

## ***Deterministic Finite Automata (DFA)***

$$A = ( Q , \Sigma , \delta , q_0 , F )$$

$Q$  = a finite set (of states)

$\Sigma$  = a finite (input alphabet) set

$\delta$  = the transition function (full function) where :

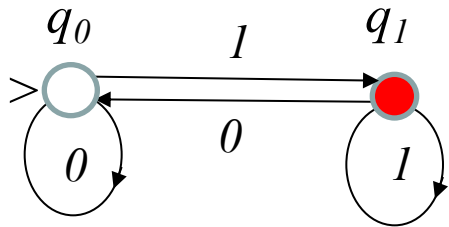
$$\delta : Q \times \Sigma \rightarrow Q ; (q, \sigma) \rightarrow \delta(q, \sigma) \in Q$$

$q_0$  = initial state,  $q_0 \in Q$

$F$  = final state set ,  $F \subseteq Q$

# Simple Representations of DFA

## (1) Visual (Graphical) : Transition Diagrams



strings (event sequences) that end up in  
*colored (final) state*

## (2) Tabular : Transition Tables

state	input	state'
$q_0$	0	$q_0$
$q_0$	1	$q_1$
$q_1$	0	$q_0$
$q_1$	1	$q_1$

no. of columns in transition table = 3

in general how many rows are there ?

**answer  $\rightarrow |\Sigma| \times |Q|$  rows**

## $\delta E = \text{Extended Transition Function}$

$$\delta E : Q \times \Sigma^* \rightarrow Q ; (q, s) \rightarrow \delta E(q, s) \in Q$$

*Inductive Definition* ( $e$  =empty string)

$$\delta E(q, e) := q, \text{ *Basis*}$$

$$\delta E(q, s.a) = \delta(\delta E(q, s), a), \text{ *Induction*}$$

$L(A) :=$  the language **accepted** by  $A$

$s \in L(A) \leftrightarrow$  (if and only if)  $\delta E(q_0, s) \in F$  ; or :

$$L(A) = (s \in \Sigma^* \mid \delta E(q_0, s) \in F)$$

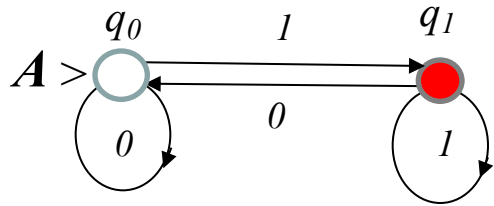
$$\Sigma^* - L(A) = (s \in \Sigma^* \mid \delta E(q_0, s) \in Q - F)$$

*Complement Language*

*Non-final states*

*Note that '-' sign is used for set subtraction hence for sets  $X$  and  $Y$  :  $X - Y := X \cap Y^c$*

**Examples** 1- Describe in simple natural language  $L(A)$  = the language accepted by  $A$

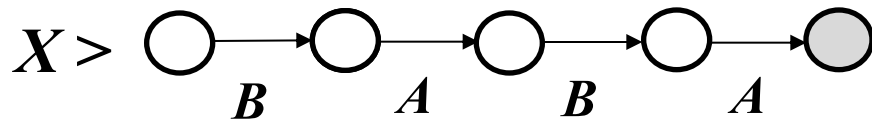


$$L(A) = \{s \in \{0,1\}^* \mid \delta E(q_0, s) \in \{q_1\}\}$$

**Answer :** all strings in  $\{0,1\}^*$  that terminate with a 1

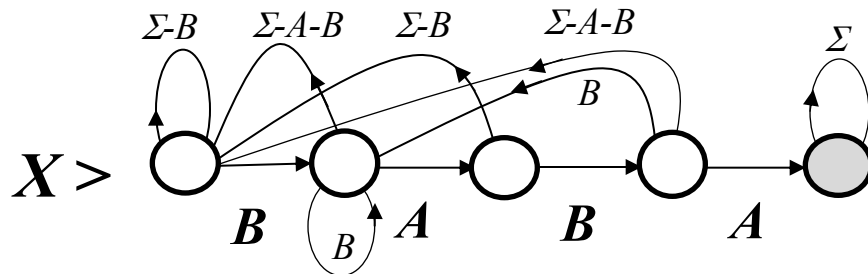
2- Design a DFA  $X$  that accepts the string of letters in Turkish alphabet in which the substring 'BABA' occurs at least once !

