

Causal Data Science

Lecture 4:2 Structural causal models

Lecturer: Sara Magliacane

UvA - Spring 2023



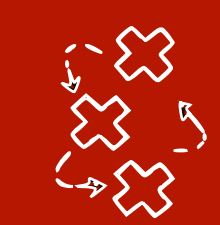
Truncated factorisation formula [Pearl 2009]

- If for any $\mathbf{W} \subset \mathbf{V}$:

$$p(X_{\mathbf{V}} | \text{do}(X_{\mathbf{W}} = x_{\mathbf{W}})) = \prod_{i \in \bar{\mathbf{V}} \setminus \bar{\mathbf{W}}} p(X_i | X_{\text{pa}(i)}) \cdot 1 / (X_{\bar{\mathbf{W}}} = x_{\bar{\mathbf{W}}})$$



doesn't change from
the observational distr.



Truncated factorisation formula [Pearl 2009]

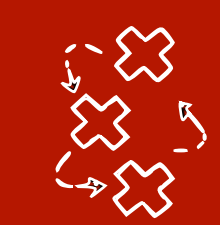
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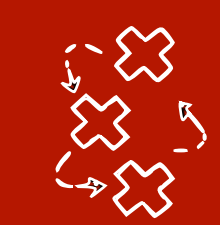
doesn't change from
the observational distr.

MODULARITY
ASSUMPTION



Causal mechanisms and Modularity

- In a causal BN (G, p) , each $p(X_i | \mathbf{X}_{\text{pa}(i)})$ is the **causal mechanism of X_i**
- **Modularity assumption:** intervening on X_j will not change any causal mechanism $p(X_i | \mathbf{X}_{\text{pa}(i)})$ for any $i \neq j$



Causal mechanisms and Modularity

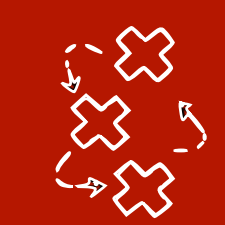
- In a causal BN (G, p) , each $p(X_i | \mathbf{X}_{\text{Pa}(i)})$ is the **causal mechanism of X_i**
- **Modularity assumption:** intervening on X_j will not change any causal mechanism $p(X_i | \mathbf{X}_{\text{Pa}(i)})$ for any $i \neq j$
- **Independent Causal Mechanism Principle:** the generative process is composed of **autonomous models** that do **not inform or influence** each other

