# FYS4150 - Computational Physics - Project 5

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#### Abstract

### 1 Diffusion of neurotransmitters

I will study diffusion as a transport process for neurotransmitters across synaptic cleft separating the cell membrane of two neurons, for more detail see [3]. The diffusion equation is the partial differential equation

$$\frac{\partial u\left(\mathbf{x},t\right)}{\partial t} = \nabla \cdot \left(D\left(\mathbf{x},t\right) \nabla u\left(\mathbf{x},t\right)\right),\,$$

where u is the concentration of particular neurotransmitters at location  $\mathbf{x}$  and time t with the diffusion coefficient D. In this study I consider the diffusion coefficient as constant, which simplify the diffusion equation to the heat equation

$$\frac{\partial u(\mathbf{x},t)}{\partial t} = D\nabla^2 u(\mathbf{x},t) .$$

I will look at the concentration of neurotransmitter u in two dimensions with  $x_1$  parallel with the direction between the presynaptic to the postsynaptic across the synaptic cleft, and  $x_2$  is parallel with both presynaptic to the postsynaptic. Hence we have the differential equation

$$\frac{\partial u\left(\left\{x_{i}\right\}_{i=1}^{2},t\right)}{\partial t}=D\sum_{j=1}^{2}\frac{\partial^{2} u\left(\left\{x_{i}\right\}_{i=1}^{2},t\right)}{\partial x_{j}^{2}},$$
(1)

where  $\{x_i\}_{i=1}^2 = (x_1, x_2) = \mathbf{x}$ . The boundary and initial condition that I'm going to study is

$$\exists \{d, w\} \subseteq \mathbb{R}_{0+} \exists \{w_i\}_{i=1}^2 \subseteq \mathbb{R}_{0+}^{w^-} \Big( \forall t \in \mathbb{R}_0 : \forall x_2 \in \mathbb{R}_{w_1}^{w_2} : u(0, x_2, t) = u_0 
\land \forall t \in \mathbb{R} \Big( \forall x_2 \in \mathbb{R}_{0+}^{w^-} : u(d, x_2, t) = 0 \land \forall x_1 \in \mathbb{R}_0^d : \Big( u(x_1, 0, t) = 0 \land u(x_1, w, t) = 0 \Big) \Big) 
\land \forall x_1 \in \mathbb{R}_{0+}^{d^-} \forall x_2 \in \mathbb{R}_{0+}^{w^-} : u\Big( \{x_i\}_{i=1}^2, 0 \Big) = 0 \land \forall x_2 \in \mathbb{R}_0^w \setminus \mathbb{R}_{w_1}^{w_2} : u(0, x_2, 0) = 0 \Big)$$
(2)

where d is the distance between the presynaptic and the postsynaptic, and w is the width of the presynaptic and postsynaptic. Note that the notation  $\forall x \in \mathbb{R}^{b^-}_{a+} \Leftrightarrow a < x < b$ , where as  $\forall x \in \mathbb{R}^b_a \Leftrightarrow a \leq x \leq b$ . Note also that these boundary conditions implies that the neurotransmitters are transmitted from presynaptic at  $x_1 = 0$  and  $w_1 \leq x_2 \leq w_2$  with constant concentration  $u_0$ ; the neurotransmitters are immediately absorbed at the postsynaptic  $x_1 = d$ ; there are no neurotransmitters at boundary width  $x_2 = 0$  and  $x_2 = w$  of the synaptic cleft; and we have the initial condition at t = 0 where there are no neurotransmitters between the pre- and postsynaptic as well on the side of the

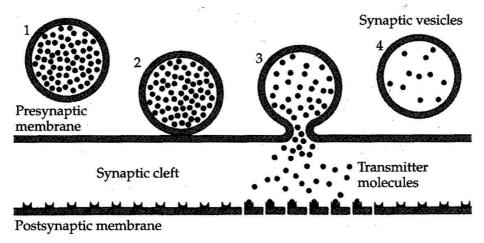


Figure 1.1: Left: Schematic drawing of the process of vesicle release from the axon terminal and release of transmitter molecules into the synaptic cleft. (From Thompson: "The Brain", Worth Publ., 2000). Right: Molecular structure of the two important neurotransmitters glutamate and GABA.

synaptic vesicles  $x_1 = 0$ ,  $0 \le x_2 < w_1$  and  $w_2 < x_2 \le w$ .

To solve the differential equation (1) with the boundary and initial condition (2) we make an ansatz that the solution is unique, which is the case for a deterministic system. We recognize the heat equation as part of the class of partial differential equations spanned by the Poisson's equation for each time instance. The Uniqueness theorem for the Poisson's equation  $\nabla^2 u = f$  [9] says that the Poisson's equation has a unique solution with the Dirichlet boundary condition, where Dirichlet boundary condition is here defined as a boundary that specifies the values the solution must have at the boundary. Not to be confused with Dirichlet boundary condition with zero at the boundary, which is just a special case and I will refer to it as 0th Dirichlet boundary condition.