Let  $\Sigma$  denote the set of all capital letters in the Turkish alphabet



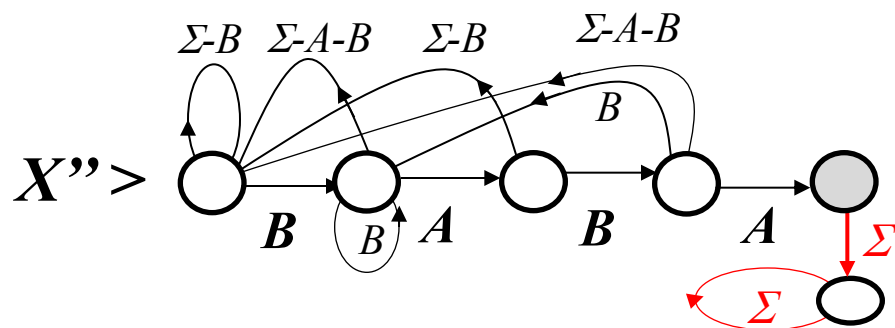
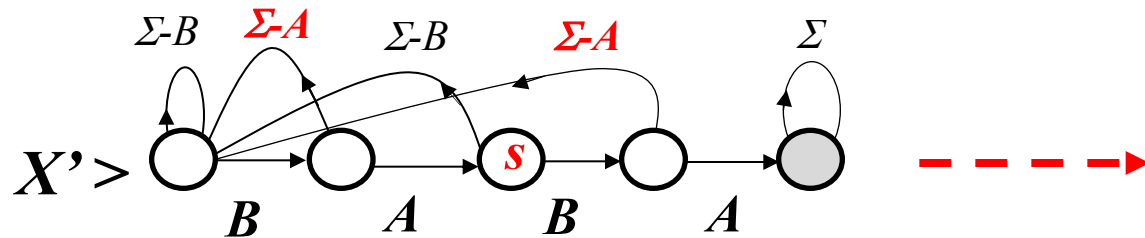
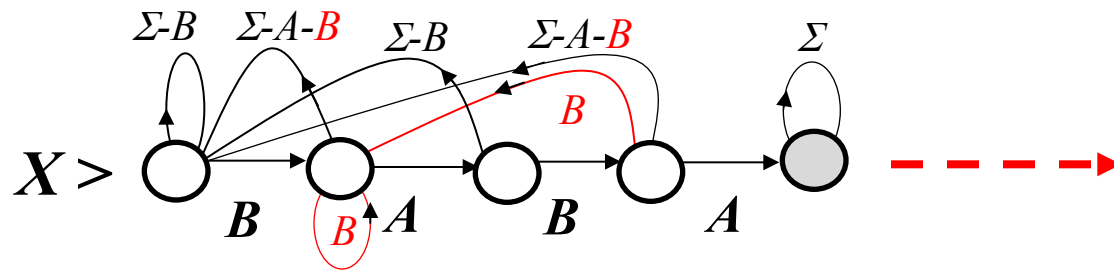
**NOT a DFA !! Why ?**

$\delta$  NOT a full function ; missing transitions !



**This is a DFA !**

## Discussion slide on Example 2



# *Nondeterministic Finite Automata (NFA)*

Same as *DFA* except :

*set of all subsets of  $Q$*

(1)  $\delta: Q \times \Sigma \rightarrow 2^Q$  (where  $2^Q := P(Q)$  = power set of  $Q$ )

(2) initial state (is a set !)  $Q_0 \subseteq Q$  ( *differs from main text !* )

*Distinction in graphical representation (transition diagram) :*

In *DFA* for every  $\sigma \in \Sigma$  there is **exactly one** outgoing transition edge from every state  $q \in Q$

In *NFA* for every  $\sigma \in \Sigma$  there may be **multiple** (including **none** !)  
outgoing transition edges from every state  $q \in Q$

## *Extended Transition Function for NFA*

$$\delta E : 2^Q \times \Sigma^* \rightarrow 2^Q ; (X, s) \rightarrow \delta E(X, s) \in 2^Q$$

*Inductive Definition*

$$\delta E(X, e) := X, \text{ *Basis*}$$

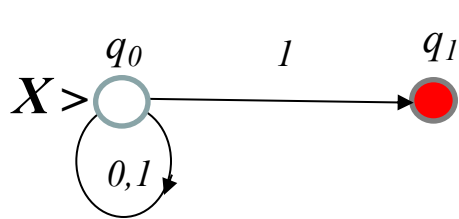
$$\delta E(X, s.a) = \cup_{q \in \delta E(X, s)} \delta(q, a), \text{ *Induction*}$$

$L(A) :=$  the language *accepted* by  $A$

$s \in L(A) \leftrightarrow$  (if and only if)  $\delta E(Q_0, s) \cap F \neq \emptyset$ ; *or* :

$L(A) := \{ s \in \Sigma^* \mid \delta E(Q_0, s) \cap F \neq \emptyset \} ; \emptyset := \text{null set}$

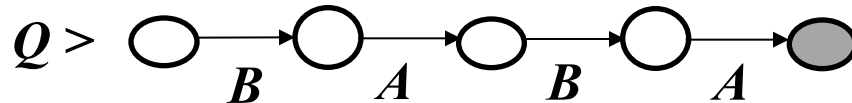
**Examples 1** - Describe in simple natural language  $L(X)$  = the language accepted by  $X$



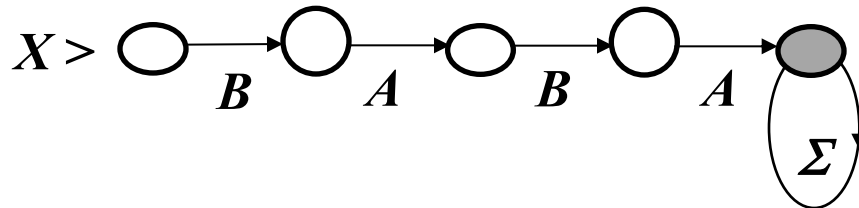
$$L(X) = (s \in \{0,1\}^* \mid \delta E(q_0, s) \cap \{q_1\} \neq \emptyset)$$