Knowing
Changing

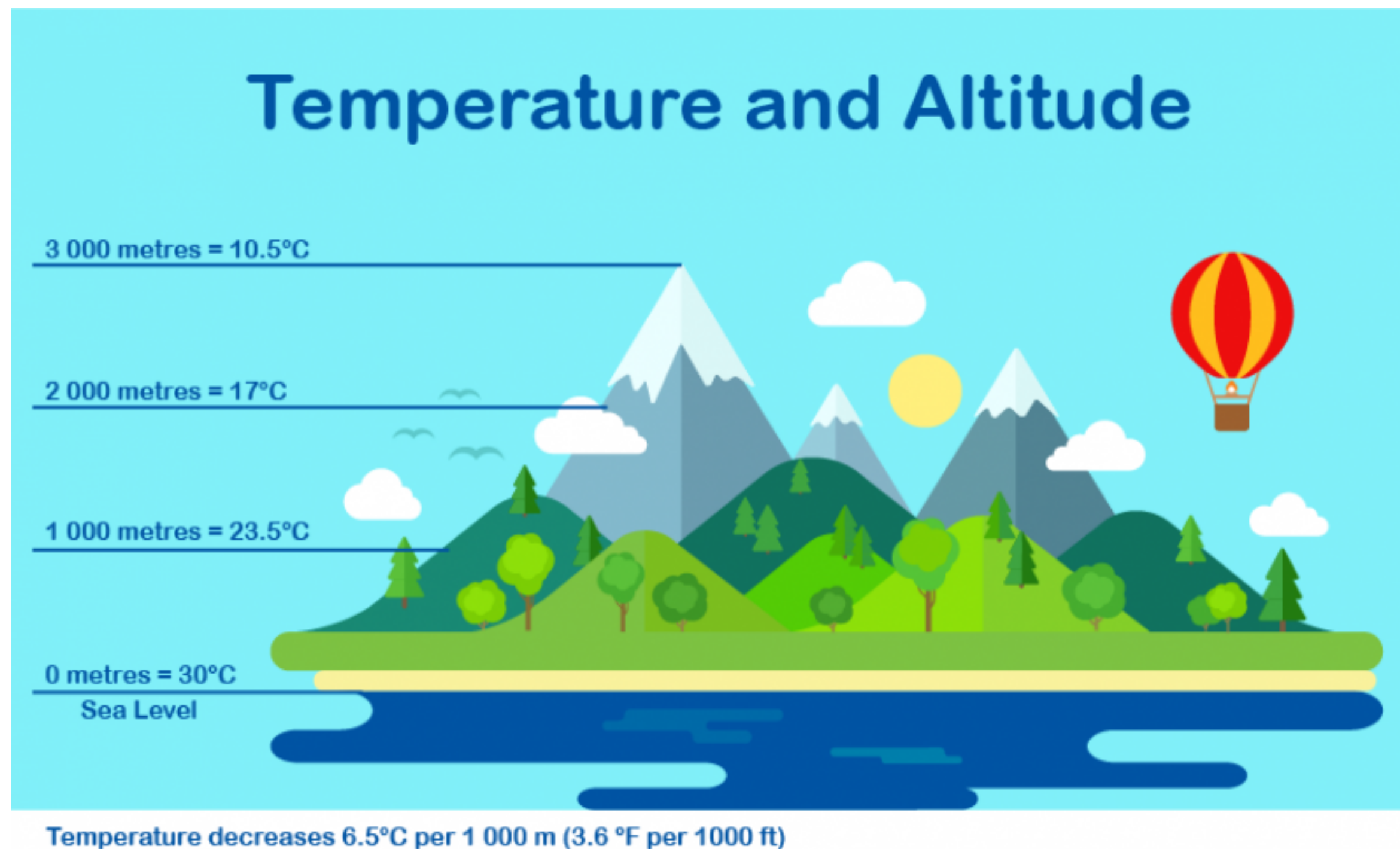
$$p(X_j | \mathbf{X}_{\text{Pa}(j)})$$

Does not give info
Does not change

$$p(X_i | \mathbf{X}_{\text{Pa}(i)}) \quad i \neq j$$

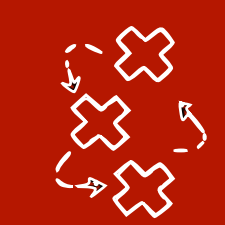


Modularity example

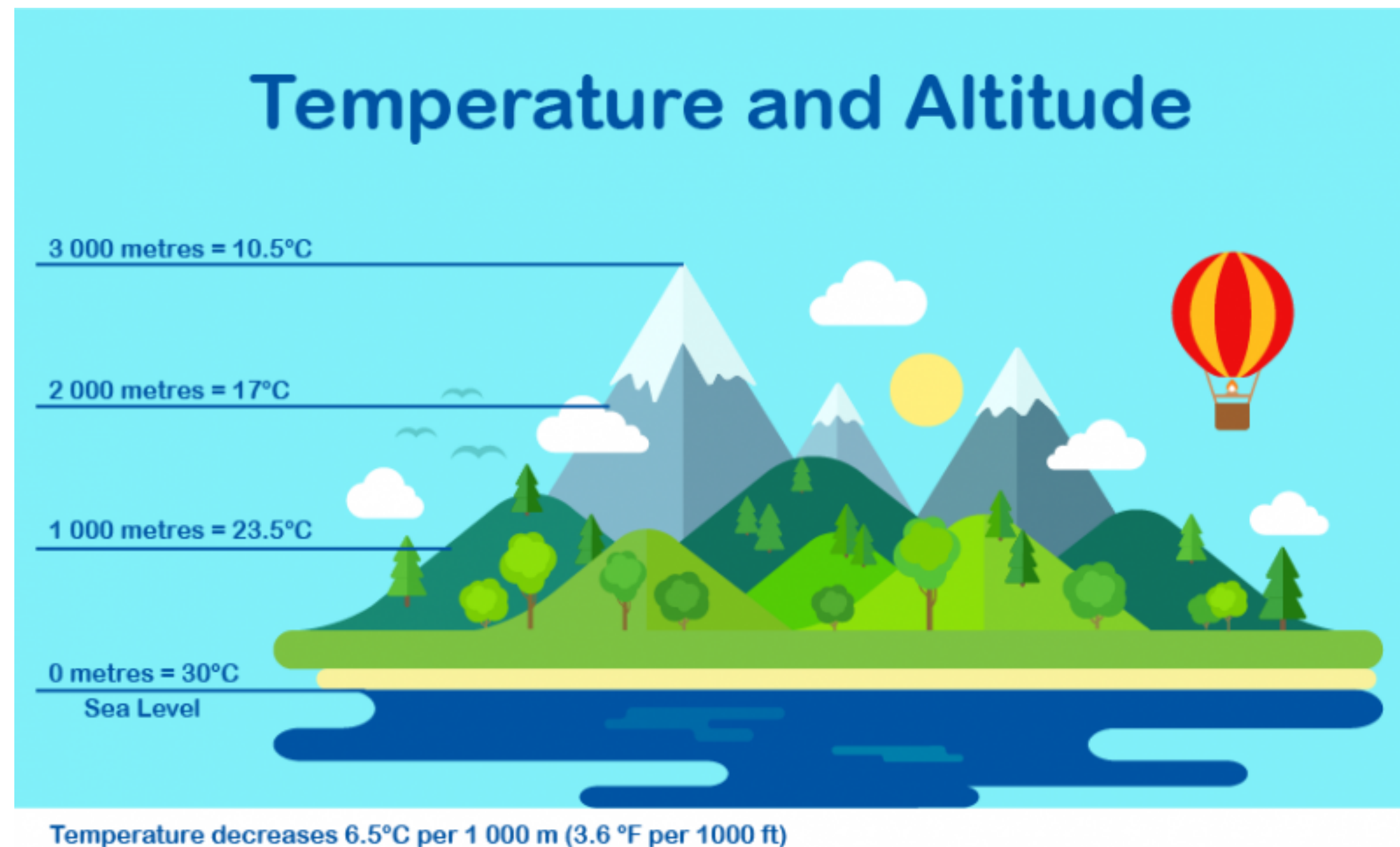


$$P(A, T) = P(T|A)P(A)$$

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Modularity example



$$P(A, T) = P(T|A)P(A)$$

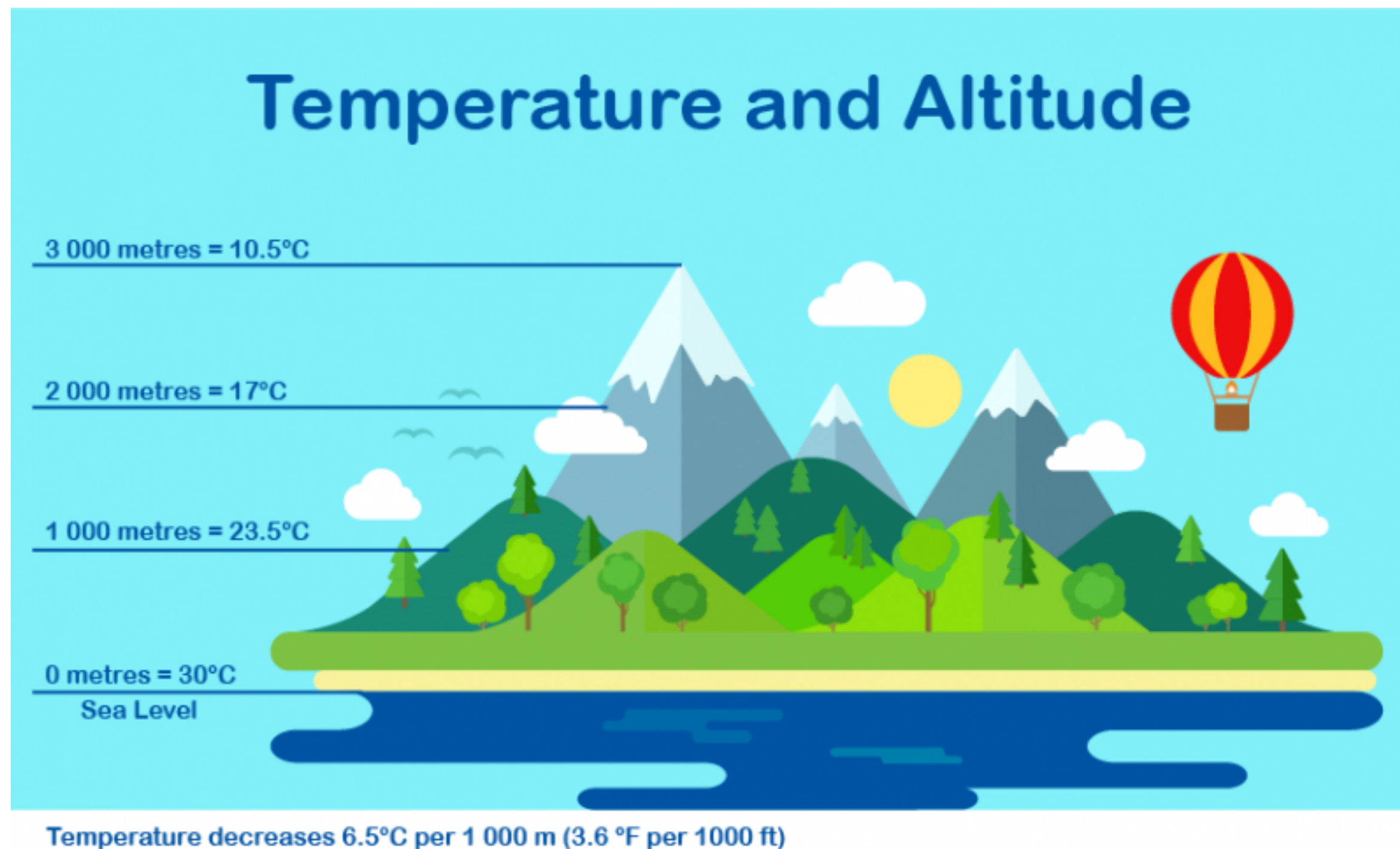
changing $P(A)$ does not
change $P(T|A)$

