



Fundamentals of Deep Learning



Efrat Shimron

Deep learning is everywhere!

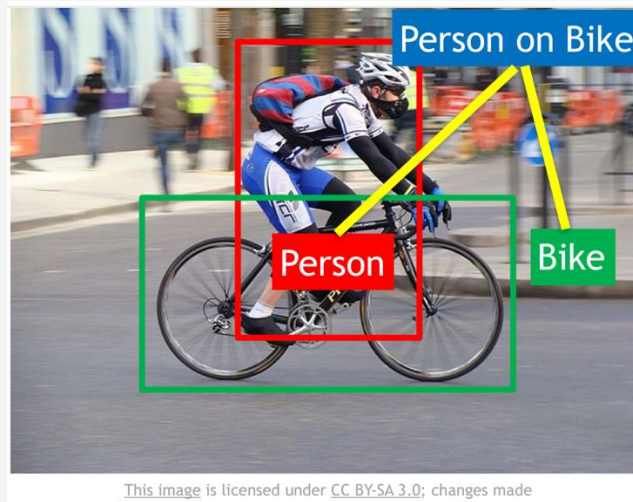
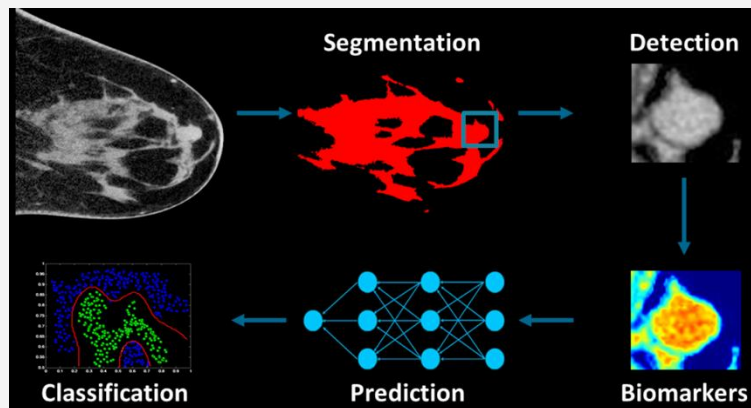


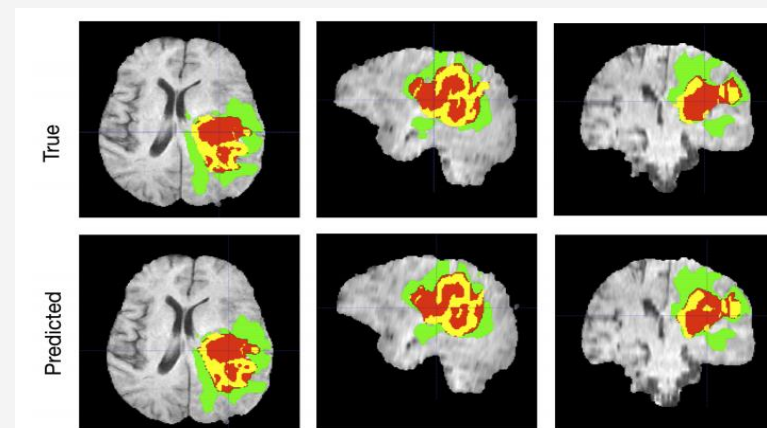
Image by Jin Clyde Monge



Mindy-support.com



<http://axti.radboudimaging.nl/>



Nvidia.com

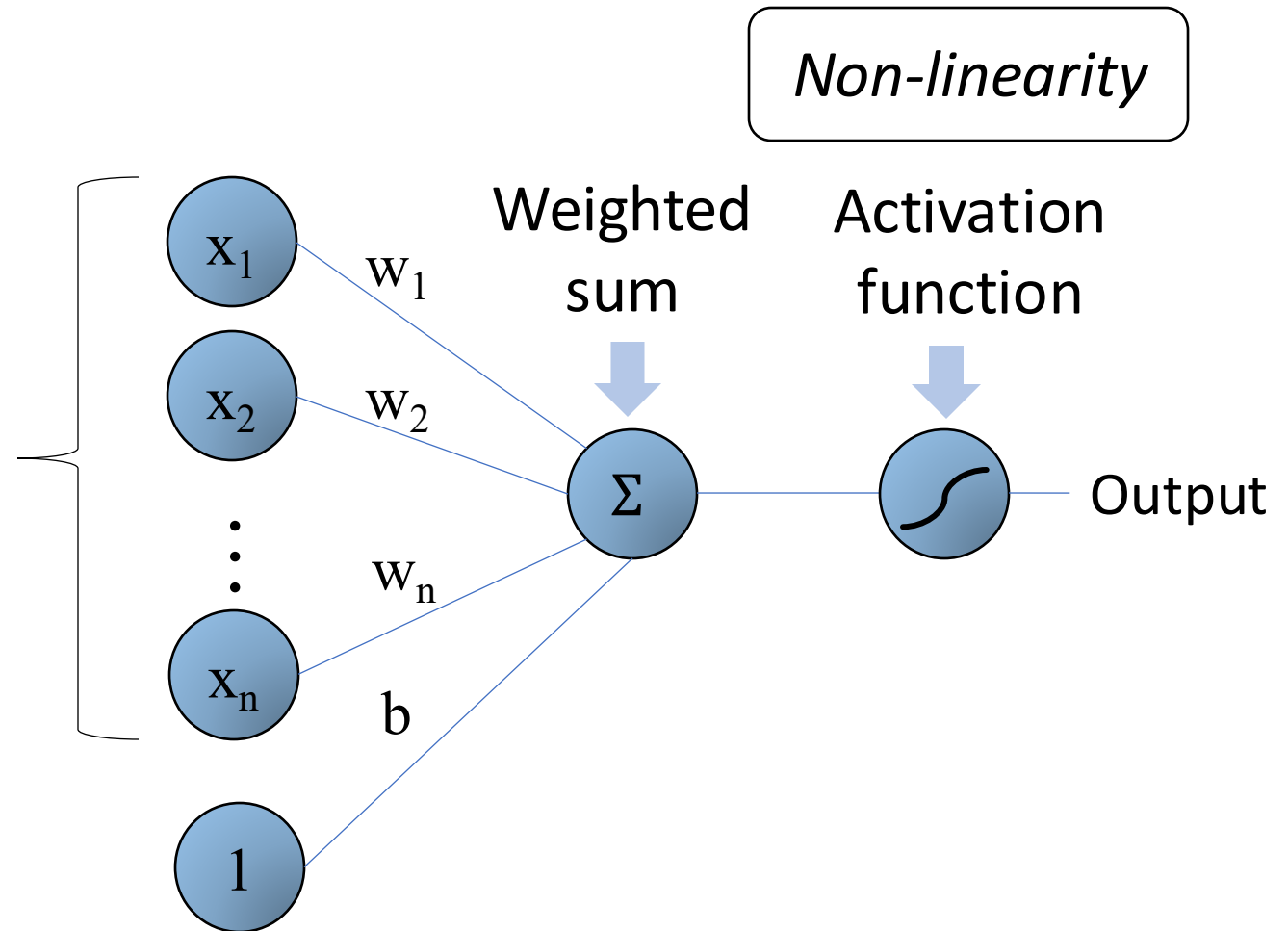
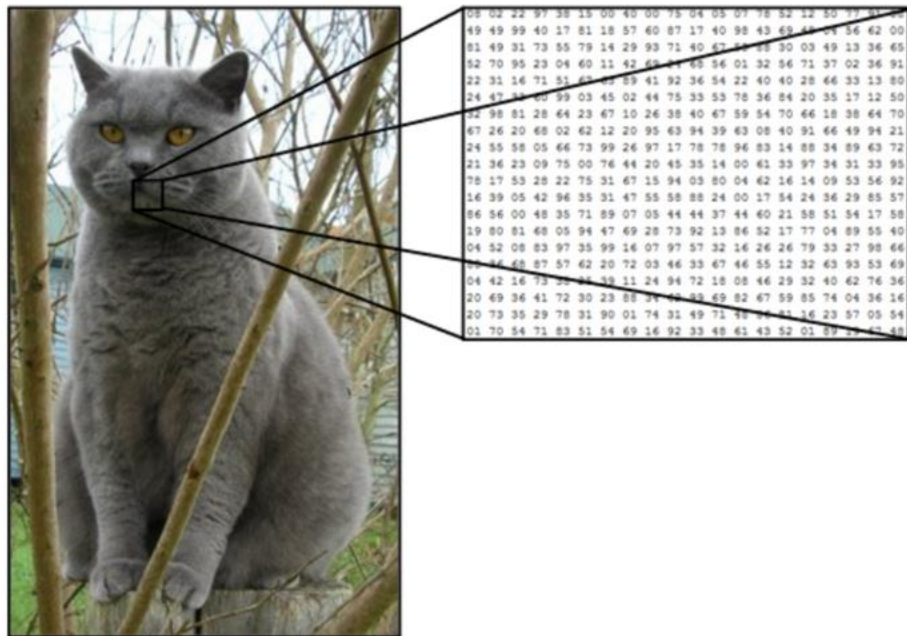


Outline

1. **Neural Networks: Basics**
2. Convolutional Neural Networks
3. Applications in MRI
4. Challenges and limitations

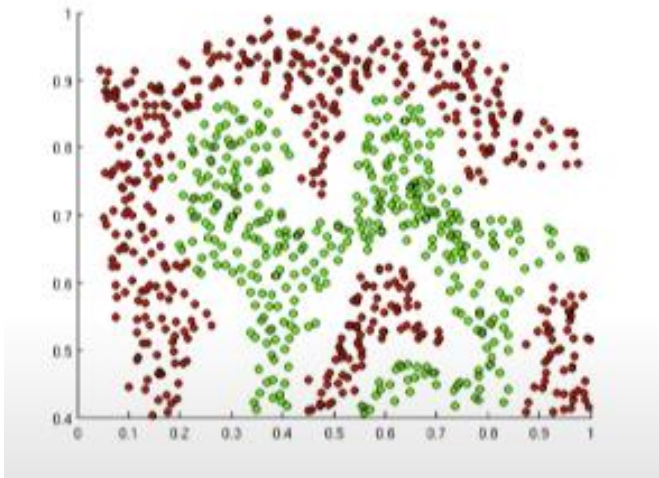


Artificial neuron

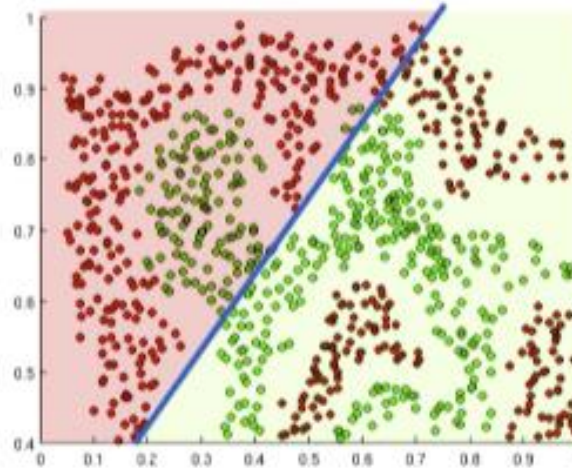


Why non-linearity?

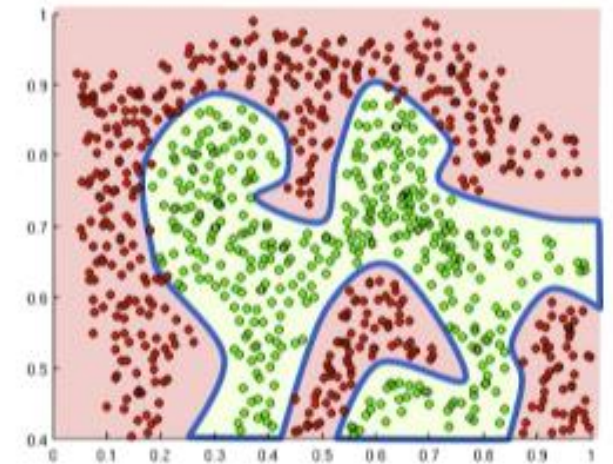
Can we separate the two groups?