Unfortunately the boundary condition in (2) is not a Dirichlet boundary, since the boundary is not specified on the side of the synaptic vesicles  $x_1 = 0$ ,  $0 \le x_2 < w_1$  and  $w_2 < x_2 \le w$ , and closer investigation will show that the boundary condition in (2) does not provide a unique solution. So we need to add further condition to make the solution unique, and I make an assumption that the total concentration u in an infinitesimal area has uniform concentration per length  $u_1$  and  $u_2$  in each direction u and u accordingly. Hence  $u = u_1u_2$  at every point and therefore we can write

$$\forall x_1 \in \mathbb{R}_0^d \forall x_2 \in \mathbb{R}_0^w \forall t \in \mathbb{R}_0 : u\left(\{x_i\}_{i=1}^2, t\right) = u_1\left(x_1, t\right) u_2\left(x_2, t\right). \tag{3}$$

Putting this into the heat equation (1) we get

$$u_{2}\left(x_{2},t\right)\frac{\partial u_{1}\left(x_{1},t\right)}{\partial t}+u_{1}\left(x_{1},t\right)\frac{\partial u_{2}\left(x_{2},t\right)}{\partial t}=D\left(u_{2}\left(x_{2},t\right)\frac{\partial^{2} u_{1}\left(x_{1},t\right)}{\partial x_{1}^{2}}+u_{1}\left(x_{1},t\right)\frac{\partial^{2} u_{2}\left(x_{2},t\right)}{\partial x_{2}^{2}}\right),$$

which can be written as two heat equations

$$\forall i \in \mathbb{N}_{1}^{2}: \frac{\partial u_{i}(x_{i}, t)}{\partial t} = D \frac{\partial^{2} u_{i}(x_{i}, t)}{\partial x_{i}^{2}}.$$
 (4)

I make another assumption that the boundary at  $u(0, x_2, t)$  determined by  $u_2(x_2, t)$  alone, and by satisfying initial condition  $u(0, x_2, 0)$  for  $u_2$ 

$$\forall t \in \mathbb{R}_0 \left( : u_2(0, t) = u_2(w, t) = 0 \land \forall x_2 \in \mathbb{R}_{w_1}^{w_2} : u_2(x_2, t) = u_0 \right) \land \forall x_2 \in \mathbb{R}_0^w \setminus \mathbb{R}_{w_1}^{w_2} : u_2(x_2, 0) = 0 \quad (5)$$

we have now determined the values on all the boundaries have therefore Dirichlet boundary condition, and therefore a unique solution of u. We found the analytical solution to the heat equation in (4) for i = 2 with similar boundary and initial condition in project 4 [3], and I will therefore not show the derivation here, but just state the solutions

$$u_{2}(x_{2},t) = u_{0} \begin{cases} \frac{x_{2}}{w_{1}} - \sum_{n=1}^{\infty} \frac{2}{n\pi} \sin\left(n\pi\left(1 - \frac{x_{2}}{w_{1}}\right)\right) \exp\left(-D\left(\frac{n\pi}{w_{1}}\right)^{2} t\right) & : x_{2} \in \mathbb{R}_{0}^{w_{1}} \\ 1 & : x_{2} \in \mathbb{R}_{w_{1}}^{w_{2}} \\ \frac{w - x_{2}}{w - w_{2}} - \sum_{n=1}^{\infty} \frac{2}{n\pi} \sin\left(n\pi\frac{x_{2} - w_{2}}{w - w_{2}}\right) \exp\left(-D\left(\frac{n\pi}{w - w_{2}}\right)^{2} t\right) & : x_{2} \in \mathbb{R}_{w_{2}}^{w}. \end{cases}$$

$$(6)$$

Since I have established that the boundary at  $u(0, x_2, t)$  determined by  $u_2(x_2, t)$  alone, means that  $u_1$  has the following boundary and initial condition

$$\forall t \in \mathbb{R}_0 \left( : u_1(0, t) = 1 \land u_1(d, t) = 0 \right) \land \forall x_1 \in \mathbb{R}_{0+}^{d-} : u_1(x_1, 0) = 0.$$
 (7)

And using the analytical solution from project 4 to heat equation (4) for i = 1 with boundary and initial condition in (7), we have

$$u_1(x_1, t) = 1 - \frac{x_1}{d} - \sum_{n=1}^{\infty} \frac{2}{n\pi} \sin\left(n\pi \frac{x_1}{d}\right) \exp\left(-D\left(\frac{n\pi}{d}\right)^2 t\right). \tag{8}$$

To summarize the solution to the concentration u is given by (3) with (6) and (8).

### 2 Numerical methods

#### **2.1** The $\theta$ -rule

The Taylor expansion is given by

$$u(x) = \sum_{n=0}^{\infty} \frac{u(x_0)}{n!} (x - x_0)^n$$
 (9)

where  $u = \frac{d^n u}{dr^n}$  and  $x_0$  is a initial value where we step from to x. If we now use the first order approximation

$$u(x) \approx u(x_0) + u^{(1)}(x_0)(x - x_0)$$
.

The first order differential equation  $\overset{(1)}{u}(x) = f(x)$  is determined when we have the initial condition  $u(x_0)$ , however  $\overset{(1)}{u}(x_0)$  is not an initial condition, and it depends on how we calculate it numerically

from the initial condition. Now note that  $u(x_0)$  is the same for different values of x in the approximation above and lets say that we calculate it as given from the approximation above;

$$\overset{(1)}{u}(x_0) \approx \frac{u(x) - u(x_0)}{x - x_0} \,. \tag{10}$$

So now use this in another point  $x_{\theta} = \theta x + (1 - \theta) x_0$  which we also approximate to the first order, and if we use the expression above for  $u(x_0)$  we get

$$u(x_{\theta}) \approx u(x_{0}) + u(x_{0})(x_{\theta} - x_{0}) = u(x_{0}) + \theta u(x_{0})(x - x_{0})$$

$$\approx u(x_{0}) + \frac{u(x) - u(x_{0})}{x - x_{0}} \theta(x - x_{0}) = \theta u(x) + (1 - \theta)u(x_{0}),$$
(11)

this is known as the  $\theta$ -rule. The  $\theta$ -rule can be used to approximate the solution of the following first order differential equation

$$\overset{(1)}{u}(x) = f\left(u(x)\right),\tag{12}$$

where we use (10) to approximate the expression u(x) and given an even better or worse approximation to the solution u(x) by approximating  $f(x) \approx f(x_{\theta})$ ;

$$\frac{u(x) - u(x_0)}{x - x_0} \approx f\left(u(x_\theta)\right) = f\left(\theta u(x) + (1 - \theta)u(x_0)\right),\,$$

which discretize to

$$\frac{u_{i+1} - u_i}{x_{i+1} - x_i} = f\left(\theta u_{i+1} + (1 - \theta)u_i\right) \quad \text{where } i \in \mathbb{N}_0 \text{ and } u_0 \text{ is an initial contidion.}$$
 (13)

We can find the next step in the numerical solution to (12) by solving this difference equation with regard to  $u_{i+1}$ . Note the above discretization is known as Forward Euler scheme (Explicit) when  $\theta = 0$ , Backward Euler scheme (Implicit) when  $\theta = 1$  and Crank-Nicolson scheme when  $\theta = \frac{1}{2}$ .