$$P(A, T) = P(A|T)P(T)$$

Changing $P(T)$ might
change $P(A|T)$



Modularity example



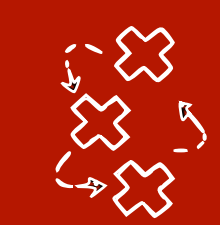
$P(T|A)$ is an invariant physical mechanism

$$P(A, T) = P(T|A)P(A)$$

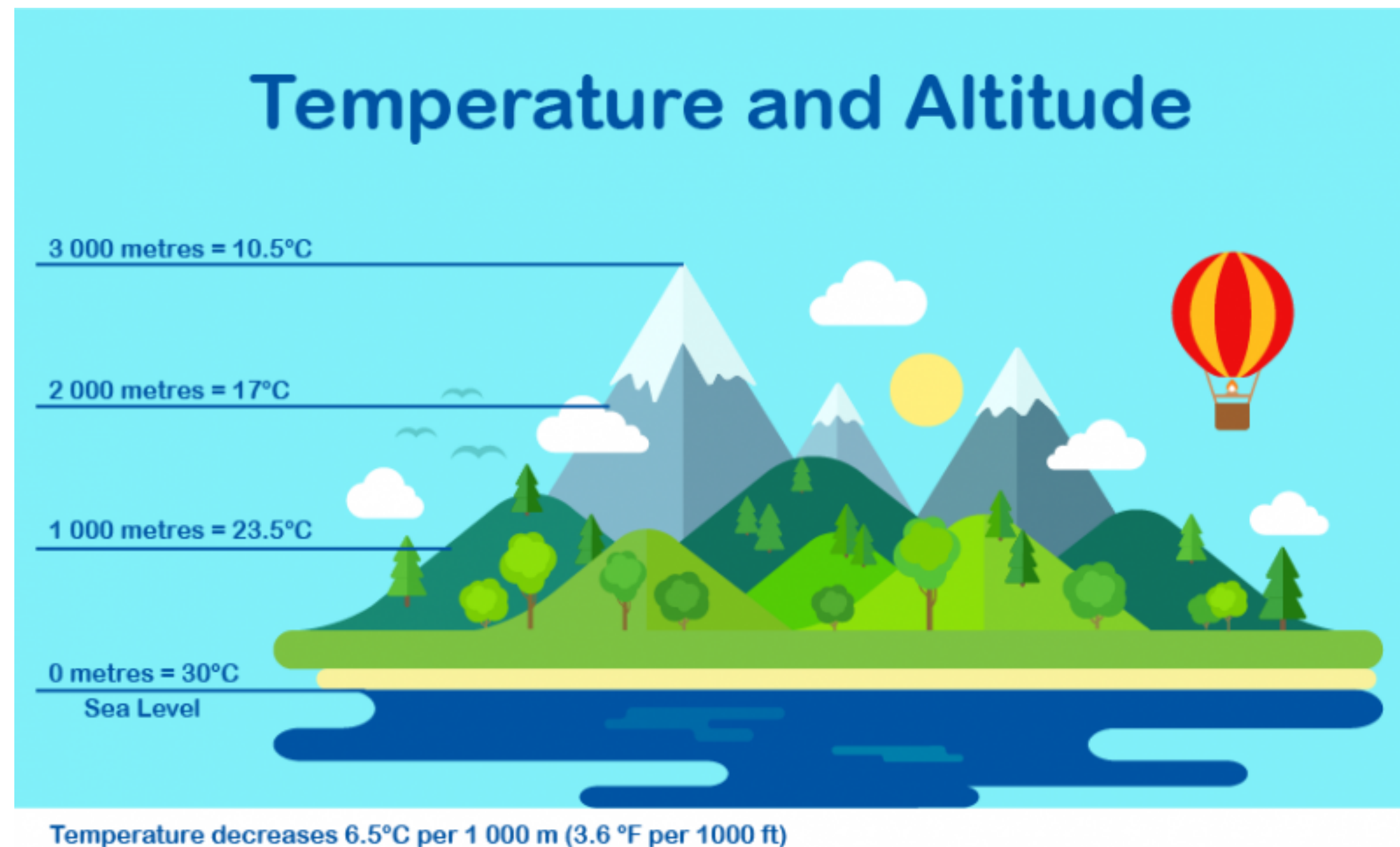
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Modularity example



$$P(A, T) = P(T|A)P(A)$$

changing $P(A)$ does not
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The **causal factorisation**
allows for **localised/sparse**
interventions