**Answer : all strings in  $\{0,1\}^*$  that terminate with a 1**

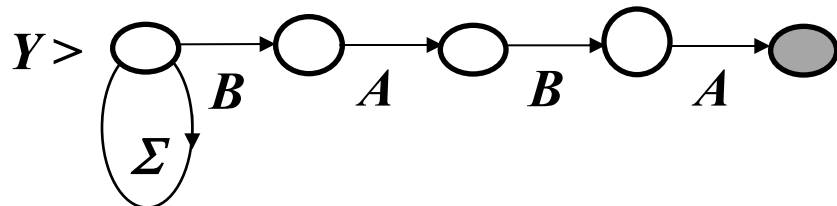
**2** - Design an NFA  $W$  that accepts only the string **BABA**.



**3** - Design an NFA  $X$  that accepts **all strings** in which **BABA** is a **prefix**.

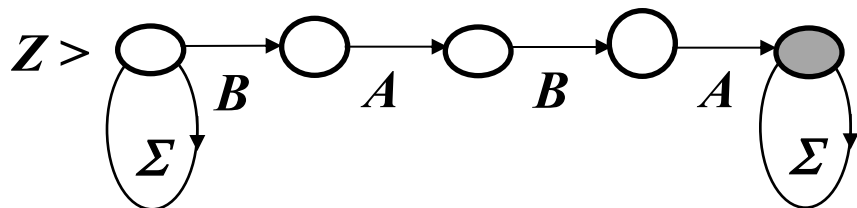


**4** - Design an NFA  $Y$  that accepts **all strings** in which **BABA** is a **postfix**.





**5** - Design an NFA **Z** that accepts *all strings* in which **BABA** is a **substring**.



**6** - Design NFAs that accepts *all strings* in which **BABA** is **NOT** a : (i) **prefix**, (ii) **postfix** (iii) **substring**.

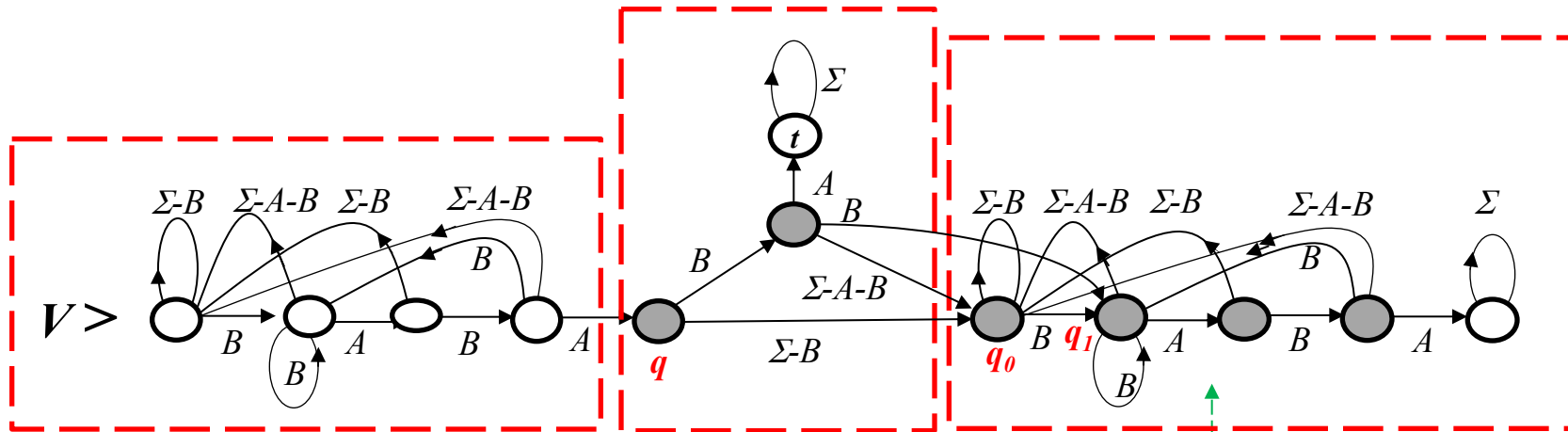
Convert respectively **X, Y, Z** into their DFA equivalents (see slides 11+etc)

and convert each into its corresponding **complement** DFA by interchanging its final and nonfinal state sets .

**7** - Design an NFA **V** in which **BABA** occurs as a **substring precisely once**.

(See next slide)

*Solution to example 7 on slide no. 9 is automaton V below*



The automaton that generates ALL strings in which the substring 'BABA' occurs **precisely once** as a **postfix** upon arrival at state  $q$

ALL sequences of length 1 or 2 that differ from  $BA$  reach from  $q$  to  $q_0$  or  $q_1$ . To avoid  $BABA$  through a second  $BA$  sequence, a trap state  $t$  is placed.

