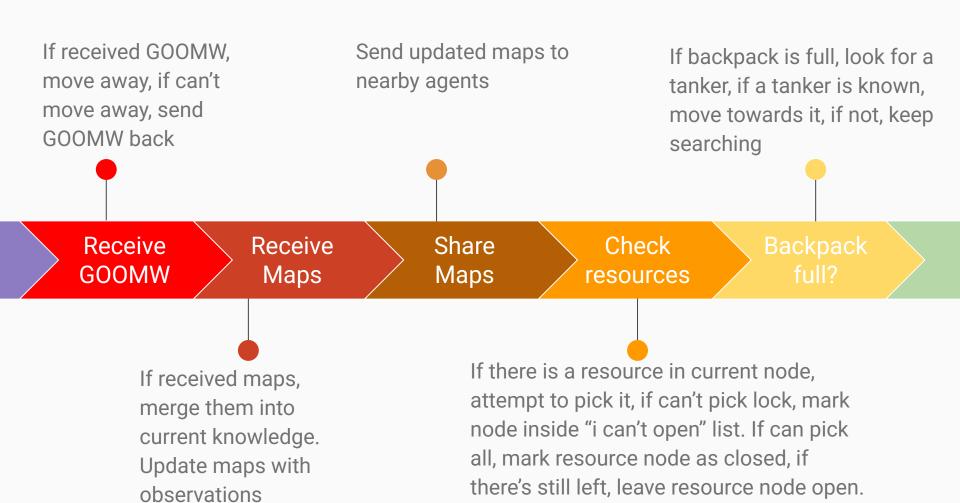
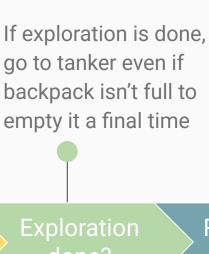
PROJET FOSYMA - DEDALE

Tarık Ege EKEN - 21110611 - Groupe 13 11/05/2025

SearchBehaviour Algorithm





If exploration is fully done, and no resources are left in backpack to empty, check expert list

If exploration is done, all resources deposited, backpack empty, everyone experts, go int dormant state

done?

Resource known?

Exploration done?

Everyone expert?

Dormant state

If backpack is not full, and there is a known resource left, go pick it up, if not, keep searching for resources

If not every other agent has access to the full exploreMap yet, move around randomly trying to get into contact with them and make everyone experts.