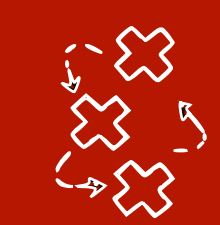


Structural equation models (SEMs)

- Let (G, p) be a Bayesian network
- We can write each variable X_i for $i \in \mathbf{V}$ as a **function of its parents** in G and a **noise term** ϵ_i in a **structural equation**:

$$X_i \leftarrow h_i(X_{\text{Pa}(i)}, \epsilon_i)$$

- We assume all noises are **independent of each other** $\forall i \neq j : \epsilon_i \perp\!\!\!\perp \epsilon_j$



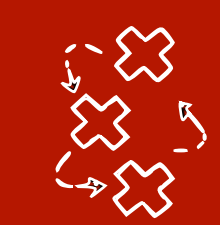
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often linear often Gaussian

- We assume all noises are **independent of each other** $\forall i \neq j : \epsilon_i \perp\!\!\!\perp \epsilon_j$

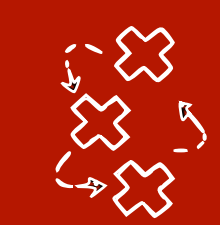


Structural **causal** models (SCMs)

- Let (G, p) be a **causal** Bayesian network
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Structural causal models (SCMs)

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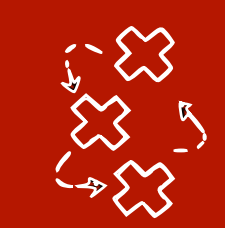
$$X_i \leftarrow h_i(X_{\text{Pa}(i)}, \epsilon_i)$$

causal mechanism

endogenous variable
 \mathbf{V}

using \leftarrow instead of $=$ to emphasize asymmetry

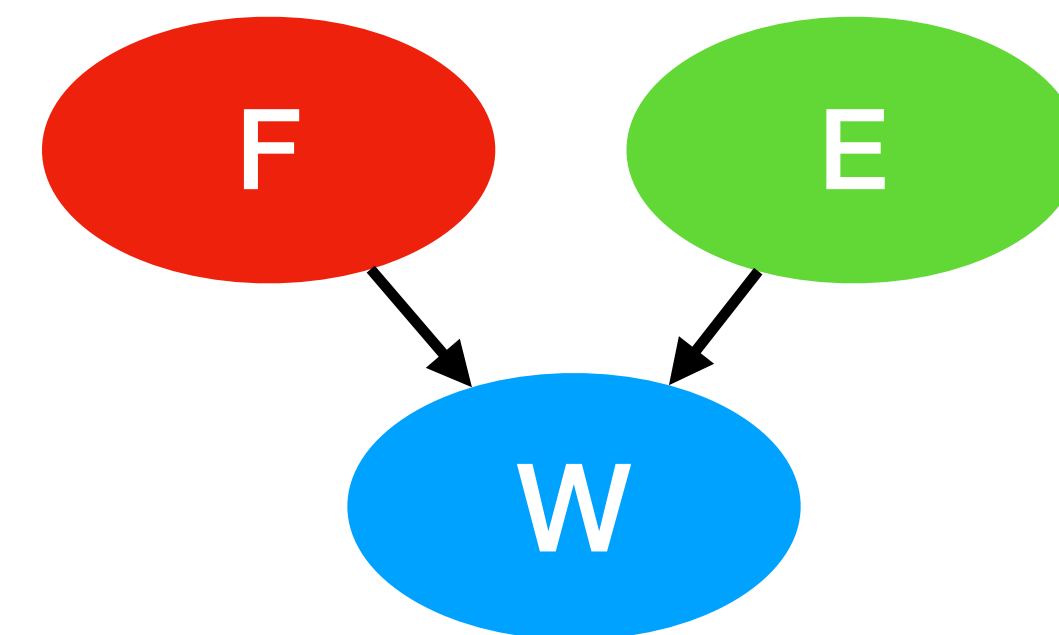
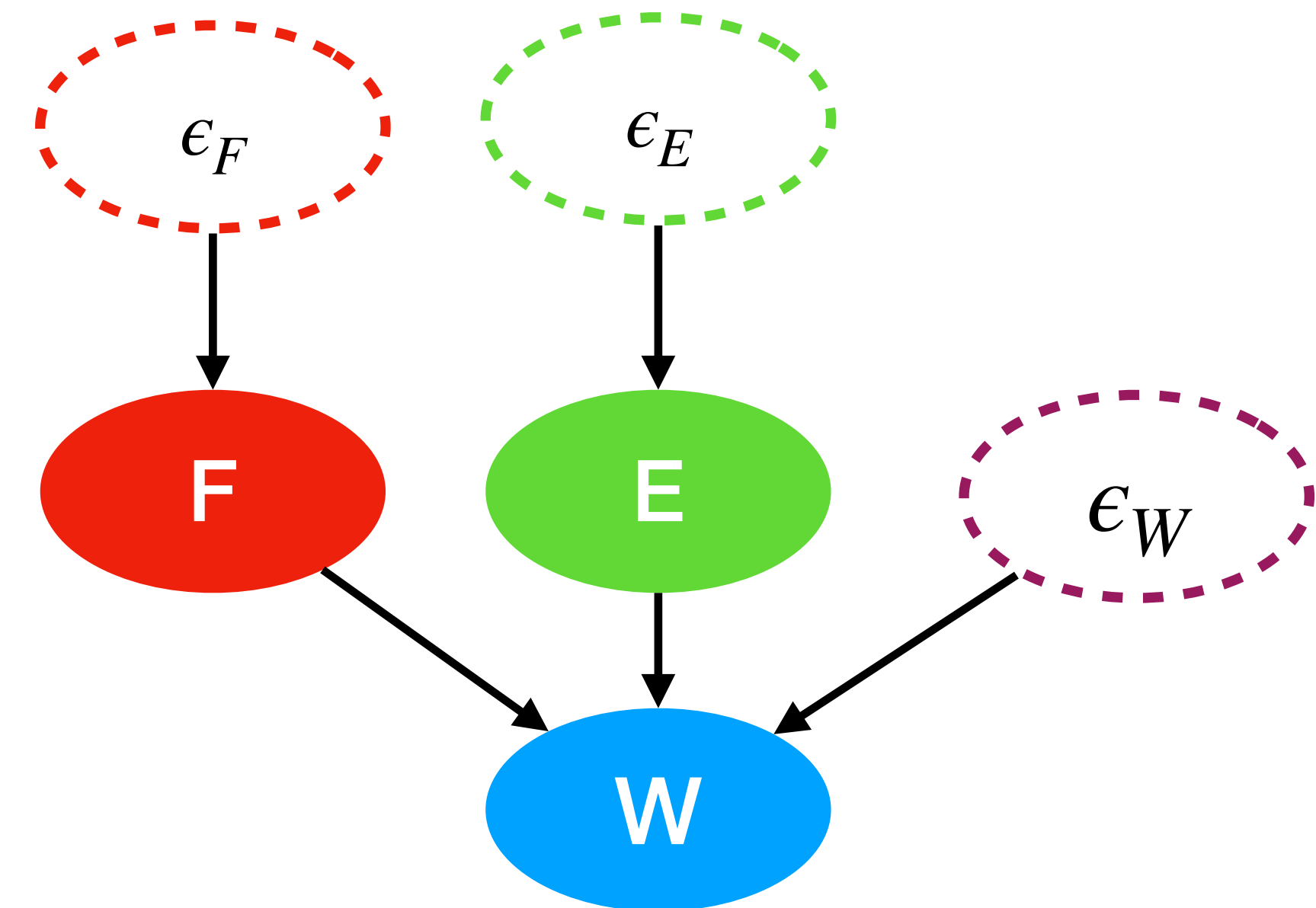
exogenous variable
 \mathbf{U}

