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Sampling frequency.

Discrete time could be defined as a vector in Matlab.

$$t = 0 : T_s : 5/f \rightarrow \text{signal frequency.}$$

↓
1/Sampling frequency f_s

Spectra plot.

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi}{N} kn} \quad 0 \leq k \leq N-1.$$

Let $W_N = e^{-j \frac{2\pi}{N}}$.

$$X(k) = \sum_{n=0}^{N-1} x(n) W_N^{kn} \quad 0 \leq k \leq N-1.$$

Matrice. Fourier.

$$X = \begin{bmatrix} X_0 \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix} = \begin{bmatrix} 1 & 1 & \dots & 1 \\ 1 & W_N & \dots & W_N^{N-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & W_N^{N-1} & \dots & W_N^{(N-1)(N-1)} \end{bmatrix} \begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix}$$

Input-based perspective.

$$x[n] \rightarrow [h[n]] \rightarrow y[n]$$

$$x[n] = \sum x[i] \delta[n-i] \Rightarrow y[n] = \sum x[i] h[n-i].$$

Note: Matlab matrix starts from 1!

$$\text{Length } y[n] = \text{length } x[n] + \text{length } h[n] - 1.$$

Output-based Perspective.

$$[h[0] \ h[1] \ \dots \ h[L_h-1]] \begin{bmatrix} x[0] \\ x[1] \\ \vdots \\ x[L_x-1] \end{bmatrix}$$

← ADD $[\text{length}(h[n]) - 1]$ here

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$$\hat{h}(w) = \sum h[n] e^{-jwn}.$$

Also we can use matrix.

$$w = \omega_0 : \frac{2\pi}{N} : \omega_{N-1}$$

$$\begin{bmatrix} e^{-j\omega_0 \cdot 0} & e^{-j\omega_0 \cdot 1} & \dots & e^{-j\omega_0 \cdot (L_h-1)} \\ e^{-j\omega_1 \cdot 0} & e^{-j\omega_1 \cdot 1} & \dots & \vdots \\ \vdots & \vdots & \ddots & \vdots \end{bmatrix} \begin{bmatrix} h[0] \\ h[1] \\ \vdots \\ h[L_h-1] \end{bmatrix}$$

length $[L_h] - 1$