### 2.2 Second order derivative

We approximated the first order derivative in (10), but we need to approximate the second order derivative to be able to solve the diffusion in (1). I start by expanding the Taylor series in (9) around the point  $x_0 \pm \Delta x$  accordingly;

$$u(x_0 \pm \Delta x) = \sum_{n=0}^{\binom{n}{n}} \frac{u(x_0)}{n!} (\pm \Delta x)^n .$$
 (14)

Now adding these two expansions

$$u(x_0 + \Delta x) + u(x_0 - \Delta x) = 2\sum_{n=0}^{\infty} \frac{u(x_0)}{(2!)} \Delta x^{2n} = 2u(x_0) + u(x_0) \Delta x^2 + 2\sum_{n=2}^{\infty} \frac{u(x_0)}{(2!)} \Delta x^{2n},$$

and solve it with

$$u(x_0) = \frac{u(x_0 + \Delta x) - 2u(x_0) + u(x_0 - \Delta x)}{\Delta x^2} - 2 \sum_{n=2}^{\infty} \frac{u(x_0)}{(2!)} \Delta x^{2(n-1)}$$
$$= \frac{u(x_0 + \Delta x) - 2u(x_0) + u(x_0 - \Delta x)}{\Delta x^2} + O(\Delta x^2),$$

So the second order derivative can be approximated with

$$u(x_0) \approx \frac{u(x_0 + \Delta x) - 2u(x_0) + u(x_0 - \Delta x)}{\Delta x^2}$$
 (15)

with the local truncation error  $O(\Delta x^2)$ .

### 2.3 The heat equation

We want to discretize the dimensionless heat equation from (1), where we use D = 1,  $u_0 = 1$  and d = 1,

$$\frac{\partial u\left(\left\{x_{i}\right\}_{i=1}^{2},t\right)}{\partial t}=\sum_{\ell=1}^{2}\frac{\partial^{2} u\left(\left\{x_{i}\right\}_{i=1}^{2},t\right)}{\partial x_{\ell}^{2}},$$

to numerically solve diffusion of neurotransmitters. First we do the  $\theta$ -rule discretization in (13)

$$\frac{u_{(i+1)\{j_k\}_{k=1}^2} - u_{i\{j_k\}_{k=1}^2}}{\Delta t} = \sum_{\ell=1}^2 \frac{\partial^2 u_{(i+\theta)\{j_k\}_{k=1}^2}}{\partial x_\ell^2} = \sum_{\ell=1}^2 \frac{\partial^2 \left(\theta u_{(i+1)\{j_k\}_{k=1}^2 + (1-\theta) u_{i\{j_k\}_{k=1}^2}}{\partial x_\ell^2}\right)}{\partial x_\ell^2}$$

$$= \sum_{\ell=1}^2 \left(\theta \frac{\partial u_{(i+1)\{j_k\}_{k=1}^2}}{\partial x_\ell^2} + (1-\theta) \frac{\partial u_{i\{j_k\}_{k=1}^2}}{\partial x_\ell^2}\right)$$

where index *i* is stepping of *t* and  $j_k$  are stepping of  $x_k$ . Note also that the following notation expand accordingly  $u_{i\{j_k\}_{k=1}^2} = u_{ij_1j_2}$ , which becomes a more elegant notation for larger *n* in  $u_{i\{j_k\}_{k=1}^n} = u_{ij_1j_2...j_n}$ . Now we implement the discretization of the second order in (15)

$$\frac{u_{(i+1)\{j_k\}_{k=1}^2} - u_{i\{j_k\}_{k=1}^2}}{\Delta t} = \sum_{\ell=1}^2 \left( \frac{\theta}{\Delta x_\ell^2} \left( u_{(i+1)\{j_k + \delta_{k\ell}\}_{k=1}^2} - 2u_{(i+1)\{j_k\}_{k=1}^2} + u_{(i+1)\{j_k - \delta_{k\ell}\}_{k=1}^2} \right) + \frac{1 - \theta}{\Delta x_\ell^2} \left( u_{i\{j_k + \delta_{k\ell}\}_{k=1}^2} - 2u_{i\{j_k\}_{k=1}^2} + u_{i\{j_k - \delta_{k\ell}\}_{k=1}^2} \right) \right), \tag{16}$$

where  $\delta_{k\ell}$  is the Kronecker delta, and we now clearly see the elegance of the notation  $u_{i\{j_k\}_{k=1}^n}$ .