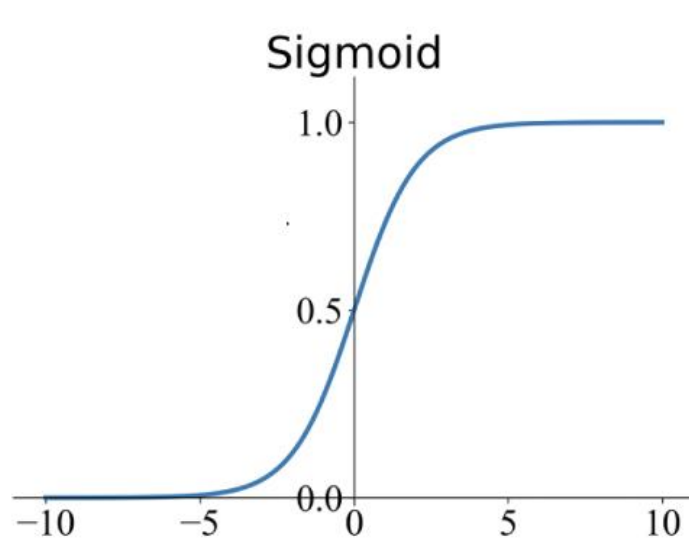
Without non-linearity



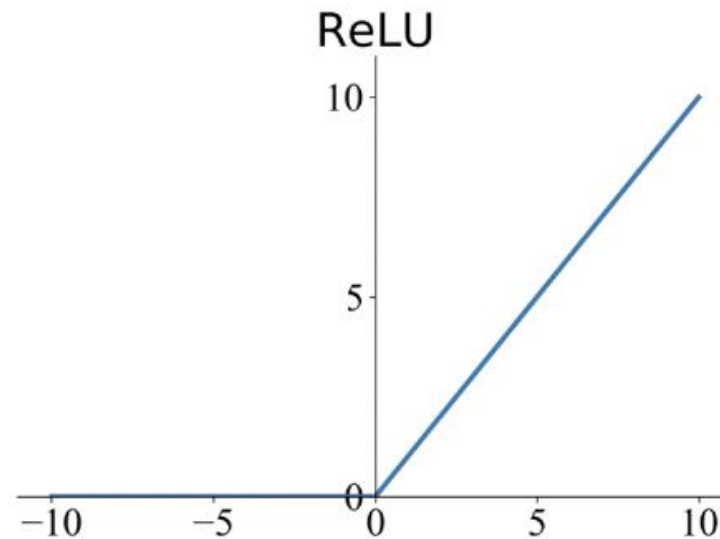
With non-linearity



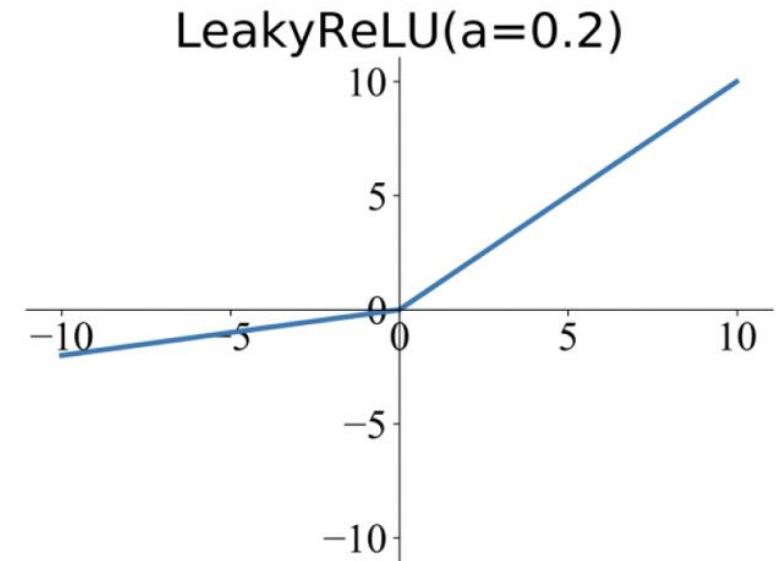
Activation functions



$$f(z) = \frac{1}{1 + e^{-z}}$$



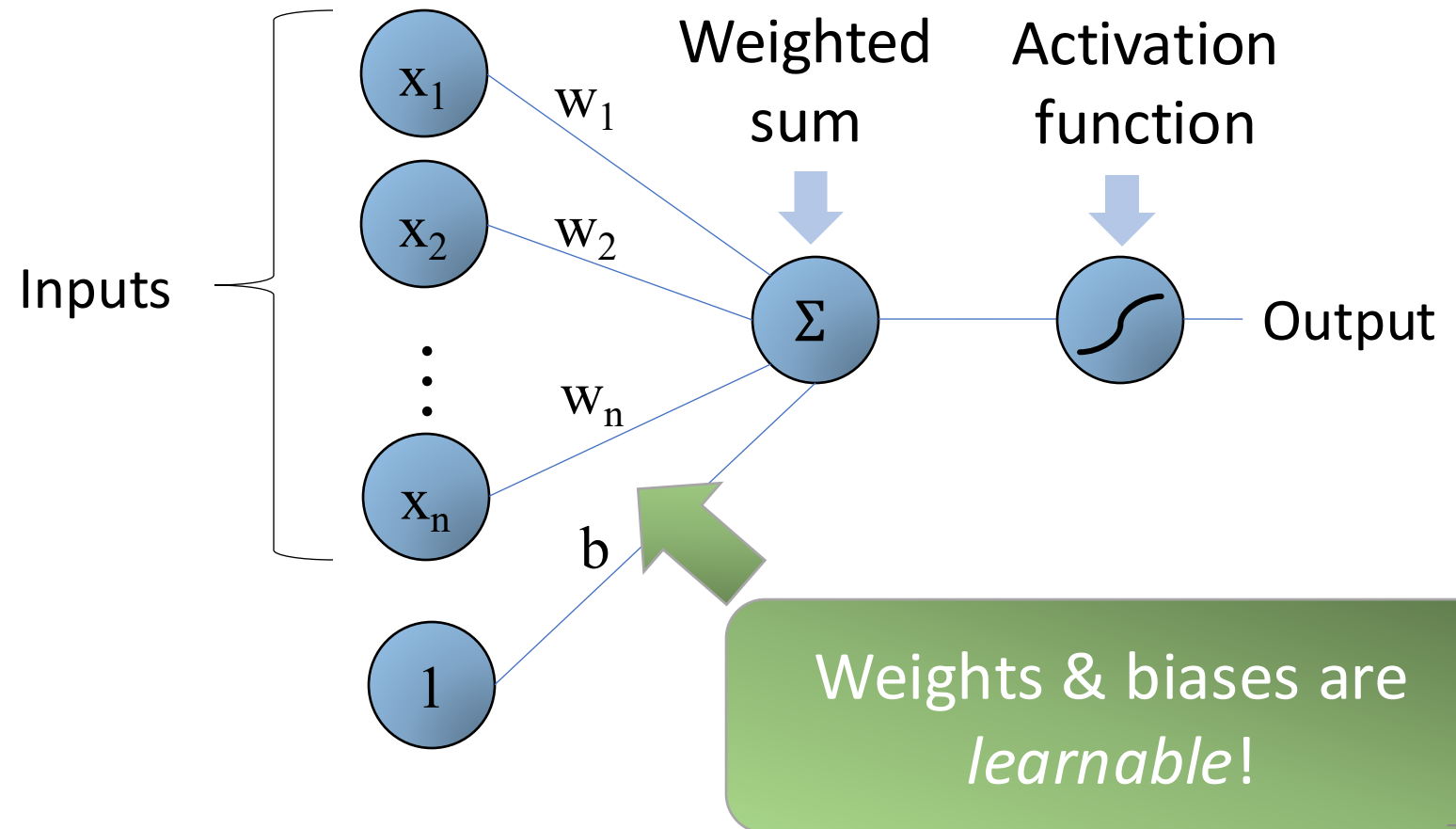
$$f(z) = \max(0, z)$$



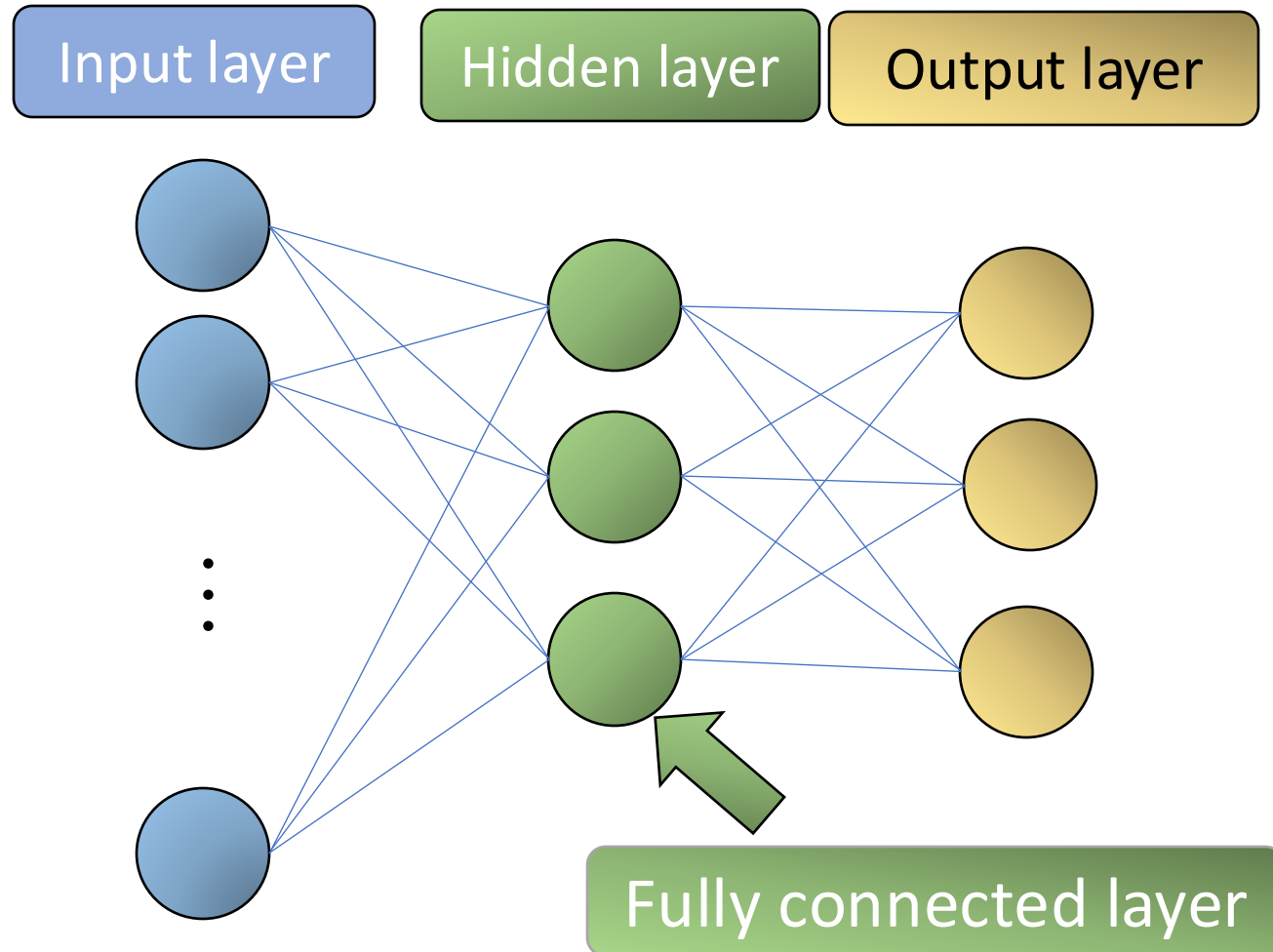
$$f(z) = \begin{cases} z & z > 0 \\ az & z \leq 0 \end{cases}$$

