



# Adventures in Bayesian Structural Time Series

## *Part 3: Structural Time Series in Bayesian Context*

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⊠ Without Regression:



⊠ Without Regression:

⊠ Prior



## ⊠ Without Regression:

- ⊠ Prior

- ⊠ Posterior





⊠ Without Regression:

⊠ Prior

⊠ Posterior

⊠ With Regression:



- ⊠ Without Regression:

- ⊠ Prior

- ⊠ Posterior

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⊠ Without Regression:

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⊠ Posterior

⊠ With Regression:

⊠ Prior

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⊠ Prior



## ⊠ Prior

- ⊠ Specify distribution on parameters (variances)



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- ⊠ Specify distribution on parameters (variances)

- ⊠ Posterior



# Without Regression

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- ❖ Specify distribution on parameters (variances)

- ❖ Posterior

- ❖ Kalman filter and Kalman smoother



# Without Regression

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- ❖ Prior

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- ❖ Posterior

- ❖ Kalman filter and Kalman smoother
  - ❖ Markov Chain Monte Carlo





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# Spike and Slab Prior

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- ⊠ Consider regression coefficients fixed through time
  - ⊠ If not, include as state variables
- ⊠ **Spike:** prior for probability of regression coefficients being zero
- ⊠ **Slab:** prior on nonzero regression coefficients and variance



## Spike

$$\gamma_k = 1 \text{ if } \beta_k \neq 0. \quad \gamma_k = 0 \text{ if } \beta_k = 0$$





# Spike and Slab Prior

## Spike

- ⊠  $\gamma_k = 1$  if  $\beta_k \neq 0$ .  $\gamma_k = 0$  if  $\beta_k = 0$
- ⊠  $\beta_\gamma$ : subset of  $\beta$ s with  $\beta_k \neq 0$



# Spike and Slab Prior

## Spike

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- ⊠  $\beta_\gamma$ : subset of  $\beta$ s with  $\beta_k \neq 0$
- ⊠ Independent Bernoulli prior:

$$\gamma \sim \prod_{i=1}^K \pi_k^{\gamma_k} (1 - \pi_k)^{1-\gamma_k}$$



## Slab

⊠  $\Omega^{-1}$ : symmetric matrix



# Spike and Slab Prior

## Slab

- ⊗  $\Omega^{-1}$ : symmetric matrix
  - ⊗  $\Omega_{\gamma}^{-1}$ : submatrix corresponding to  $\gamma_k = 1$



# Spike and Slab Prior

## Slab

- ⊠  $\Omega^{-1}$ : symmetric matrix
  - ⊠  $\Omega_{\gamma}^{-1}$ : submatrix corresponding to  $\gamma_k = 1$
- ⊠ Conjugate prior:

$$\beta_{\gamma} | \sigma_{\varepsilon}^2, \gamma \sim N(b_{\gamma}, \sigma_{\varepsilon}^2 \Omega_{\gamma}) \quad \frac{1}{\sigma_{\varepsilon}^2} | \gamma \sim \text{Gamma} \left( \frac{\nu}{2}, \frac{ss}{2} \right)$$





## Full Prior

$$p(\beta, \gamma, \sigma_\varepsilon^2) = p(\beta_\gamma | \gamma, \sigma_\varepsilon^2) p(\sigma_\varepsilon^2 | \gamma) p(\gamma)$$



# Specifying Spike and Slab Prior

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⊠  $ss, v$ : prior sum of squares and prior sample size



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- ⊠  $\Omega^{-1}$ : based on design matrix  $X$ 
  - ⊠  $\Omega^{-1} = \frac{k}{n} X^T X$



# Spike and Slab Posterior

Posterior of  $\beta$  and  $\sigma_\varepsilon^2$  given  $\gamma, y^*$

⊠  $Z_t^*$ : observation matrix  $Z_t$  with  $\beta^T x_t = 0$



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$$\beta_\gamma | \sigma_\varepsilon, \gamma, y^* \sim N(\tilde{\beta}_\gamma, \sigma_\varepsilon^2 V_\gamma) \quad \frac{1}{\sigma_\varepsilon^2} | \gamma, y^* \sim \text{Gamma}\left(\frac{N}{2}, \frac{SS_\gamma}{2}\right)$$





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⊠  $\tilde{\beta}_\gamma = V_\gamma (X_\gamma^T y^* + \Omega_\gamma^{-1} b_\gamma)$



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⊠  $V_\gamma^{-1} = (X^T X)_\gamma + \Omega_\gamma^{-1}$

⊠  $\tilde{\beta}_\gamma = V_\gamma (X_\gamma^T y^* + \Omega_\gamma^{-1} b_\gamma)$

⊠  $N = v + n$

⊠  $SS_\gamma = ss + y^{*T} y^* + b_\gamma^T \Omega_\gamma^{-1} b_\gamma - \tilde{\beta}_\gamma^T V_\gamma^{-1} \tilde{\beta}_\gamma$



Posterior of  $\gamma$  given  $y^*$ :

$$\gamma|y^* \sim C(y^*) \frac{|\Omega_\gamma^{-1}|^{1/2}}{|V_\gamma^{-1}|^{1/2}} \frac{p(\gamma)}{SS_\gamma^{N/2-1}}$$





⊠ Combination of:



- ⊠ Combination of:
  - ⊠ stochastic Kalman smoother



- ⊠ Combination of:
  - ⊠ stochastic Kalman smoother
  - ⊠ MCMC:



⊠ Combination of:

⊠ stochastic Kalman smoother

⊠ MCMC:

⊠ stochastic search variable selection



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⊠ stochastic Kalman smoother

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⊠ stochastic search variable selection

⊠ Gibbs sampler