

## Robustness

To protect the electronics of the robot, we used an easily replaceable **paddle-stick “Iron-Man” themed casing**. Maintenance on the electronics can be easily performed by removing and replacing the casing, adding to the robustness of the build.

Furthermore, the **large wheels** assist the robot in keeping it stable and to climb stairs, and the **plywood chassis** effectively houses the electronic components enabling the robot to function in most environments and traverse through rough terrain.

Additionally, the **code is robust** in that it has been written and tested to ensure that errors are handled effectively. Moreover, the code is modular and optimised, making it easy to understand and perform maintenance.



## Aesthetic Appeal

A **sleek and compact design** is used on the robot, such a design allows the robot more agile and manoeuvrable in tight spaces. Furthermore, **the robot is conspicuous**. In a rescue context, the robot can be easily spotted by victims due to its conspicuous design, with **reflective taping** on the casing enabling the **robot to be seen in the dark**. With an **“Iron-Man” themed casing** for the electronics, victims in rescue contexts can rest assured that help is on the way when they see **the robot superhero!**

## Engineering Quality

In accordance with the **size and weight constraints** set by our client, in its fully extended position, our robot is 180 mm wide and 145 mm tall, and is thus able to fit inside a cylinder 250 mm in both diameter and height and it also weighs about 999.97 g which is less than 1000 g.

With an **efficient UI and simple control commands**, the robot is easily able to be controlled by the operator.



## Innovation

Instead of 3D printing a plastic claw or purchasing an expensive Arduino claw, **our claw utilises a string and paddle-stick mechanic** that is connected to a DC motor that can close and contain the tennis ball on command. As string and paddle sticks are both cheap and recyclable, the claw is not only innovative, but also **sustainable and an inexpensive component** of the robot to replicate.