Artificial neuron

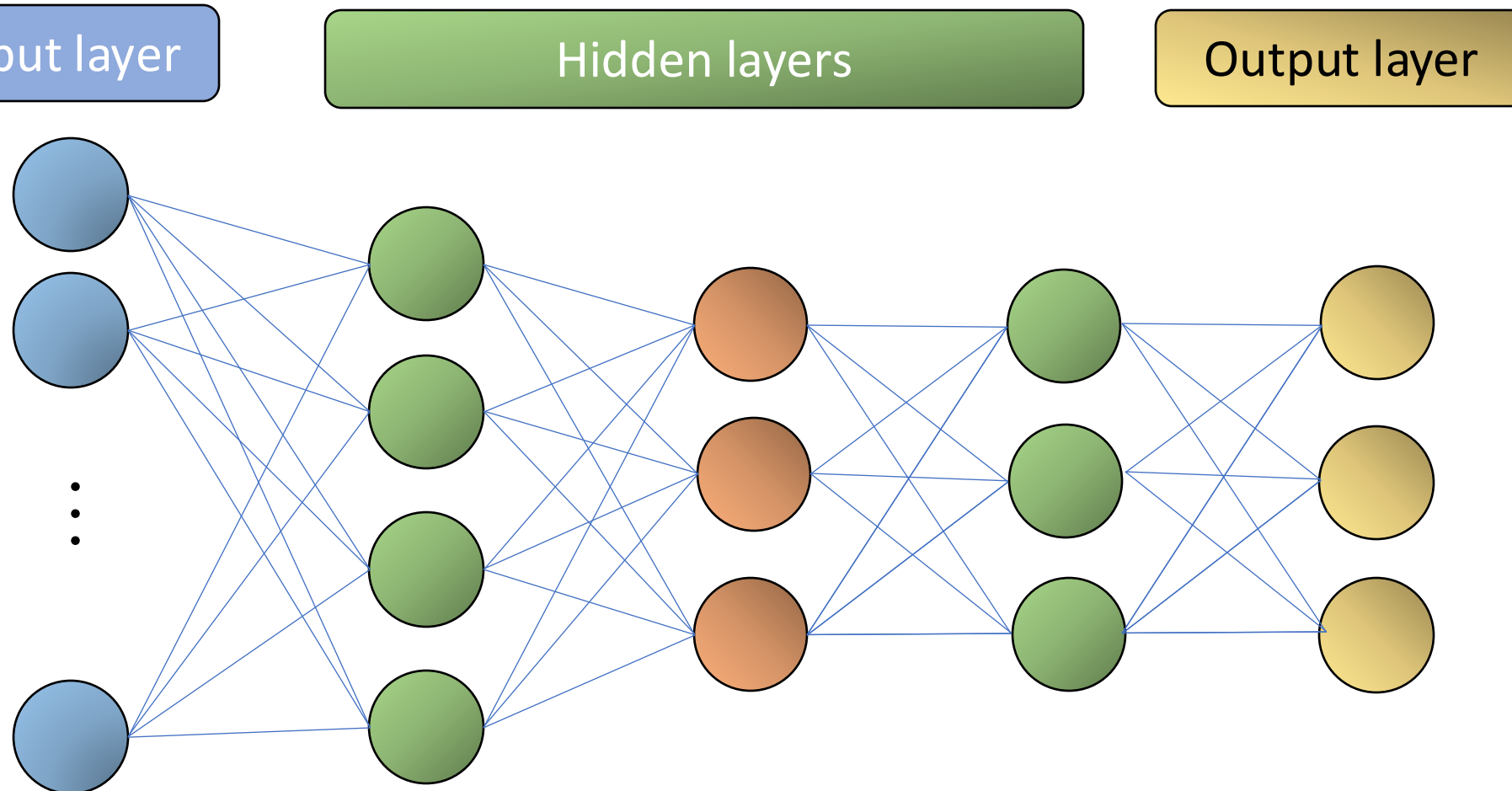
$$Y = f \left(\sum (input * weight) + bias \right)$$



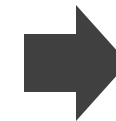
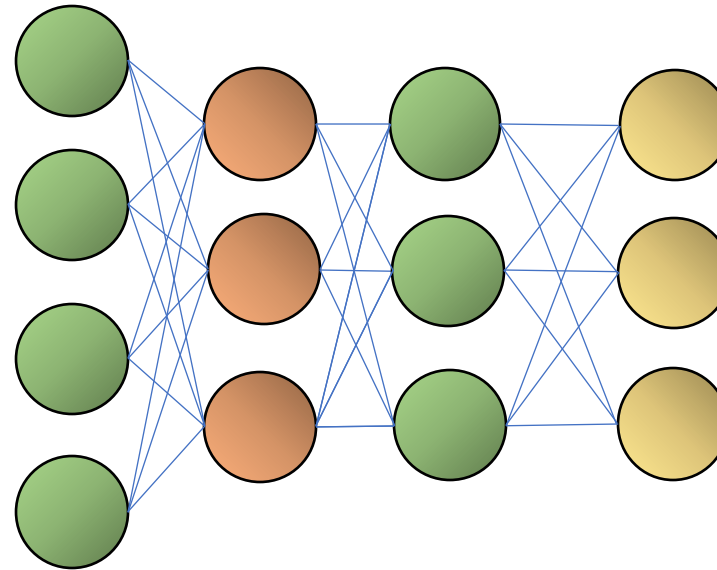
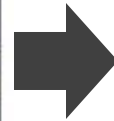
Simple neural networks



Simple neural networks



Setting up the problem



Bat
Plane
Boat
Car
Plane
...

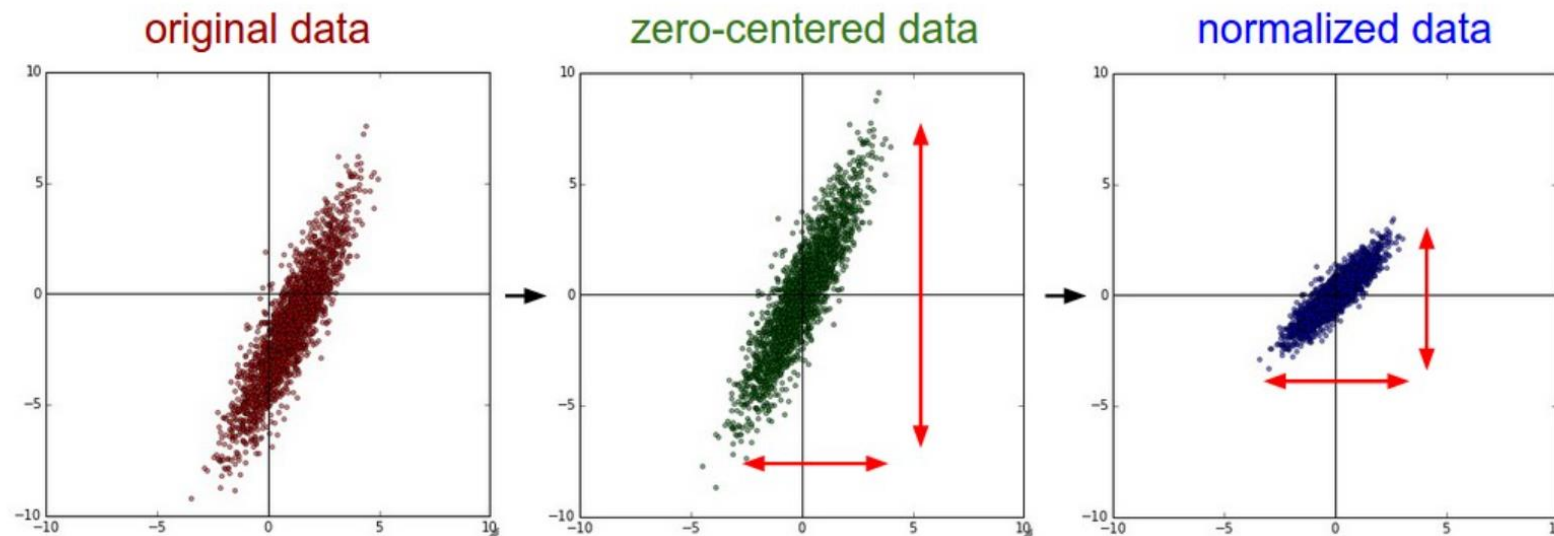
Setting up the problem

Database of input-output pairs

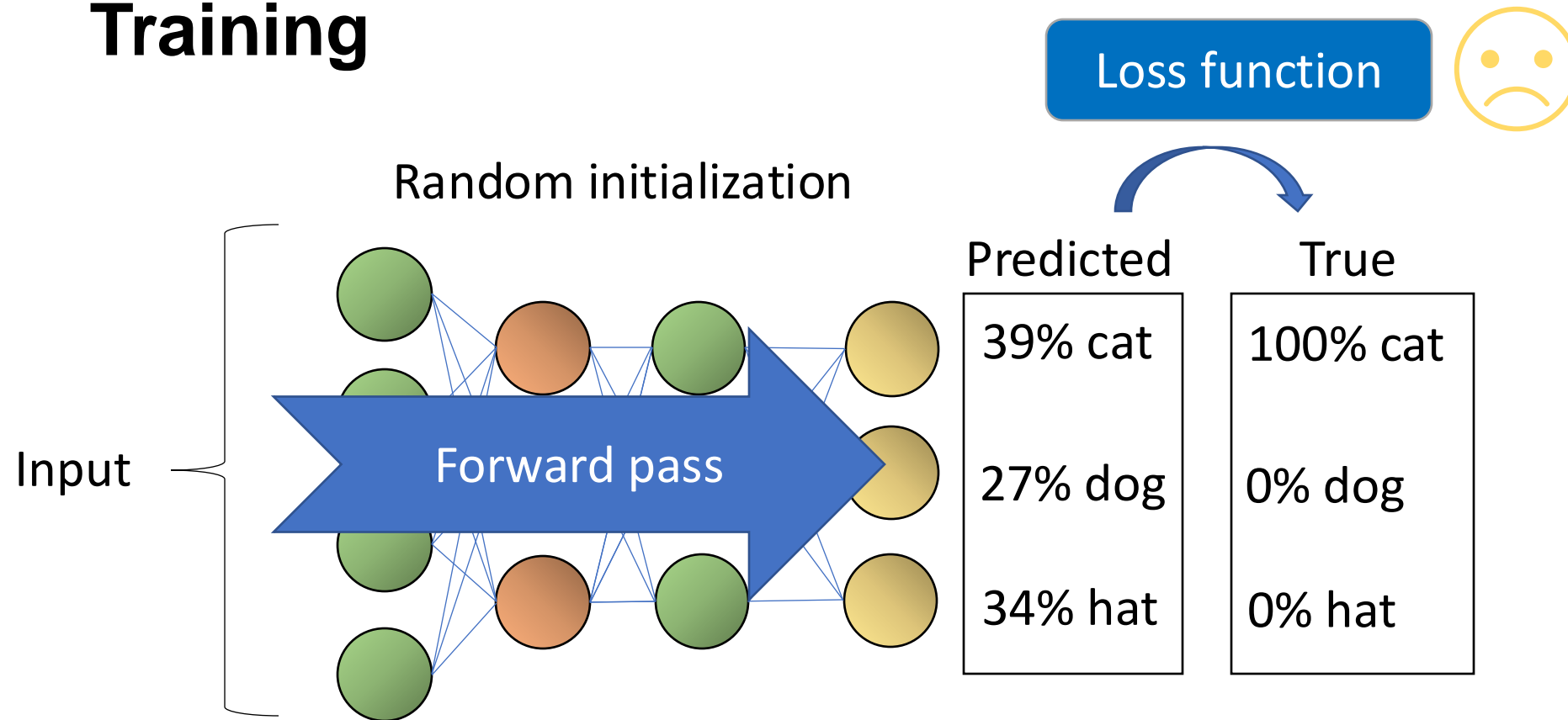
- ImageNet, CIFAR10, ...

