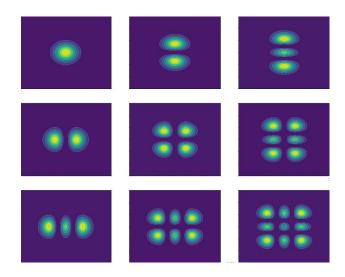
# Tilt-to-Length Coupling: Effects of Beam Shape and Photoreceiver Selection on LISA Signals

#### Paul Edwards



## TILT-TO-LENGTH COUPLING IN LISA

- Misalignments between LISA optical bench and bi-directional telescope introduce noise (TTL coupling).
- TTL in the TM interferometry is expected via spacecraft angular jitter relative to the reflected beam.
  - S/C jitter  $\sim 10 \text{ nrad}/\sqrt{\text{Hz}}$
  - OB Lateral alignment offset  $\sim 20 \ \mu m$
  - Combined  $\sim 20 \text{ pm}/\sqrt{\text{Hz}}$
- Selection of received and reference beam shape and photoreceiver dimensions can play a critical role in reducing TTL.
- Light path simulation provides an avenue for refining tolerances and the shift-tilt parameter space which may be incorporated into LISANODE.

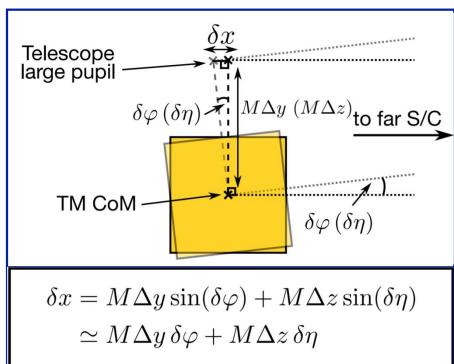


Fig. 1. TTL coupling from S/C jitter coupled to lateral offset.

Beat note signal phase, for received(RX) and reference (LO) beam :

$$\phi_{beat} = \arg \left[ \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} E_{LO}^* E_{RX} \, dx dy \right]$$

• Phase of DWS and LPS is calculated for planes of split photodetector with appropriate integration bounds (e.g., half-plane PD with left(L) and right(R) sides):  $\Phi_{DWS} = \frac{1}{2} [\phi_R - \phi_L] \qquad \Phi_{LPS} = \frac{1}{2} [\phi_R + \phi_L]$ 

• Superposition of HG modes provide a spatial component of electric field. e.g., the received beam(rec):

$$E_{rec} = E_{0 (rec)} e^{i((\omega_{rec}t) + \phi_2)} \sum_{n,m=0} u_{nm}(w_{0 rec}, z_{0 rec})$$

### HERMITE-GAUSS MODES

$$u_{nm}(x,y,z) = (2^{n+m-1}n!m!\pi)^{-1/2} \frac{1}{w(z)} H_n\left(\frac{\sqrt{2}x}{w(z)}\right) H_m\left(\frac{\sqrt{2}y}{w(z)}\right) \exp\left(\frac{-ik(x^2+y^2)}{2R_c(z)} - \frac{x^2+y^2}{w(z)^2}\right)$$

 Set of exact solutions to paraxial wave equation using Hermite polynomials

$$\nabla_t^2 u(x, y, z) - 2ik\partial z u(x, y, z) = 0$$

Orthonormal, s.t.:

$$\int \int dx dy \ u_{nm} u_{n'm'}^* = \delta_{nn'} \delta_{mm'}$$

 Can approximate any paraxial beam as superposition of HG modes (e.g., tilted, shifted tophat and Gaussian)

