

This directory contains the Equalizer example, used in Sander’s PhD Thesis [1], and modelled using shallow-embedded signals.

0.1 Overview

The main task of the equalizer system is to adjust the audio signal according to the **Button Control**, that works as a user interface. In addition, the bass level must not exceed a predefined threshold to avoid damage to the speakers.

This specification can be naturally decomposed into four functions shown in Figure ?? . The subsystems **Button Control** and **Distortion Control**, are control dominated (grey shaded), while the **Audio Filter** and the **Audio Analyzer** are data flow dominated subsystems.

The **Button Control** subsystem monitors the button inputs and the override signal from the subsystem **Distortion Control** and adjusts the current bass and treble levels. This information is passed to the subsystem **Audio Filter**, which receives the audio input, and filters and amplifies the audio signal according to the current bass and treble levels. This signal, the output signal of the equalizer, is analyzed by the **Audio Analyzer** subsystem, which determines, whether the bass exceeds a predefined threshold. The result of this analysis is passed to the subsystem **Distortion Control**, which decides, if a minor or major violation is encountered and issues the necessary commands to the **Button Control** subsystem.

The frequency characteristics of the **Equalizer** is adjusted by the coefficients for the three FIR-filters in the **AudioFilter**.

```

module Equalizer(equalizer) where

import ForSyDe.Shallow

import ButtonControl
import DistortionControl
import AudioAnalyzer
import AudioFilter

```

The structure of the equalizer is expressed as a network of blocks:

```

equalizer lpCoeff bpCoeff hpCoeff dftPts
          bassUp bassDn trebleUp trebleDn input = (bass, treble)
where
  (bass, treble) = buttonControl overrides bassUp bassDn
                                     trebleUp trebleDn
  output        = audioFilter lpCoeff bpCoeff hpCoeff bass
                                     treble input
  distFlag      = audioAnalyzer dftPts output
  overrides     = distortionControl delayedDistFlag
  delayedDistFlag = delaySY Abst distFlag

```

Since the equalizer contains a feedback loop, the signal **DistFlag** is delayed one event cycle using the initial value \perp .

0.2 Overview

The subsystem `Button Control` works as a user interface in the equalizer system. It receives the four input signals $\overline{\text{BassDn}}$, $\overline{\text{BassUp}}$, $\overline{\text{TrebleDn}}$, $\overline{\text{TrebleUp}}$ and the override signal $\overline{\text{Override}}$ from the `Distortion Control` and calculates the new bass and treble values for the output signals $\overline{\text{Bass}}$ and $\overline{\text{Treble}}$. The subsystem contains the main processes `Button Interface` and `Level Control`. The process `Level Control` outputs a new value, if either the signal $\overline{\text{Button}}$ or the signal $\overline{\text{Overr}}$ is present, otherwise the output value is absent. The process `Hold Level` is modeled by means of `holdSY (0.0, 0.0)` that outputs the last present value, if the input value is absent. The process `unzipSY` transforms a signal of tuples (the current bass and treble level) into a tuple of signals (a bass and a treble signal).

```
module ButtonControl (buttonControl) where

import ForSyDe.Shallow
import EqualizerTypes
--import Combinators

data State      = Operating
                | Locked deriving(Eq, Show)
type Level      = Double
type Bass       = Level
type Treble     = Level

buttonControl :: Signal (AbstExt OverrideMsg) -> Signal (AbstExt
    Sensor)
                -> Signal (AbstExt Sensor) -> Signal (AbstExt
    Sensor)
                -> Signal (AbstExt Sensor) -> (Signal Bass,Signal
    Treble)
buttonControl overrides bassDn bassUp trebleDn trebleUp
    = (bass, treble)
    where (bass, treble) = unzipSY levels
          levels = holdSY (0.0, 0.0) $ levelControl button
            overrides
          button = buttonInterface bassDn bassUp trebleDn
            trebleUp
```