The automaton starting at initial state  $q_0$  accepts ALL strings that do NOT have the substring 'BABA' in it

**FACT** : If a DFA  $X$  accepts the language  $L(X)$  then the DFA that accepts the complement language  $\Sigma^*-L(X)$  is same as  $X$  except  $F$  is replaced with  $Q-F$

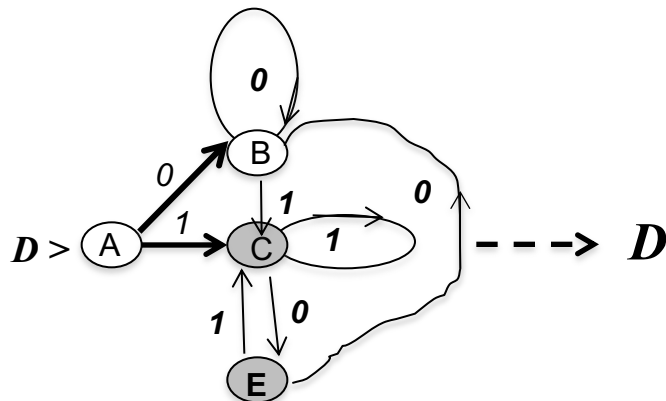
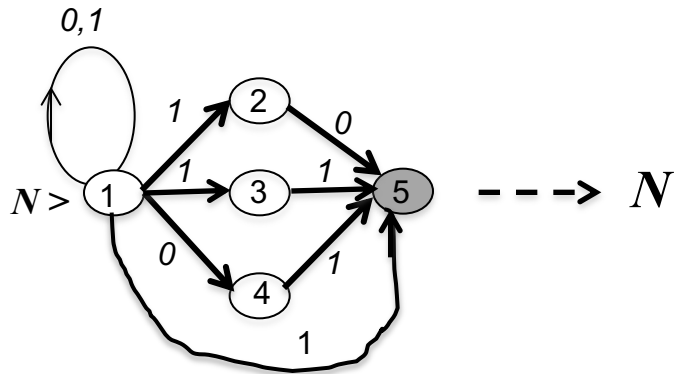
## *Construction of Equivalent DFA $D$ from a given NFA $N$*

**Problem** : Given an NFA  $N = (Q, \Sigma, \delta_N, Q_0, F_N)$  construct a DFA  $D = (2^Q, \Sigma, \delta_D, Q_0, F_D)$  such that  $L(N) = L(D)$

**Idea** : Construct DFA  $D$  where every state of  $D$  is a **subset** of states of  $N$ ; and let the **subset-to-subset transitions** of  $N$  be the simple **state-to-state transitions** in  $D$ . Whenever a final state in  $F_N$  is visited in  $N$  by a string  $s$  then by letting  $F_D$  be the **set of all subsets** of  $Q$  where at least one state of an **element** of  $F_D$  is in  $F_N$  it is also accepted by  $D$  by definition of  $N$ .

## Example for DFA equivalent **D** for an NFA **N**

$L = \{s \in \{0,1\}^* \mid s = u.v ; |v| \leq 2 ; v \text{ has at least one } 1 ; u, v \in \{0,1\}^*\}$



$A \rightarrow$

$B \rightarrow$

*final*  $C \rightarrow$

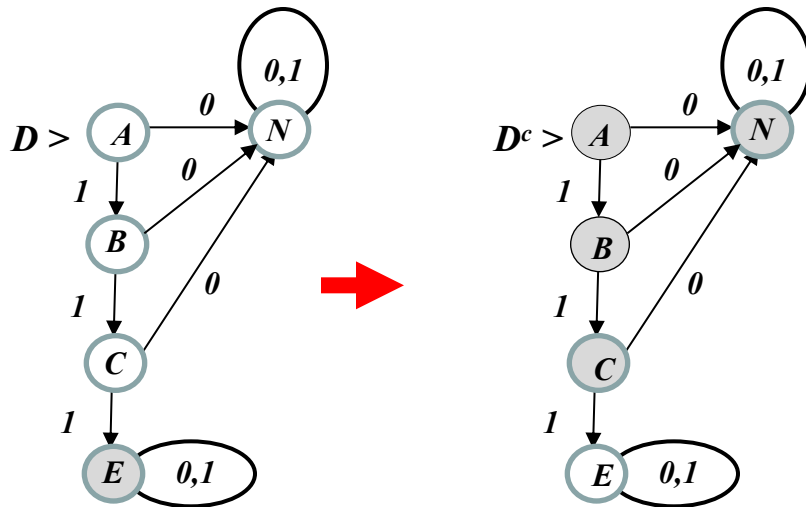
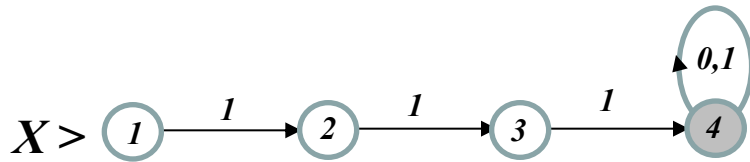
*final*  $E \rightarrow$

state	input	next
1	0	1,4 (B)
1	1	1,2,3,5 (C)
1,4	0	1,4 (B)
1,4	1	1,2,3,5 (C)
1,2,3,5	0	1,4,5 (E)
1,2,3,5	1	1,2,3,5 (C)
1,4,5	0	1,4 (B)
1,4,5	1	1,2,3,5 (C)

