Chapter 1

Contest

Template.py

```
import sys
 2 from collections import *
   from itertools import permutations #No repeated elements
   sys.setrecursionlimit(10**5)
  itr = (line for line in sys.stdin.read().strip().split('\n'))
 INP = lambda: next(itr)
 7 def ni(): return int(INP())
 8 def nl(): return [int(_) for _ in INP().split()]
12 def solve(n,a):
      pass
16 t = ni()
17 for case in range(t):
       n = ni()
      a = nl()
      solve(n,a)
```

Troubleshooting: Pre-submit: Write a few simple test cases if sample is not enough. Are time limits close? If so, generate max cases. Is the memory usage fine? Could anything overflow? Make sure to submit the right file.

Wrong answer: Print your solution! Print debug output, as well. Are you clearing all data structures between test cases? Can your algorithm handle the whole range of input? Read the full problem statement again. Do you handle all corner cases correctly? Have you understood the problem correctly? Any uninitialized variables? Any overflows? Confusing N and M, i and j, etc.? Are you sure your algorithm works? What special cases have you not thought of? Are you sure the STL functions you use work as you think? Add some assertions, maybe resubmit. Create some testcases to run your algorithm on. Go through the algorithm for a simple case. Go through this list again. Explain your algorithm

to a teammate. Ask the teammate to look at your code. Go for a small walk, e.g. to the toilet. Is your output format correct? (including whitespace) Rewrite your solution from the start or let a teammate do it.

Runtime error: Have you tested all corner cases locally? Any uninitialized variables? Are you reading or writing outside the range of any vector? Any assertions that might fail? Any possible division by 0? (mod 0 for example) Any possible infinite recursion? Invalidated pointers or iterators? Are you using too much memory? Debug with resubmits (e.g. remapped signals, see Various).

Time limit exceeded: Do you have any possible infinite loops? What is the complexity of your algorithm? Are you copying a lot of unnecessary data? (References) How big is the input and output? (consider buffering output) What do your teammates think about your algorithm?

Memory limit exceeded: What is the max amount of memory your algorithm should need? Are you clearing all data structures between test cases?

Chapter 2

Mathematics

2.1 Equations

$$ax^2 + bx + c = 0 \Rightarrow x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

The extremum is given by x = -b/2a.

$$ax + by = e$$

$$cx + dy = f$$

$$x = \frac{ed - bf}{ad - bc}$$

$$y = \frac{af - ec}{ad - bc}$$

In general, given an equation Ax = b, the solution to a variable x_i is given by

$$x_i = \frac{\det A_i'}{\det A}$$

where A'_i is A with the i'th column replaced by b.

Recurrences

If $a_n = c_1 a_{n-1} + \cdots + c_k a_{n-k}$, and r_1, \ldots, r_k are distinct roots of $x^k + c_1 x^{k-1} + \cdots + c_k$, there are d_1, \ldots, d_k s.t.

$$a_n = d_1 r_1^n + \dots + d_k r_k^n.$$

Non-distinct roots r become polynomial factors, e.g. $a_n = (d_1 n +$ $d_2)r^n$.

2.3Trigonometry

$$\sin(v + w) = \sin v \cos w + \cos v \sin w$$
$$\cos(v + w) = \cos v \cos w - \sin v \sin w$$

$$\tan(v+w) = \frac{\tan v + \tan w}{1 - \tan v \tan w}$$

$$\sin v + \sin w = 2\sin\frac{v+w}{2}\cos\frac{v-w}{2}$$

$$\cos v + \cos w = 2\cos\frac{v+w}{2}\cos\frac{v-w}{2}$$

$$(V+W)\tan(v-w)/2 = (V-W)\tan(v+w)/2$$

where V, W are lengths of sides opposite angles v, w.

 $a\cos x + b\sin x = r\cos(x-\phi)$

$$a\cos x + b\sin x = r\cos(x - \phi)$$

$$a\sin x + b\cos x = r\sin(x + \phi)$$

where $r = \sqrt{a^2 + b^2}$, $\phi = \operatorname{atan2}(b, a)$.