0.3 The Process Button Interface

The `Button Interface` monitors the four input buttons $\overline{\text{BassDn}}$, $\overline{\text{BassUp}}$, $\overline{\text{TrebleDn}}$, $\overline{\text{TrebleUp}}$ and indicates if a button is pressed. If two or more buttons are pressed the conflict is resolved by the priority order of the buttons.

```
buttonInterface :: Signal (AbstExt Sensor) -> Signal (AbstExt
    Sensor)
                -> Signal (AbstExt Sensor) -> Signal (AbstExt
    Sensor)
                -> Signal (AbstExt Button)
buttonInterface bassUp bassDn trebleUp trebleDn
    = zipWith4SY f bassUp bassDn trebleUp trebleDn
    where f (Prst Active) _ _ _ = Prst BassUp
```

```

f _ (Prst Active) _ _ = Prst BassDn
f _ _ (Prst Active) _ = Prst TrebleUp
f _ _ _ (Prst Active) = Prst TrebleDn
f _ _ _ _ = Abst

```

0.4 The Process Level Control

The process has a local state that consists of a mode and the current values for the bass and treble levels (Figure ??). The **Level Control** has two modes, in the mode **Operating** the bass and treble values are stepwise changed in 0.2 steps. However, there exists maximum and minimum values which are -5.0 and +5.0. The process enters the mode **Locked** when the **Override** input has the value **Lock**. In this mode an additional increase of the bass level is prohibited and even decreased by 1.0 in case the **Override** signal has the value **CutBass**. The subsystem returns to the **Operating** mode on the override value **Release**. The output of the process is an absent extended signal of tuples with the current bass and treble levels.

```

levelControl :: Signal (AbstExt Button) -> Signal (AbstExt
  OverrideMsg)
  -> Signal (AbstExt (Bass,Treble))
levelControl button overrides
  = mealy2SY nextState output (initState, initLevel) button
  overrides

nextState :: (State,(Double,Double)) -> AbstExt Button
  -> AbstExt OverrideMsg -> (State,(Double,Double))
nextState (state, (bass, treble)) button override
  = (newState, (newBass, newTreble)) where
    newState = if state == Operating then
      if override == Prst Lock then
        Locked
      else
        Operating
    else
      if override == Prst Release then
        Operating
      else
        Locked

    newBass = if state == Locked then
      if override == Prst CutBass then
        decreaseLevel bass cutStep
      else
        if button == Prst BassDn then
          decreaseLevel bass step
        else
          bass
    else — state = Operating
      if button == Prst BassDn then
        decreaseLevel bass step
      else
        if button == Prst BassUp then
          increaseLevel bass step

```

```

        else
            bass

    newTreble = if button == Prst TrebleDn then
        decreaseLevel treble step
    else
        if button == Prst TrebleUp then
            increaseLevel treble step
        else
            treble

output :: (a, (Bass, Treble)) -> AbstExt Button -> AbstExt
    OverrideMsg
    -> AbstExt (Bass, Treble)
output _      Abst Abst = Abst
output (_, levels) _      = Prst levels

```

The process uses the following initial values.

```

initState = Operating
initLevel = (0.0, 0.0)
maxLevel  = 5.0
minLevel  = -5.0
step      = 0.2
cutStep   = 1.0

```

The process uses the following auxiliary functions.

```

decreaseLevel :: Level -> Level -> Level
decreaseLevel level step = if reducedLevel >= minLevel then
    reducedLevel
    else
        minLevel
    where reducedLevel = level - step

increaseLevel :: Level -> Level -> Level
increaseLevel level step = if increasedLevel <= maxLevel then
    increasedLevel
    else
        maxLevel
    where increasedLevel = level + step

```

The block `Distortion Control` is directly developed from the SDL-specification, that has been used for the MASCOT-model [BjJa2000]. The specification is shown in Figure ??.

Figures/DistortionControl-eps-converted-to.pdf

Figure 1: SDL-description of *Distortion Control*

The `Distortion Control` is a single FSM, which is modeled by means of the skeleton `mealySY`. The global state is not only expressed by the explicit states - `Passed`, `Failed` and `Locked -`, but also by means of the variable `cnt`. The state

machine has two possible input values, `Pass` and `Fail`, and three output values, `Lock`, `Release` and `CutBass`.