Initial processing steps

- subtract mean, normalize, ...



Training



Training: Loss functions

Cross-entropy loss - useful for classification

$$\mathcal{L}_{CE} = - \sum_{i=1}^n t_i \log(p_i)$$

$i=1, \dots, n$ class

t_i true probability of the label

p_i predicted probability

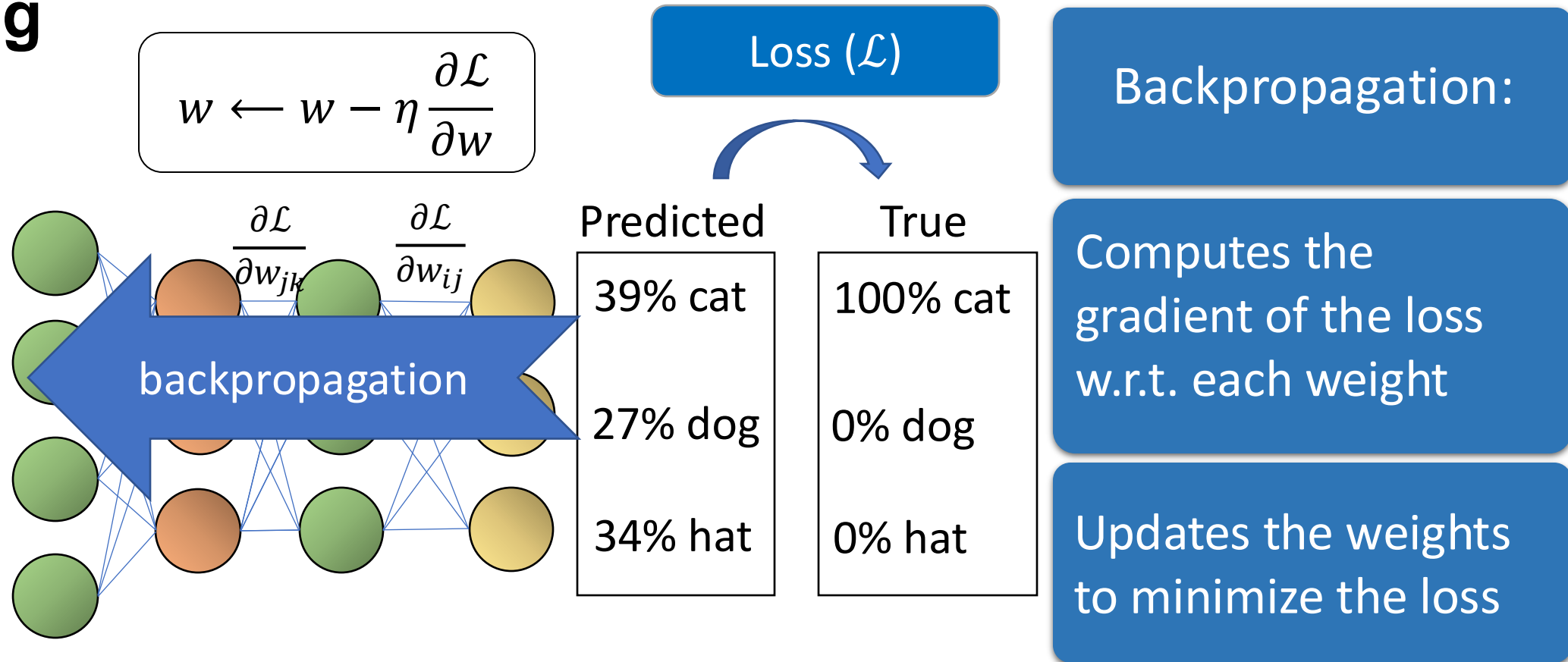
Mean Squared Error (MSE) loss - useful for regression

$$\mathcal{L}_{MSE} = \frac{1}{n} \sum_{i=1}^n (y_i - \tilde{y}_i)^2$$

There are many other loss functions!

MAE, VGG loss, ...

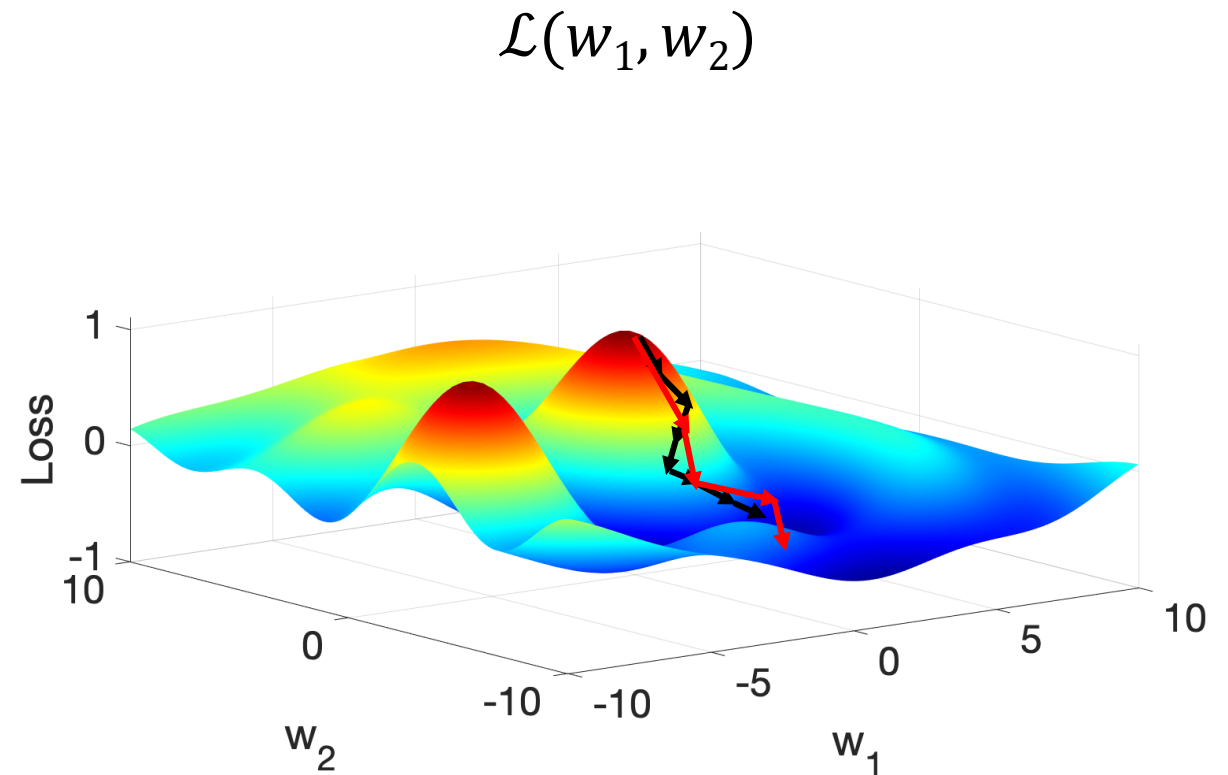
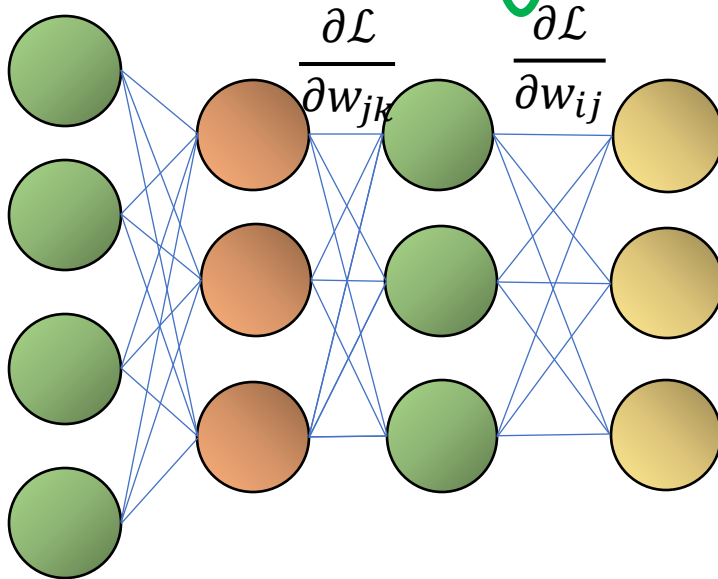
Training



Training

Learning rate

$$\eta \frac{\partial \mathcal{L}}{\partial w}$$



Optimization algorithms:
Gradient Descent, Adam, ...



Training

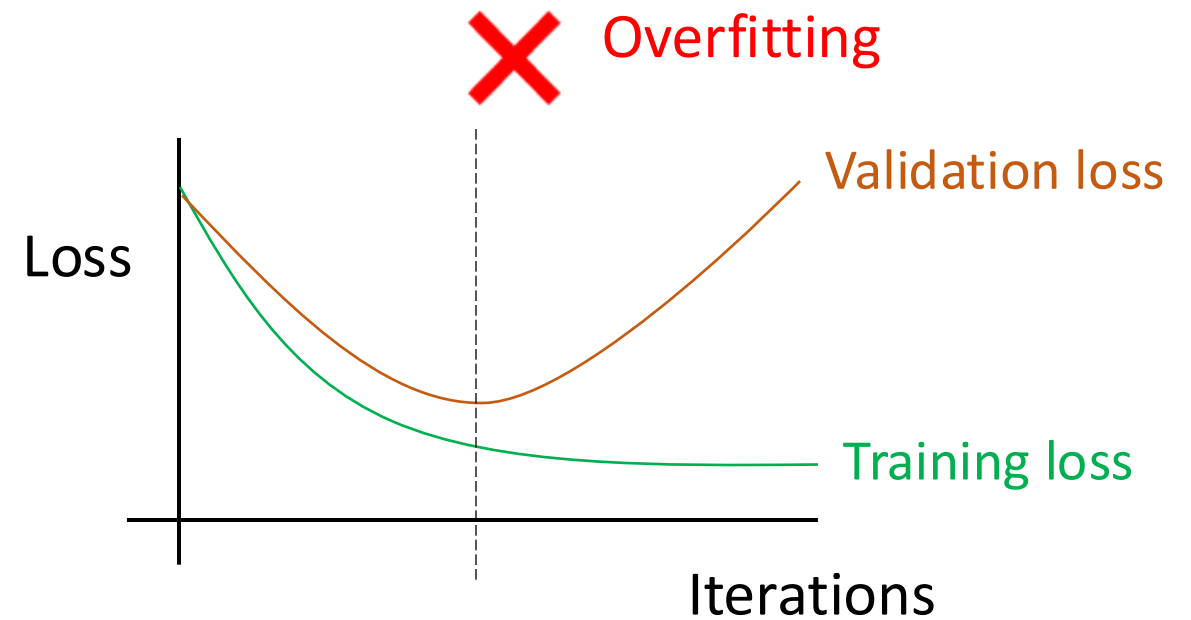
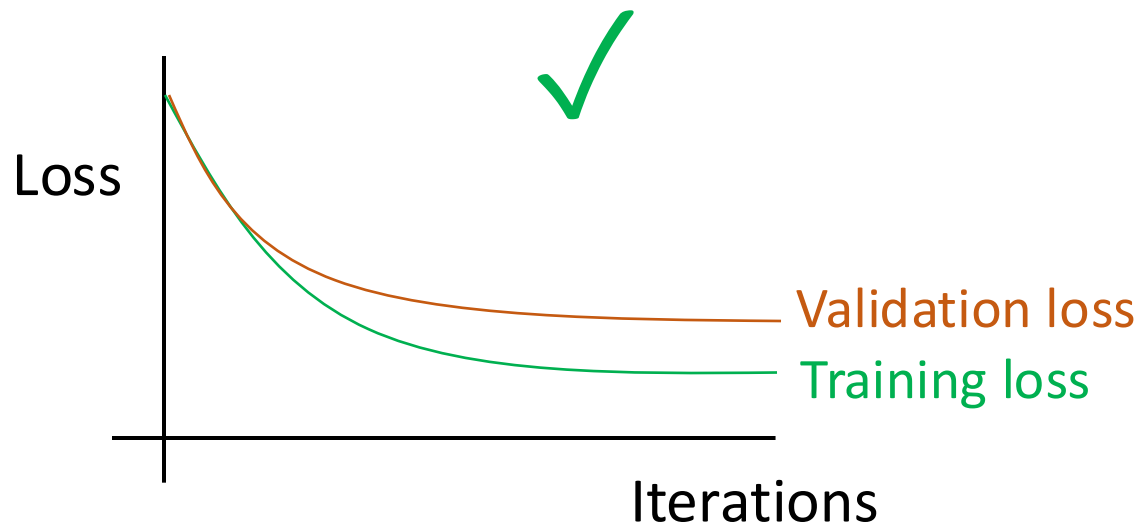
Split data: **train** / **validation** / **test**