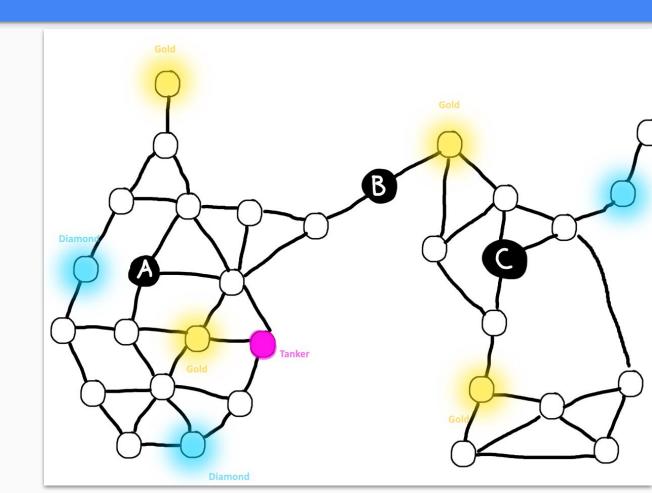
StayOutOfWayBehaviour Algorithm

If received GOOMW, move away, if can't move away, send GOOMW back

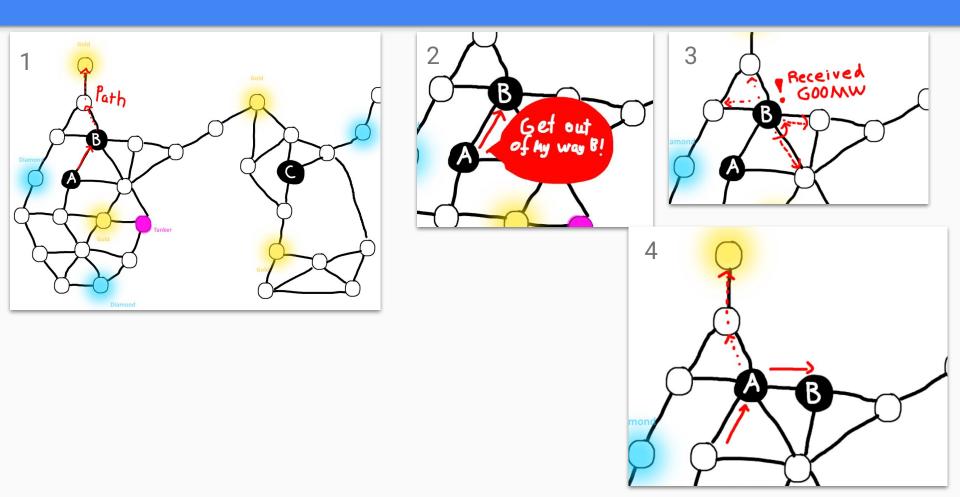


GOOMW Treatment Scenarios

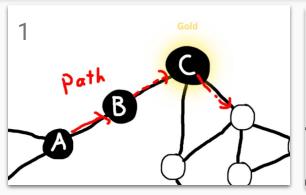
Demonstration

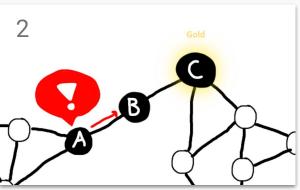


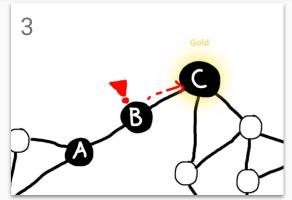
Standard GOOMW Case

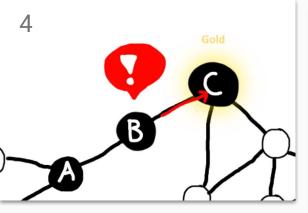


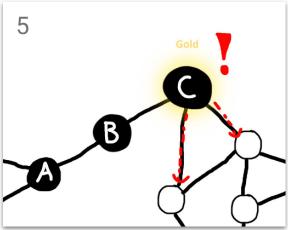
Edge Case (Train situation)

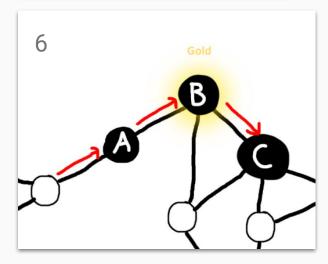






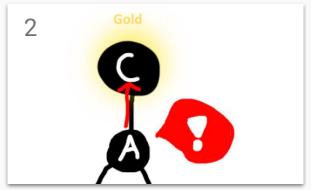


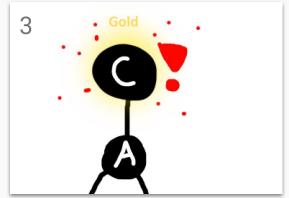


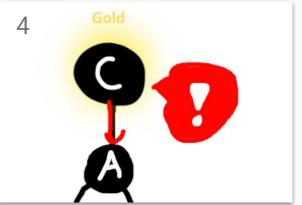


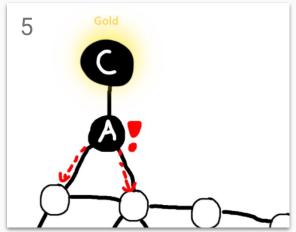
Edge Case (Dead end situation)

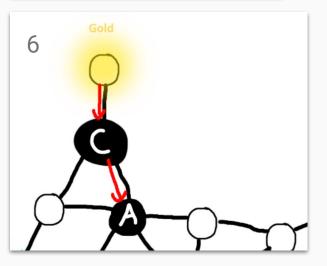












Conclusion

Key Features

- Collision avoidance with GOOMW
- Expert verification
- Spontaneous + autonomous decision making

Problems

- Bug where turn speed goes up during collision avoidance?
- Isn't great against wumpuses
- Too many messages
- Some reliance on luck, some edge cases for blocking still happen