The dimensionless initial condition from (4) gives us

$$u_{0\{j_k\}_{k=1}^2} = \begin{cases} 1 & : j_1 = 0 \text{ and } x_{2j_2} \in \mathbb{R}_{w_1}^{w_2} \\ 0 & : \text{elsewhere,} \end{cases}$$

where  $x_{2j_2} = x_{20} + \frac{j_2}{\Delta x_2}$ . For the explicit scheme  $\theta = 0$  we get

$$u_{(i+1)\{j_k\}_{k=1}^2} = u_{i\{j_k\}_{k=1}^2} + \sum_{\ell=1}^2 \alpha_\ell \left( u_{i\{j_k + \delta_{k\ell}\}_{k=1}^2} - 2u_{i\{j_k\}_{k=1}^2} + u_{i\{j_k - \delta_{k\ell}\}_{k=1}^2} \right)$$

$$(17)$$

where

$$\alpha_{\ell} = \frac{\Delta t}{\Delta x_{\ell}^2}$$
 and  $n_{\ell} = \frac{1}{\Delta x_{\ell}}$ ,

where  $n_{\ell}$  is number of grid points in  $\ell$  direction.

### 2.3.1 Stability and convergence

According to Lax equivalence theorem a consistent finite difference method for well-posed (a solution exists, unique and continuous) linear initial value problem, the method is convergent if and only if stable. Which means that we only can show either stability and convergence to show both.

There is a theorem that states that a matrix **A** converges  $\lim_{i\to\infty} \mathbf{A}^i = 0$  if and only if the spectral radius  $\rho(\mathbf{A}) < 1$ . The spectral radius is defined as

$$\rho\left(\mathbf{A}\right) = \max_{m} \left| \lambda_{m} \right| ,$$

where  $\lambda_m$  are the eigenvalues of **A**. The explicit scheme in (17) can be written as  $\mathbf{u}_{i+1} = \mathbf{A}\mathbf{u}_i = \mathbf{A}^{i+1}\mathbf{u}_0$ , and the this matrix can be written as

$$\mathbf{A} = \mathbf{I} - \sum_{\ell=1}^{2} \alpha_{\ell} \mathbf{B}$$

where **I** is the identity matrix and **B** is the tridiagonal matrix -1, 2, -1. This implies that the eigenvalues  $\mu_m$  of **B** is related to the eigenvalues  $\lambda_m$  of **A** as follows

$$\lambda_m = 1 - \sum_{\ell=1}^2 \alpha_\ell \mu_m \,. \tag{18}$$

The eigenvalues  $\mu_m$  can be found from the eigenequation

$$-u_{i\{j_k+\delta_{k\ell}\}_{k=1}^2} + 2u_{i\{j_k\}_{k=1}^2} - u_{i\{j_k-\delta_{k\ell}\}_{k=1}^2} = \mu_m u_{i\{j_k\}_{k=1}^2}.$$
 (19)

If we divide this equation by  $\Delta x_{\ell}^2$  we get a discretization of the following equation

$$u\left(\left\{x_{i}\right\}_{i=1}^{2},t\right)=-\omega_{\ell m}\frac{\partial^{2} u\left(\left\{x_{i}\right\}_{i=1}^{2},t\right)}{\partial x_{\ell}^{2}},$$

which has the solution

$$u\left(\left\{x_{i}\right\}_{i=1}^{2},t\right) = A\left(t\right) \prod_{\ell=1}^{2} \sin\left(\omega_{\ell m} x_{\ell} + \varphi_{\ell}\right)$$

where

$$\omega_{\ell m} = \frac{\Delta x_{\ell}}{\sqrt{\mu_m}} = \frac{1}{n_{\ell} \sqrt{\mu_m}}.$$

Now using this solution into the eigenequation (19) we get

$$-\sin\left(\omega_{\ell m}\left(x_{\ell j_{\ell}}+\Delta x_{\ell}\right)+\varphi_{\ell}\right)+2\sin\left(\omega_{\ell m}x_{\ell j_{\ell}}+\varphi_{\ell}\right)-\sin\left(\omega_{\ell m}\left(x_{\ell j_{\ell}}-\Delta x_{\ell}\right)+\varphi_{\ell}\right)=\mu_{i}\sin\left(\omega_{\ell m}x_{\ell j_{\ell}}+\varphi_{\ell}\right)$$

which can be simplified with the trigonometrical relation  $\sin(u + v) = \sin u \cos v + \cos u \sin v$ 

$$\mu_m = 2(1 - \cos(\omega_{\ell m} \Delta x_{\ell}))$$
  $\Rightarrow$   $0 < \mu_m \le 4$  for real  $\mu_m$ .

note that  $\mu_m \neq 0$  because of  $\omega_{\ell m} \propto \frac{1}{\sqrt{\mu_m}}$ . Inserting these eigenvalues into (18) and using the convergence condition  $\rho(\mathbf{A}) < 1$  yields the following inequality

$$-1 < 1 - \sum_{\ell=1}^{2} \alpha_{\ell} \mu_{m} < 1$$

which result in the constraint for convergences

$$\sum_{\ell=1}^{2} \alpha_{\ell} < \frac{1}{2},$$

where the  $\alpha_{\ell}$  is always positive. So when we want to solve the heat equation explicitly we must chose a time step accordingly

$$\Delta t < \frac{1}{2\sum_{\ell=1}^{2} n_{\ell}^{2}}.$$
 (20)

#### 2.4 Jacobi's iterative method

When we have  $\theta \neq 0$  in (16) we have implicit schemes, and I rewrite (16) with unknowns on the left side and knowns on the right side;

$$\begin{aligned} \forall k \in \mathbb{N}_{1}^{2} \forall j_{k} \in \mathbb{N}_{1}^{n_{k}-2} : \left(1 + 2\theta \sum_{\ell=1}^{2} \alpha_{\ell}\right) u_{(i+1)\{j_{k}\}_{k=1}^{2}} - \theta \sum_{\ell=1}^{2} \alpha_{\ell} \left(u_{(i+1)\{j_{k}+\delta_{k\ell}\}_{k=1}^{2}} + u_{(i+1)\{j_{k}-\delta_{k\ell}\}_{k=1}^{2}}\right) \\ &= \left(1 - 2\left(1 - \theta\right) \sum_{\ell=1}^{2} \alpha_{\ell}\right) u_{i\{j_{k}\}_{k=1}^{2}} + \left(1 - \theta\right) \sum_{\ell=1}^{2} \alpha_{\ell} \left(u_{i\{j_{k}+\delta_{k\ell}\}_{k=1}^{2}} + u_{i\{j_{k}-\delta_{k\ell}\}_{k=1}^{2}}\right), \end{aligned}$$