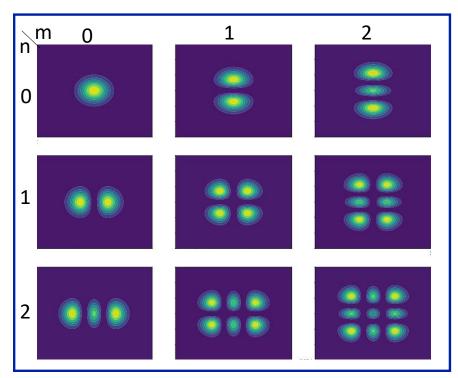
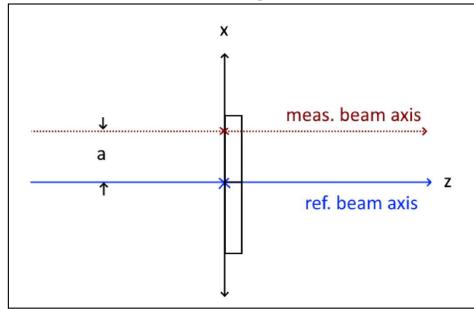


Fig. 2. Intensity profiles of HG modes (n,m)=(0,0) to (2,2).

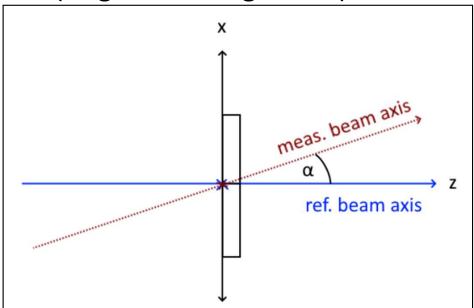
# HG Mode Approximation for Shifted and Tilted Beams

#### **Shift** (Lateral Misalignment)



**Fig. 3.** Measurement beam laterally misaligned in *x* wrt reference beam axis.

#### Tilt (Angular Misalignment)



**Fig. 4.** Tilt of measurement beam by  $\alpha$  wrt reference beam.

## 1<sup>ST</sup>-ORDER APPROXIMATION

Shift: 
$$a << w_0$$

$$u_{00}(x - a, y, 0) = \left(\frac{2}{\pi}\right)^{-1/2} \left(\frac{1}{w_0}\right) \exp\left(-\frac{(x - a)^2 + y^2}{w_0^2}\right)$$

$$= \left(\frac{2}{\pi}\right)^{-1/2} \left(\frac{1}{w_0}\right) \exp\left(-\frac{y^2}{w_0^2}\right) \exp\left(-\frac{(x - a)^2}{w_0^2}\right)$$

$$= u_{00}(x, y, 0) \times \exp\left(\frac{2ax + a^2}{w_0^2}\right)$$

$$= u_{00}(x, y, 0) \left[1 + \frac{2ax}{w_0^2} + \mathcal{O}\left(\frac{a}{w}\right)^2\right]$$

$$\approx u_{00} + \left(\frac{2ax}{w_0^2}\right) u_{00}$$

$$= u_{00}(x, y, 0) + \frac{a}{w_0} u_{10}(x, y, 0)$$

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Shifted then tilted Gaussian: 
$$\sum_{n,m} u_{nm}(x,y,0) = \left[1 + i\left(\frac{\pi a\alpha}{\lambda}\right)\right]u_{00} + \left[\frac{a}{w_0} + i\left(\frac{\pi w_0\alpha}{\lambda}\right)\right]u_{10} + i\left(\frac{\sqrt{2}\pi a\alpha}{\lambda}\right)u_{20}$$

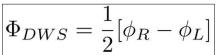
# 1<sup>ST</sup>-ORDER SIGNALS AT HALF-PLANE PD WITH GAPS GAUSSIAN-GAUSSIAN, SHIFTED-TILTED BEAM

$$\phi_R = \arctan\left(\frac{\frac{\pi\alpha}{\lambda} \left[ a \left( - \operatorname{erf}(\frac{\sqrt{2}r}{w_0}) + 1 + \frac{2\sqrt{2}r \exp(-\frac{2r^2}{w_0^2})}{\sqrt{\pi}w_0} \right) + w_0 \sqrt{\frac{2}{\pi}} \left( \exp(-\frac{2r^2}{w_0^2}) \right) \right] - \operatorname{erf}(\frac{\sqrt{2}r}{w_0}) + 1 + \sqrt{\frac{2}{\pi}} \frac{a}{w_0} \exp(\frac{-2r^2}{w_0^2}) \right) \right]}$$

