# MATH50003 Numerical Analysis

III.4 Polynomial Interpolation and Regression

### Part III

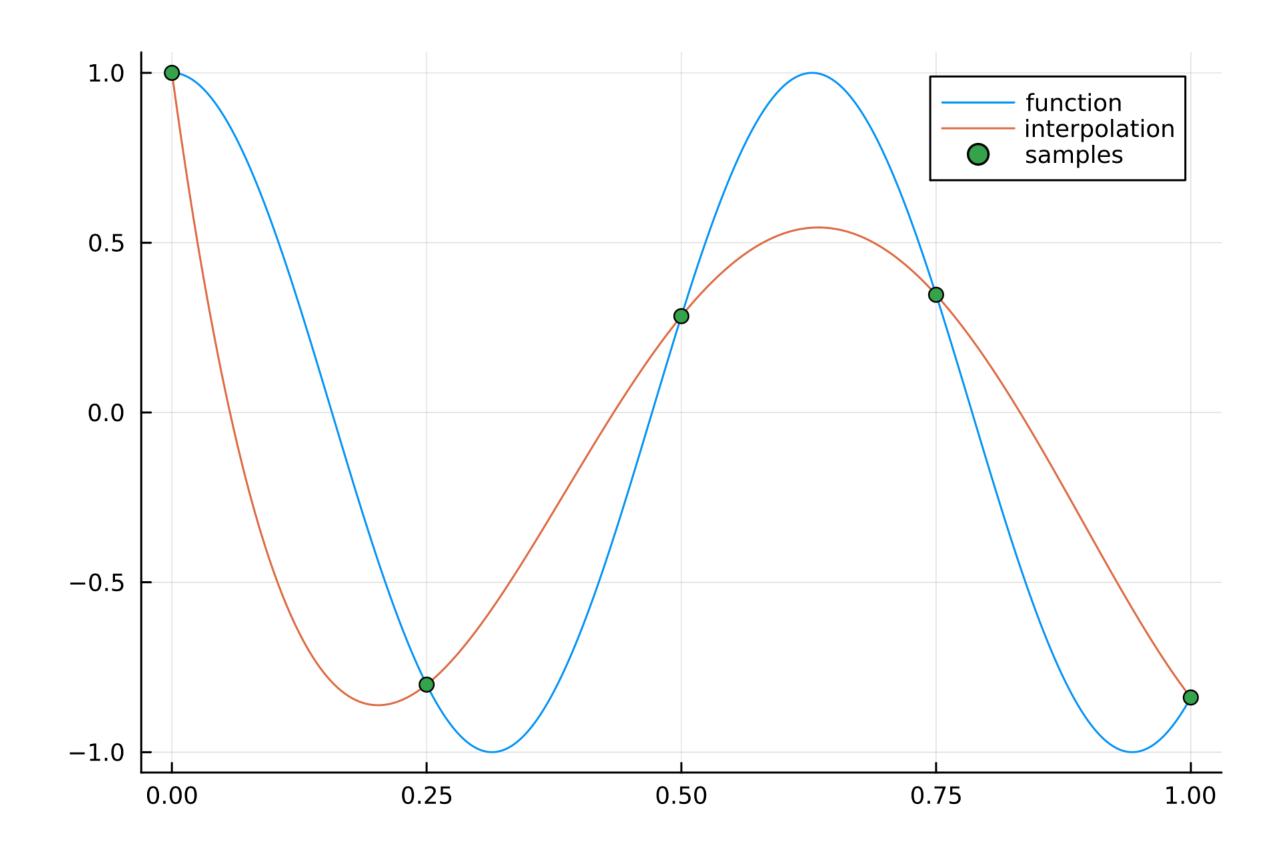
#### **Numerical Linear Algebra**

Software Application Theory

- 1. Structured matrices such as banded
- 2. Differential Equations via finite differences
- 3. LU and Cholesky factorisation for solving linear systems
- 4. Polynomial regression for approximating data via least squares
- 5. Orthogonal matrices such as Householder reflections
- 6. QR factorisation for solving rectangular least squares problems

