

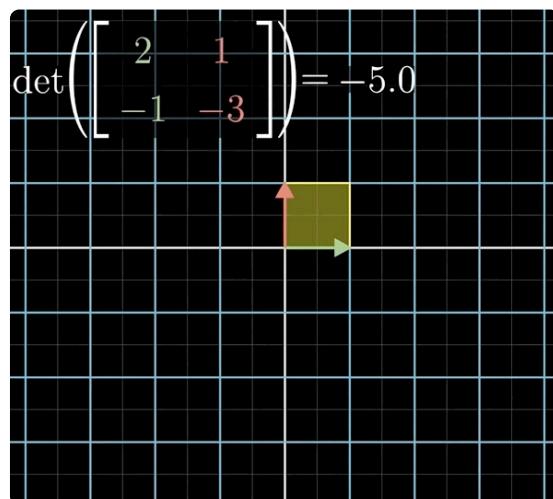
Waitlist and section changes : will be announced later this week
HW1 due Friday

Outline

Recap PSD matrices
Unconstrained optimization
Convexity
Constrained optimization

PSD matrices

A is PSD iff $x^T A x \geq 0 \quad \forall x \in \mathbb{R}^d$
iff all eigenvalues are nonnegative

$$\det \begin{pmatrix} 2 & 1 \\ -1 & -3 \end{pmatrix} = -5.0$$


$f(x) = \text{gradient at } x \nabla f(x) \in \mathbb{R}^d$
Hessian at $x \nabla^2 f(x) \in \mathbb{R}^{d \times d}$

x^* is a local min if $\exists r > 0$ s.t. $f(x^*) \leq f(x)$
 $\forall x$ s.t. $\|x - x^*\| \leq r$

global min ($r \rightarrow \infty$) $f(\underline{x}^*) \leq f(\underline{x}) \forall \underline{x}$

Property 1: If $f(\underline{x})$ is diff'ble and \underline{x}^* is local min
then $\nabla f(\underline{x}^*) = 0$ (stationary point)

Proof: we have $f(\underline{x}^*) \leq f(\underline{x}^* + t\underline{y}) \forall \underline{y}$ and
small enough t .

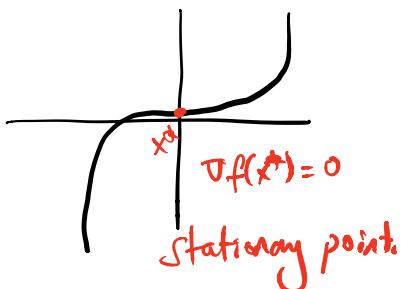
($t \geq 0$) Define $g(t) \triangleq f(\underbrace{\underline{x}^* + t\underline{y}}_z)$ (should increase with t)

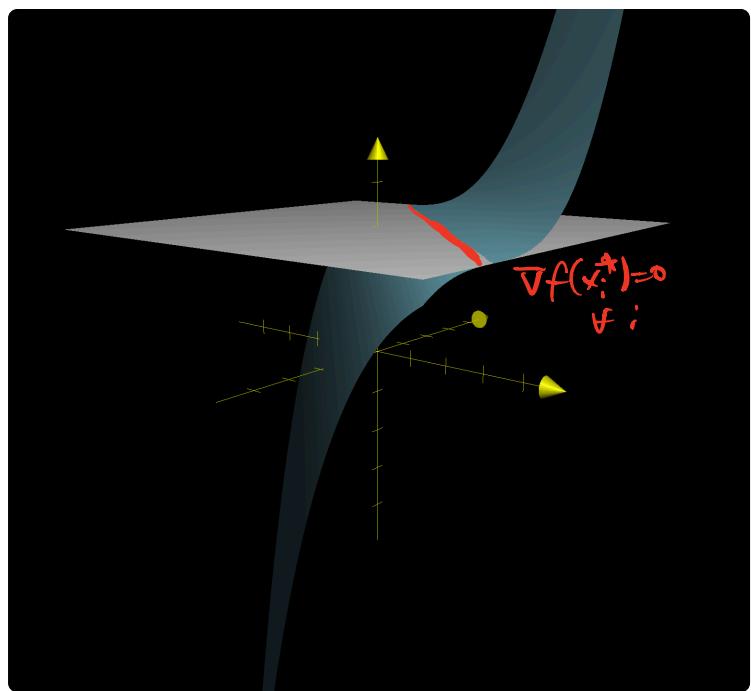
$$(1) \quad g'(0) = \sum_{i=1}^d \underbrace{\frac{\partial f(z)}{\partial z_i}}_{\sim} \cdot \underbrace{\frac{\partial z_i}{\partial t}}_{t=0} = \sum_{i=1}^d \left. \frac{\partial f(x)}{\partial x_i} \right|_{x=\underline{x}^*} \cdot y_i \\ = \langle \nabla f(\underline{x}^*), \underline{y} \rangle$$