## Another example for DFA equivalent **D** for an NFA **X**

$L = (s \in \{0,1\}^* \mid s \text{ does NOT have a prefix } 1.1.1)$

$L^c = (s \in \{0,1\}^* \mid s = 1.1.1.v ; v \in \{0,1\}^*)$



$q$	$\sigma$	$q'$
$X > 1 = A$	0	$N = \text{Null}$
1	1	$2 = B$
$2 = B$	0	$N$
$B$	1	$3 = C$
$3 = C$	0	$N$
$C$	1	$4 = E^*$
$4 = E^*$	0	$E^*$
$E^*$	1	$E^*$
$N$	0	$N$
$N$	1	$N$

## Theory

**Problem** : Given an NFA  $N = (Q, \Sigma, \delta_N, Q_0, F_N)$  construct a DFA  $D = (2^Q, \Sigma, \delta_D, Q_0, F_D)$  such that  $L(N) = L(D)$

**Solution** :

$$(1) \delta_D(X, \sigma) := \delta_N E(X, \sigma) ; \delta_D(\emptyset, \sigma) := \emptyset, \quad \forall \sigma \in \Sigma$$

$$(2) F_D := (Y \subseteq Q \mid Y \cap F_N \neq \emptyset)$$

To prove that  $L(D) = L(N)$  first show that  $\delta_D E(Q_0, u) = \delta_N E(Q_0, u)$  using induction on the length of  $u$ .

$\delta_D E(Q_0, e) = \delta_N E(Q_0, e) = Q_0$  by definition (*basis ; s=e case*)

$$\delta_D E(Q_0, s.a) = \delta_D(\delta_D E(Q_0, s), a) = \delta_D(X, a) = \delta_N E(X, a) \text{ where } X = \delta_D E(Q_0, s)$$

*But by induction hypothesis* :  $\delta_D E(Q_0, s) = \delta_N E(Q_0, s) = X$  ; hence

$$\delta_D E(Q_0, s.a) = \delta_D(X, a) = \delta_N E(X, a) = \delta_N E(Q_0, s.a) ; \text{ by def. of } \delta_N E(Q_0, s.a)$$

Finally  $L(N)=L(D)$  is proved as follows :

$$s \in L(N) \Leftrightarrow \delta_N E(Q_0, s) \cap F_N \neq \emptyset \quad ; \text{ by def. of } L(N)$$

$$\Leftrightarrow \delta_N E(Q_0, s) \in F_D \quad ; \text{ since } F_D := (Y \subseteq Q \mid Y \cap F_N \neq \emptyset)$$

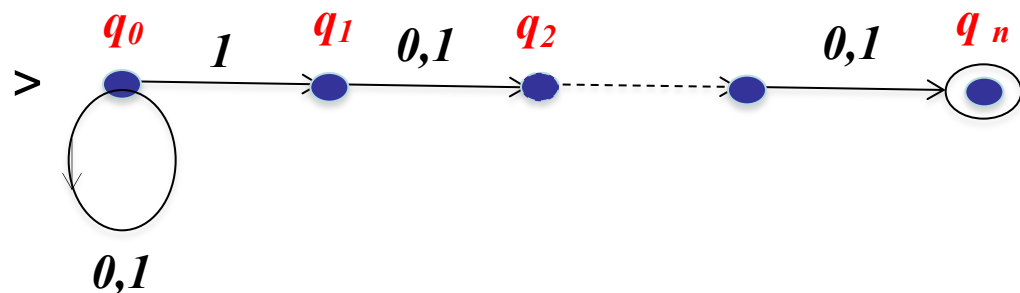
$$\Leftrightarrow \delta_D E(Q_0, s) \in F_D \quad ; \text{ since } \delta_D E(Q_0, s) = \delta_N E(Q_0, s)$$

