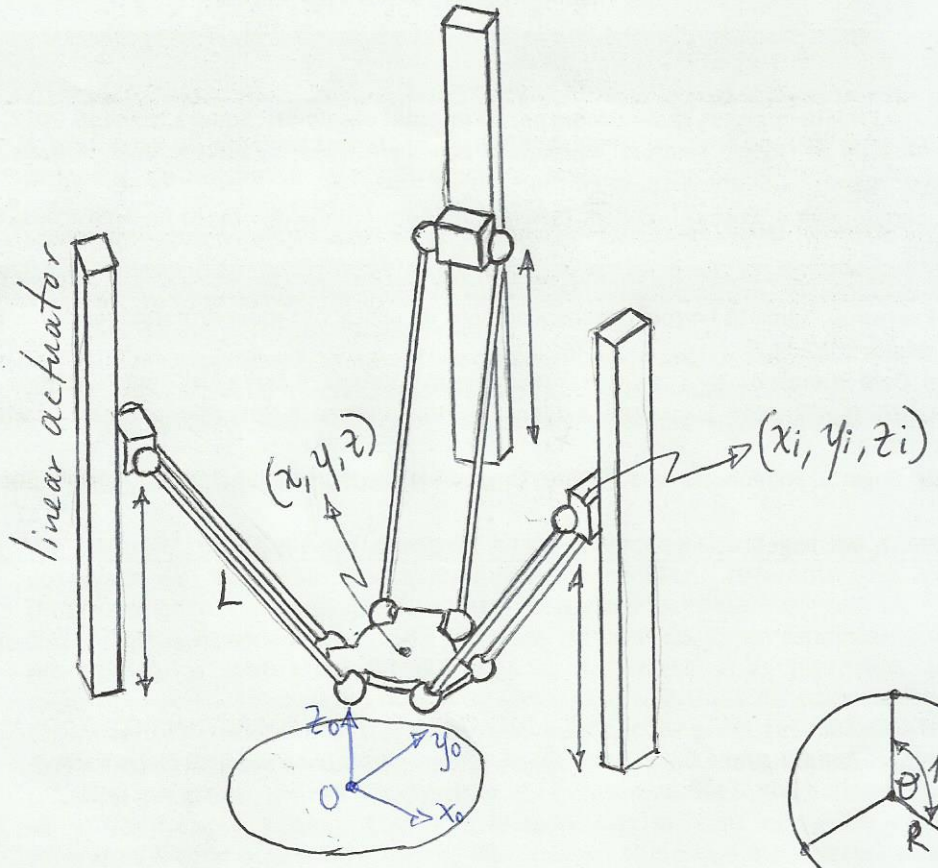

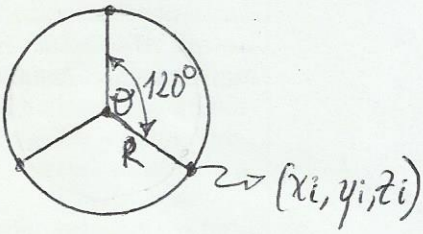

$$x_i = R\cos\theta_i \qquad i = 1, 2, 3$$
$$y_i = R\sin\theta_i$$

$$\theta_i = \frac{2i-2}{3}\pi \qquad i = 1, 2, 3$$

$$z_i = z \pm \sqrt{L^2 - (x - x_i)^2 - (y - y_i)^2} \qquad i = 1, 2, 3$$