## III.4.1 Polynomial interpolation

Find a polynomial equal to data at a grid



**Definition 20** (interpolatory polynomial). Given distinct points  $\mathbf{x} = [x_1, \dots, x_n]^{\top} \in \mathbb{F}^n$  and  $data \ \mathbf{f} = [f_1, \dots, f_n]^{\top} \in \mathbb{F}^n$ , a degree n-1 interpolatory polynomial p(x) satisfies

$$p(x_j) = f_j$$

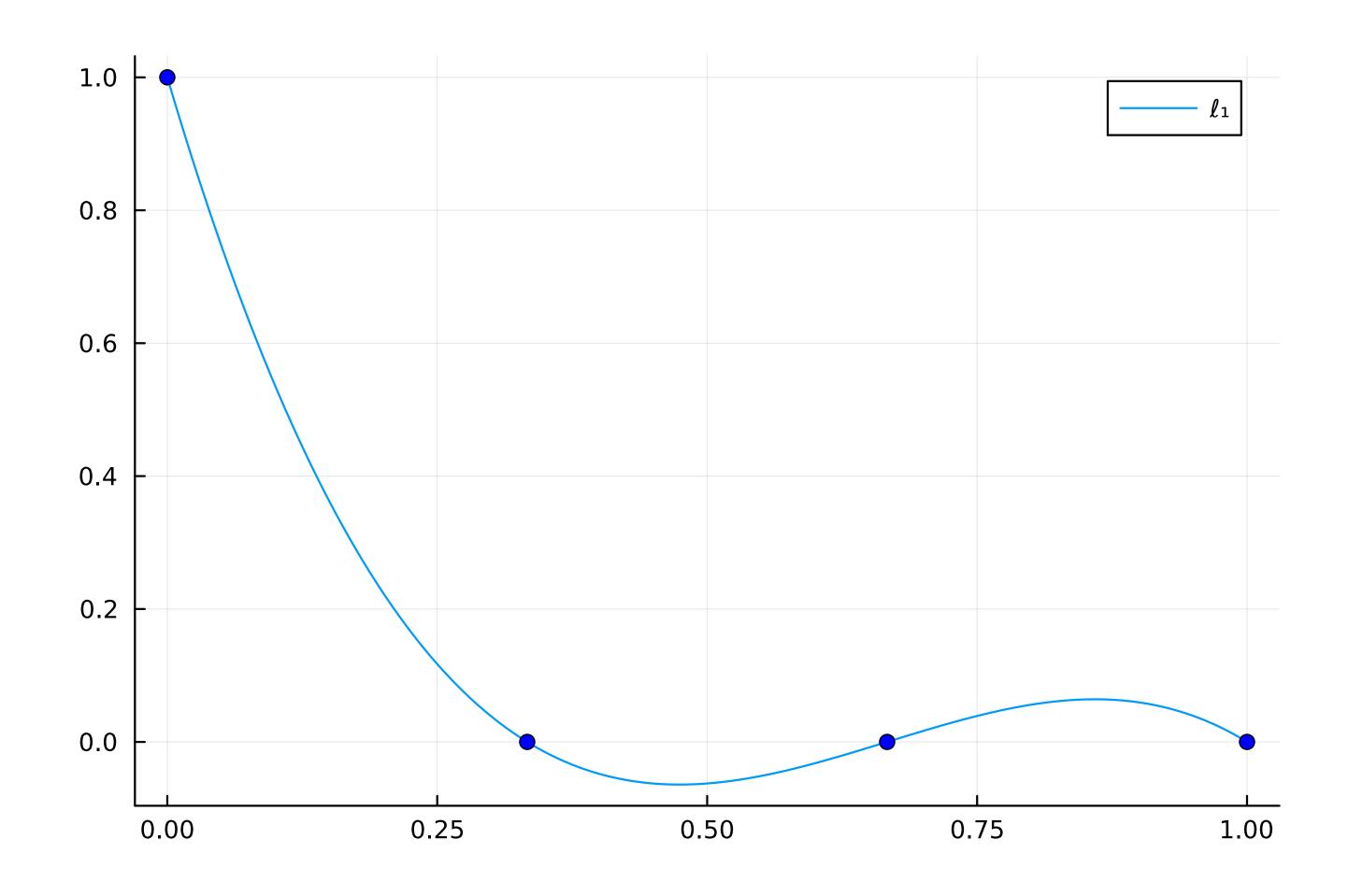
**Definition 21** (Vandermonde). The *Vandermonde matrix* associated with  $\boldsymbol{x} \in \mathbb{F}^m$  is the matrix

$$V_{\boldsymbol{x},n} := \begin{bmatrix} 1 & x_1 & \cdots & x_1^{n-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_m & \cdots & x_m^{n-1} \end{bmatrix} \in \mathbb{F}^{m \times n}.$$

**Proposition 7** (interpolatory polynomial uniqueness). Interpolatory polynomials are unique and therefore square Vandermonde matrices are invertible.