Geometry

2.4.1 Triangles

Side lengths: a, b, c

Semiperimeter: $p = \frac{a+b+c}{2}$

Area: $A = \sqrt{p(p-a)(p-b)(p-c)}$ Circumradius: $R = \frac{abc}{4A}$

Inradius: $r = \frac{A}{}$

Length of median (divides triangle into two equal-area triangles): $m_a = \frac{1}{2}\sqrt{2b^2 + 2c^2 - a^2}$

Length of bisector (divides angles in two):

$$\sqrt{bc\left[1-\left(\frac{a}{b+c}\right)^2\right]}$$

Law of sines: $\frac{\sin \alpha}{a} = \frac{\sin \beta}{b} = \frac{\sin \gamma}{c} = \frac{1}{2R}$ Law of cosines: $a^2 = b^2 + c^2 - 2bc \cos \alpha$

Law of tangents: $\frac{a+b}{a-b} = \frac{\tan \frac{\alpha+\beta}{2}}{\tan \frac{\alpha-\beta}{2}}$

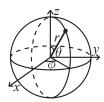
2.4.2 Quadrilaterals

With side lengths a, b, c, d, diagonals e, f, diagonals angle θ , area A and magic flux $F = b^2 + d^2 - a^2 - c^2$:

$$4A = 2ef \cdot \sin \theta = F \tan \theta = \sqrt{4e^2f^2 - F^2}$$

For cyclic quadrilaterals the sum of opposite angles is 180° , ef =ac + bd, and $A = \sqrt{(p-a)(p-b)(p-c)(p-d)}$.

Spherical coordinates



$$x = r \sin \theta \cos \phi \qquad r = \sqrt{x^2 + y^2 + z^2}$$

$$y = r \sin \theta \sin \phi \qquad \theta = a\cos(z/\sqrt{x^2 + y^2 + z^2})$$

$$z = r \cos \theta \qquad \phi = a\tan(y, x)$$

Derivatives/Integrals

$$\frac{d}{dx}\arcsin x = \frac{1}{\sqrt{1-x^2}} \qquad \frac{d}{dx}\arccos x = -\frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx}\tan x = 1 + \tan^2 x \qquad \frac{d}{dx}\arctan x = \frac{1}{1+x^2}$$

$$\int \tan ax = -\frac{\ln|\cos ax|}{a} \qquad \int x\sin ax = \frac{\sin ax - ax\cos ax}{a^2}$$

$$\int e^{-x^2} = \frac{\sqrt{\pi}}{2}\operatorname{erf}(x) \qquad \int xe^{ax}dx = \frac{e^{ax}}{a^2}(ax-1)$$

Integration by parts:

$$\int_{a}^{b} f(x)g(x)dx = [F(x)g(x)]_{a}^{b} - \int_{a}^{b} F(x)g'(x)dx$$

2.6Sums

$$c^{a} + c^{a+1} + \dots + c^{b} = \frac{c^{b+1} - c^{a}}{c-1}, c \neq 1$$

$$1 + 2 + 3 + \dots + n = \frac{n(n+1)}{2}$$

$$1^{2} + 2^{2} + 3^{2} + \dots + n^{2} = \frac{n(2n+1)(n+1)}{6}$$

$$1^{3} + 2^{3} + 3^{3} + \dots + n^{3} = \frac{n^{2}(n+1)^{2}}{4}$$

$$1^{4} + 2^{4} + 3^{4} + \dots + n^{4} = \frac{n(n+1)(2n+1)(3n^{2} + 3n - 1)}{30}$$

2.7Series

$$e^{x} = 1 + x + \frac{x^{2}}{2!} + \frac{x^{3}}{3!} + \dots, (-\infty < x < \infty)$$

$$\ln(1+x) = x - \frac{x^{2}}{2} + \frac{x^{3}}{3} - \frac{x^{4}}{4} + \dots, (-1 < x \le 1)$$

$$\sqrt{1+x} = 1 + \frac{x}{2} - \frac{x^{2}}{8} + \frac{2x^{3}}{32} - \frac{5x^{4}}{128} + \dots, (-1 \le x \le 1)$$

$$\sin x = x - \frac{x^{3}}{3!} + \frac{x^{5}}{5!} - \frac{x^{7}}{7!} + \dots, (-\infty < x < \infty)$$

$$\cos x = 1 - \frac{x^{2}}{2!} + \frac{x^{4}}{4!} - \frac{x^{6}}{6!} + \dots, (-\infty < x < \infty)$$

Probability theory

Let X be a discrete random variable with probability $p_X(x)$ of assuming the value x. It will then have an expected value (mean) $\mu = \mathbb{E}(X) = \sum_{x} x p_X(x)$ and variance $\sigma^2 = V(X) =$ $\mathbb{E}(X^2) - (\mathbb{E}(X))^2 = \sum_x (x - \mathbb{E}(X))^2 p_X(x)$ where σ is the standard deviation. If X is instead continuous it will have a probability density function $f_X(x)$ and the sums above will instead be integrals with $p_X(x)$ replaced by $f_X(x)$.