$$(2) \quad g'(0) = \lim_{t \rightarrow 0^+} \frac{f(\underline{x}^* + t\underline{y}) - f(\underline{x}^*)}{t} \geq 0 \quad (\text{by local min})$$

$$(1) \& (2) \Rightarrow \langle \nabla f(\underline{x}^*), \underline{y} \rangle \geq 0 \quad \forall \underline{y}.$$

$$\text{pick } \underline{y} = -\nabla f(\underline{x}^*) \Rightarrow -\langle \nabla f(\underline{x}^*), \nabla f(\underline{x}^*) \rangle \geq 0 \\ -\|\nabla f(\underline{x}^*)\|_2^2 \geq 0 \\ \nabla f(\underline{x}^*) = 0 \quad \square.$$





Property 2 If f is twice cont. diff'ble and x^* is a local minimum, then $\nabla^2 f(x^*)$ is positive semidefinite

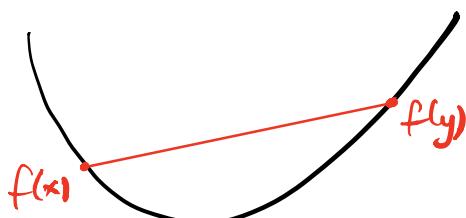
$$z^\top \nabla^2 f(x^*) z \geq 0 \quad \forall z \in \mathbb{R}^d.$$

Intuition: By Taylor's exp.

$$f(x) \approx f(0) + \langle \nabla f(0), x \rangle + \underbrace{\frac{1}{2} x^\top \nabla^2 f(0) x}_{\geq 0}$$

Convexity: We say f is convex if

$$f(tx + (1-t)y) \leq t f(x) + (1-t)f(y) \quad \forall x, y \in \mathbb{R}^d \\ t \in [0,1]$$



• f is convex $\Leftrightarrow -f$ convex

- convex \Rightarrow easy to understand the problem of min. f

Property 3 : If f is convex, then every local min. is a global min.

Proof: Suppose x^* is a local min but not global.
Then $\exists y^* \text{ s.t. } f(y^*) < f(x^*)$. By convexity

$$\begin{aligned} f(tx^* + (1-t)y^*) &\leq t f(x^*) + (1-t) \underbrace{f(y^*)}_{\geq f(x^*)} \\ &< t f(x^*) + (1-t) f(x^*) \\ &= f(x^*) \end{aligned}$$

Let $t \rightarrow 1 \Rightarrow$ contradiction to local min. of x^*
 $\therefore x^*$ is globally min.

(Does not mean unique global minimum.)

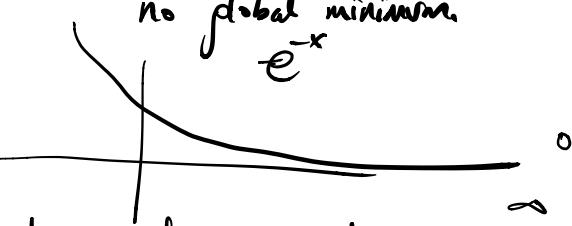
Property 4 If f is strictly convex, then f has at most one global min.