where the boundary are given at the indices  $j_k = 0$  and  $j_k = n_k - 1$  where  $n_k$  are the number of points i k direction. Now I will transform this into a linear algebra problem  $\mathbf{A}_{i+1}\mathbf{v}_{i+1} = \mathbf{b}_i$ , where elements of  $\mathbf{v}_{i+1}$  are

$$v_{(i+1)j} = v_{(i+1)(j_1 n_2 + j_2)} = u_{(i+1)\{j_k\}_{k-1}^2}.$$
(21)

The fixed boundary values with  $u_0 = 1$  at the presynaptic  $x_1 = 0$  and  $w_1 \le x_2 \le w_2$  are given by the indices j in the set

$$\mathbb{B}_1 = \mathbb{N}_{m_1}^{m_2}$$
.

We have non-fixed values at the boundary on the side of the synaptic vesicles at the presynaptic  $x_1 = 0$ ,  $0 \le x_2 < w_1$  and  $w_2 < x_2 < w$ , and are given by the indices j in the set

$$\mathbb{B}_2 = j \in \mathbb{N}_0^{n_2 - 1} \setminus \mathbb{B}_1.$$

The boundary values at the postsynaptic  $x_1 = d$  are given by the indices j in the set

$$\mathbb{B}_3 = \mathbb{N}_{n_1 n_2 - n_2}^{n_1 n_2 - 1} .$$

The left side boundary  $x_2 = 0$  are given by the indices j in the set

$$\mathbb{B}_4 = \{\ell n_2\}_{\ell=1}^{n_1-2} \ .$$

The right side boundary  $x_2 = w$  are given by the indices j in the set

$$\mathbb{B}_5 = \{\ell n_2 - 1\}_{\ell=2}^{n_1-1} .$$

And the boundary as a whole are given by the indices j in the set

$$\mathbb{B} = \bigcup_{i=1}^{5} \mathbb{B}_{i}.$$

The inner points are given by the indices j in the set

$$\mathbb{I} = \mathbb{N}_0^{n_1 n_2 - 1} \setminus \mathbb{B} .$$

We can now write the matrix elements of  $A_{(i+1)}$ 

$$a_{(i+1)jk} = a_{jk} = \begin{cases} 1 & : \forall j \in \mathbb{B} \setminus \mathbb{B}_2 : j = k \\ 1 + 2\theta\alpha_2 & : \forall j \in \mathbb{B}_2 : j = k \\ 1 + 2\theta\sum_{\ell=1}^2 \alpha_\ell & : \forall j \in \mathbb{I} : j = k \\ -\theta\alpha_2 & : \forall j \in \mathbb{I} \cup \mathbb{B}_2 : k \in \{j-1, j+1\} \\ -\theta\alpha_1 & : \forall j \in \mathbb{I} : k \in \{j-n_2, j+n_2\} \end{cases}$$
 (diffusion in  $x_2$  direction) (22)

and the elements of the vector  $\mathbf{b}_i$  are

$$b_{ij} = b_{i(j_{1}n_{2}+j_{2})} = \begin{cases} 1 & : j \in \mathbb{B}_{1} \\ (1-2(1-\theta)\alpha_{2})u_{i0j_{2}} + (1-\theta)\alpha_{2}\left(u_{i0(j_{2}+1)} + u_{i0(j_{2}-1)}\right) & : j \in \mathbb{B}_{2} \\ (1-2(1-\theta)\sum_{\ell=1}^{2}\alpha_{\ell})u_{i\{j_{k}\}_{k=1}^{2}} + (1-\theta)\sum_{\ell=1}^{2}\alpha_{\ell}\left(u_{i\{j_{k}+\delta_{k\ell}\}_{k=1}^{2}} + u_{i\{j_{k}-\delta_{k\ell}\}_{k=1}^{2}}\right) & : j \in \mathbb{I} \\ 0 & : \text{otherwise.} \end{cases}$$

Unfortunately is the linear algebra problem  $\mathbf{A}\mathbf{v}_{i+1} = \mathbf{b}_i$  is computational expensive to solve for the matrix in (22). To lower the computational time I therefore prepare the matrix  $\mathbf{A}$  for Jacobi's iterative method by splitting it into a diagonal matrix  $\mathbf{D}$  and a remainder matrix  $\mathbf{R}$ ;

$$A = D + R$$
.

From (22) we see that the elements of the diagonal matrix are given by

$$d_{jk} = \begin{cases} 1 & : \forall j \in \mathbb{B} \setminus \mathbb{B}_2 : j = k \\ 1 + 2\theta\alpha_2 & : \forall j \in \mathbb{B}_2 : j = k \\ 1 + 2\theta\sum_{\ell=1}^2 \alpha_\ell & : \forall j \in \mathbb{I} : j = k \\ 0 & : \text{ otherwise,} \end{cases}$$
 (fixed boundary)
$$(\text{side of vesicles})$$

$$(\text{the inner points } u_{(i+1)j_1j_2})$$

and the elements of the remainder matrix are given by

$$r_{jk} = \begin{cases} -\theta \alpha_2 &: \forall j \in \mathbb{I} \cup \mathbb{B}_2 : k \in \{j-1, j+1\} \\ -\theta \alpha_1 &: \forall j \in \mathbb{I} : k \in \{j-n_2, j+n_2\} \\ 0 &: \text{otherwise.} \end{cases}$$
 (diffusion in  $x_1$  direction) (25)