Expectation is linear:

$$\mathbb{E}(aX + bY) = a\mathbb{E}(X) + b\mathbb{E}(Y)$$

For independent X and Y,

$$V(aX + bY) = a^2V(X) + b^2V(Y).$$

2.8.1 Discrete distributions

Binomial distribution

The number of successes in n independent yes/no experiments, each which yields success with probability p is Bin(n,p), n = $1, 2, \ldots, 0 \le p \le 1.$

$$p(k) = \binom{n}{k} p^k (1-p)^{n-k}$$

$$\mu = np, \, \sigma^2 = np(1-p)$$

Bin(n, p) is approximately Po(np) for small p.

First success distribution

The number of trials needed to get the first success in independent yes/no experiments, each wich yields success with probability p is $F_{S}(p), 0 \le p \le 1.$

$$p(k) = p(1-p)^{k-1}, k = 1, 2, ...$$

 $\mu = \frac{1}{p}, \sigma^2 = \frac{1-p}{p^2}$

Poisson distribution

The number of events occurring in a fixed period of time t if these events occur with a known average rate κ and independently of the time since the last event is $Po(\lambda)$, $\lambda = t\kappa$.

$$p(k) = e^{-\lambda} \frac{\lambda^k}{k!}, k = 0, 1, 2, \dots$$
$$\mu = \lambda, \sigma^2 = \lambda$$

Continuous distributions

Uniform distribution

If the probability density function is constant between a and b and 0 elsewhere it is U(a, b), a < b.

$$f(x) = \begin{cases} \frac{1}{b-a} & a < x < b \\ 0 & \text{otherwise} \end{cases}$$
$$\mu = \frac{a+b}{2}, \ \sigma^2 = \frac{(b-a)^2}{12}$$

Exponential distribution

The time between events in a Poisson process is $Exp(\lambda)$, $\lambda >$

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & x \ge 0\\ 0 & x < 0 \end{cases}$$
$$\mu = \frac{1}{\lambda}, \, \sigma^2 = \frac{1}{\lambda^2}$$

Normal distribution

Most real random values with mean μ and variance σ^2 are well described by $\mathcal{N}(\mu, \sigma^2)$, $\sigma > 0$.

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

If $X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2)$ and $X_2 \sim \mathcal{N}(\mu_2, \sigma_2^2)$ then

$$aX_1 + bX_2 + c \sim \mathcal{N}(\mu_1 + \mu_2 + c, a^2\sigma_1^2 + b^2\sigma_2^2)$$

2.9 Markov chains

A Markov chain is a discrete random process with the property that the next state depends only on the current state. Let X_1, X_2, \ldots be a sequence of random variables generated by the Markov process. Then there is a transition matrix $\mathbf{P} = (p_{ij})$, with $p_{ij} = \Pr(X_n = i | X_{n-1} = j)$, and $\mathbf{p}^{(n)} = \mathbf{P}^n \mathbf{p}^{(0)}$ is the probability distribution for X_n (i.e., $p_i^{(n)} = \Pr(X_n = i)$), where $\mathbf{p}^{(0)}$ is the initial distribution.

 π is a stationary distribution if $\pi = \pi \mathbf{P}$. If the Markov chain is irreducible (it is possible to get to any state from any state), then $\pi_i = \frac{1}{\mathbb{E}(T_i)}$ where $\mathbb{E}(T_i)$ is the expected time between two visits in state i. π_j/π_i is the expected number of visits in state j between two visits in state i.

For a connected, undirected and non-bipartite graph, where the transition probability is uniform among all neighbors, π_i is proportional to node i's degree.

A Markov chain is *ergodic* if the asymptotic distribution is independent of the initial distribution. A finite Markov chain is ergodic iff it is irreducible and *aperiodic* (i.e., the gcd of cycle lengths is 1). $\lim_{k\to\infty} \mathbf{P}^k = \mathbf{1}\pi$.