For example: **70%** / **15%** / **15%**

What's the difference between validation and test?

- Validation data –
 - Used *during training* for model evaluation
 - Enables hyperparameter & architecture optimization
- Test data –
 - Should not be accessed during training!

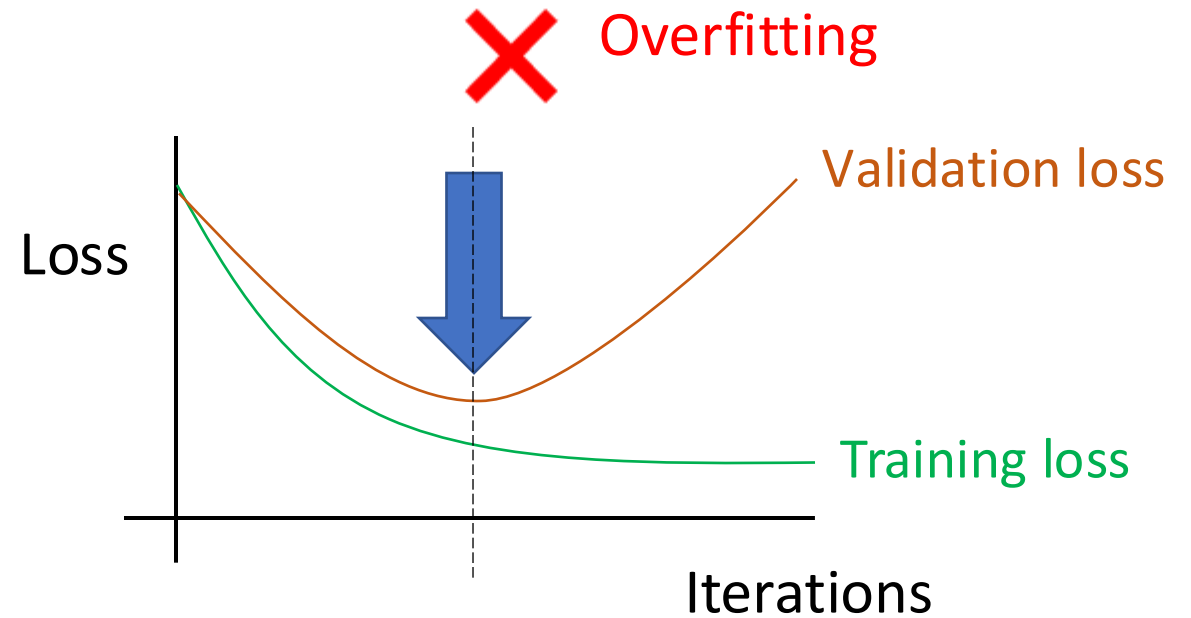
Training



Training

How to avoid overfitting:

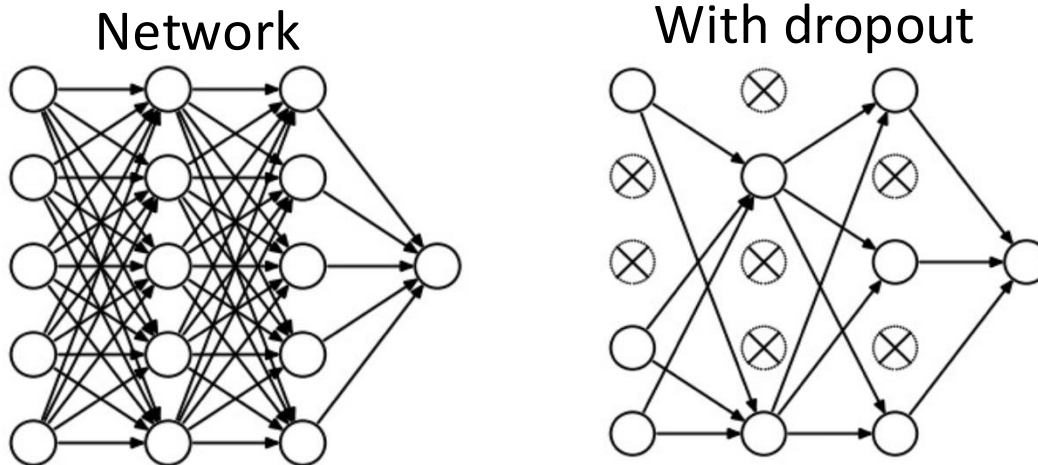
- Early stopping
- Data augmentation – rotations, scaling etc.



Training

How to avoid overfitting:

- Early stopping
- Data augmentation – rotations, scaling etc.
- Dropout
 - Some layers are randomly dropped



Training

How to avoid overfitting:

- Early stopping
- Data augmentation – rotations, scaling etc.
- Dropout
- Regularization

$$\mathcal{L} = \text{Error}(y, \tilde{y}) + \mathcal{R}(w)$$

- L1 regularization

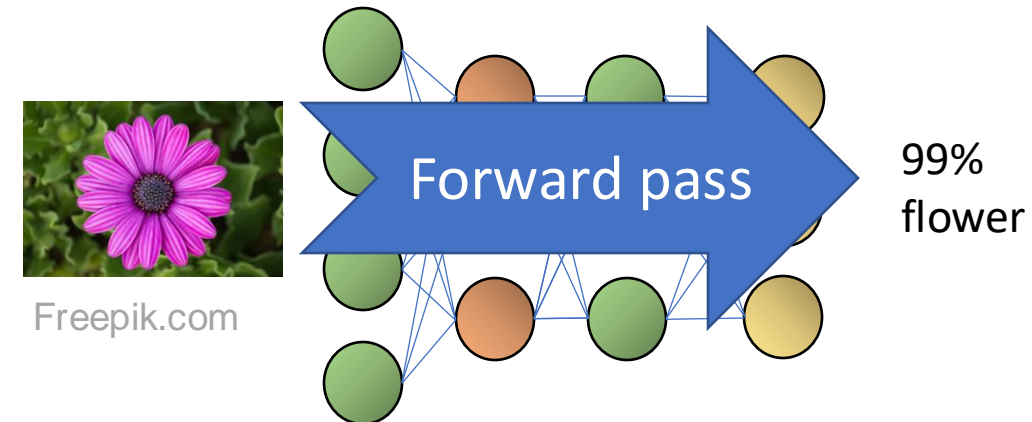
$$\mathcal{L} = \text{Error}(y, \tilde{y}) + \lambda \sum_i |w_i|$$

- L2 regularization

$$\mathcal{L} = \text{Error}(y, \tilde{y}) + \lambda \sum_i w^2$$

Test

- Test data – new input
- No dropout



Outline

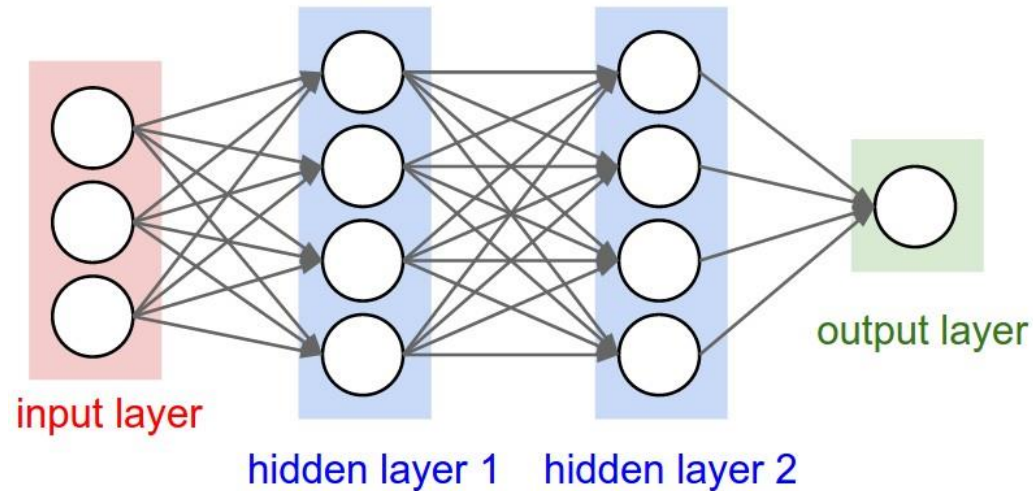
1. Neural Networks: Basics
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Why CNNs?