We can now introduce Jacobi's iterative method

$$\mathbf{v}_{i+1}^{(\ell)} = \begin{cases} \mathbf{v}_i & : \ell = 0\\ \mathbf{D}^{-1} \left( \mathbf{b}_i - \mathbf{R} \mathbf{v}_{i+1}^{(\ell-1)} \right) & : \ell \in \mathbb{N}_1 \end{cases}$$

where  $\ell$  is the number of iterations and  $\ell = 0$  are the starting point. Rewriting it on element form yields

$$v_{(i+1)j}^{(\ell)} = \begin{cases} v_j & : \ell = 0\\ \frac{1}{d_{jj}} \left( b_j - \sum_{k \neq j} r_{jk} v_{(i+1)k}^{(\ell-1)} \right) & : j \in \mathbb{N}_1 . \end{cases}$$

Using (21) and (25) we have the iterative solution to the heat equation in (6) with the boundaries in (2)

$$u_{(i+1)\{j_{k}\}_{k=1}^{2}}^{(\ell)} = \begin{cases} u_{i\{j_{k}\}_{k=1}^{2}} & : \ell = 0 \\ 1 & : j_{1} = 0 \land j_{2} \in \mathbb{N}_{m_{1}}^{m_{2}} \\ c_{0} + c_{1} \left( u_{(i+1)0(j_{2}+1)}^{(\ell-1)} + u_{(i+1)0(j_{2}-1)}^{(\ell-1)} \right) & : j_{1} = 0 \land j_{2} \in \mathbb{N}_{0}^{n_{2}-1} \setminus \mathbb{N}_{m_{1}}^{m_{2}} \end{cases}$$

$$c_{2} + \sum_{o=1}^{2} c_{o+2} \left( u_{(i+1)\{j_{k}+\delta_{ko}\}_{k=1}^{2}}^{(\ell-1)} + u_{(i+1)\{j_{k}-\delta_{ko}\}_{k=1}^{2}}^{(\ell-1)} \right) & : j_{1} \in \mathbb{N}_{1}^{n_{1}-2} \land j_{2} \in \mathbb{N}_{1}^{n_{2}-2} \end{cases}$$

$$(26)$$

$$c_0 = c_5 u_{i0j_2} + c_6 \left( u_{i0(j_2+1)} + u_{i0(j_2-1)} \right) \tag{27}$$

$$c_1 = \frac{\theta \alpha_2}{1 + 2\theta \alpha_2} \tag{28}$$

$$c_2 = c_7 u_{i\{j_k\}_{k=1}^2} + \sum_{\ell=1}^2 c_{\ell+7} \left( u_{i\{j_k + \delta_{k\ell}\}_{k=1}^2} + u_{i\{j_k - \delta_{k\ell}\}_{k=1}^2} \right)$$
(29)

$$c_3 = \frac{\theta \alpha_1}{1 + 2\theta \sum_{\ell=1}^2 \alpha_\ell} \tag{30}$$

$$c_4 = \frac{\theta \alpha_2}{1 + 2\theta \sum_{\ell=1}^2 \alpha_\ell} \tag{31}$$

$$c_5 = \frac{1 - 2(1 - \theta)\alpha_2}{1 + 2\theta\alpha_2} \tag{32}$$

$$c_6 = \frac{(1-\theta)\alpha_2}{1+2\theta\alpha_2} \tag{33}$$

$$c_7 = \frac{1 - 2(1 - \theta) \sum_{\ell=1}^2 \alpha_\ell}{1 + 2\theta \sum_{\ell=1}^2 \alpha_\ell}$$
(34)

$$c_8 = \frac{(1-\theta)\alpha_1}{1 + 2\theta\sum_{\ell=1}^2 \alpha_\ell}$$
 (35)

$$c_9 = \frac{(1-\theta)\alpha_2}{1+2\theta\sum_{\ell=1}^2 \alpha_{\ell}}$$
 (36)

#### 2.4.1 Stability and convergence

The same procedure as discussed for convergence and stability for the explicit scheme applies for the Jacobi method as well, but now with the spectral radius  $\rho(\mathbf{D}^{-1}\mathbf{R}) < 1$ , because the Jacobi method are given by

$$\mathbf{v}_{i+1}^{(\ell)} = \mathbf{D}^{-1} \left( \mathbf{b}_i - \mathbf{R} \mathbf{v}_{i+1}^{(\ell-1)} \right) = \mathbf{D}^{-1} \sum_{i=0}^{\ell-1} \left( -\mathbf{D}^{-1} \mathbf{R} \right)^j \mathbf{b}_i + \left( -\mathbf{D}^{-1} \mathbf{R} \right)^\ell \mathbf{v}_{i+1}^{(0)}.$$

Similar steps as shown in section 2.3.1 it can be shown that the always converges for our diffusion problem. More generally it can be shown that the Jacobi iterative method converges when the matrix A = D + R is diagonally dominant

$$|a_{ii}| > \sum_{i \neq i} |a_{ij}|,$$

which is the case for the matrix spanned out by (22) because  $1 + 2\theta\alpha_2 > 2\theta\alpha_2$  and  $1 + 2\theta\sum_{\ell=1}^2 \alpha_\ell > 2\theta\sum_{\ell=1}^2 \alpha_\ell$ .

