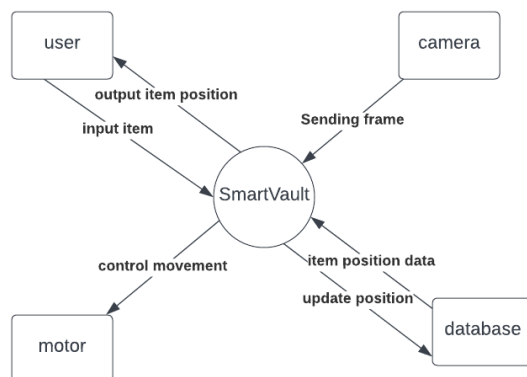


Figure 1: context of work

3.2 Finite State Machine Description

To make the behaviour of the product to achieve the target task, the Finite State Machine is created to describe the behaviour with detailed description provided after the picture.

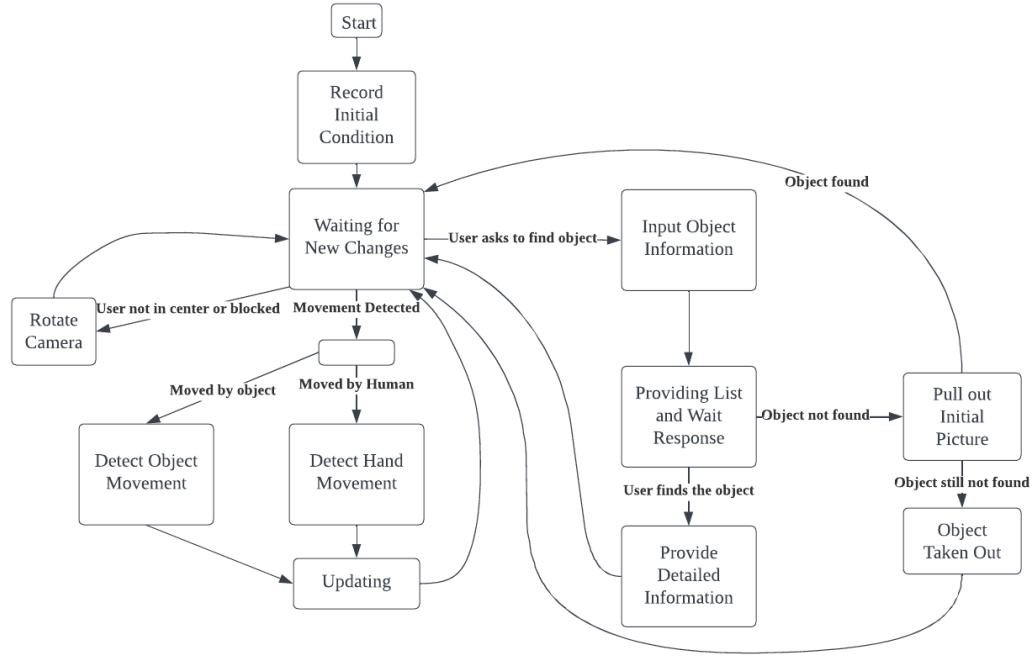


Figure 2: The Picture of Finite State Machine

Record Initial Condition: The device will take a picture of the room as the initial position information for each object and save it to the database.

Waiting for New Changes: The device will wait for future operations made by human or changes of objects detected by the camera.

Detect Object Movement: When the device detects the movement of an object that is made by another object (for example, colliding with another object and fall), it will trace the new location of the object.

Detect Hand Movement: When the device detects the movement of the user, it will track the movement of the hand to identify which object is being moved and remember its final location.

Updating: The device will record the updated information (including time, Location, picture of object, and so on) of the object into the database.

Input Object Information When the user want to find one object in the room, the user interface will ask the user to input information of the object (like size, color, last time saw it, and so on).

Providing List and Wait Response: After the user has input the information, the system will provide a list of objects with pictures that satisfy the input information.

Provide Detailed Information: When the user find the target object, the device will display the detailed information about the object like showing the current location on the screen.

Pull Out Initial Picture: When the object is not found in the list, the device will display the picture taken just after the program starts to let the user find the object.

Object Taken Out: If the object is still not found, the system will think that the object is taken out of the room or is hidden behind another object.

Rotate Camera: If the device found the human body detected is not in the center of the screen or the camera is covered by something else, it will send signals to the motor to rotate the camera until problem solved.