A Markov chain is an A-chain if the states can be partitioned into two sets **A** and **G**, such that all states in **A** are absorbing $(p_{ii} = 1)_{,i}$ and all states in **G** leads to an absorbing state in **A**. The probability for absorption in state $i \in \mathbf{A}$, when the initial state is $j_{,i}^1$ is $a_{ij} = p_{ij} + \sum_{k \in \mathbf{G}} a_{ik} p_{kj}$. The expected time until absorption, when the initial state is i, is $t_i = 1 + \sum_{k \in \mathbf{G}} p_{ki} t_k$.

The formula for elements in pascals triangel is

$$(n+1)C(r) = (n)C(r-1) + (n)C(r)$$

Chapter 3

Graph Algorithms

bfs:

djikstra:

```
from heapq import heappop as pop, heappush as push
# adj: adj-list where edges are tuples (node id, weight):
# (1) --2-- (0) --3-- (2) has the adj-list:
\# adj = [[(1, 2), (2, 3)], [(0, 2)], [0, 3]]
def dijk(adj, S, T):
   N = len(adj)
   INF = 10 * * 18
    dist = [INF] *N
   pq = []
    def add(i, dst):
        if dst < dist[i]:</pre>
            dist[i] = dst
            push (pq, (dst, i))
    add(S, 0)
    while pq:
        D, i = pop(pq)
        if i == T: return D
        if D != dist[i]: continue
        for j, w in adj[i]:
            add(j, D + w)
    return dist[T]
```

twoSat:

```
# used in sevenkingdoms, illumination
import sys
sys.setrecursionlimit(10**5)
class Sat:
    def __init__(self, no_vars):
        self.size = no_vars*2
        self.no_vars = no_vars
        self.adj = [[] for _ in range(self.size)]
        self.back = [[] for _ in range(self.size)]
    def add_imply(self, i, j):
        self.adj[i].append(j)
        self.back[j].append(i)
    def add_or(self, i, j):
        self.add_imply(i^1, j)
        self.add_imply(j^1, i)
    def add_xor(self, i, j):
        self.add_or(i, j)
        self.add_or(i^1, j^1)
    def add_eq(self, i, j):
        self.add_xor(i, j^1)
    def dfs1(self, i):
        if i in self.marked: return
        self.marked.add(i)
        for j in self.adj[i]:
            self.dfs1(j)
        self.stack.append(i)
    def dfs2(self, i):
       if i in self.marked: return
        self.marked.add(i)
        for j in self.back[i]:
            self.dfs2(j)
        self.comp[i] = self.no c
    def is_sat(self):
        self.marked = set()
        self.stack = []
        for i in range(self.size):
            self.dfs1(i)
        self.marked = set()
        self.noc = 0
        self.comp = [0]*self.size
        while self.stack:
            i = self.stack.pop()
            if i not in self.marked:
                self.no_c += 1
                self.dfs2(i)
        for i in range(self.no_vars):
            if self.comp[i*2] == self.comp[i*2+1]:
                return False
        return True
    # assumes is_sat.
    # If not xi is after xi in topological sort,
    # xi should be FALSE. It should be TRUE otherwise.
    # https://codeforces.com/blog/entry/16205
    def solution(self):
        V = []
        for i in range(self.no vars):
            V.append(self.comp[i*2] > self.comp[i*2^1])
        return V
    __name__ == '___main___':
    S = Sat(1)
```