#### 2.5 Markov chains

I assume that diffusion is a memoryless physical process that approximates to a stochastic process, hence diffusion is assumed to satisfy the Markov property and therefore is a Markov process where the transition between states are described by Markov chains

$$w_{(i+1)\{j_k\}_{k=1}^n}^+ = \sum_{\{\ell_k\}_{k=1}^n} W_{\{j_k\}_{k=1}^n \{\ell_k\}_{k=1}^n} w_{i\{\ell_k\}_{k=1}^n},$$
(37)

where  $w_{i\{j_k\}_{k=1}^n}$  is the probability distribution function "PDF" at time step i, and  $W_{\{j_k\}_{k=1}^n\{\ell_k\}_{k=1}^n}$  is the transition probability from state  $\{\ell_k\}_{k=1}^n$  to  $\{j_k\}_{k=1}^n$ . And the reverse Markov chain is given by

$$w_{(i+1)\{j_k\}_{k=1}^n}^- = \sum_{\{\ell_k\}_{k=1}^n} W_{\{\ell_k\}_{k=1}^n \{j_k\}_{k=1}^n} w_{i\{j_k\}_{k=1}^n},$$
(38)

Using the assumption that diffusion can be modelled as Markov process then we can use a Master equation to describe the normalized concentration at time step i+1 by the difference of transition to and from the state  $\left\{j_k\right\}_{k=1}^n$  plus the amount that stays in the state;

$$u_{(i+1)\{j_k\}_{k=1}^n} = W_{\{j_k\}_{k=1}^n \{j_k\}_{k=1}^n w_{i\{j_k\}_{k=1}^n} + w_{(i+1)\{j_k\}_{k=1}^n}^+ - w_{(i+1)\{j_k\}_{k=1}^n}^-$$
(39)

Note that the reverse Markov chain is all the transitions that a state  $\{j_k\}_{k=1}$  takes, including transition to itself. Therefore the reverse Markov chain in time step i+1 describes the transition of the entire concentration at time step i;

$$u_{i\{j_k\}_{k=1}^n} = w_{(i+1)\{j_k\}_{k=1}^n}^-$$
.

We assume that one can't stay in the same state  $W_{\{j_k\}_{k=1}^n \{j_k\}_{k=1}^n} = 0$ , hence all of the concentration should transition to other states at any given time step, which yields

$$u_{(i+1)\{j_k\}_{k=1}^n} = w_{(i+1)\{j_k\}_{k=1}^n}^+ - u_{i\{j_k\}_{k=1}^n}.$$

$$(40)$$

Further, diffusion is assumed to be approximated as stochastic move in distance and direction, where distance and direction is stochastically independent. Which means that transition probability can be written as

$$W_{\{j_k\}_{k=1}^n \{\ell_k\}_{k=1}^2} = T_{\{j_k\}_{k=1}^n \{\ell_k\}_{k=1}^2} A_{\{j_k\}_{k=1}^n \{\ell_k\}_{k=1}^2}, \tag{41}$$

where  $T_{\{j_k\}_{k=1}^n \{\ell_k\}_{k=1}^2}$  is the probability of moving the distance between the states  $\{j_k\}_{k=1}^n$  and  $\{\ell_k\}_{k=1}^2$ , and  $A_{\{j_k\}_{k=1}^n \{\ell_k\}_{k=1}^2}$  is the probability of moving in the direction between the states  $\{j_k\}_{k=1}^n$  and  $\{\ell_k\}_{k=1}^2$ .

Assume that we move a distance  $\ell$  from state  $\left\{j_k\right\}_{k=1}^n$ , which means that the states  $\left\{j_k + \delta_{km}\ell\right\}$  are the possible destinations, which puts the following constraint on the direction probability A;

$$\sum_{m=1}^{n} \left( A_{\left\{ j_{k} + \delta_{km}\ell \right\}_{k=1}^{n} \left\{ j_{k} \right\}_{k=1}^{n}} + A_{\left\{ j_{k} - \delta_{km}\ell \right\}_{k=1}^{n} \left\{ j_{k} \right\}_{k=1}^{n}} \right) = 1.$$

Now assuming isotropic diffusion, which means that

$$\forall m, o \in \mathbb{N}_{1}^{n} : A_{\{j_{k} \pm \delta_{km}\ell\}_{k=1}^{n} \{j_{k}\}_{k=1}^{n}} = A_{\{j_{k} \pm \delta_{ko}\ell\}_{k=1}^{n} \{j_{k}\}_{k=1}^{n}}$$
$$\forall m, o \in \mathbb{N}_{1}^{n} : T_{\{j_{k} \pm \delta_{km}\ell\}_{k=1}^{n} \{j_{k}\}_{k=1}^{n}} = T_{\{j_{k} \pm \delta_{ko}\ell\}_{k=1}^{n} \{j_{k}\}_{k=1}^{n}}$$

and the constraint on the direction probability then yields

$$A = A_{\{j_k\}_{k=1}^n \{\ell_k\}_{k=1}^n} = \frac{1}{2n},$$
(42)

and the distance probability T is only dependent on the distance  $\ell$ 

$$p_{\ell} = T_{\{j_k \pm \delta_{km}\ell\}_{k=1}^n \{j_k\}_{k=1}^n},$$

which has the constraint

$$\sum_{\ell} p_{\ell} = 1.$$

Then the normalized concentration (40) is now given by

$$u_{(i+1)(j_k)_{k=1}^n} = \frac{1}{2n} \sum_{\ell} p_{\ell} \sum_{m=1}^n \left( u_{i\{j_k + \delta_{km}\ell\}_{k=1}^n} + u_{i\{j_k - \delta_{km}\ell\}_{k=1}^n} \right) - u_{i\{j_k\}_{k=1}^n},$$

which can be rewritten to

$$\frac{u_{(i+1)\{j_k\}_{k=1}^n - u_{i\{j_k\}_{k=1}^n}}}{\Delta t} = \sum_{\ell} \frac{p_{\ell} (\ell \Delta x)^2}{2n\Delta t} \sum_{m=1}^n \frac{u_{i\{j_k + \delta_{km}\ell\}_{k=1}^n - 2u_{i\{j_k\}_{k=1}^n} + u_{i\{j_k - \delta_{km}\ell\}_{k=1}^n}}{(\ell \Delta x)^2}.$$
 (43)