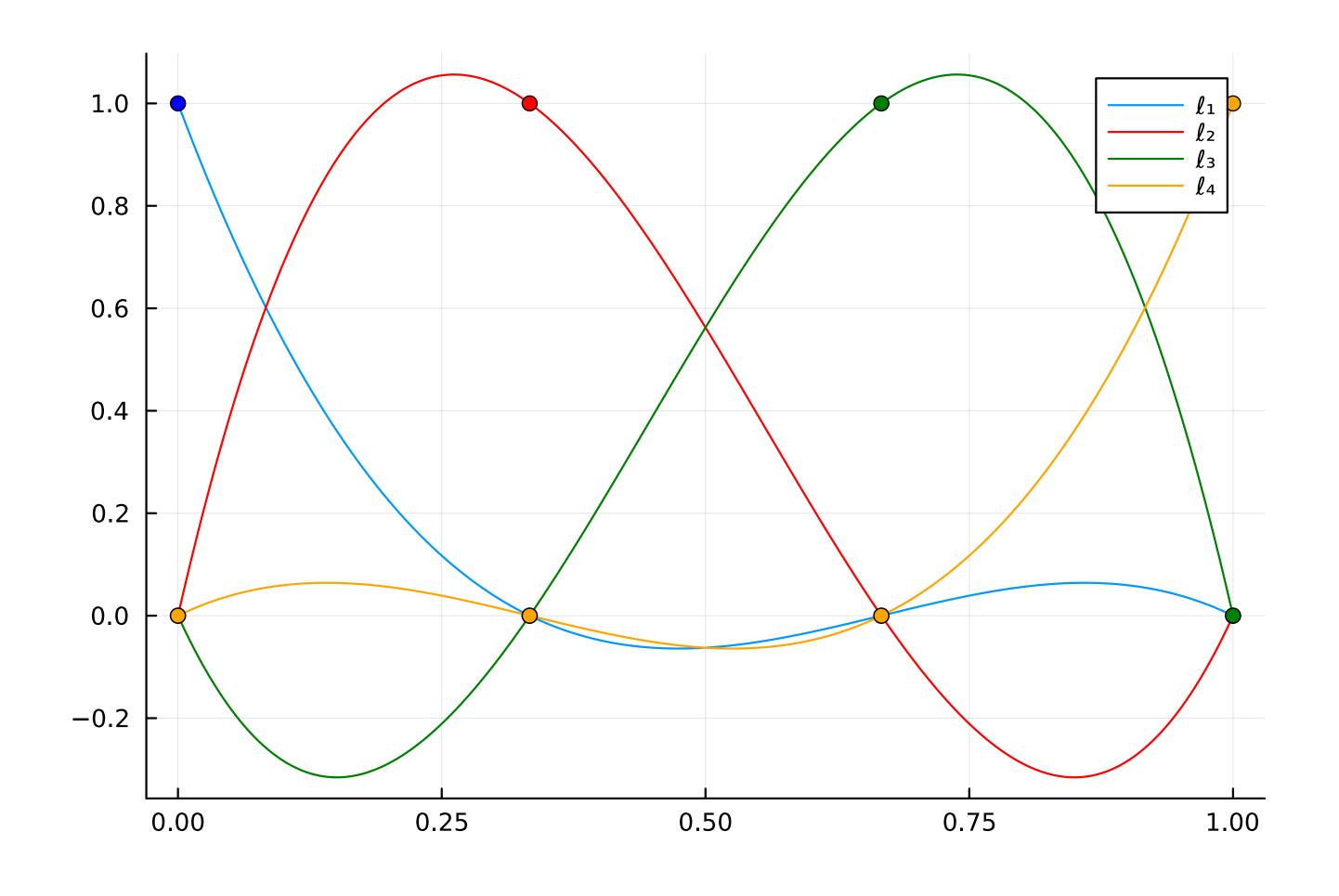
**Definition 22** (Lagrange basis polynomial). The Lagrange basis polynomial is defined as

$$\ell_k(x) := \prod_{i \neq k} \frac{x - x_j}{x_k - x_j} = \frac{(x - x_1) \cdots (x - x_{k-1})(x - x_{k+1}) \cdots (x - x_n)}{(x_k - x_1) \cdots (x_k - x_{k-1})(x_k - x_{k+1}) \cdots (x_k - x_n)}$$



