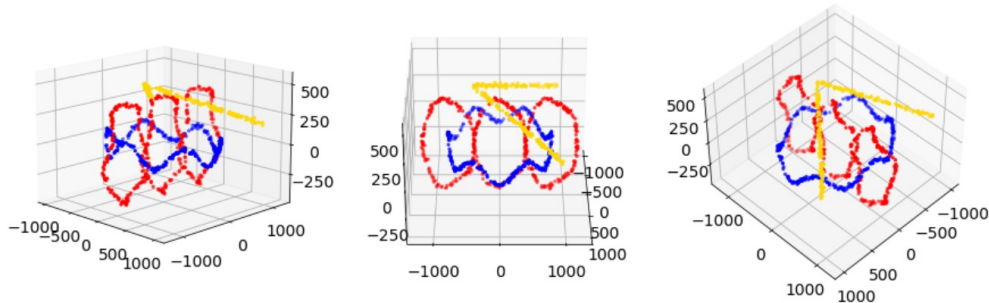


## LCPB 22-23 Exercise 3, data visualization and clustering

### Exercise 4A

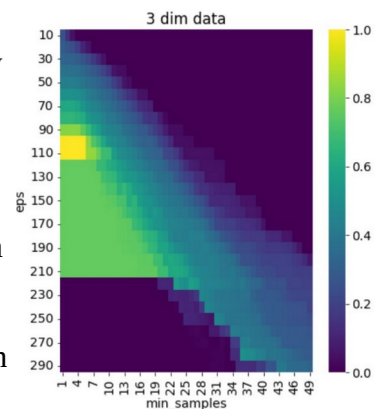
Consider data generated during the lesson, with  $N=600$  samples.



1. Choose a perplexity for t-SNE and run a few times its algorithm by varying “random\_state”. How do the results compare with each other?
2. “*eps*” and “*minPts*” in DBSCAN algorithm for clustering  
Refine the grid with more values of “*eps*” and “*minPts*” and show a heat-map of the normalized mutual information (NMI) between true and predicted clusters is varying.  
The result might look like this one on the right.

Is there a correlation between these two parameters in providing a high NMI?

Note: in the lesson we have looked at the typical distance between a point and its closest neighbor, but this does not say what is the typical distance from the 2<sup>nd</sup>, 3<sup>rd</sup>, ..., “minPts”-neighbor.



Another possibility to consider for tuning “*eps*” and “*minPts*” is the [plotting of ranked distances](#).