$$\Leftrightarrow s \in L(D) \quad ; \text{ by def. of } L(D)$$

## *A 'bad case' example for NFA-to-DFA conversion*

$$L = (s \in \{0,1\}^* \mid s = u.1.v ; |v| = n-1, n > 1, u, v \in \{0,1\}^*)$$

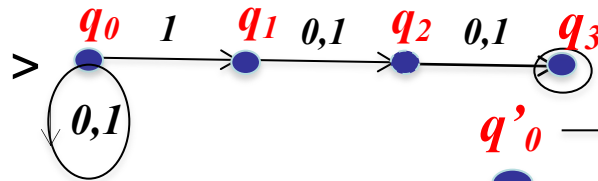
*An  $n+1$  state NFA to accept  $L$*



**Fact :** Any DFA  $D$  to accept  $L$  has at least  $2^n$  states

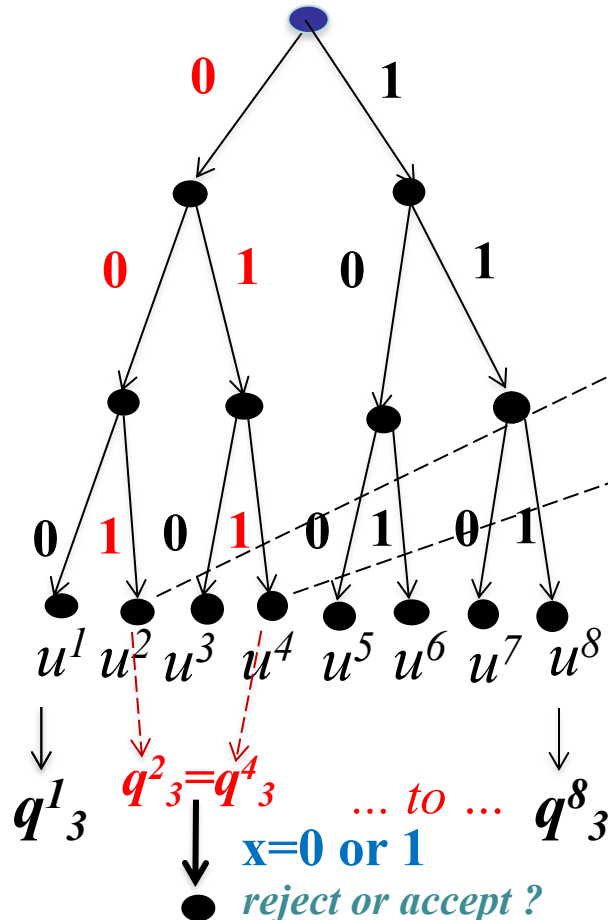


## A special case : $n=3$



$q'_0$

Initial state of a DFA equivalent



Suppose not !!

say  $q^2_3 = q^4_3$  driven by

$u^2 = 001$  and  $u^4 = 011$  respectively

But that is impossible since inputs  $001x$  (to be rejected) and  $011x$  (to be accepted) are either both accepted or both rejected violating the design !

must all be 8 distinct states !

## ***Proof of Fact***

(1) Consider all  $(2^n)$  sequences of 0 and 1s of length  $n$  ; denote each by  $u^k$  for  $k=1,\dots,2^n$  and  $j$ th input of  $u^k$  by  $u_j^k$  for  $j=1,\dots,n$ .

(2) Apply each sequence  $u^k$  starting from the initial state  $q'_0$  of  $D$  and let  $q_n^k$  be the state of  $D$  arrived at the end of the application of  $u^k$ .

***Claim  $k \neq p$  implies  $q_n^k \neq q_n^p$  !***

(3) Suppose the claim is false for some  $k \neq p$  (***i.e.  $q_n^k = q_n^p$  !***) then let  $j$  be the first (smallest) index for which  ***$u_j^k = 1$  and  $u_j^p = 0$***

(4) Then after  $n-j$  steps the corresponding states ***merge*** at the same value  $q_n^k = q_n^p$

(5) But then it becomes impossible to differentiate inputs of length  $n+j$  starting with  $u^k$  and  $u^p$  although at  $j$ th stage one continues with 1 (to be accepted by  $D$ ) and the other with 0 (to be rejected by  $D$ ) ! ***A contradiction !***

## *NFA with $\varepsilon$ -transitions*

$$N\varepsilon = (Q, \Sigma, \delta_{N\varepsilon}, Q_0, F)$$

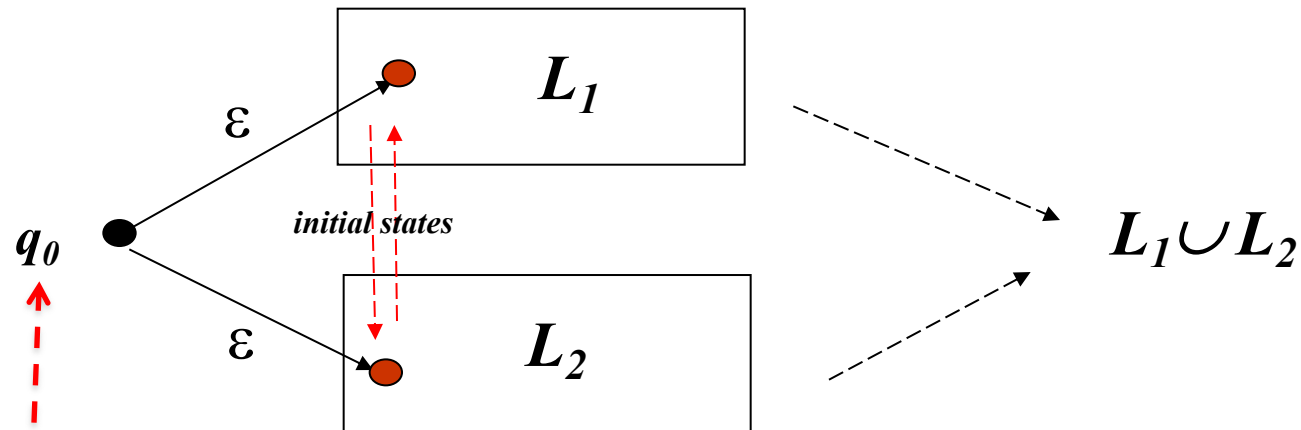
*Difference is in  $\delta_{N\varepsilon} : Q \times (\Sigma \cup \varepsilon) \rightarrow 2^Q$*

$\delta_{N\varepsilon}(q, \varepsilon) \in 2^Q$  is called (a bundle of)  **$\varepsilon$ -transitions**

*In computing the language accepted,  $L(N\varepsilon)$ ,  $\varepsilon$ -transitions do not count, i.e., they are defined as invisible and erased !*

