

# Adventures in Bayesian Structural Time Series Part 3: Structural Time Series in Bayesian Context Andrew Bates, Josh Gloyd, Tyler Tucker





- Without Regression:
  - Prior



- Without Regression:
  - Prior
  - Posterior



- Without Regression:
  - Prior
  - Posterior
- With Regression:



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Prior



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  - Specify distribution on parameters (variances)



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- - ★ Kalman filter and Kalman smoother



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  - Specify distribution on parameters (variances)
- - Kalman filter and Kalman smoother
  - Markov Chain Monte Carlo

# Spike and Slab Prior



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- © Consider regression coefficients fixed through time
  - If not, include as state variables
- Spike: prior for probability of regression coefficients being zero
- Slab: prior on nonzero regression coefficients and variance



#### Spike

- $\ \ \ \ \gamma_k = 1 \ \text{if} \ \beta_k \neq 0. \ \gamma_k = 0 \ \text{if} \ \beta_k = 0$
- $\otimes$   $\beta_{\gamma}$ : subset of  $\beta$ s with  $\beta_k \neq 0$
- $\ \, \ \, \ \,$  Independent Bernoulli prior:

$$\gamma \sim \prod_{i=1}^K \pi_k^{\gamma_k} (1 - \pi_k)^{1 - \gamma_k}$$



#### Slab

- $\otimes \Omega^{-1}$ : symmetric matrix
  - $\Omega_{\gamma}^{-1}$ : submatrix corresponding to  $\gamma_k = 1$
- © Conjugate prior:

$$eta_{\gamma} ig| \sigma_{arepsilon}^2, \gamma \sim \mathit{N}(\mathit{b}_{\gamma}, \sigma_{arepsilon}^2 \Omega_{\gamma}) \qquad rac{1}{\sigma_{arepsilon}^2} ig| \gamma \sim \mathrm{Gamma}\left(rac{\mathit{v}}{2}, rac{\mathit{ss}}{2}
ight)$$



#### Full Prior

$$p(\beta, \gamma, \sigma_{\varepsilon}^{2}) = p(\beta_{\gamma}|\gamma, \sigma_{\varepsilon}^{2})p(\sigma_{\varepsilon}^{2}|\gamma)p(\gamma)$$

# Specifying Spike and Slab Prid San Diego State University

- ss, v: prior sum of squares and prior sample size
  - $\otimes$  Expected  $R^2$ , expected model size
- $\otimes \pi_k$ : inclusion probability for regression coefficients
- $\otimes \Omega^{-1}$ : based on design matrix X

# Spike and Slab Posterior



### Posterior of $\beta$ and $\sigma_{\varepsilon}^2$ given $\gamma, y^*$

$$\otimes$$
  $Z_t^*$ : observation matrix  $Z_t$  with  $\beta^T x_t = 0$ 

$$\emptyset \ y^* = (y_1^*, y_2^*, \dots, y_n^*)^T$$

$$\beta_{\gamma} | \sigma_{\varepsilon}, \gamma, y^* \sim N(\tilde{\beta}_{\gamma}, \sigma_{\varepsilon}^2 V_{\gamma}) \quad \frac{1}{\sigma_{\varepsilon}^2} | \gamma, y^* \sim \operatorname{Gamma}\left(\frac{N}{2}, \frac{SS_{\gamma}}{2}\right)$$

$$\nabla_{\gamma}^{-1} = (X^T X)_{\gamma} + \Omega_{\gamma}^{-1}$$

$$\otimes N = v + n$$



## Posterior of $\gamma$ given $y^*$ :

$$\gamma | y^* \sim C(y^*) \frac{|\Omega_{\gamma}^{-1}|^{1/2}}{|V_{\gamma}^{-1}|^{1/2}} \frac{p(\gamma)}{SS_{\gamma}^{N/2-1}}$$

# Posterior Sampling



- Combination of:
  - stochastic Kalman smoother
  - - stochastic search variable selection
    - Gibbs sampler