3.2.1 Individual Product Use Cases

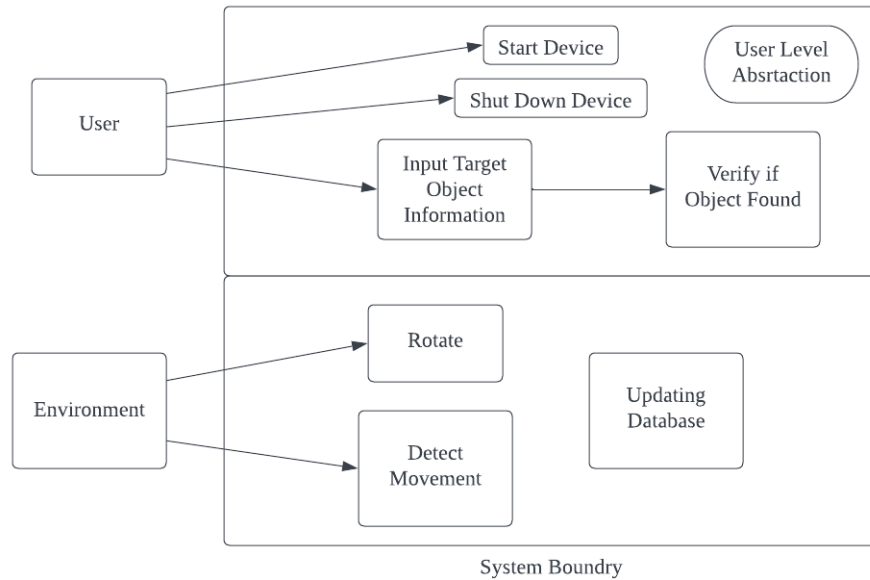


Figure 3: The Picture of Use Case Diagram

The Use Case Diagram shown above describes some actions that the user can interact with the system. The line in the middle shows the boundaries between user and the internal program. The outmost large box shows the boundary for the whole system. All user can do is just to start and shut down the program. Th user can also find the target object by typing the information about the object and verify if the object is found. The system will interact with the environment by rotating its camera and detecting the movement of the object in the room. It will also ba able to update its database when the position of the object is changed.

3.3 Functional Requirements

The following are the functional requirements of the project. They are separated into 2 main parts: Image Processing and Storage, and UI Interface Menu.

3.3.1 Image Processing and Storage Requirements

IPR1: The device should be able to identify human's body.

IPR2: The device must be able to identify human's hand.

IPR3: The device must be able to take a photo automatically when required.

IPR4: The device should be able to identify all the small items being exposed to the camera.

IPR5: The device should be able to take a photo once the change of the location of an item is captured.

IPR6: The device should be able to differentiate one item from another items which are identified by the system through 3 main parameters, `item_shape`, `item_color` and `item_size`.

IPR7: The device must be able to store all the photos into a file, and indicate the time when it was taken.

IPR8: The device must be able to name each item with a unique ID.

IPR9: The device should be able to arrange the photos stored in the file in ascending or descending order according to the time it was taken.

IPR10: The device should be able to arrange the photos stored in the file in ascending or descending order according to their IDs.

3.3.2 UI Interface Menu Functional Requirements

UIR1: The UI should be able to let user to choose whether to highlight a certain item or not.

UIR2: The UI should be able to let user to switch the ordering method.

UIR3: The UI must be able to notify the user when the WIFI signal is weak or unstable.

UIR4: The UI must be able to allow the user to view the system's status at any given point in time.

4 Nonfunctional Requirements

The next paragraphs will talk about about nonfunctional requirements in the designing of the smartVault, which will be discussed in several different parts.

4.1 Look and Feel Requirements

4.1.1 Appearance Requirements

APR1: The device should not have exposed internal electronic wiring.

APR2: The sharp corners should not be exposed to the users and should be covered by some soft materials.

4.1.2 style

Not Applicable.

4.2 Usability and Humanity Requirements

4.2.1 Easy of Use Requirements

EUR1: The device should be easy to installed in the room.

EUR2: Fonts, blanks and graphics shown on the screen should be big and visible enough for the user to use without inserting wrong information.

4.2.2 Personalization and Internationalization Requirements

Not applicable.

4.2.3 Learning Requirements

LR1: The software part of the product should be easy to install.

LR2: The product should be easy to set up in its working environment.

Rationale: The device can identify objects in the room in a short time after powering up.

4.2.4 Understandability and Politeness Requirements

UPR1: The graphics used should be readable and visible to the user.

Rationale: Easy for clients to find objects that wish to find in the room.

4.3 Accessibility Requirements

AR1: The display window should be concise enough for user to understand

4.4 Performance Requirements

4.4.1 Speed and Latency Requirements

SLR1: The response time of the product to show the location of the object should be less than 5 seconds.