When we have the Kronecker delta distribution  $p_{\ell} = \delta_{1\ell}$  this becomes the discretization of the heat equation in (1)

$$\frac{u_{(i+1)\{j_k\}_{k=1}^n - u_{i\{j_k\}_{k=1}^n}}}{\Delta t} = \frac{\Delta x^2}{2n\Delta t} \sum_{m=1}^n \frac{u_{i\{j_k + \delta_{km}\}_{k=1}^n - 2u_{i\{j_k\}_{k=1}^n + u_{i\{j_k - \delta_{km}\}_{k=1}^n}}}{\Delta x^2},$$

with the relation to the diffusion constant D as follows

$$\Delta x = \sqrt{2nD\Delta t} \,. \tag{44}$$

For a general distribution  $p_{\ell}$  we see from (43) that the step length now is given by

$$\Delta x_{\ell} = \ell \Delta x = \ell \sqrt{2nD\Delta t} \,. \tag{45}$$

If we use a random generator to make a proposition to move at each time step, we get a deterministic running time with approximation in the result, which is known as Monte Carlo algorithm.

#### 2.5.1 Metropolis-Hastings algorithm

The steps above with Markov chains are designed to give a approximated time evolution. However if we are only interested in the steady state solution, we can derive a faster algorithm to reach it, which is the Metropolis-Hastings algorithm. To derive the Metropolis-Hastings algorithm we start by looking back at the Master equation in (39) for equilibrium, where we realize that transition to and from the state  $\left\{j_k\right\}_{k=1}^n$  must be equal

$$\lim_{i \to \infty} \left( w_{(i+1)\{j_k\}_{k=1}^n}^+ - w_{(i+1)\{j_k\}_{k=1}^n}^- \right) = 0$$

and that concentration remains the same

$$\lim_{i \to \infty} u_{(i+1)\{j_k\}_{k=1}^n} = \lim_{i \to \infty} W_{\{j_k\}_{k=1}^n \{j_k\}_{k=1}^n} w_{i\{j_k\}_{k=1}^n} = \lim_{i \to \infty} u_{i\{j_k\}_{k=1}^n}.$$

Using the equality of transition to and from the state  $\{j_k\}_{k=1}^n$  at equilibrium, the Markov chains in (37) and (38), with proposed transition distribution T which is independent of the accepted A, must satisfy the following equation

$$\sum_{\{\ell_k\}_{k=1}^n} \left( T_{\{j_k\}_{k=1}^n \{\ell_k\}_{k=1}^n} A_{\{j_k\}_{k=1}^n \{\ell_k\}_{k=1}^n} w_{i\{\ell_k\}_{k=1}^n} - T_{\{\ell_k\}_{k=1}^n \{j_k\}_{k=1}^n} A_{\{\ell_k\}_{k=1}^n \{j_k\}_{k=1}^n} w_{i\{j_k\}_{k=1}^n} \right) = 0,$$

which is satisfied by the relation

$$\frac{A_{\{j_k\}_{k=1}^n\{\ell_k\}_{k=1}^n}}{A_{\{\ell_k\}_{k=1}^n\{j_k\}_{k=1}^n}} = \frac{T_{\{\ell_k\}_{k=1}^n\{j_k\}_{k=1}^n} w_{i\{j_k\}_{k=1}^n}}{T_{\{j_k\}_{k=1}^n\{\ell_k\}_{k=1}^n} w_{i\{\ell_k\}_{k=1}^n}},$$

where T is a distribution that we propose and A is a probability to accept the proposition. We reach equilibrium faster when the transition from states are as large as possible, which means  $A_{\{j_k\}_{k=1}^n \{\ell_k\}_{k=1}^n}$  should be as close to 1 as possible and still satisfy that  $A_{\{\ell_k\}_{k=1}^n \{j_k\}_{k=1}^n} \leq 1$ , which is the Metropolis-Hastings algorithm;

$$A_{\{\ell_k\}_{k=1}^n \{j_k\}_{k=1}^n} = \min\left(1, \frac{T_{\{j_k\}_{k=1}^n \{\ell_k\}_{k=1}^n W_i \{\ell_k\}_{k=1}^n}}{T_{\{\ell_k\}_{k=1}^n \{j_k\}_{k=1}^n W_i \{j_k\}_{k=1}^n}}\right),\tag{46}$$

where the two states change accordingly when we transition from  $\{j_k\}_{k=1}^2$  to  $\{\ell_k\}_{k=1}^2$ 

$$u_{(i+1)\{j_k\}_{k=1}^n} = \left(1 - T_{\{\ell_k\}_{k=1}^n \{j_k\}_{k=1}^n} A_{\{\ell_k\}_{k=1}^n \{j_k\}_{k=1}^n}\right) u_{i\{j_k\}_{k=1}^n}$$

$$u_{(i+1)\{\ell_k\}_{k=1}^n} = u_{i\{\ell_k\}_{k=1}^n} + T_{\{\ell_k\}_{k=1}^n \{j_k\}_{k=1}^n} A_{\{\ell_k\}_{k=1}^n \{j_k\}_{k=1}^n} u_{i\{j_k\}_{k=1}^n}.$$

The move is accepted with

and reject the move with

### 2.5.2 Wall boundary

### 3 Attachments

The source files developed are

### 4 Resources

- 1. QT Creator 5.3.1 with C11
- 2. Eclipse Standard/SDK Version: Luna Release (4.4.0) with PyDev for Python
- 3. Ubuntu 14.04.1 LTS
- 4. ThinkPad W540 P/N: 20BG0042MN with 32 GB RAM

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