maxflow:

```
1 from collections import defaultdict
2 class Dinitz:
      def __init__(self, sz, INF=10**10):
          self.G = [defaultdict(int) for _ in range(sz)]
          self.sz = sz
          self.INF = INF
      def add_edge(self, i, j, w):
          self.G[i][j] += w
9
10
11
      def bfs(self, s, t):
          level = [0] * self.sz
12
13
          q = [s]
          level[s] = 1
14
          while q:
15
           q2 = []
16
17
              for u in q:
18
               for v, w in self.G[u].items():
                     if w and level[v] == 0:
19
                          level[v] = level[u] + 1
20
                          q2.append(v)
             q = q2
          self.level = level
          return level[t] != 0
24
25
26
      def dfs(self, s, t, FLOW):
          if s in self.dead: return 0
          if s == t: return FLOW
29
          for idx in range(self.pos[s], len(self.adj[s])):
             u = self.adj[s][idx]
              w = self.G[s][u]
              F = self.dfs(u, t, min(FLOW, w))
33
              if F:
                 self.G[s][u] -= F
                  self.G[u][s] += F
                  if self.G[s][u] == 0:
                     self.pos[s] = idx+1
                      if idx + 1 == len(self.adj[s]):
                         self.dead.add(s)
41
                 return F
              self.pos[s] = idx+1
          self.dead.add(s)
          return 0
      def setup after bfs(self):
46
          self.adj = [[v for v, w in self.G[u].items() if w and 38
       self.level[u] + 1 == self.level[v]] for u in range(self.sz39
       ) ]
          self.pos = [0]*self.sz
49
          self.dead = set()
      def max_flow(self, s, t):
          flow = 0
51
52
          while self.bfs(s, t):
              self.setup_after_bfs()
53
              while True:
                  pushed = self.dfs(s, t, self.INF)
                  if not pushed: break
                  flow += pushed
         return flow
```

```
hopcroftCarp:
# Hopcroft-Karp bipartite max-cardinality matching and max
    independent set
# David Eppstein, UC Irvine, 27 Apr 2002
# Used in https://open.kattis.com/problems/cuckoo
def bipartiteMatch(graph):
   '''Find maximum cardinality matching of a bipartite graph (5
    The input format is a dictionary mapping members of U to a
   of their neighbors in V. The output is a triple (M, A, B)
    where M is a
   dictionary mapping members of V to their matches in U, A is
    the part
   of the maximum independent set in U, and B is the part of
    the MIS in V.
   The same object may occur in both U and V, and is treated
    as two
   distinct vertices if this happens.""
   # initialize greedy matching (redundant, but faster than
    full search)
   matching = {}
   for u in graph:
     for v in graph[u]:
        if v not in matching:
              matching[v] = u
               break
   while 1:
       # structure residual graph into layers
        # pred[u] gives the neighbor in the previous layer for
       # preds[v] gives a list of neighbors in the previous
    layer for v in V
       # unmatched gives a list of unmatched vertices in final 6
     layer of V,
       # and is also used as a flag value for pred[u] when u
    is in the first layer
     preds = {}
       unmatched = []
       pred = dict([(u,unmatched) for u in graph])
       for v in matching:
         del pred[matching[v]]
       layer = list(pred)
       # repeatedly extend layering structure by another pair 14
    of layers
       while layer and not unmatched:
         newLayer = {}
           for u in laver:
               for v in graph[u]:
                   if v not in preds:
                       newLayer.setdefault(v,[]).append(u)
           layer = []
           for v in newLayer:
               preds[v] = newLayer[v]
               if v in matching:
                   layer.append(matching[v])
                   pred[matching[v]] = v
                   unmatched.append(v)
       # did we finish layering without finding any
    alternating paths?
       if not unmatched:
```

```
unlayered = {}
       for u in graph:
          for v in graph[u]:
               if v not in preds:
                   unlayered[v] = None
       return (matching, list (pred), list (unlayered))
   # recursively search backward through layers to find
alternating paths
   # recursion returns true if found path, false otherwise
   def recurse(v):
      if v in preds:
          L = preds[v]
          del preds[v]
          for u in L:
              if u in pred:
                  pu = pred[u]
                   del pred[u]
                   if pu is unmatched or recurse (pu):
                       matching[v] = u
                       return 1
       return 0
  for v in unmatched: recurse(v)
```

Hungarian Algorithm

```
# used on https://open.kattis.com/problems/arboriculture
# G is Bipartite graph N x M (N <= M) where [i][j] is cost to
     match L[i] and R[j]
# Ported from: https://raw.githubusercontent.com/kth-
     competitive-programming/kactl/main/content/graph/
     WeightedMatching.h
# Description: Given a weighted bipartite graph, matches every
    node on
# the left with a node on the right such that no
# nodes are in two matchings and the sum of the edge weights is
     minimal. Takes
\# cost[N][M], where cost[i][j] = cost for L[i] to be matched
    with R[j] and
# Returns: (min cost, match), where L[i] is matched with R[
    match[i]].
# Negate costs for max cost.
# Time: O(N^2M)
def hungarian(G):
    INF = 10 * *18
    if len(G) == 0:
       return 0, []
    n, m = len(G) + 1, len(G[0]) + 1
    u, v, p = [0]*n, [0]*m, [0]*m
    ans = [0] * (n-1)
    for i in range(1, n):
        p[0], j0 = i, 0
        dist, pre = [INF]*m, [-1]*m
        done = [False] * (m+1)
        while True:
            done[i0] = True
            i0, j1, delta = p[j0], 0, INF
            for j in range(1, m):
                if done[i]: continue
                cur = G[i0 - 1][j-1] - u[i0] - v[j]
                if cur < dist[j]:</pre>
                    dist[j], pre[j] = cur, j0
                if dist[j] < delta:</pre>
                    delta, j1 = dist[j], j
```

```
for j in range(0, m):
35
                  if done[j]:
                      u[p[j]] += delta
36
                                                                  18
                       v[j] -= delta
                                                                  20
                      dist[j] -= delta
39
               j0 = j1
40
41
              if p[j0] == 0: break
42
          while j0:
               j1 = pre[j0]
              p[j0] = p[j1]
               j0 = j1
      return -v[0], ans
```