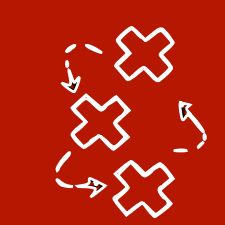


Example SCM

$$\begin{cases} F \leftarrow 2000 + \epsilon_F \\ E \leftarrow 500 + \epsilon_E \\ W \leftarrow \frac{F - E - 1500}{7700} + 0.1\epsilon_W \end{cases}$$

$$\epsilon_E, \epsilon_F, \epsilon_W \sim \mathcal{N}(0, 100)$$





Interventions in SCMs

- An intervention $\text{do}(X_i = x_i)$ can be modelled by replacing

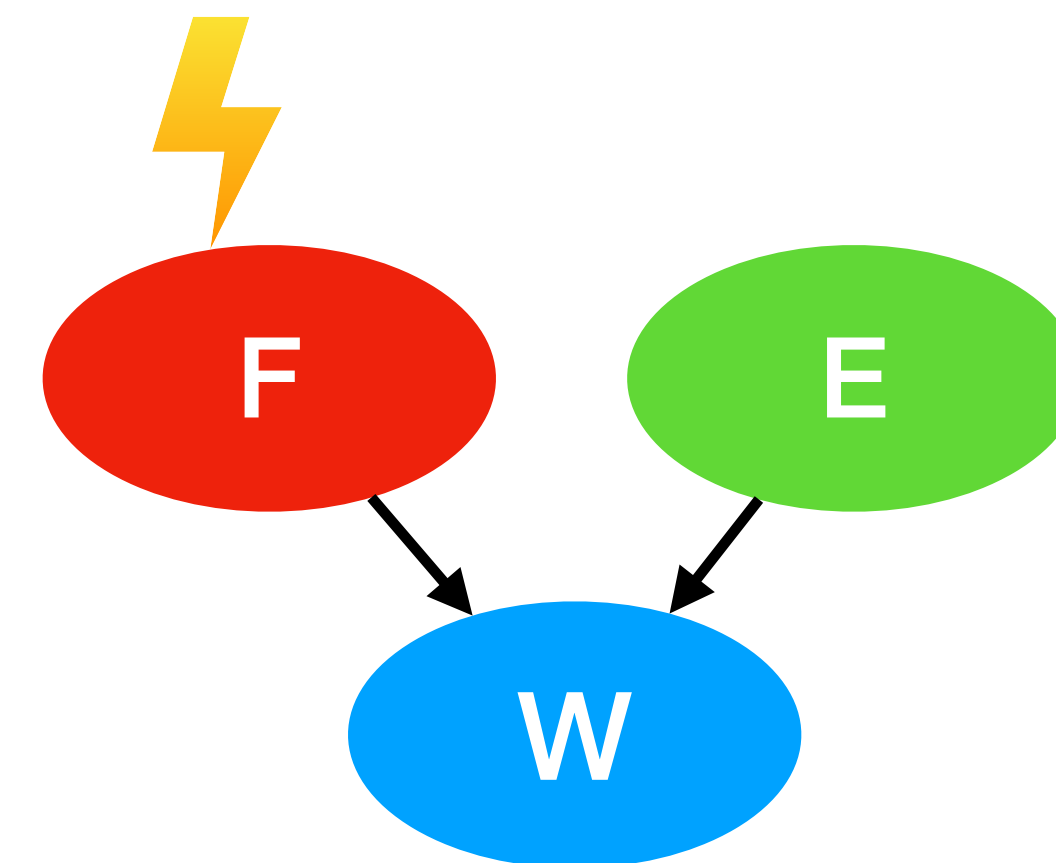
$$X_i \leftarrow h_i(X_{\text{Pa}(i)}, \epsilon_i) \text{ with } X_i \leftarrow x_i$$

