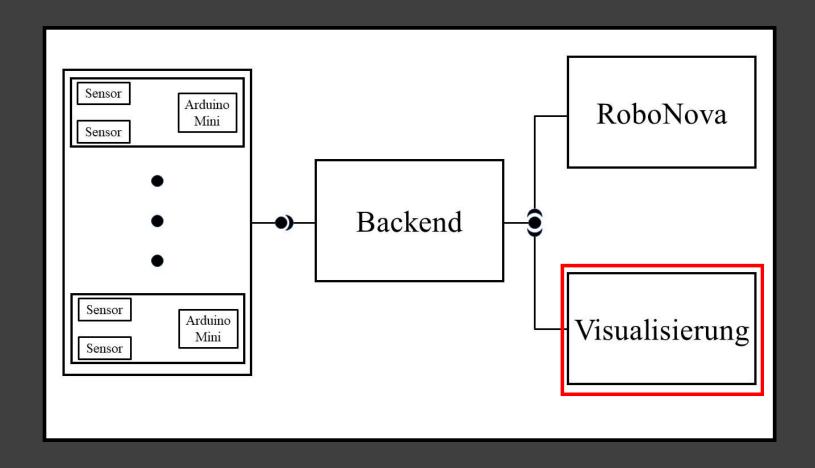
RoboMirror

Arduino & Sensorik Kommunikation Backend Visualisierung Robo Nova





Eggs & Bacon

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T: 1581.000000; X: -2.267809; Y: -1.565962; Z: 3.137791;
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T: 1787.000000; X: -1.913680; Y: -1.564182; Z: 2.839930;
T: 1891.000000; X: -2.320260; Y: -1.702900; Z: 3.260004;
T: 1994.000000; X: -2.408881; Y: -1.365763; Z: 3.176082;
T: 2099.000000; X: -2.255591; Y: -1.528930; Z: 3.118600;
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T: 2306.000000; X: -2.172700; Y: -1.496351; Z: 3.030912;
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T: 2719.000000; X: -2.183105; Y: -1.644816; Z: 3.118035;
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T: 2926.000000; X: -2.308969; Y: -1.520646; Z: 3.163770;
T: 3030.000000; X: -2.278848; Y: -1.469620; Z: 3.114105;
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T: 3650.000000; X: -1.932080; Y: -1.561417; Z: 2.917134;
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T: 5098.000000; X: -31.036886; Y: -1.442568; Z: 31.590395;
T: 5202.000000; X: -41.246429; Y: -0.461184; Z: 41.735821;
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T: 5/09 000000: X: -/5 053535: V: -0 362938: 7: /5 5/0180
```





OSTBAYERISCHE
TECHNISCHE HOCHSCHULE
REGENSBURG

Eggs & Bacon

Vorarbeit

30%

o Einarbeitung Blender

o Einarbeitung Unity

Software

30%

o TCP Socket

o Input Verarbeitung flexibel

o TCP Test Server

Organisatorisches

20%

o Motiviert sein

o Informiert sein

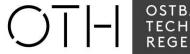




Herausforderungen

20%

- o Künstlerische "Begabung"
- o Blender Bedienung
- o Eigene Motivation





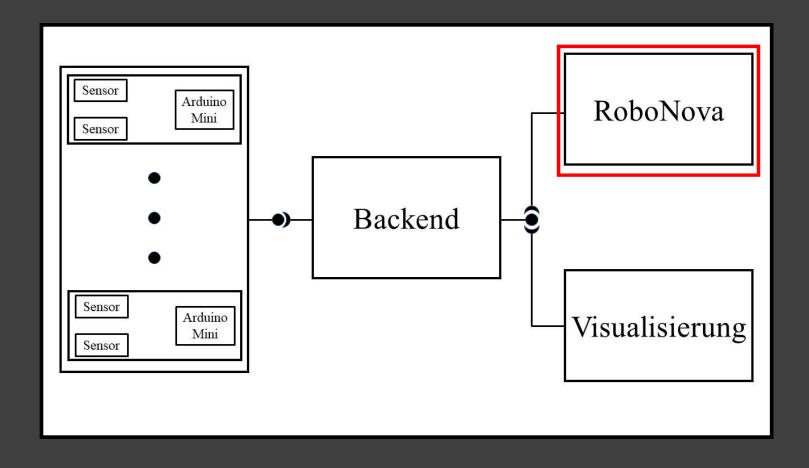
Fazit

- o Neuer Einblick
- o Cooles Projekt
- o Geile Truppe



RoboMirror

Arduino & Sensorik Kommunikation Backend Visualisierung Robo Nova





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