ShortestCycle

```
1 from collections import *
2 def shortest_cycle(G):
       ''' Returns the length of shortest cycle even in an
       undirected graph.
      Floyd Warshall only handles directed graphs,
      but considers an undirected edge to be a cycle of length 2.
      G is adjacency list. '''
      n = len(G)
      ans = 10 * *18
      INF = 10 * * 9
      for i in range(n):
10
11
          dist = [INF] * n
          par = [-1] * n
12
          dist[i] = 0
13
14
          q = deque()
15
          q.append(i)
          while q:
16
17
              x = q[0]
18
              q.popleft()
19
               for child in G[x]:
20
                  if dist[child] == INF:
21
                       dist[child] = 1 + dist[x]
23
24
                       par[child] = x
                       q.append(child)
26
27
                   elif par[x] != child and par[child] != x:
                       ans = \min (ans, dist[x] +
29
                                      dist[child] + 1)
```

ConvexHull:

```
def convex_hull(pts):
    pts = sorted(set(pts))

if len(pts) <= 2:
    return pts

def cross(o, a, b):
    return (a[0] - o[0]) * (b[1] - o[1]) - (a[1] - o[1]) * 2e (b[0] - o[0])

lo = []
for p in pts:
    while len(lo) >= 2 and cross(lo[-2], lo[-1], p) <= 0:
    lo.append(p)

def convex_hull(pts):
    zeturn (a[0] - o[0]) * (b[1] - o[1]) - (a[1] - o[1]) * 2e (b[0] - o[1]) * 2e (b[0]
```

```
hi = []
for p in reversed(pts):
    while len(hi) >= 2 and cross(hi[-2], hi[-1], p) <= 0: 30
          hi.pop()
    hi.append(p)

return lo[:-1] + hi[:-1]</pre>
```

Chapter 4

Data Structures

Segment tree:

```
class SegmentTree:
   def __init__(self, arr, func=min):
       self.sz = len(arr)
       assert self.sz > 0
       self.func = func
       sz4 = self.sz*4
       self.L, self.R = [None]*sz4, [None]*sz4
       self.value = [None] *sz4
       def setup(i, lo, hi):
           self.L[i], self.R[i] = lo, hi
           if lo == hi:
               self.value[i] = arr[lo]
           mid = (lo + hi)//2
           setup(2*i, lo, mid)
            setup(2*i + 1, mid+1, hi)
           self._fix(i)
       setup(1, 0, self.sz-1)
    def _fix(self, i):
        self.value[i] = self.func(self.value[2*i], self.value
    [2*i+1])
    def _combine(self, a, b):
       if a is None: return b
       if b is None: return a
       return self.func(a, b)
    def query(self, lo, hi):
       assert 0 <= lo <= hi < self.sz
       return self.__query(1, lo, hi)
    def __query(self, i, lo, hi):
       l, r = self.L[i], self.R[i]
       if r < lo or hi < 1:</pre>
           return None
        if lo <= 1 <= r <= hi:</pre>
```