## Typical Applications of $\varepsilon$ - transitions

### 1- Implementation of the union language $L_1 \cup L_2$



*A single initial state  
connecting to all initial states*

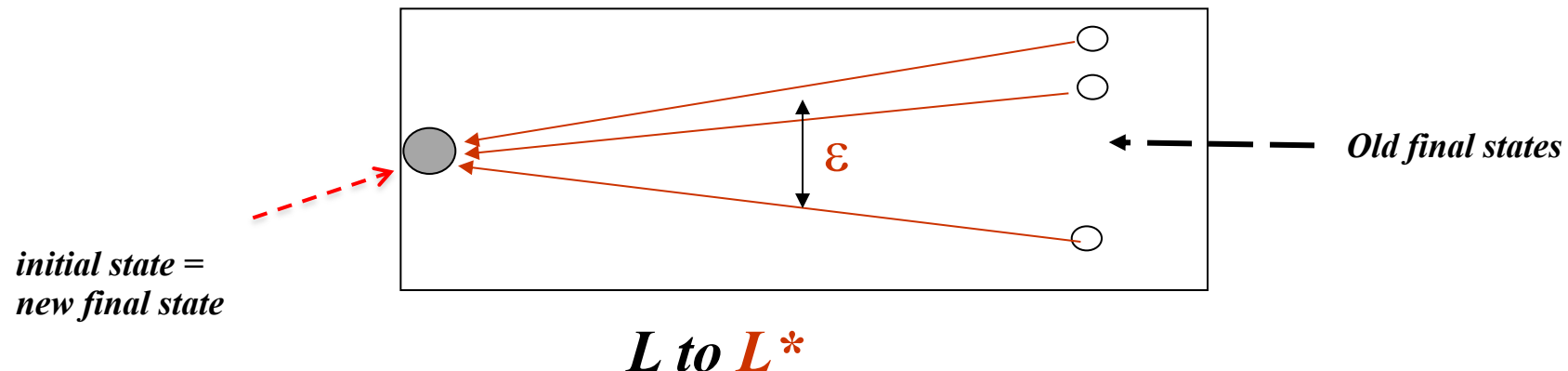
## 2- Implementation of the *star* or *Kleene-closure* language $L^*$ given $L$

What is  $L^*$  language ?

$$L^* := ( s \in \Sigma^* \mid s = u_1 \cdot u_2 \cdot \dots \cdot u_k ; u_j \in L, j = 1, \dots, k ; k \geq 0 )$$

*concatenation of strings*

Note that  $s = e \in L^*$  ( $k=0$  case above)



## *Eliminating $\varepsilon$ -transitions*

*Idea : define  $\varepsilon$ -closures inductively (recursively)*

*Let  $X \subseteq Q$  and compute  $ECLOSE(X) \subseteq Q$  recursively as below :*

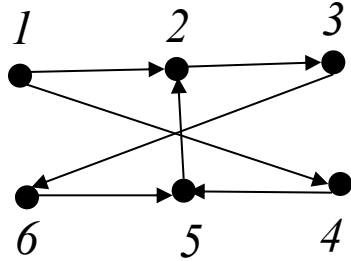
*$ECLOSE(X) = X$  , **basis***

*If  $y \in ECLOSE(X)$  then set :*

*$ECLOSE(X) := ECLOSE(X) \cup \delta_{N\varepsilon}(y, \varepsilon)$  , **recursion***

## Example for computing E-closures

*All transitions are epsilon-transitions*



*Progress in inductive steps  $\rightarrow$*

***E-CLOSURE (1)***  $\rightarrow (1) \rightarrow (1, 2, 4) \rightarrow (1, 2, 4, 3, 5) \rightarrow (1, 2, 4, 3, 5, 6)$

***E-CLOSURE (4)***  $\rightarrow (4) \rightarrow (4, 5) \rightarrow (4, 5, 2) \rightarrow (4, 5, 2, 3) \rightarrow (4, 5, 2, 3, 6)$

*The language  $L(N\varepsilon)$  accepted by an automaton  $N\varepsilon$  with  $\varepsilon$ -transitions*

*Extended Transition Function for  $N\varepsilon$  :*

$\delta_{N\varepsilon}E(X, e) := ECLOSE(X)$  ; **basis**

$\delta_{N\varepsilon}E(X, s.a) := \cup_{y \in Y} ECLOSE(\delta_{N\varepsilon}(y, a))$ ,  $Y = \delta_{N\varepsilon}E(X, s)$  : **induction**

$L(N\varepsilon)$  = language accepted by  $N\varepsilon$

$$= \{ s \in \Sigma^* \mid \delta_{N\varepsilon}E(Q_0, s) \cap F \neq \emptyset \}$$

$\sim N :=$  **NFA-equivalent** for  $N\varepsilon$  with no  $\varepsilon$ -transitions

$\sim N := (Q, \Sigma, \delta_{\sim N}, Q'_0, F)$

where :  $\delta_{\sim N}(q, a) := \delta_{N\varepsilon}E(\{q\}, a)$  ;  $Q'_0 := ECLOSE(Q_0)$