The `mealySY` creates a process that can be interpreted as a Mealy-machine. It takes two functions, `nxtSt` to calculate the next state and `out` to calculate the output. The state is represented by a pair of the explicit state and the variable `cnt`. The initial state is the same as in the SDL-model, given by the tuple `(Passed, 0)`. The `nxtSt` function uses pattern matching. Whenever an input value matches a pattern of the `nxtSt` function the corresponding right hand side is evaluated, giving the next state. An event with an absent value leaves the state unchanged. The output function is modeled in a similar way. The output is absent, when no output message is indicated in the SDL-model.

```

module DistortionControl (distortionControl) where

import ForSyDe.Shallow
import EqualizerTypes

data State = Passed
           | Failed
           | Locked

distortionControl :: Signal (AbstExt AnalyzerMsg)
                  -> Signal (AbstExt OverrideMsg)

distortionControl distortion
  = mealySY nxtSt out (Passed, 0) distortion

lim = 3

--      State      Input      NextState
nxtSt (state, cnt) (Abst)      = (state, cnt)
nxtSt (Passed, cnt) (Prst Pass) = (Passed, cnt)
nxtSt (Passed, _ ) (Prst Fail) = (Failed, lim)
nxtSt (Failed, cnt) (Prst Pass) = (Locked, cnt)
nxtSt (Failed, cnt) (Prst Fail) = (Failed, cnt)
nxtSt (Locked, _ ) (Prst Fail) = (Failed, lim)
nxtSt (Locked, cnt) (Prst Pass) = (newSt, newCnt)
  where newSt = if (newCnt == 0) then Passed
                else Locked
        newCnt = cnt - 1

--      State      Input      Output
out (Passed, _) (Prst Pass) = Abst
out (Passed, _) (Prst Fail) = Prst Lock
out (Failed, _) (Prst Pass) = Abst
out (Failed, _) (Prst Fail) = Prst CutBass
out (Locked, _) (Prst Fail) = Abst
out (Locked, cnt) (Prst Pass) =
  if (cnt == 1) then Prst Release
  else Abst
out _ _ _ = Abst

module TestEqualizer where

import System.IO

```

```

import Equalizer
import EqualizerTypes
import ForSyDe.Shallow
import AudioFilter
import AudioAnalyzer

audioIn = takeS (pts * 4) $ infiniteS (id) 1.0

bassUp = signal [Prst Active, Prst Active, Abst, Abst,
                Prst Active, Prst Active, Abst, Abst,
                Prst Active, Prst Active, Abst, Abst,
                Prst Active, Prst Active, Abst, Abst]

bassDn = signal [Abst, Abst, Prst Active, Abst,
                Abst, Abst, Prst Active, Abst,
                Abst, Abst, Prst Active, Abst,
                Abst, Abst, Prst Active, Abst]

trebleUp = signal [Abst, Abst, Abst, Abst,
                  Abst, Abst, Abst, Prst Active,
                  Abst, Abst, Abst, Abst,
                  Abst, Abst, Abst, Prst Active]

trebleDn = signal [Abst, Abst, Abst, Prst Active,
                  Abst, Abst, Abst, Prst Active,
                  Abst, Abst, Abst, Prst Active,
                  Abst, Abst, Abst, Prst Active]

overrides = signal [Abst, Abst, Abst, Abst,
                   Prst Lock, Abst, Abst, Abst,
                   Abst, Prst CutBass, Abst, Abst,
                   Prst Release, Abst, Abst, Abst]

bass = infiniteS id 0.0
treble = infiniteS id 0.0
dataflow = audioAnalyzer 2 (audioFilter lpCoeff bpCoeff hpCoeff
    bass treble audioIn)

testEqualizer = equalizer lpCoeff bpCoeff hpCoeff 2 bassUp
    bassDn trebleUp trebleDn audioIn
--testButtonInterface = buttonInterface bassUp bassDn trebleUp
    trebleDn

lpCoeff = vector
    [ 0.01392741661548, 0.01396895728902,
      0.01399870011280, 0.01401657422649,
      0.01402253700635, 0.01401657422649,
      0.01399870011280, 0.01396895728902,
      0.01392741661548 ]

bpCoeff = vector
    [ 0.06318761339784, 0.08131651217682,
      0.09562326700432, 0.10478344432968,
      0.10793629404886, 0.10478344432968,
      0.09562326700432, 0.08131651217682,
      0.06318761339784 ]

hpCoeff = vector
    [ -0.07883878579454, -0.09820015927379,