$$\phi_{L} = \arctan\left(\frac{\frac{\pi\alpha}{\lambda} \left[ a \left( \operatorname{erf}(\frac{\sqrt{2}l}{w_{0}}) + 1 - \frac{2\sqrt{2}l \exp(-\frac{2l^{2}}{w_{0}^{2}})}{\sqrt{\pi}w_{0}} \right) - w_{0} \sqrt{\frac{2}{\pi}} \left( \exp(-\frac{2l^{2}}{w_{0}^{2}}) \right) \right]}{\operatorname{erf}(\frac{\sqrt{2}l}{w_{0}}) + 1 - \sqrt{\frac{2}{\pi}} \frac{a}{w_{0}} \exp(\frac{-2l^{2}}{w_{0}^{2}})}\right)$$

$$\Phi_{DWS} = \frac{1}{2} [\phi_R - \phi_L]$$

$$\Phi_{LPS} = \frac{1}{2} [\phi_R + \phi_L]$$



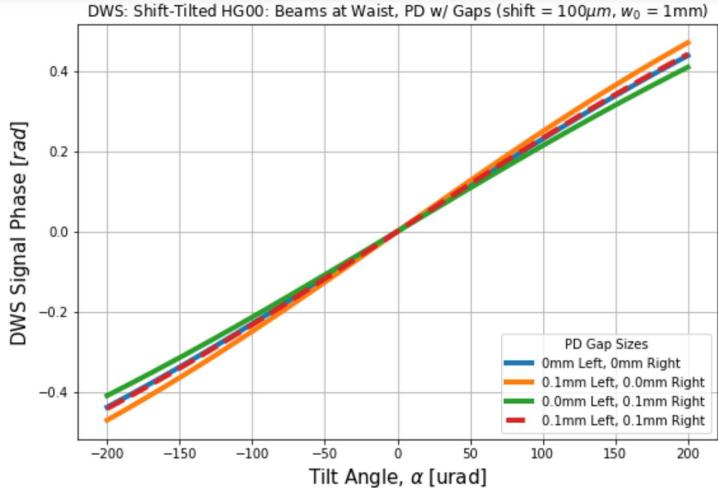


Fig. 5. DWS signal phase, first-order with gaps in half-plane PD.

## 2<sup>ND</sup> ORDER APPROXIMATION IN SHIFT

$$u_{00}(x - a, y, 0) = \left(\frac{2}{\pi}\right)^{-1/2} \left(\frac{1}{w_0}\right) \exp\left(-\frac{(x - a)^2 + y^2}{w_0^2}\right)$$

$$= \left(\frac{2}{\pi}\right)^{-1/2} \left(\frac{1}{w_0}\right) \exp\left(-\frac{y^2}{w_0^2}\right) \exp\left(-\frac{(x - a)^2}{w_0^2}\right)$$

$$= \left(\frac{2}{\pi}\right)^{-1/2} \left(\frac{1}{w_0}\right) \exp\left(-\frac{y^2}{w_0^2}\right) \exp\left(-\frac{x^2}{w_0^2}\right) \exp\left(-\frac{(a^2 - 2ax)}{w_0^2}\right)$$

$$= u_{00}(x, y, 0) \times exp\left(\frac{2ax - a^2}{w_0^2}\right)$$

$$= u_{00}(x, y, 0) \left[1 + \frac{2ax}{w_0^2} + \frac{a^2(2x^2 - w_0^2)}{w_0^4} + \mathcal{O}\frac{a^3}{w}\right]$$

$$\approx u_{00} + \frac{2ax}{w_0^2}u_{00} + \frac{a^2(\frac{2x^2}{w_0^4} - \frac{1}{w_0^2})u_{00}}{u_0^4}$$

$$= u_{00}(x, y, 0) + \frac{a}{w_0}u_{10}(x, y, 0) + \frac{a^2(\frac{1}{\sqrt{2}w_0^2}u_{20} - \frac{1}{2w_0^2}u_{00})}{u_{00}}$$