4.4.2 Safety-Critical Requirements

SCR1: The base of the device should be strong enough without falling from the floor.

SCR2: The device should not infringe on user's privacy.

SCR3: The rotating speed of the motor should be slow enough without hurting people.

4.4.3 Precision and Accuracy Requirements

PAR1: The time based value used in the device should be precised to minute.

PAR2: The location value used in the device should be precised to whole number.

PAR3: Other numeric values used in the device should be rounded to one decimal place.

4.4.4 Reliability and Availability Requirements

RAR1: The device should not over-rotate to an unexpected angle.

RAR2: The device should be available to work for the whole time of except for maintenance or updating time.

4.4.5 Robustness or Fault-Tolerance Requirements

RFR1: The data stored in the file should not be deleted or changed even after the program shuts down.

RFR2: The device should be able to notify user for an error occurs in the program.

Rationale: The user should be notified if he or she has a wrong input or having inappropriate actions.

4.4.6 Capacity Requirements

CR1: The device should be able to store the any information about the location of each object detected from the camera.

4.4.7 Scalability or extensibility Requirements

Not applicable.

4.4.8 Longevity Requirements

LR1: The device should store the information about the objects until it is changed into a different environment.

4.5 Operational and Environmental Requirements

4.5.1 Expected Physical Environment

EPE1: The device is supposed to work in any indoor space.

4.5.2 Requirements for Interfacing with Adjacent Systems

Not applicable.

4.5.3 Productization Requirements

Not applicable.

4.5.4 Release Requirements

No applicable.

4.6 Maintainability and Support Requirements

4.6.1 Maintenance Requirements

MR1: The maintenance for the device should be done by the developers.

4.6.2 Supportability Requirements

SR1: The device is supported by any computers supports both C and python programming languages.

4.6.3 Adaptability Requirements

Not Applicable.

4.7 Security Requirements

4.7.1 Access Requirements

AR1: Any one except for the users is not allowed to access the any file that stores the information about the objects in the room. **AR1:** Any one except for the users is not allowed to access the any file that stores the information about the objects in the room.

4.7.2 Integrity Requirements

IR1: Data in teh files should not be changed unnecessarily.

IR2: The files are locked whhen teh device shuts down.

4.7.3 Privacy Requirements

PR1: Other users are not allowed to access any file in the computer.

PR2: The camera should only work for a specific user.

4.7.4 Audit Requirements

Not applicable.

4.7.5 Immunity Requirements

Not applicable.

4.8 Cultural and Political Requirements

4.8.1 Cultural Requirements

Not applicable.

4.8.2 Plitical Requirements

Not applicable.

4.9 Legal Requirements

4.9.1 Compliance Requirements

CR1: The performance of the product should not violate the laws that protect the privacy of thee user.

4.9.2 Standards Requirements

Not applicable.

5 Project Issues

5.1 Open Issues

- Limit of 180 rotation degree of servo motor

- Accuracy of object detection
- How to distinguish two objects with very limited resources
- How to recognize the same object in different angles
- How to guarantee the stability of the serial communication

5.2 Off-the-Shelf Solutions

- Huskylens - is a AI camera which can learn new objects and recognize them. It has the machine learning technology enables projects to interact with people and environments which allows many kinds of system control.
- NVIDIA Jetson TX2 - is an embedded AI computer device. It has 8GB memory and 59.7GB/s of memory bandwidth which provides a high quality AI performance to build efficient AI models including computer vision.

5.3 New Problems

5.3.1 Effects on the Current Environment

Any changes to the exist database may cause the data related to each object missing

5.3.2 Effect on the Installed Systems

Changes to the motorized camera mount will affect the algorithm or logic of the controller board

5.3.3 Potential User Problems

Changes to the user interface may change the way that user used to search the object

5.3.4 Limitations in the Anticipated Implementation Environment

NA

5.3.5 Follow-Up Problems

The changes in computer vision algorithm may cause the whole system malfunction

5.4 Tasks

5.4.1 Project Planning

NA

5.4.2 Planning of the Development Phases

NA

5.5 Migration to the New Product

5.5.1 Requirements for Migration to the New Product

- All the objects data should be stored
- Motorized camera mount should be calibrated before using
- The spec of camera should be kept in same as possible

5.5.2 Data that Has to be Modified or translated for the new system

- Objects data need to be transfer ed into the new system

5.6 Risks

- Connection lost between the board and camera during the motor movement.
- Inappropriate distance measure and control between the object and the motor which furthermore cause damage or stuck.
- Physical damage from collision with objects .
- Physical damage from wire twisting during rotation.
- Unexpected movement caused by the delay of data transfer