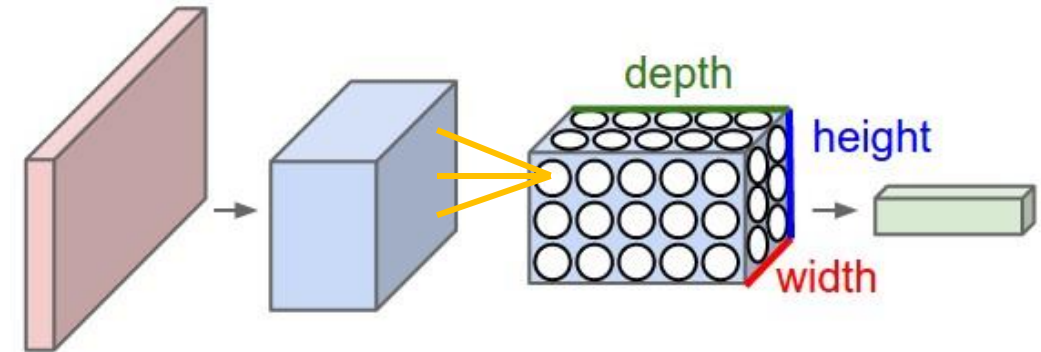
- Fully connected neural networks don't scale well to large images
 - Typical image: 300x200 pixels x 3 channels (RGB)
 - Full connectivity – computationally demanding, wasteful
- CNNs are more suited to images

Regular network



- Full connectivity

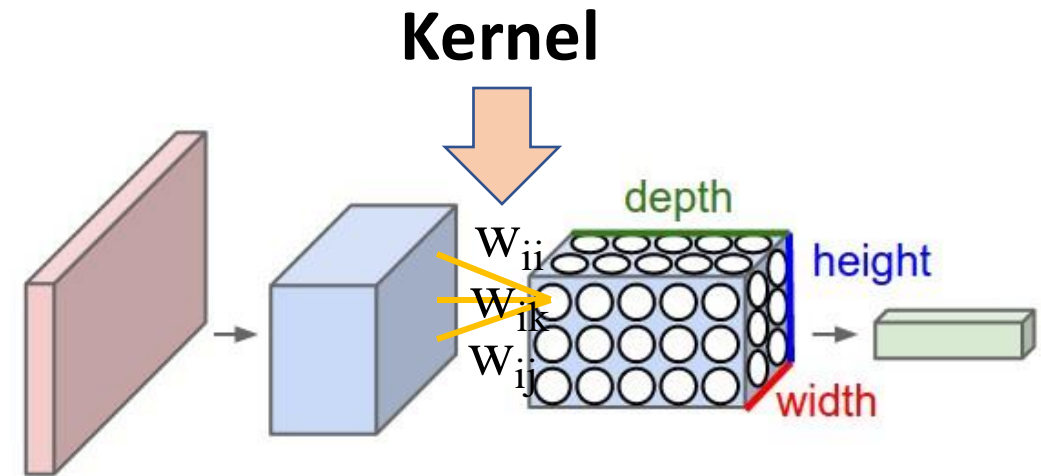
CNN



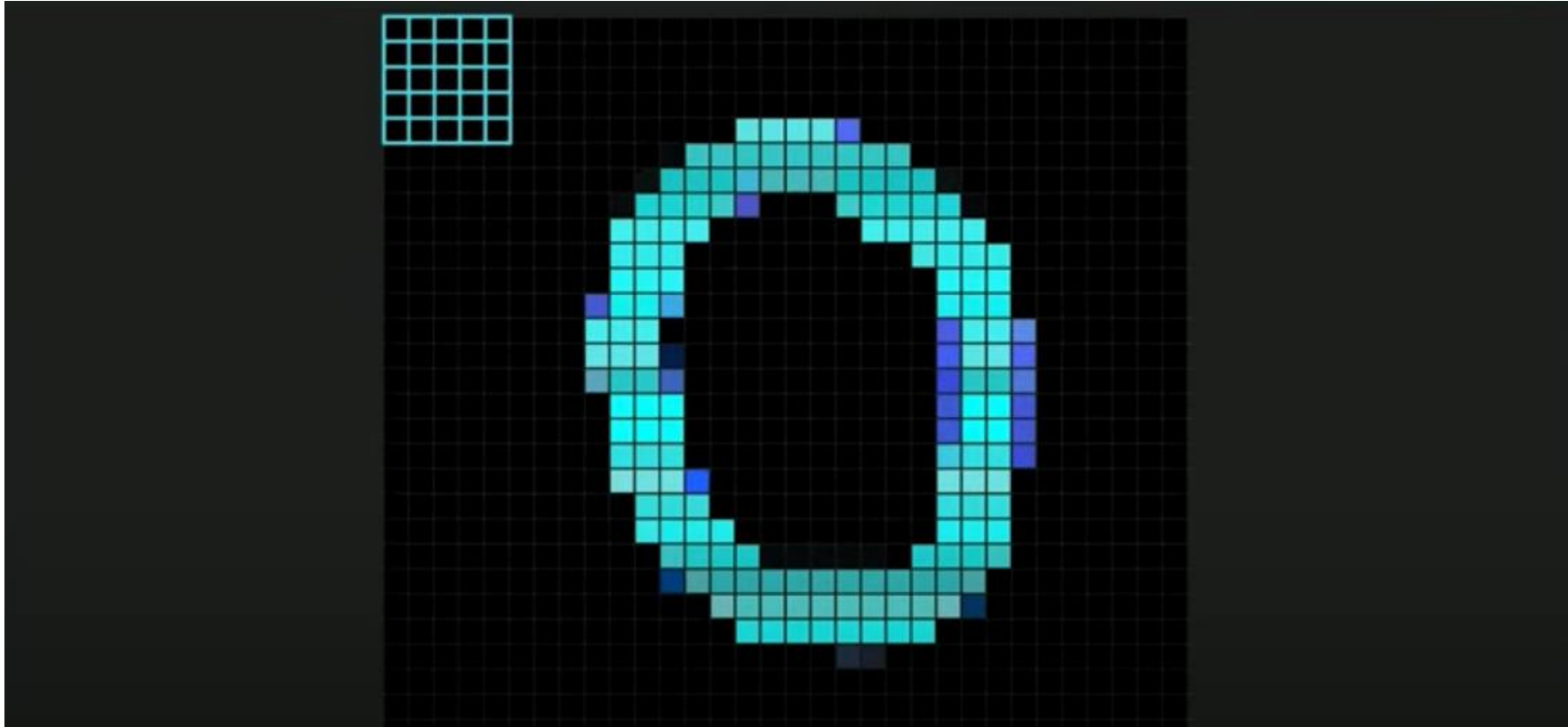
- Connections to only *a few* neurons
- Layers have depths (3D structure)
- Computationally efficient
- Suitable to high-dimensional data

- **Conv layer**

- Computes a sliding dot-product of the input and the kernel (weights matrix)
- Produces a feature map



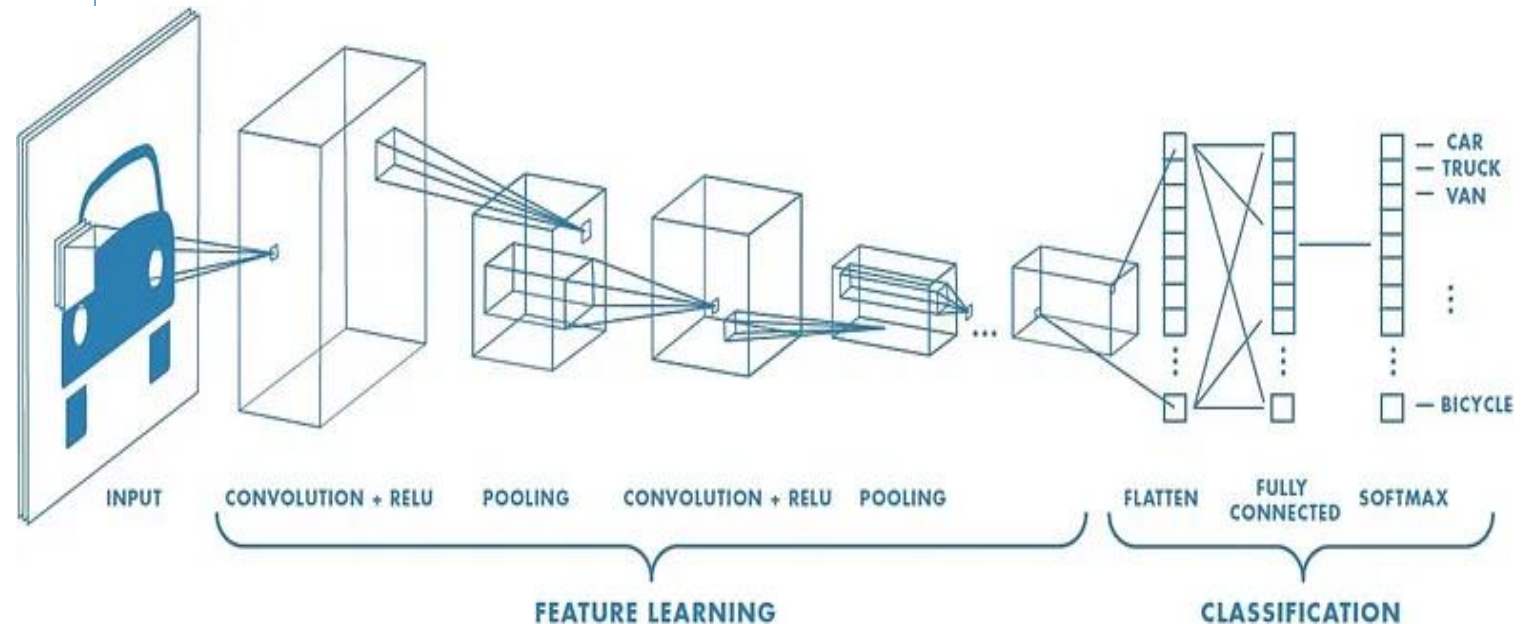
- **Conv layer**



Futurology <https://www.youtube.com/watch?v=pj9-rr1wDhM>

- **Conv layer**
- **ReLU layer**
 - Element-wise activation function
- **Pooling layer**
 - Down-sampling operation
 - Example: max pooling
 - Benefit: translation invariance
- **Fully Connected layer**

Repeated several times



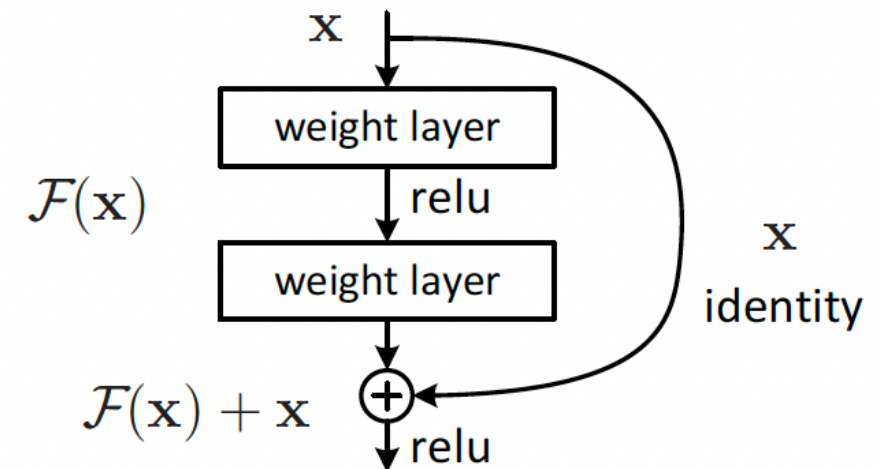
S. Saha towardsdatascience.com

Goodfellow et al., *Deep Learning*, MIT Press (2006)

Basic architectures for medical imaging

ResNet

- Very deep NNs are hard to train due to vanishing gradients
- Introduced
 - Residual blocks
 - Skips connections
- Enables training very deep networks
→ excellent performance (SoTA in 2015)