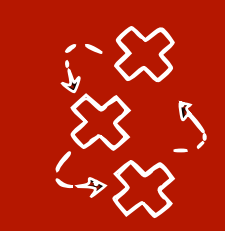
$$\text{do}(F=1200)$$

$$\begin{cases} F \leftarrow \cancel{2000} + \epsilon_F \\ E \leftarrow 500 + \epsilon_E \\ W \leftarrow \frac{F - E - 1500}{7700} + 0.1\epsilon_W \end{cases}$$

$$F \leftarrow 1200$$

$$\epsilon_E, \epsilon_F, \epsilon_W \sim \mathcal{N}(0, 100)$$

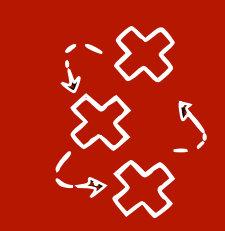




Example 3.2 in Elements of Causal Inference

$$\begin{cases} X \leftarrow \epsilon_X \\ Y \leftarrow 4 \cdot X + \epsilon_Y \end{cases}$$

$$\epsilon_X, \epsilon_Y \sim \mathcal{N}(0,1)$$

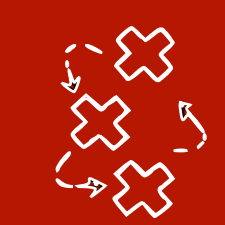


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$$P(X) = \mathcal{N}(0,1)$$



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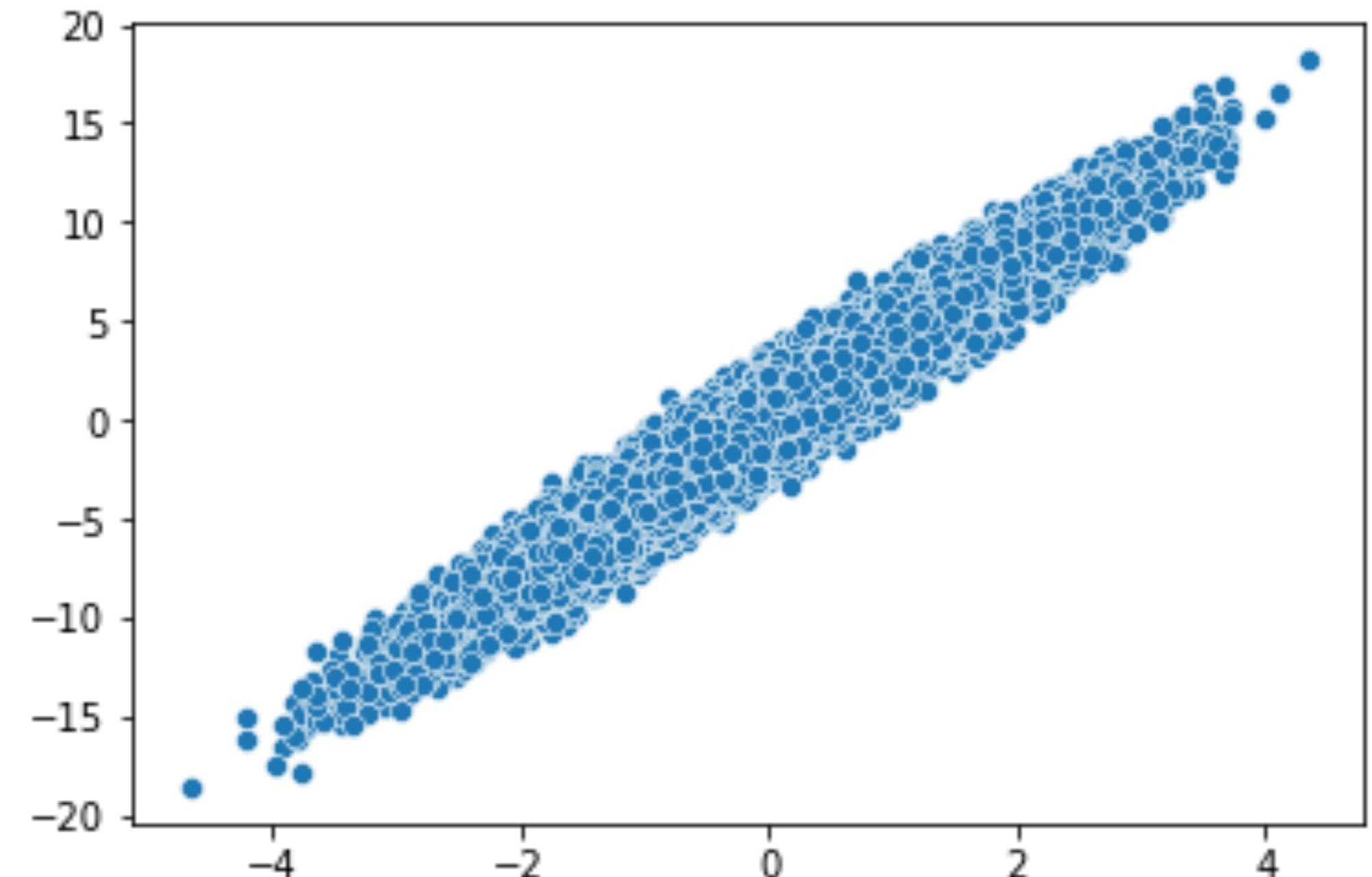
$$\epsilon_X, \epsilon_Y \sim \mathcal{N}(0,1)$$

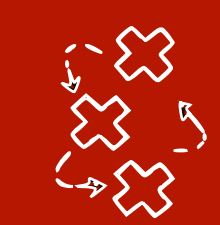
$$P(X) = \mathcal{N}(0,1)$$

$$P(Y) = 4 \cdot \mathcal{N}(0,1) + \mathcal{N}(0,1) = \mathcal{N}(0,17)$$

```
x = randn(n_samples)
y = 4 * x + randn(n_samples)
# plot P(X,Y)
sns.scatterplot(x=x,y=y)
```

<AxesSubplot:>





Example 3.2 in Elements of Causal Inference

$$\begin{cases} X \leftarrow \epsilon_X \\ Y \leftarrow 4 \cdot X + \epsilon_Y \end{cases}$$