Proof: exercise.

Exercise: Give an example $f(x)$ s.t. (1) convex and more than one global opt

$$\inf_x e^{-x} = 0$$

(2) strictly convex and no global minimum.



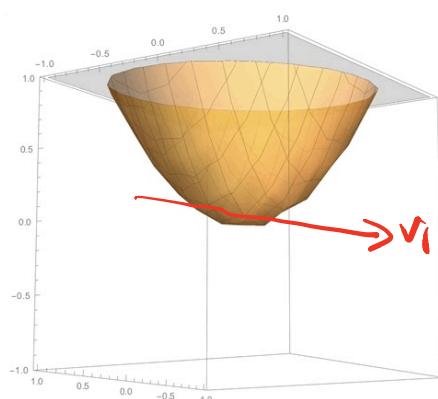
Second order characterization of convexity

Let f be a twice cont. diff. function. Then

(a) f is convex $\Leftrightarrow \nabla^2 f(x)$ is PSD $\forall x \in \mathbb{R}^d$.

(b) f is strictly convex $\Leftrightarrow \nabla^2 f(x)$ is PD $\forall x \in \mathbb{R}^d$.

ex. $f(x) = x^4$ V
 $f'(x) = 4x^3$
 $f''(x) = 12x^2 \Rightarrow \nabla^2 f(x) \Big|_{x=0} = 0$



$$H = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$$

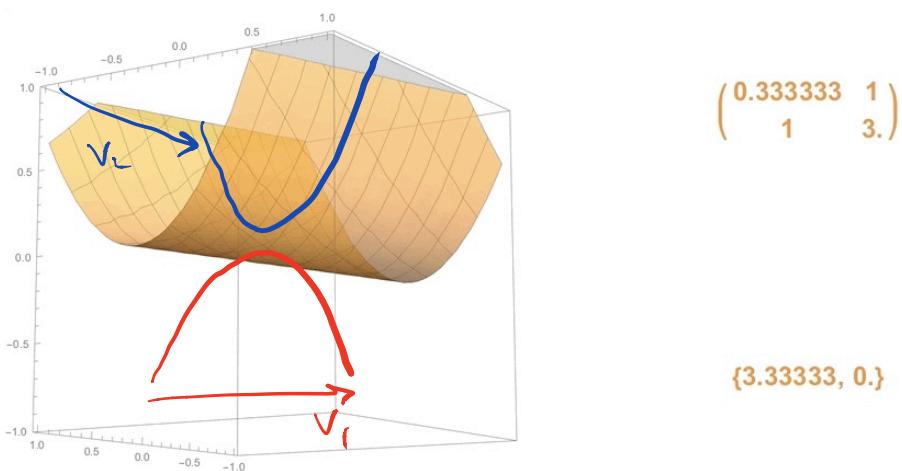
{4., 2.}

$$f(x) \approx f(0) + \langle \nabla f(0), x \rangle + \underbrace{x^T \nabla^2 f(0) x}_{\lambda \cdot v_i^T \lambda \cdot v_i}$$

v_i is an eigenvector with eigenvalue λ

$$f(v_i t) \approx f(0) + \langle \nabla f(0), x \rangle.$$

$$f(v_i t) \approx f(0) + \langle \nabla f(0), x \rangle + \underbrace{v_i^T \nabla^2 f(0) v_i \cdot t^2}_{\frac{v_i^T \lambda v_i}{-t^2}}$$



$$\{3.33333, 0\}$$

First order characterization of convexity

Property 5:

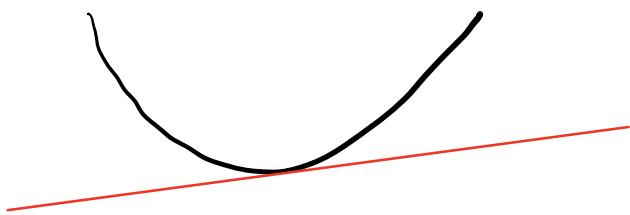
Suppose $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is diff'ble