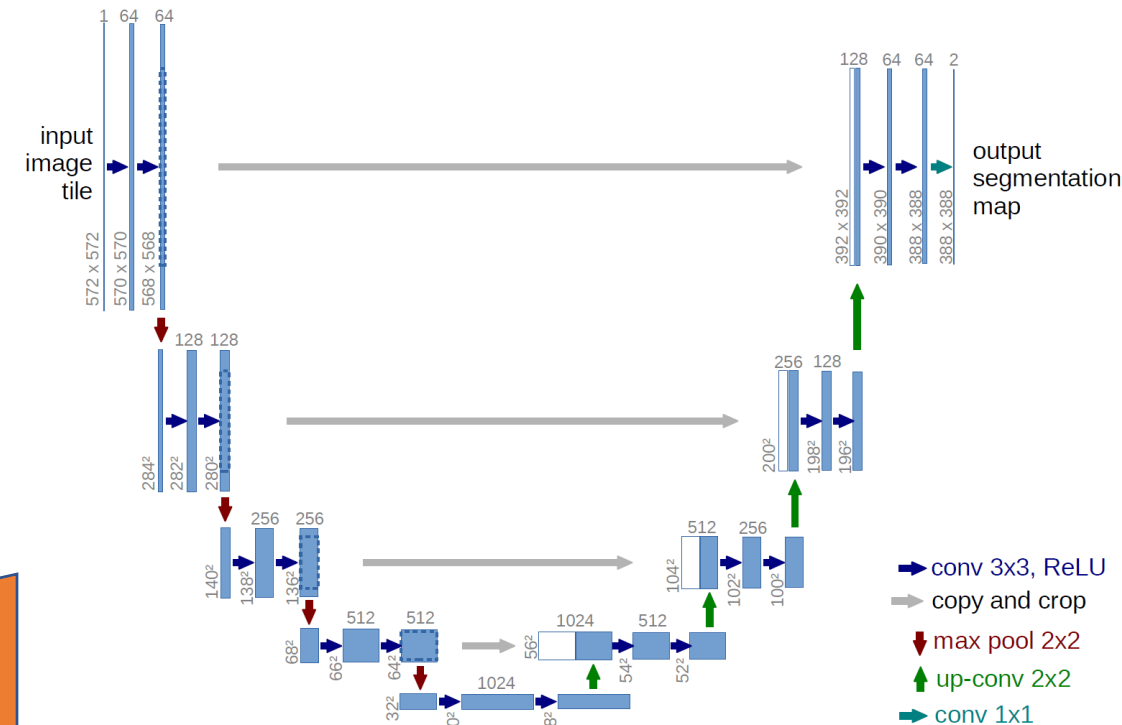
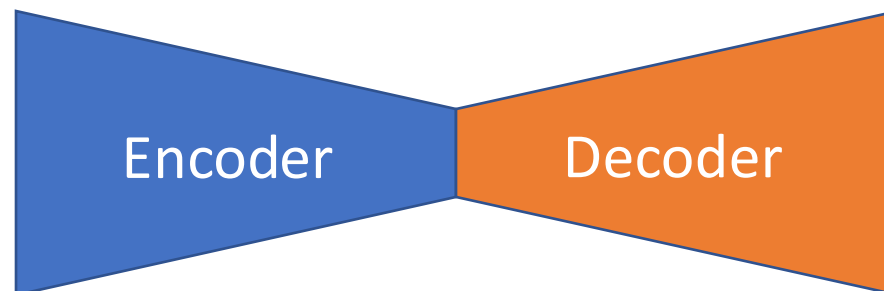


He, Kaiming, et al. "Deep residual learning for image recognition." *CVPR* 2016

Basic architectures for medical imaging

U-NET

- CNN, encoder-decoder
- Down-sampling & up-sampling
- Skip connections
- Developed for segmentation
- Highly popular



There are many other architectures!

- AlexNet (2012)
- Recurrent Neural Networks (RNNs)
- Long Short Term Memory (LSTM)
- VGG
- AutoEncoders
- Generative Adversarial Networks (GANs)
- Diffusion models
- Vision Transformers

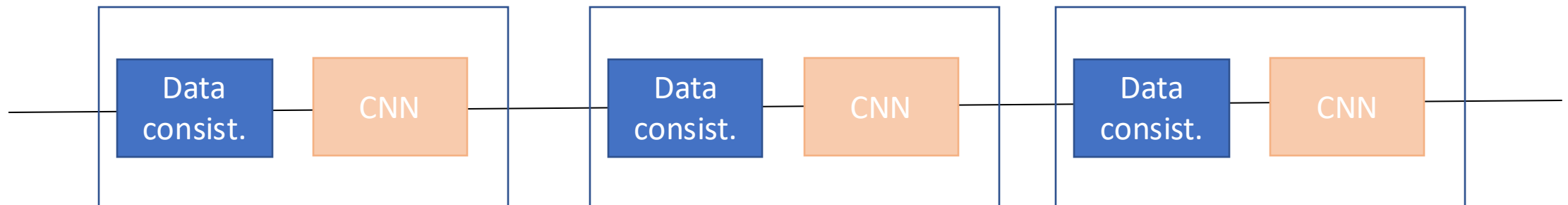
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Image reconstruction

- Aim: scan acceleration by reconstruction from sub-sampled k-space data
- Early DL approaches: **data-driven**, image-to-image
- Current focus: **physics-guided/model-based iterative methods**
 - Unrolled network:

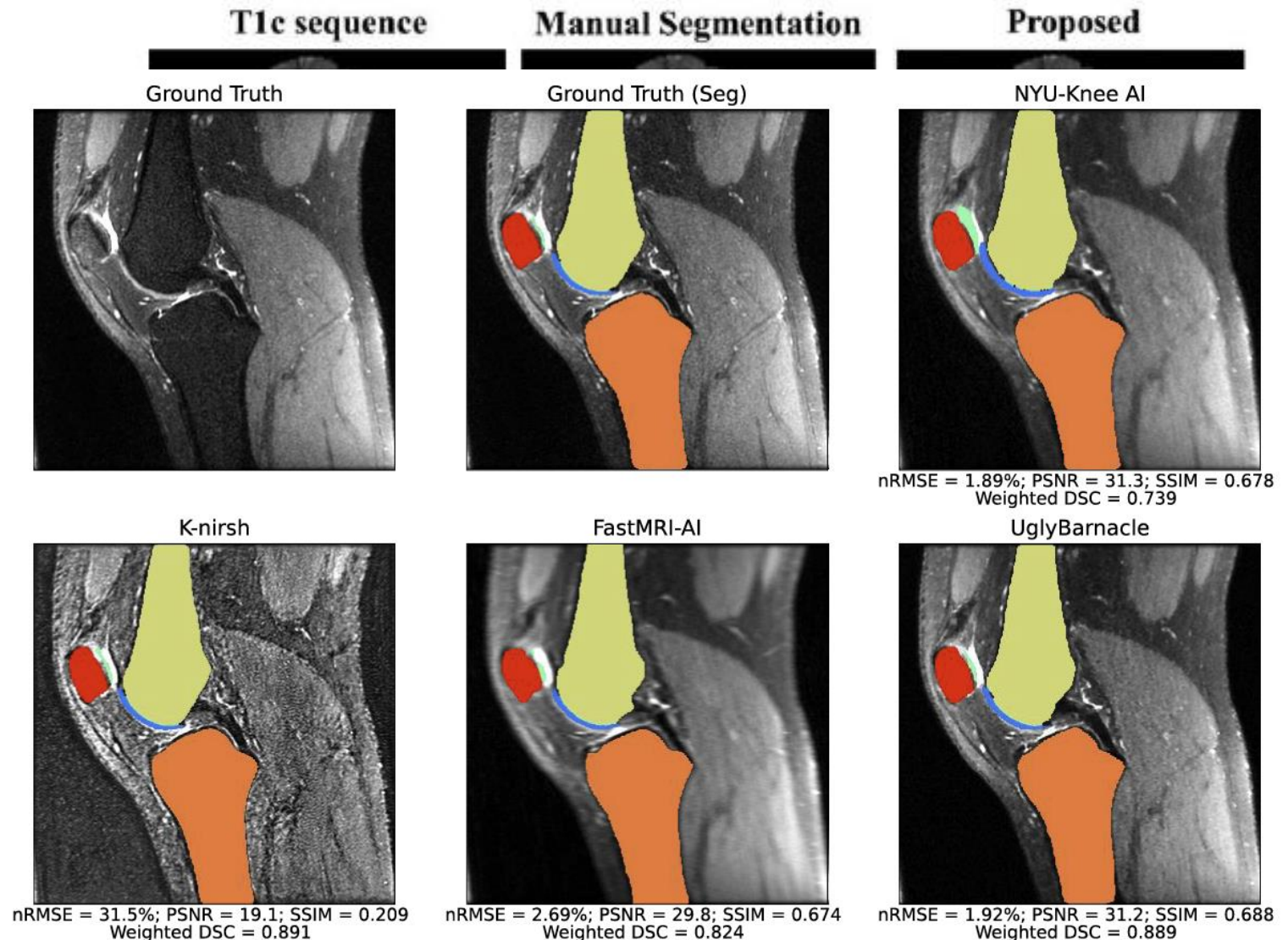


Yang et al., NIPS 2016; Wang et al., ISBI 2016; Schlemper et al., IEEE TMI, 2016; Zhu et al., Nature 2017; Hammernik et al., MRM 2018; Aggarwal et al. IEEE TMI 2018; Jalal et al., NeurIPS 2021

Segmentation

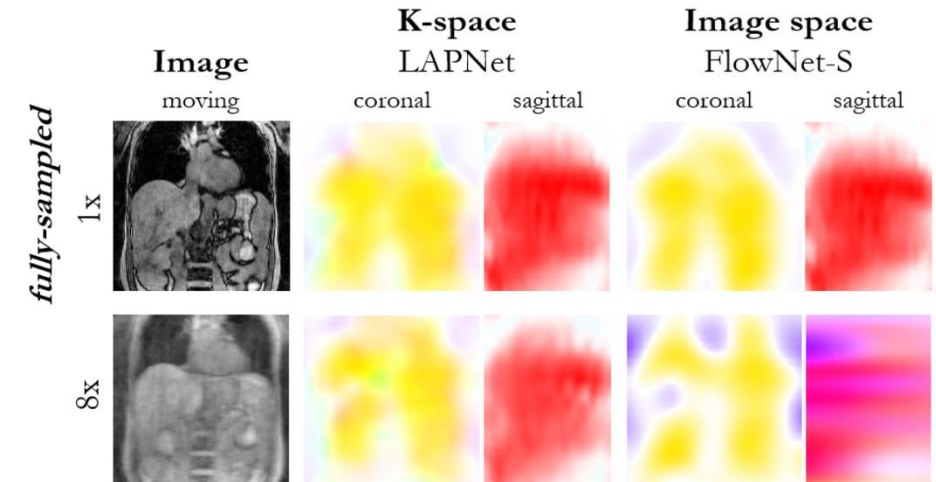
Brain tumor segmentation using CNNs [1]

K2S Challenge: from 8x under-sampled k-space to segmentation[2]

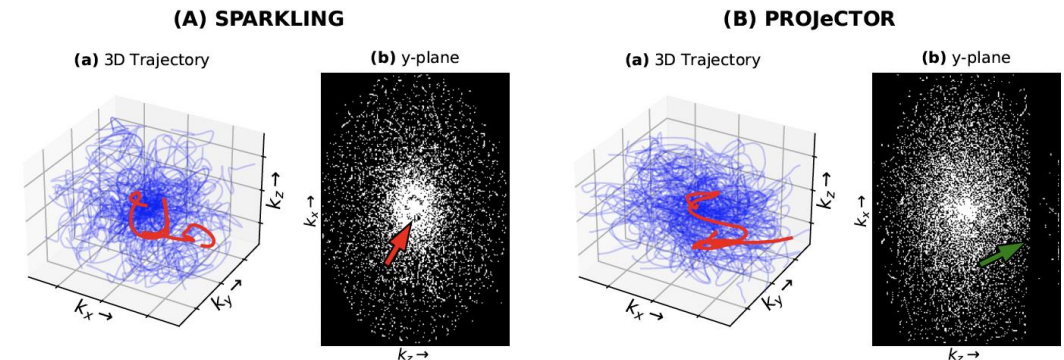


Other applications

- Image registration
- Motion correction
- Automated pulse sequence design
- Protocol optimization
- Contrast synthesis
- Quantitative MRI
- Classification



Kustner et al., IEEE TMI 2021



Chaithya & Ciuciu, Bioengineering, 2023

Reviews: Lundervold, et al. *Zeitschrift für Medizinische Physik* (2019); Mazurowski et al., *JMRI* (2019); Alzubaidi et al. *Journal Bf big Data* (2021); Hammernik et al., *Sig Proc. Mag.* (2023) Spieker et al. *arXiv* (2023)