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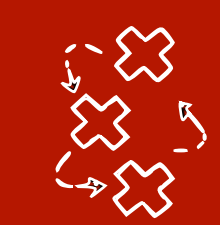
$$P(Y) = \mathcal{N}(0,17)$$

$$\text{do}(X=2):$$

$$\begin{cases} X \leftarrow 2 \\ Y \leftarrow 4 \cdot X + \epsilon_Y \end{cases}$$

$$\epsilon_X, \epsilon_Y \sim \mathcal{N}(0,1)$$

$$P(X | \text{do}(X=2)) = \begin{cases} 1 & X=2 \\ 0 & X \neq 2 \end{cases}$$



Example 3.2 in the SCM Jupyter notebook

$do(X=2):$

$$\begin{cases} X \leftarrow 2 \\ Y \leftarrow 4 \cdot X + \epsilon_Y \end{cases}$$

$$\epsilon_X, \epsilon_Y \sim \mathcal{N}(0,1)$$

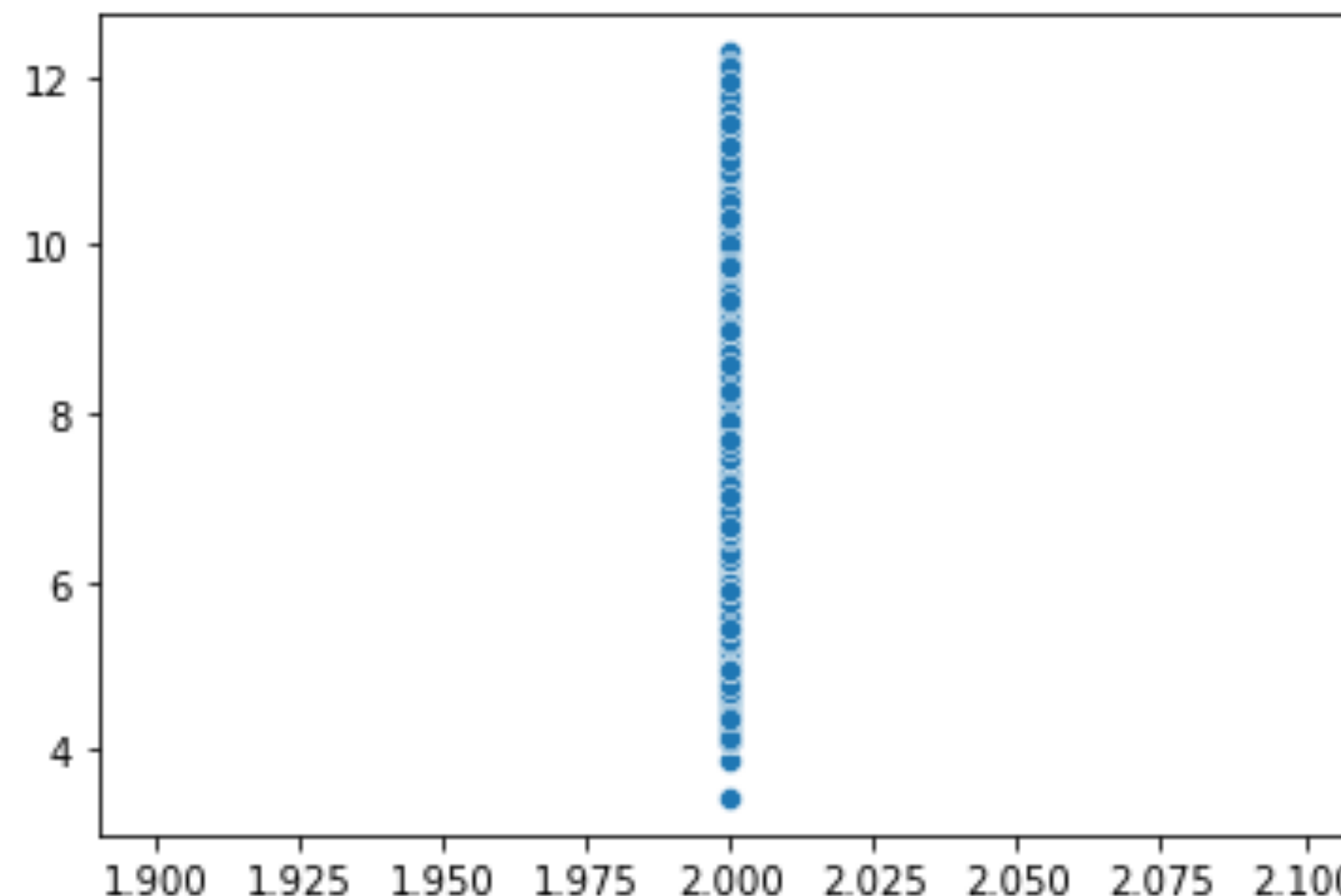
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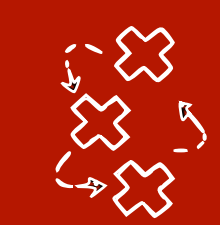
$$P(Y | do(X=2)) = \mathcal{N}(8, 1)$$

```
x_do_x = np.array([2] * n_samples, dtype="int32")
y_do_x = 4 * x_do_x + randn(n_samples)

# plot P(X,Y | do(X=2))
sns.scatterplot(x=x_do_x, y=y_do_x)
```

<AxesSubplot:>





A side note: perfect vs soft interventions

- We introduce a new operator that can represent a **hypothetical intervention** on the whole population, i.e. a perturbation of the system:

$$\text{do}(X_i = x_i) \text{ which changes } P(X_i | X_{\text{Pa}(i)}) \rightarrow \mathbf{1}(X_i = x_i)$$

- This is called a **perfect** (or surgical) **intervention**
- There are also other types of intervention, e.g. **soft interventions which change** $P(X_i | X_{\text{Pa}(i)}) \rightarrow P'(X_i | X_{\text{Pa}(i)})$



An example of soft interventions and shift interventions

$$\begin{cases} X \leftarrow \epsilon_X \\ Y \leftarrow 4 \cdot X + \epsilon_Y \end{cases}$$

$$\epsilon_X, \epsilon_Y \sim \mathcal{N}(0,1)$$

$$P(X) = \mathcal{N}(0,1)$$

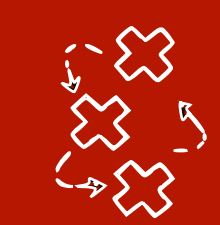
$$P(Y) = \mathcal{N}(0,17)$$

$$\begin{cases} X \leftarrow \epsilon_X \\ Y \leftarrow 4 \cdot X + \epsilon_Y \end{cases}$$

