



## Adventures in Bayesian Structural Time Series

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# What is BSTS?

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- ▶ Comprised of 3 components:
  - ▶ Structural Time Series model (a.k.a. state space model)
  - ▶ Spike and Slab regression
  - ▶ Bayesian model averaging
- ▶ Predicting the Present with Bayesian Structural Time Series by Steven L. Scott and Hal Varian (Google)
- ▶ Implementation
  - ▶ R: bsts
    - ▶ or Causal Impact
  - ▶ Python: Causal Impact



# Structural Time Series

- ▶ Data from unobserved **state space** plus noise
- ▶ Model the latent state space instead of the data directly

## Local Level Model

- ▶  $y_t$ : data
- ▶  $\mu_t$ : latent state

$$y_t = \mu_t + \varepsilon_t$$

$$\varepsilon_t \sim N(0, \sigma_\varepsilon^2)$$

$$\mu_{t+1} = \mu_t + \xi_t$$

$$\xi_t \sim N(0, \sigma_\xi^2)$$

Analogous to the intercept in linear regression but allowing for the intercept to vary over time



## Local Linear Trend Model

- ▶  $y_t, \mu_t$ : same as before
- ▶  $\nu_t$ : slope (additional state component)

$$y_t = \mu_t + \varepsilon_t$$

$$\varepsilon_t \sim N(0, \sigma_\varepsilon^2)$$

$$\mu_{t+1} = \mu_t + \nu_t + \xi_t$$

$$\xi_t \sim N(0, \sigma_\xi^2)$$

$$\nu_{t+1} = \nu_t + \zeta_t$$

$$\zeta_t \sim N(0, \sigma_\zeta^2)$$



# Structural Time Series

## General Form

- ▶  $y_t$ : data
- ▶  $\alpha_t$ : state component

$$y_t = Z_t' \alpha_t + \varepsilon_t \qquad \varepsilon_t \sim N(0, H_t) \qquad (1)$$

$$\alpha_{t+1} = T_t \alpha_t + R_t \eta_t \qquad \eta_t \sim N(0, Q_t) \qquad (2)$$

- ▶ (1): **observation equation**
- ▶ (2): **transition equation**



# Structural Time Series in Bayesian Context

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- ▶ Spike and slab regression
  - ▶ Used when regression components are included
  - ▶ Variable selection technique
  - ▶ Prior on regression coefficients
- ▶ Bayesian Model Averaging
  - ▶ Consequence of spike and slab prior
  - ▶ Different  $\beta$ s included in each draw of posterior (i.e. different model on each draw)
- ▶ Prior Elicitation and Posterior Sampling
  - ▶ Inclusion probabilities for regression coefficients
  - ▶ Or: expected model size, expected  $R^2$ , weight given to  $R^2$
  - ▶ Gibbs sampler (stochastic search variable selection) to draw from posterior
  - ▶ For details see paper by Scott and Varian