# 2<sup>ND</sup> ORDER APPROXIMATION IN TILT

$$u_{00(tilt)}(x, y, 0) = u_{00} \exp(i\phi)$$

$$= u_{00} \exp\left[ikx \sin(\alpha)\right]$$

$$\approx u_{00} \exp\left[ikx(\alpha - \frac{\alpha^3}{6})\right]$$

$$\approx u_{00}[1 + \alpha ikx - \frac{1}{2}\alpha^2(kx)^2]$$

## 2<sup>ND</sup>-ORDER APPROXIMATION: DWS SIGNAL PHASE

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#### **Shift**

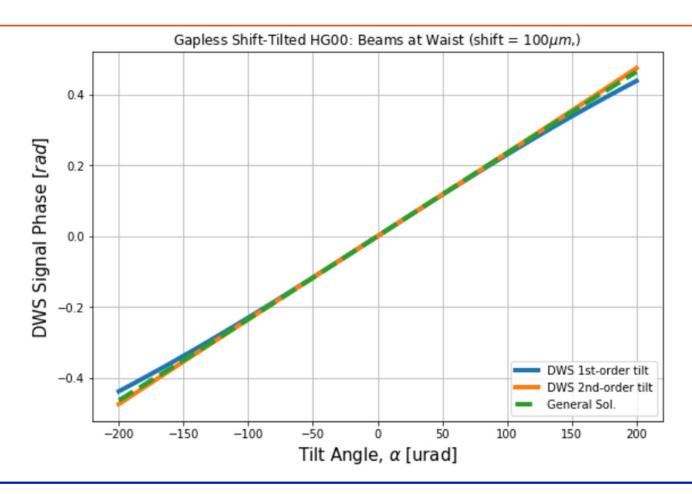
$$\frac{1}{2} \left[ \arctan \left[ \frac{\frac{\pi \alpha}{\lambda} \left[ a + \sqrt{\frac{2}{\pi}} w_0 \right]}{1 + \sqrt{\frac{2}{\pi}} \frac{a}{w_0} \left[ -a^2 \frac{1}{2w_0^2} \right]} \right] - \arctan \left[ \frac{\frac{\pi \alpha}{\lambda} \left[ a - \sqrt{\frac{2}{\pi}} w_0 \right]}{1 - \sqrt{\frac{2}{\pi}} \frac{a}{w_0} \left[ -a^2 \frac{1}{2w_0^2} \right]} \right] \right]$$

### <u>Tilt</u>

$$\frac{1}{2} \left[ \arctan \left[ \frac{\frac{\pi \alpha}{\lambda} \left[ a + \sqrt{\frac{2}{\pi}} w_0 \right]}{1 + \sqrt{\frac{2}{\pi}} \frac{a}{w_0} \left[ -\frac{1}{16} \alpha^2 k^2 \left[ w_0^2 + a w_0 \left( \frac{1}{4} \sqrt{\frac{2}{\pi}} \right) \right]} \right] - \arctan \left[ \frac{\frac{\pi \alpha}{\lambda} \left[ a - \sqrt{\frac{2}{\pi}} w_0 \right]}{1 - \sqrt{\frac{2}{\pi}} \frac{a}{w_0} \left[ -\frac{1}{16} \alpha^2 k^2 \left[ w_0^2 - a w_0 \left( \frac{1}{4} \sqrt{\frac{2}{\pi}} \right) \right]} \right] \right] \right] \right]$$