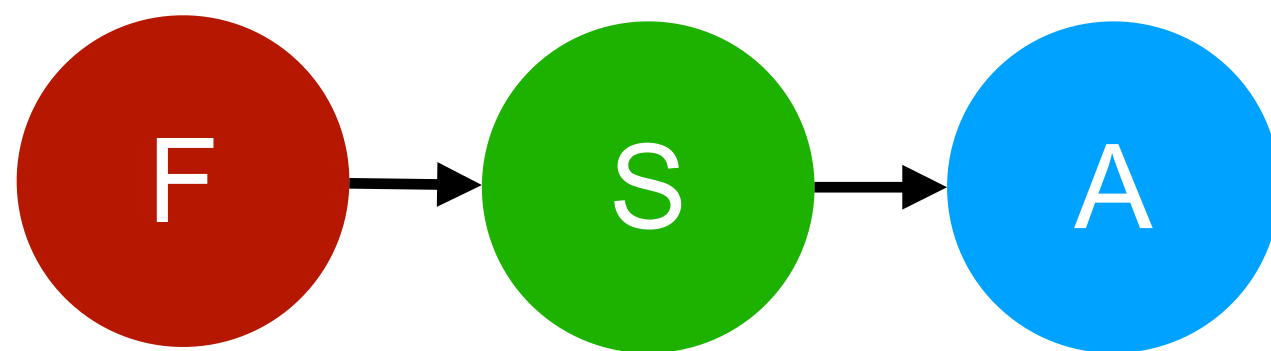
$$Y \leftarrow 2 \cdot X + \epsilon_Y$$

$$\begin{cases} X \leftarrow \epsilon_X \\ Y \leftarrow 4 \cdot X + \epsilon_Y + \epsilon' \end{cases}$$

$$Pa_{G^{do(Y)}}(Y) \subseteq Pa_G(Y)$$



Structural causal model for exercise in Canvas



$$P(F=1) = 0.01$$

$$P(S=1 | F=1) = 0.9$$

$$P(S=1 | F=0) = 0.2$$

$$P(A=1 | S=1) = 0.8$$

$$P(A=1 | S=0) = 0.1$$

$$\begin{cases} F \leftarrow \varepsilon_F \\ S \leftarrow h_S(F, \varepsilon_S) \\ A \leftarrow h_A(S, \varepsilon_A) \end{cases}$$

$\varepsilon_F, \varepsilon_S, \varepsilon_A$ are all indep.

```
n = 1000
```

```
F = binomial(1, 0.01, n)
```

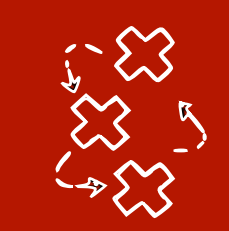
```
S = F * binomial(1, 0.9, n) + (1-F) * binomial(1, 0.2, n)
```

```
A = S * binomial(1, 0.8, n) + (1-S) * binomial(1, 0.1, n)
```

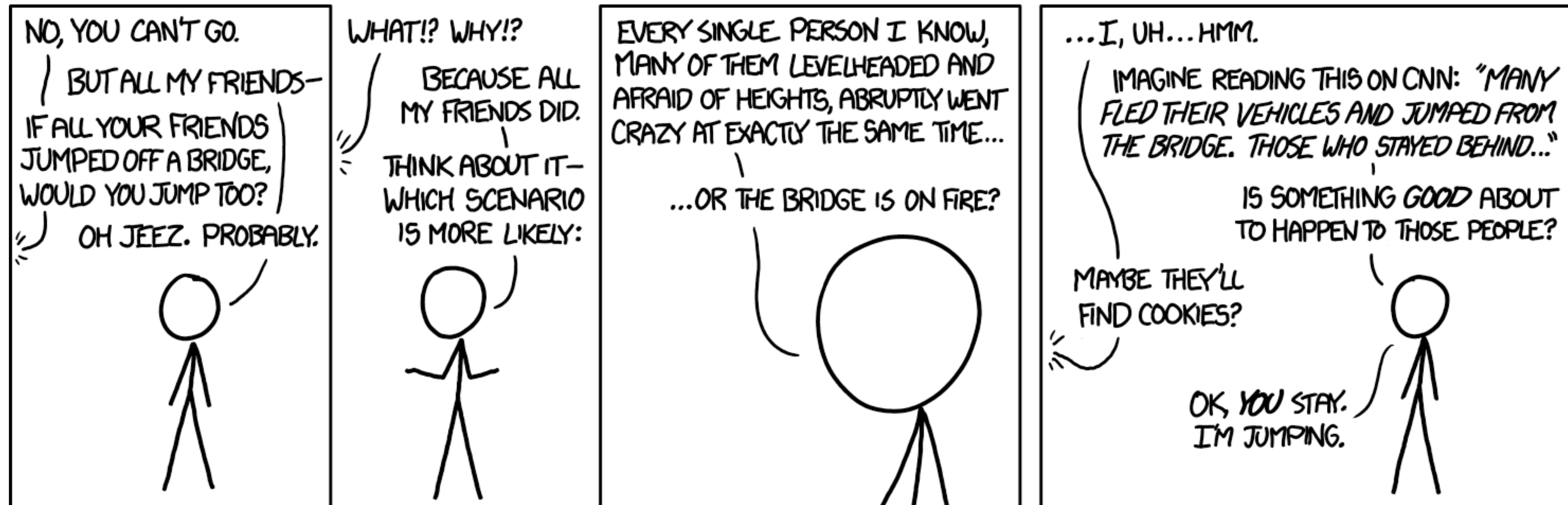
```
df = pd.DataFrame({"F":F, "S":S, "A": A})
```

```
P_S1 = len(df[S==1])/n
```

```
P_F1givenS1 = len(df[(df.F==1) & (df.S==1)]) / len(df[S==1])
```



Questions??



<https://xkcd.com/1170/>