E18-D80NK Long Range Adjustable IR Sensor

Technical Manual Rev 1r0





Adjustable Infrared sensor switch manual is an IR distance switch with adjustable range of 3cm to 80cm (up to 2.6ft). Useful for robot interaction, collision detection and proximity applications. Compatible in all gizDuino boards microcontroller.

Features:

Guard mode: Reverse polarity protection

Material: Plastic

Appearance: Threaded cylindrical Ambient temperature: -25 to 70 deg C Brown: +5V,Black: Signal,Blue: GND

Output: 1 - No detection 0 - Object detected

General Specifications:

Input Supply Voltage: 5VDC

Load current: 100mA

Sensing range: 3cm to 80 cm adjustable **Sensing object:** Translucency, opaque **Output operation:** Normally Open (O) **Ouput DC:** three-wire system (NPN)

Model No.: E18-D80NK-N

Diameter: 18mm *Length:* 45mm



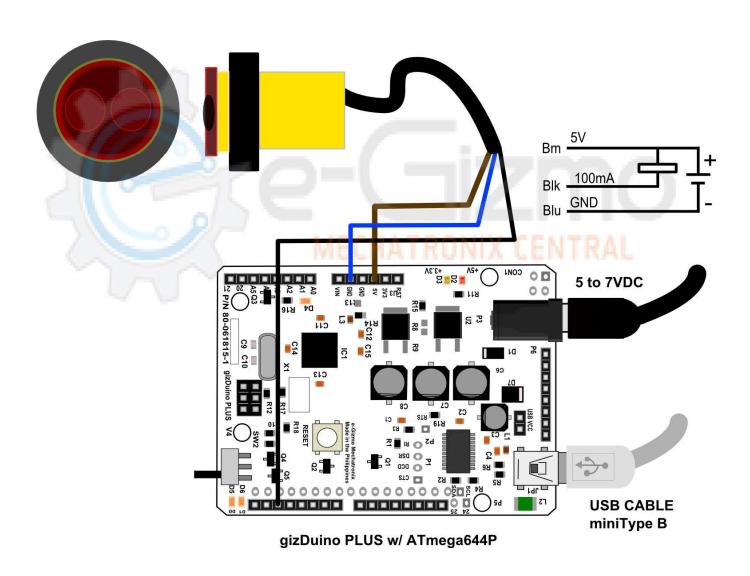


Figure 1. Sample connections



```
E18-D80NK Long Range
                                         //
                                                  Upload this code to the gizDuino PLUS
//
                                         //
         Adjustable IR sensor
                                                   Microcontroller, then Open the Serial Monitor
//
                                         //
                                                  to see the results.
//
     This sample sketch is reading the
                                         //
   digital signal output of IR sensor and
//displaying the results data in serial monitor //
//
//
           Codes by:
//
     e-Gizmo Mechatronix Central
//
      Taft, Manila, Philippines
                                         //
//
       http://www.egizmo.com
                                         //
                                         //
         October 12,2016
//
//LED ANODE CONNECTED TO DIGITAL PIN 13
int LEDPIN = 13;
//INFRARED PROXIMITY SENSOR SWITCH CONNECTED TO DIGITTAL PIN 2
int INPUTPIN = 2;
//THIS VARIABLE WILL READ THE VALUE FROM THE SENOSOR
int VAL = 0;
void setup()
 Serial.begin(9600);
 pinMode(LEDPIN, OUTPUT); //LED SET AS OUTPUT
 pinMode(INPUTPIN, INPUT); //IR SENSOR AS INPUT
void loop()
 // READ THE INPUT VALUE
 VAL = digitalRead(INPUTPIN);
 //CHECK THE INPUT IS HIGH
 if (VAL == HIGH)
 {
  digitalWrite(LEDPIN, LOW); //LED IS OFF
  Serial.println(VAL);
 }
 else
  digitalWrite(LEDPIN, HIGH); //LED IS TURNED ON
  Serial.println(VAL);
 delay(500);
```