```

```

-0.11354603917221, -0.12339860164118,
0.87320570334018, -0.12339860164118,
-0.11354603917221, -0.09820015927379,
-0.07883878579454 ]

zeros = infiniteS id 0.0

audioFilterD = audioFilter lpCoeff bpCoeff hpCoeff zeros zeros
pts = 4

main = do
  -- Test AudioFilter
  putStr "\n-->Test AudioFilter \n"
  filterInfile <- openFile "Test/AudioIn.mat" ReadMode
  filterContents <- hGetContents filterInfile
  putStr (show (audioFilterD (readS filterContents)))
  writeFile "Test/audioOut.dat" (writeS (audioFilterD (
    readS filterContents)))
  -- Test AudioAnalyzer
  putStr "\n--> Test AudioAnalyzer \n"
  analyzerInfile <- openFile "Test/audioOut.dat"
    ReadMode
  analyzerOutfile <- openFile "Test/analyzerOut.dat"
    WriteMode
  analyzerContents <- hGetContents analyzerInfile
  putStr (show (audioAnalyzer pts ((readS
    analyzerContents) :: Signal Double)))
  hPutStr analyzerOutfile (writeS (audioAnalyzer pts ((
    readS analyzerContents) :: Signal Double)))

  --fftInfile <- openFile "audioOut.txt" ReadMode
  --fftOutfile <- openFile "fftOut.txt" WriteMode
  --contents <- hGetContents fftInfile
  --putStr (writeS (((readS contents) :: Signal Double))
  --)
  --hPutStr fftOutfile (writeS (((readS contents) ::
    Signal Double)))
  putStr "\nDone.\n"

module TestButtonControl where

import ButtonControl
import EqualizerTypes
import ForSyDe.Shallow

bassUp = signal [Prst Active, Prst Active, Abst, Abst,
  Prst Active, Prst Active, Abst, Abst,
  Prst Active, Prst Active, Abst, Abst,
  Prst Active, Prst Active, Abst, Abst]

bassDn = signal [Abst, Abst, Prst Active, Abst,
  Abst, Abst, Prst Active, Abst,
  Abst, Abst, Prst Active, Abst,
  Abst, Abst, Prst Active, Abst]

```

```

trebleUp = signal [Abst, Abst, Abst, Abst,
                  Abst, Abst, Abst, Prst Active,
                  Abst, Abst, Abst, Abst,
                  Abst, Abst, Abst, Prst Active]

trebleDn = signal [Abst, Abst, Abst, Prst Active,
                  Abst, Abst, Abst, Prst Active,
                  Abst, Abst, Abst, Prst Active,
                  Abst, Abst, Abst, Prst Active]

overrides = signal [Abst, Abst, Abst, Abst,
                   Prst Lock, Abst, Abst, Abst,
                   Abst, Prst CutBass, Abst, Abst,
                   Prst Release, Abst, Abst, Abst]

testButtonControl = buttonControl overrides bassUp bassDn
                  trebleUp trebleDn
—testButtonInterface = buttonInterface bassUp bassDn trebleUp
                  trebleDn

module TestDistortionControl where

import DistortionControl
import EqualizerTypes
import ForSyDe.Shallow

flag = signal
      [Abst, Abst, Abst, Prst Fail,
       Abst, Abst, Abst, Prst Fail,
       Abst, Abst, Abst, Prst Fail,
       Abst, Abst, Abst, Prst Fail,
       Abst, Abst, Abst, Prst Pass,
       Abst, Abst, Abst, Prst Pass,
       Abst, Abst, Abst, Prst Pass,
       Abst, Abst, Abst, Prst Pass,
       Abst, Abst, Abst, Prst Fail,
       Abst, Abst, Abst, Prst Fail,
       Abst, Abst, Abst, Prst Fail,
       Abst, Abst, Abst, Prst Pass,
       Abst, Abst, Abst, Prst Pass,
       Abst, Abst, Abst, Prst Pass,
       Abst, Abst, Abst, Prst Pass,
       Abst, Abst, Abst, Prst Fail,
       Abst, Abst, Abst, Prst Pass,
       Abst, Abst, Abst, Prst Fail,
       Abst, Abst, Abst, Prst Pass,
       Abst, Abst, Abst, Prst Pass]

testDistortionControl = distortionControl flag

```

References

- [1] Ingo Sander. “System Modeling and Design Refinement in ForSyDe”. NR 20140805. PhD thesis. KTH, Microelectronics and Information Technology, IMIT, 2003, pp. xvi, 228. ISBN: 91-7283-501-X.