

Bayesian Data Analysis Session 2

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Recap

With Bayesian stats we put a distribution on the model parameters. They get updated by observed data.

$$P(\theta|D) = \frac{P(D|\theta)P(\theta)}{P(D)}$$

It is almost always infeasible to obtain the posterior directly, because the marginal $P(D)$ is too complex to obtain.

We have seen that we can use sampling to normalize the posterior.

Many θ s

Acceptance-rejection sampling impractical with many parameters.
Why?

Alternative MCMC.

General idea:

$f(x)$ is proportional to posterior

θ_1 is some initialisation value.

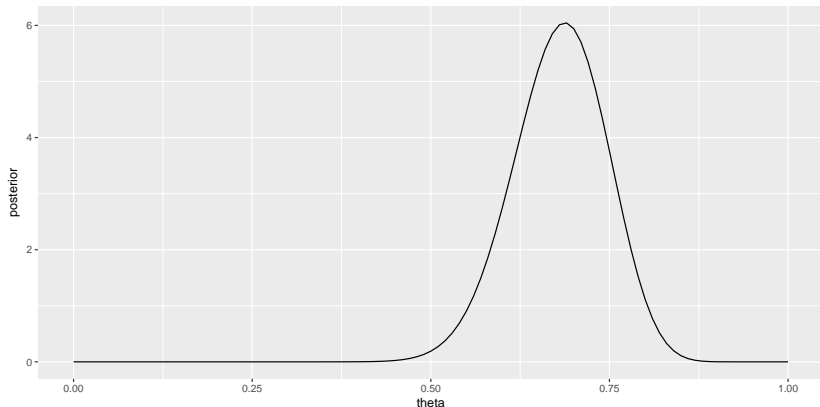
For values 2 to T :

1. sample $\theta_{t+1} \sim N(\theta_t, \sigma)$
2. accept θ_{t+1} with $P = \min\left(\frac{f(\theta_{t+1})}{f(\theta_t)}, 1\right)$
3. if accepted next iteration with $\theta_t = \theta_{t+1}$, else redo with θ_t

Example beta-binomial

We know that beta-binomial is conjugate, so we check with the analytical solution.

Lets do a $Beta(3, 3)$ posterior and a 31 successes out of 44 likelihood. Posterior is $Beta(34, 16)$.



Integration

So the function $P(D|\theta)P(\theta)$ is proportional to the posterior, but does not integrate to 1.

```
posterior_prop <- function(theta) {  
  dbeta(theta, 3, 3) * dbinom(31, 44, theta)  
}  
  
integrate(posterior_prop, 0, 1)
```

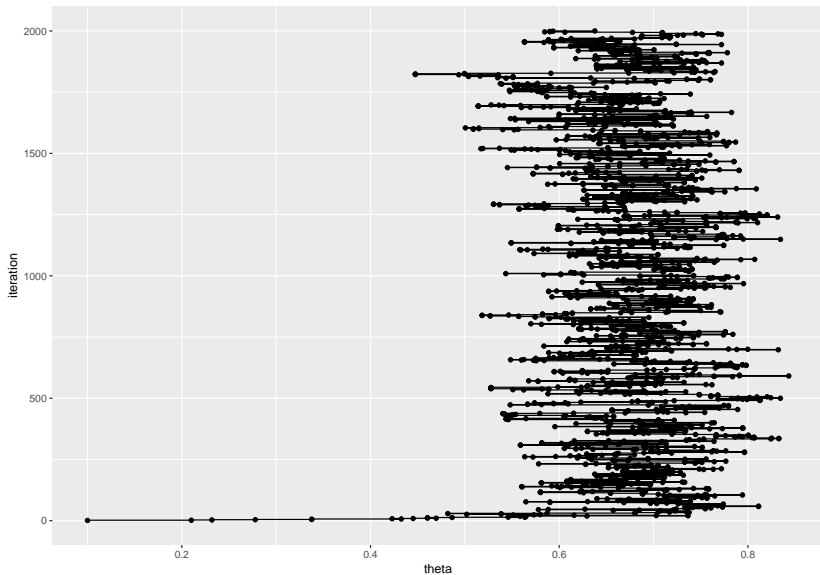
```
## 0.02907361 with absolute error < 3.9e-06
```

Metropolis

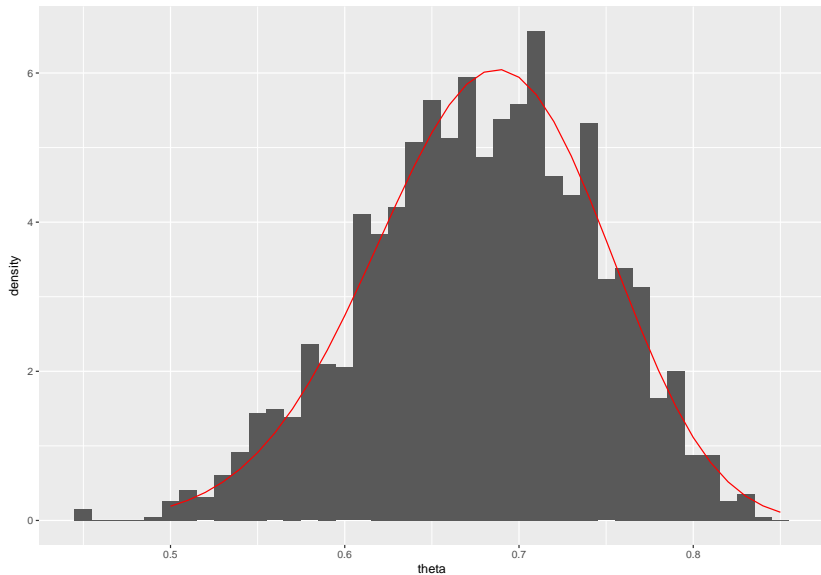
Start with a value of $\theta = 0.1$, proposal $\sigma = 0.05$.

```
set.seed(4242)
current_theta <- 0.1
theta_frame <- data_frame(iteration = 1:2000, theta = 0)
for(i in 1:nrow(theta_frame)) {
  theta_frame$theta[i] <- current_theta
  proposed <- rnorm(1, current_theta, 0.05)
  accept <- (posterior_prop(proposed) /
             posterior_prop(current_theta)) >
    runif(1)
  if (accept) current_theta <- proposed
}
```

Metropolis



Compare with analytical



Metropolis

The MCMC needs to “find” the posterior first. First samples are always discarded (burn-in).

What would happen when we increased σ , and when we decrease it?

Stationary = MCMC reached the posterior. Usually start multiple chains from different initial points and see if they all reach the same distribution.

With many θ 's

Vanilla Metropolis theoretically always works, but can be very impractical.

The proposal distribution must be fit for the problem at hand, so desires manual specification.

Default settings easily under- or overshoot. Both yielding efficiency loss.

Long waiting times and convergence issues.

Gibbs sampling (JAGS)

Often we cannot derive the joint posterior of all θ but we can get conditional posterior of individual θ values.

In each iteration we update the θ values one-by-one, by conditioning on the current value of the other parameters. This allows to sample directly from the distribution.

Pro: sampling guaranteed from posterior (no rejections)

Con: one-by-one, conditionals must be known.

Hamiltonian MC (Stan)

Before sampling from the proposal, calculate the gradient of the function at the current (multivariate) point.

Determine a trajectory in the direction of the highest gradient, sample from this trajectory.

Pro: very effective especially with correlated parameters, can be used when posterior is unknown.

Con: gradient calculations