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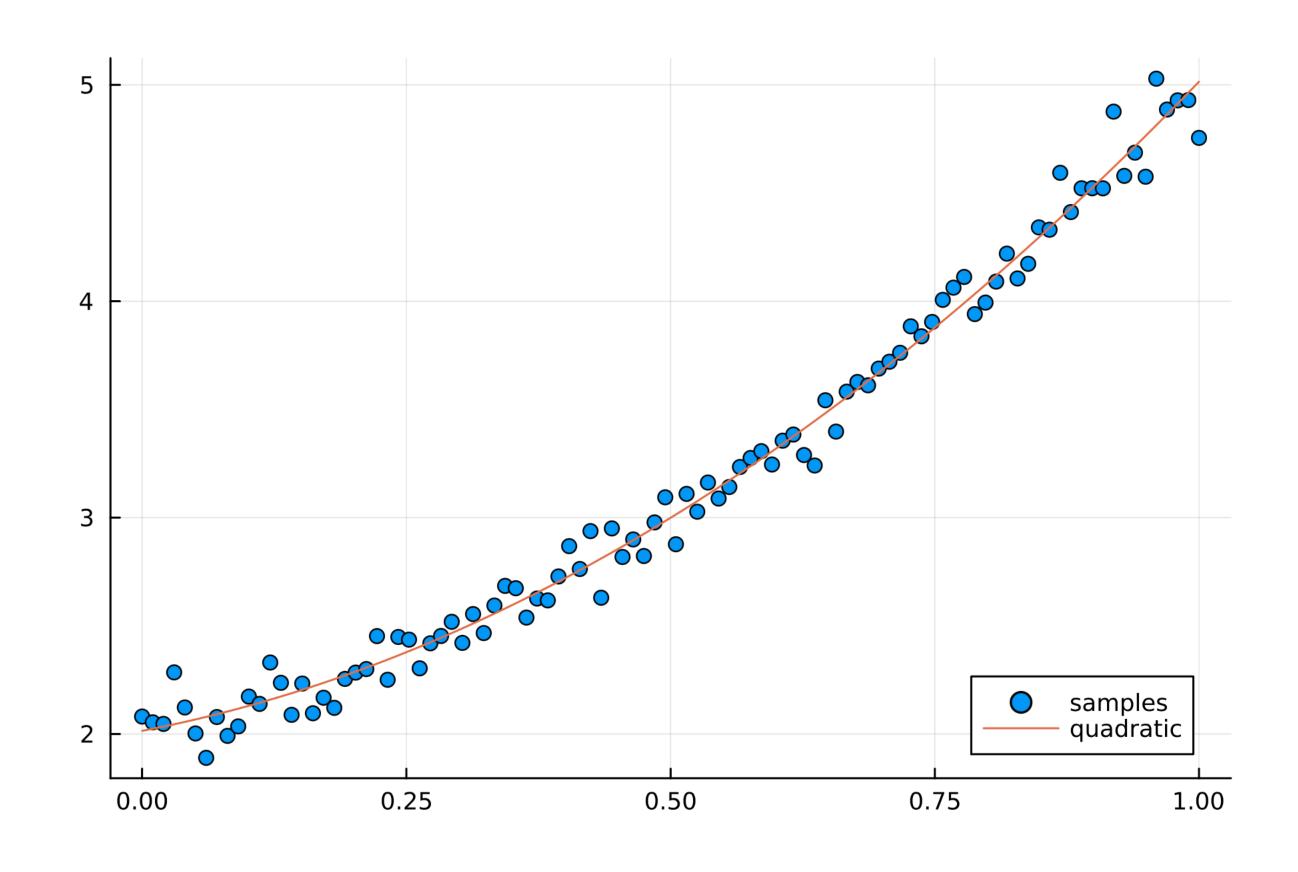
**Theorem 6** (Lagrange interpolation). The unique interpolation polynomial is:

$$p(x) = f_1 \ell_1(x) + \dots + f_n \ell_n(x)$$

Example 22 (interpolating an exponential).

## III.4.2 Polynomial regression

How to fit a polynomial to lots of data?



Find a polynomial such that:

$$\begin{bmatrix} p(x_1) \\ \vdots \\ p(x_m) \end{bmatrix} \approx \underbrace{\begin{bmatrix} f_1 \\ \vdots \\ f_m \end{bmatrix}}_{\boldsymbol{f}}.$$