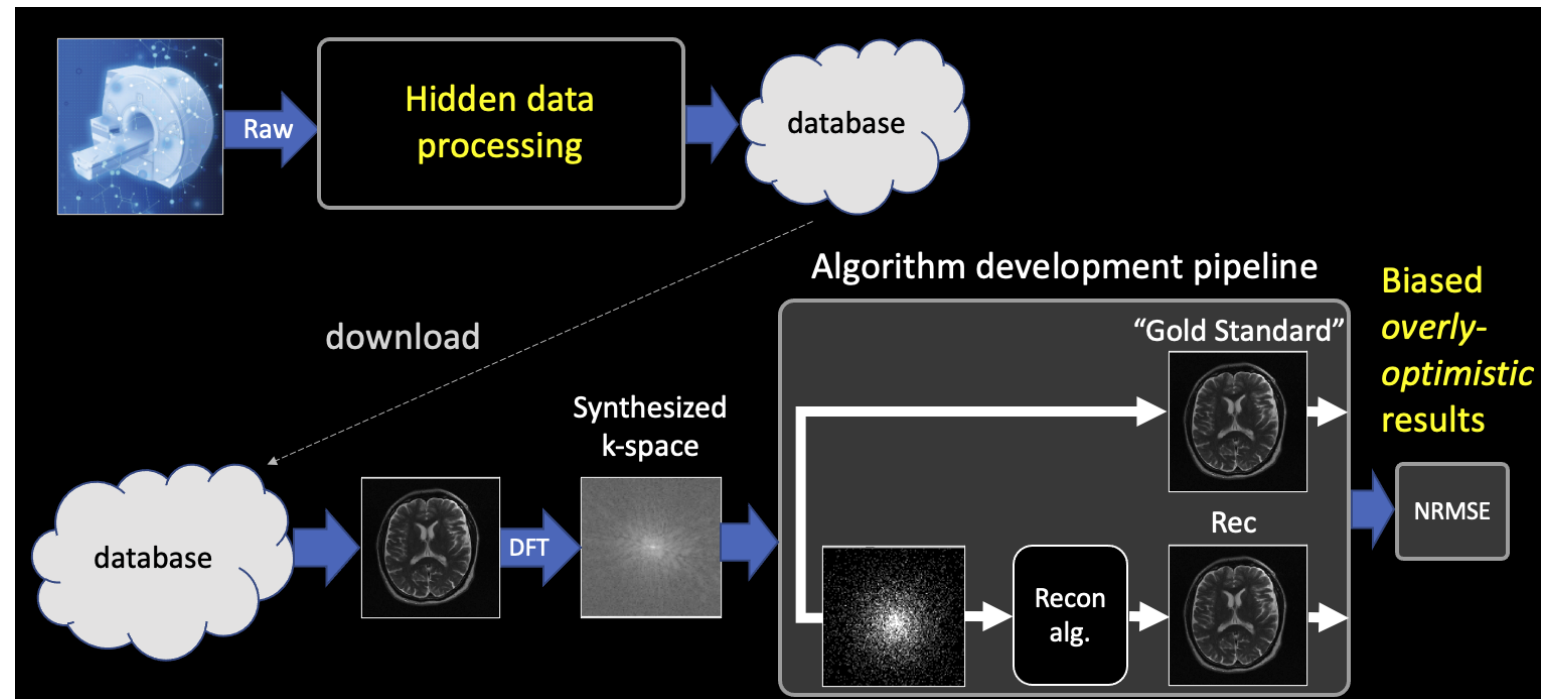
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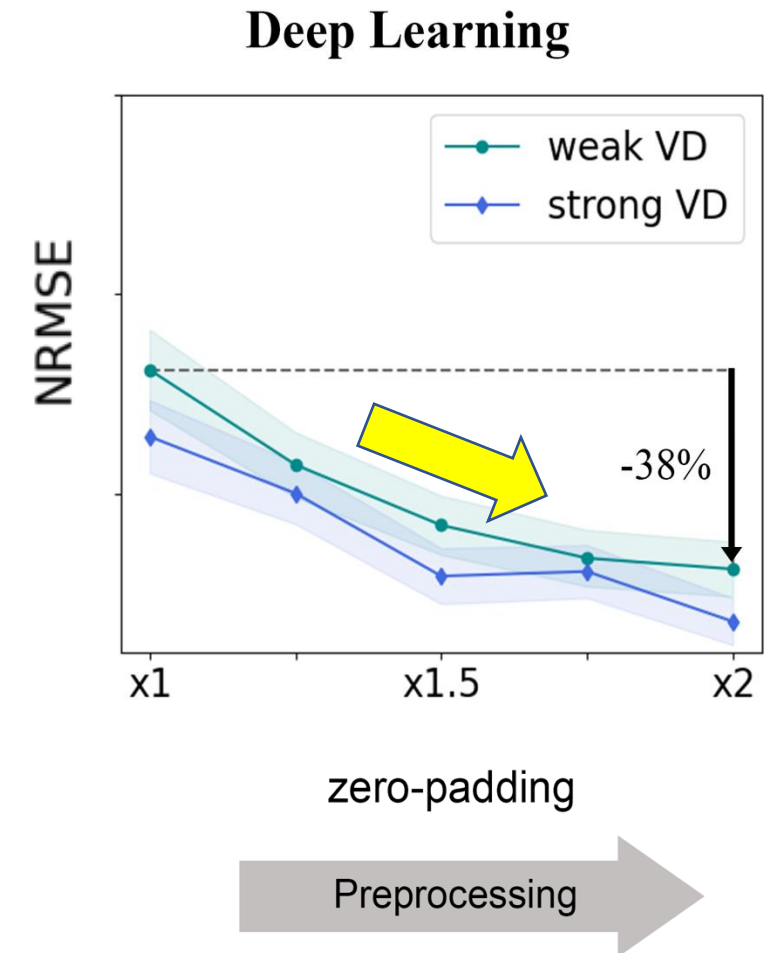
Limited data availability

- DL is data-hungry, but training data are scarce
- **Common workaround: "off-label" data use**
- **Biased, overly optimistic results**



Limited data availability

- DL is data-hungry, but training data are scarce
- **Common workaround: "off-label" data use**
 - Biased, overly optimistic results
 - Algorithmic failure for real-world data

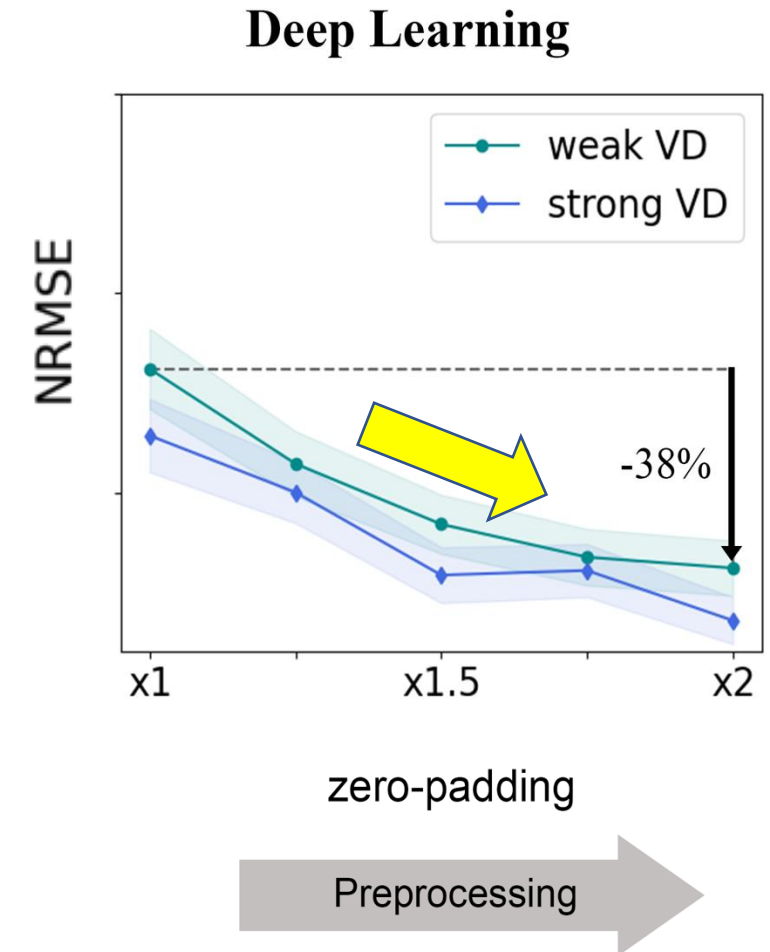


Limited data availability

- DL is data-hungry, but training data are scarce

Practical Solutions

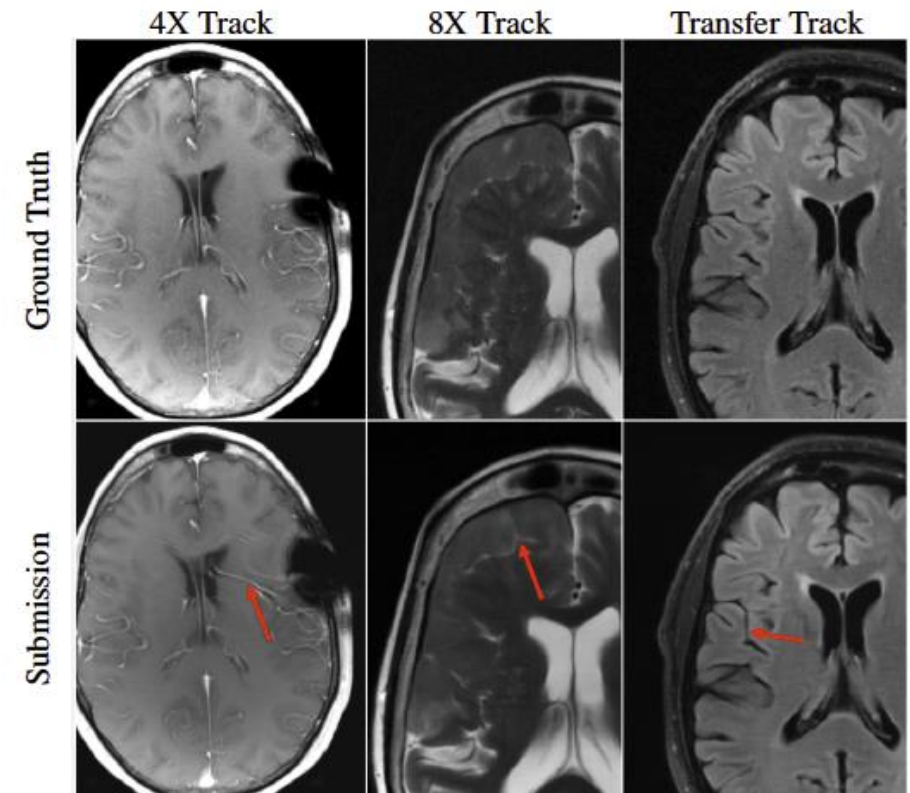
- Augmentation
- Transfer learning
- Pre-training on other data & fine-tuning
- Training on synthesized/simulated data
- If using processed data: *report* the preprocessing



Hallucinations

- DL can produce *hallucinated structures which look realistic* – hard to detect!
- Open problem
- Uncertainty estimation may help

2nd FastMRI challenge



Muckley et al., arXiv, 2020

Summary

Deep learning is very powerful

Many opportunities for
novelty and breakthroughs

However, problems must be
addressed!



My Lab has Open positions!



Technion

Team



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Our recent publications

Review paper

[Deep learning for accelerated and robust MRI reconstruction](#)

Reinhard Heckel, Mathews Jacob, Akshay Chaudhari, Or Perlman, Efrat Shimron,
(MAGMA 2024)

[K-band: Self-supervised MRI Reconstruction via Stochastic Gradient Descent over K-space Subsets](#)

Frederic Wang, Han Qi, Alfredo De Goyeneche, Michael Lustig, Efrat Shimron (arXiv
2023)

[Implicit data crimes: Machine learning bias arising from misuse of public data](#)

Efrat Shimron, Jonathan Tamir, Ke Wang, Michael Lustig