Then $f(x)$ is convex iff $\forall x, y \in \mathbb{R}^d$

$$f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle$$

Similarly strictly convex iff $\forall x \neq y$

$$f(y) > f(x) + \langle \nabla f(x), y - x \rangle.$$



Pf: (first direction) Assume $f(x)$ convex

$$\begin{aligned} f(ty + (1-t)x) &\leq t f(y) + (1-t) f(x) \\ &= f(x) + t(f(y) - f(x)) \end{aligned}$$

Rearrange

$$\underline{f(x + t(y-x)) - f(x)} \leq f(y) - f(x) \leftarrow$$

t

Let $t \rightarrow 0$

$$= \langle \nabla f(x), y - x \rangle \leq f(y) - f(x). \quad \square$$

Property 6 : f convex, cont. diff'ble then x^* is a global min iff $\nabla f(x^*) = 0$

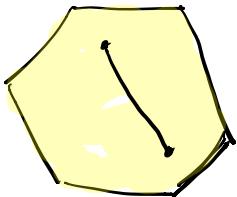
Pf. Forward implication is property 1

Reverse implication follows from property 5.

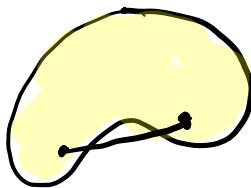
$$f(y) \geq f(x^*) + \underbrace{\langle \nabla f(x^*), y - x^* \rangle}_0$$

Convex sets: A set $C \subseteq \mathbb{R}^d$ is convex if for any two points $x, y \in C$, the segment $[x, y]$ lies in C

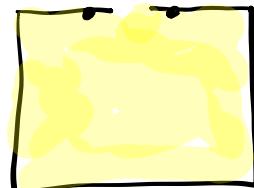
$$\{t\underline{x} + (1-t)\underline{y} : 0 \leq t \leq 1\} \subseteq C$$



convex



not convex

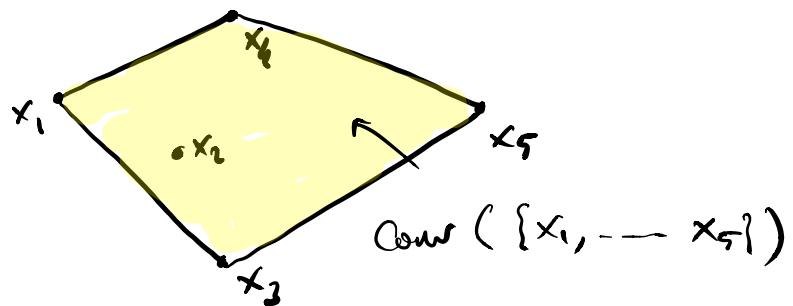


not convex

Convex hull: of a set of points $X \subseteq \mathbb{R}^d$ denoted $\text{conv}(X)$ is the set of all convex combinations of points in X

$$\text{conv}(X) = \left\{ \sum_{i=1}^m \alpha_i \underline{x}_i : x_i \in X, \alpha_i \geq 0, \sum_{i=1}^m \alpha_i = 1 \right\}$$

- $\text{conv}(X)$ is the smallest convex set that contains X .



Constrained Optimization

$$\min_x f(x)$$

$$\text{subject to } g_i(x) \leq 0 \quad \forall i \{1, \dots, m\}$$

x (opt variable) is feasible if it satisfies all the constraints

$$\sum x_i = 1 \quad \text{Equality constraint can be written as}$$

$$h(x) = 0, \quad g_1(x) = h(x) \leq 0$$

$$g_2(x) = -h(x) \leq 0$$

Lagrangian: associated to const opt problem has the form

$$\mathcal{L}(x, \lambda) = f(x) + \sum_{i=1}^m \lambda_i g_i(x) = f(x) + \lambda^T g(x)$$

$$\text{where } \lambda_i \geq 0 \quad \forall i$$

$$\lambda = \begin{bmatrix} \lambda_1 \\ \vdots \\ \lambda_m \end{bmatrix}$$