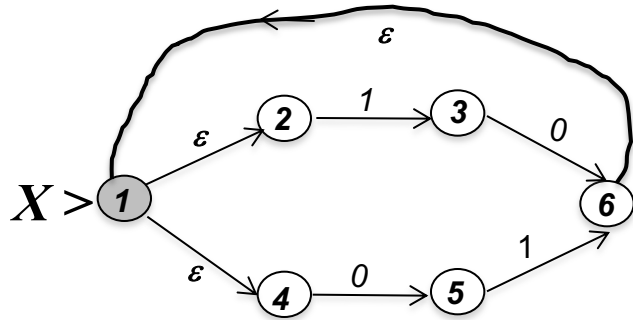
**Fact :  $L(\sim N) = L(N\varepsilon)$**



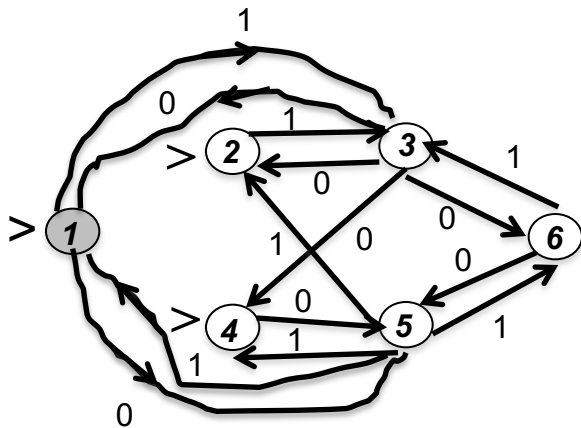
## Example for $\epsilon$ -NFA to NFA without $\epsilon$ -transitions transformation

$$L_1 = \{01\}, L_2 = \{10\}$$

$$L := \{L_1 \cup L_2\}^*$$

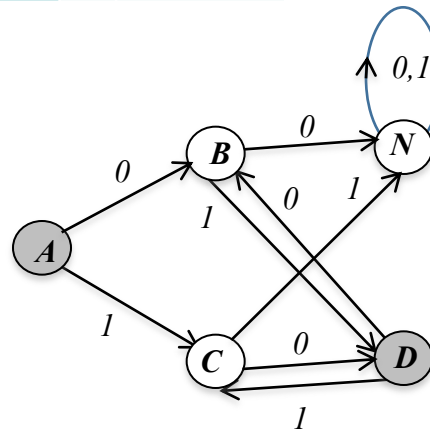


**NFA Equivalent**



**DFA Equivalent**

**Y**



$Q$	$\sigma$	$Q'$
$A^*=1,2,4$	0	$B=5$
$A=1,2,4$	1	$C=3$
$B=5$	0	$N$
$B=5$	1	$D^*=1,2,4,6$
$C=3$	0	$D$
$C=3$	1	$N$
$D^*$	0	$B$
$D$	1	$C$
$N$	0	$N$
$N$	1	$N$

$q$	$\sigma$	$q'$
$>1^*$	0	5
1	1	3
$>2$	0	$\emptyset$
2	1	3
3	0	1,2,4,6
3	1	$\emptyset$
$>4$	0	5
4	1	$\emptyset$
5	0	$\emptyset$
5	1	1,2,4,6
6	0	5
6	1	3

## *A Resume of equivalence formulas for DFA , NFA and $\varepsilon$ -NFA*

(1)  $\delta_A : Q \times \Sigma \rightarrow Q$  ;  $\delta_A E : Q \times \Sigma^* \rightarrow Q$  ;  $s \in L(A) \Leftrightarrow \delta_A E(q_0, s) \in F$

(2)  $\delta_N : Q \times \Sigma \rightarrow 2^Q$  ;  $\delta_N E : 2^Q \times \Sigma^* \rightarrow 2^Q$  ;  $s \in L(N) \Leftrightarrow \delta_N E(Q_0, s) \cap F \neq \emptyset$

(3) *Deterministic Equivalent  $D$  of an NFA  $N$  such that  $L(N) = L(D)$*

$$D = (2^Q, \Sigma, \delta_D, Q_0, F_D) ; \delta_D (X, \sigma) := \cup_{\{v \in X\}} \delta_N (v, \sigma) ; \delta_D (\emptyset, \sigma) := \emptyset$$

$$F_D := \{ Y \subseteq Q \mid Y \cap F_N \neq \emptyset \}$$

(4)  $\delta_{N\varepsilon} : Q \times \Sigma \cup \{\varepsilon\} \rightarrow 2^Q$  ;  $\delta_{N\varepsilon} E : 2^Q \times \Sigma^* \rightarrow 2^Q$  ;  $s \in L(N\varepsilon) \Leftrightarrow \delta_{N\varepsilon} E(Q_0, s) \cap F \neq \emptyset$

(5) *Equivalent  $\sim N$  without  $\varepsilon$ -transitions of an  $\varepsilon$ -NFA  $N\varepsilon$  such that  $L(\sim N) = L(N\varepsilon)$*

$$\sim N := (Q, \Sigma, \delta_{\sim N}, Q'_0, F) ; \delta_{\sim N}(q, a) := \delta_{N\varepsilon} E(\{q\}, a) ; Q'_0 := ECLOSE(Q_0)$$