5.7 Costs

Product	Price
USB Camera	\$30
PTZ Mount	\$25
Arduino	\$30
Motors	\$15
Total	\$100

5.8 User Documentation and Training

5.8.1 User Documentation Requirements

- User manuals
- Installation manuals
- Technical specifications to accompany the product

5.8.2 Training Requirements

NA

5.9 Waiting Room

- Expanding chassis's activity area including rotation angle and planar movement.
- Developing new algorithm regarding data transfer to enable faster real-time reaction.
- Adding alarm in case that object not found in the assigned area as an application of storage security.

5.10 Ideas for Solutions

- Use DC motor with decoder to implement the unlimited rotation degree of camera mount

- Use Field Oriented Control algorithm to implement the unlimited rotation degree of camera mount
- Use frame-to-frame comparison to detect the relocation of objects
- Predict the possible location of objects by tracking the users path in the room
- Beeper alert when the camera view is not cleared

6 Appendix

This section has been added to the Volere template. This is where you can place additional information.

6.1 Symbolic Parameters

The definition of the requirements will likely call for `SYMBOLIC_CONSTANTS`. Their values are defined in this section for easy maintenance.

6.2 Reflection

Our team consists of 5 mechatronics student and is developing a mechatronics system where both hardware and software components are essential for success. There are many different skills and knowledge that ties into the success of the project. Many of these required skills might be new and unfamiliar to some of the group members. However, as this is a project over a span of 6 months, there are plenty of time and opportunities to pick up and master some new skills. The learning of such skills will be delegated to different team members and mastered by them before delivering and teaching others member about it.

The project is heavily relying on a functional, reliable, and efficient software system that involve live time object detection and image processing. The coding will be done in Python, so each member needs to have adequate skill of programming in Python and able to develop and test a python program. Knowledge of image processing and object detection also should be acquired. In order to master the skills for programming in python and image processing, team members should practice and conduct research on different object detection method. It is required for the assigned team members to compare and learn from different method and making sure that our chosen method would yield the best results given our requirements. This part of the learning is assigned to Edward, Peng and Jinhua. Edward has gained relevant knowledge through courses he took and projects he did. Peng and Jinhua have great enthusiasm for this topic and would like to conduct research on it.

Another software component is the user interface. Members of the team should be able to build and maintain a working webpage using JavaScript. This skill is obtained by Edward through his co-op and other experiences.

Erping and Jinhua also are assigned to perfect their abilities in such area. The path to success for this is to read relevant documents and tutorials, as well as practicing with small projects. In order to communicate between the software and hardware, related programming skills are needed. Erping as the lead developer for this topic has multiple experiences and with the help of Guangwei who has exceptional skills in this field, they will be able to excel the required skills and guide other members of the team.

On the hardware side, Guangwei will be the lead and responsible for the learning and teaching of the related skills. 3D modeling is needed for the building and 3D printing the camera mount. This skill is assigned to Guangwei and can be mastered through practicing and watching tutorials. Arduino board is the chosen board for handling the control of the motors and repositioning of the camera. Sufficient knowledge and skills to program Arduino is needed. This task is assigned to Erping and Guangwei. They both have experiences in this field and will be able to teach the rest of the team. Knowledge associated with handling motor movement is also needed and can be mastered by reviewing course notes and refreshing past knowledge.

Aside from the hardware and software system, there are also skills associated with team management and team communication. In order to maintain a desired work plan and team coordination, it is important for all members of the team to possess the skills to work under a team environment. Members need to be comfortable and familiar with github and in order to excel, one must practice different github actions and commends. One also can improve on this by watching tutorial videos. Working in a team environment, it is important to have good communication skills and making sure people are on the same page. This can be mastered by actively engage in team meetings and ask for help when needed.

To conclude, for a professional project like the capstone, there are many aspects to it and many skills are required. It is important to delegate different learning tasks to individual and be able to teach the new skillset to the rest of the team. The following are the skills mentioned in previous paragraphs and is the overview of the assignment of the learning process:

1. communication and team management (All)
2. Github (All)
3. Python, image processing and object detection (Edward, Jinhua, Peng)

4. Arduino and control (Erping and Guangwei)
5. Motor control (Erping and Guangwei)
6. Javascript (Edward, Peng, Jinhua)
7. 3D modeling and 3D printing (Erping and Guangwei)
8. Writing and presenting reports (All)