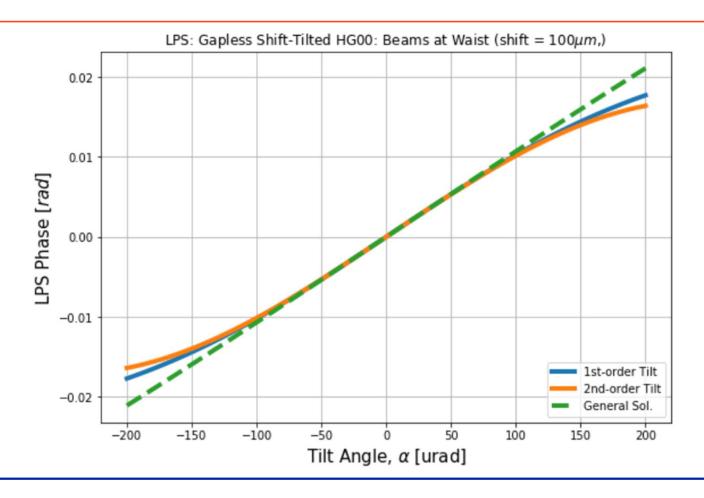
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## 2<sup>ND</sup> -ORDER TILT : DWS

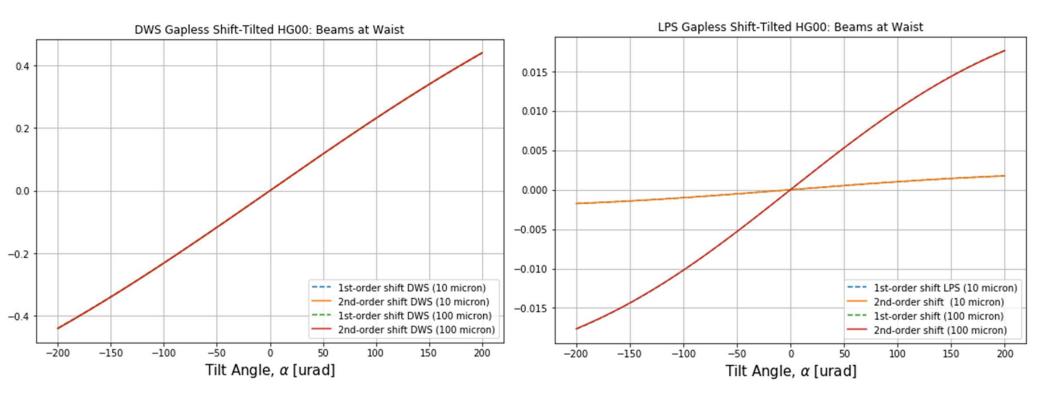


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## 2<sup>ND</sup> -ORDER TILT : LPS

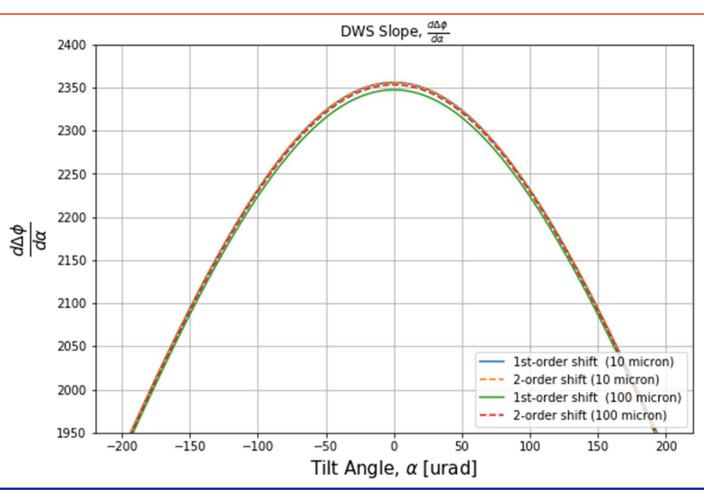


## 2<sup>ND</sup> -ORDER SHIFT: DWS



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# 2<sup>ND</sup> -ORDER SHIFT: DWS



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## **FUTURE DEVELOPMENTS**

- Third-order (tilt)
- Tophat-Gaussian interference
- Tophat-Tophat (?)
- Changing Center of Rotation (CoR) relative to PD and aperture

## **FUTURE DEVELOPMENTS**

**CASE 1:** CoR on PD, no offset