Tested on: https://open.kattis.com/problems/supercomputer

```
return self.value[i]
   return self._combine(
        self.__query(i*2, lo, hi),
        self.__query(i*2 + 1, lo, hi)
def assign(self, pos, value):
   assert 0 <= pos < self.sz
   return self.__assign(1, pos, value)
def __assign(self, i, pos, value):
   l, r = self.L[i], self.R[i]
   if pos < 1 or r < pos: return</pre>
   if pos == 1 == r:
       self.value[i] = value
       return
   self.__assign(i*2, pos, value)
   self.__assign(i*2 + 1, pos, value)
   self._fix(i)
def inc(self, pos, delta):
   assert 0 <= pos < self.sz
   self.__inc(1, pos, delta)
def __inc(self, i, pos, delta):
   l, r = self.L[i], self.R[i]
   if pos < 1 or r < pos: return
   if pos == 1 == r:
       self.value[i] += delta
   self.__inc(i*2, pos, delta)
   self.__inc(i*2 + 1, pos, delta)
   self._fix(i)
# for indexing - nice to have but not required
def __setitem__(self, i, v):
   self.assign(i, v)
def __fixslice__(self, k):
   return slice(k.start or 0, self.sz if k.stop == None
def __getitem__(self, k):
   if type(k) == slice:
       k = self.__fixslice__(k)
        return self.query(k.start, k.stop - 1)
   elif type(k) == int:
       return self.query(k, k)
```

Fenwick Tree:

```
# Tested on: https://open.kattis.com/problems/froshweek
class FenwickTree: # zero indexed calls!
    # Give array or size!
    def __init__(self, blob):
       if type(blob) == int:
            self.sz = blob
            self.data = [0] * (blob+1)
       elif type(blob) == list:
           A = blob
            self.sz = len(A)
            self.data = [0]*(self.sz + 1)
            for i, a in enumerate(A):
                self.inc(i, a)
    \# A[i] = v
    def assign(self, i, v):
       currV = self.query(i, i)
       self.inc(i, v - currV)
    # A[i] += delta
```

```
\# this method is ~3x faster than doing A[i] += delta
20
       def inc(self, i, delta):
          i += 1 # (to 1 indexing)
21
          while i <= self.sz:</pre>
22
              self.data[i] += delta
              i += i&-i # lowest oneBit
24
      # sum(A[:i+1])
      def sum(self, i):
         i += 1 # (to 1 indexing)
          S = 0
          while i > 0:
              S += self.data[i]
30
              i -= i&-i
31
          return S
32
       # return sum(A[lo:hi+1])
33
34
       def query(self, lo, hi):
           return self.sum(hi) - self.sum(lo-1)
35
       # for indexing - nice to have but not required
37
38
       def __fixslice__(self, k):
           return slice(k.start or 0, self.sz if k.stop == None
39
       else k.stop)
       def __setitem__(self, i, v):
           self.assign(i, v)
       def __getitem__(self, k):
          if type(k) == slice:
               k = self.__fixslice__(k)
               return self.query(k.start, k.stop - 1)
           elif type(k) == int:
              return self.query(k, k)
```

RMQ:

```
1 import math
2 class RMO:
       def __init__(self, arr, func=min):
           self.sz = len(arr)
           self.func = func
           MAXN = self.sz
           LOGMAXN = int(math.ceil(math.log(MAXN + 1, 2)))
           self.data = [[0]*LOGMAXN for _ in range(MAXN)]
           for i in range (MAXN):
10
               self.data[i][0] = arr[i]
11
           for j in range(1, LOGMAXN):
                for i in range (MAXN - (1 << j) + 1):
12
13
                   self.data[i][j] = func(self.data[i][j-1],
                           self.data[i + (1 << (j-1))][j-1])
15
       def query(self, a, b):
16
           if a > b:
17
18
               # some default value when query is empty
19
20
          d = b - a + 1
           k = int(math.log(d, 2))
21
           return self.func(self.data[a][k], self.data[b-(1<<k)</pre>
        +1][k])
```

Uniion Find:

```
class UnionFind:
def __init__(self, N):
self.parent = [i for i in range(N)]
self.sz = [1]*N
def find(self, i):
path = []
while i != self.parent[i]:
```

```
path.append(i)
    i = self.parent[i]
    for u in path: self.parent[u] = i
    return i

def union(self, u, v):
    uR, vR = map(self.find, (u, v))
    if uR == vR: return False
    if self.sz[uR] < self.sz[vR]:
        self.parent[uR] = vR
        self.sz[vR] += self.sz[uR]

else:
    self.parent[vR] = uR
    self.sz[uR] += self.sz[vR]

return True</pre>
```

Chapter 5

Div

Hungarian algorithm:

```
# G is Bipartite graph N x M (N <= M) where [i][j] is cost to
    match L[i] and R[j]
# Description: Given a weighted bipartite graph, matches every
# the left with a node on the right such that no
# nodes are in two matchings and the sum of the edge weights is
     minimal. Takes
\# \cos[N][M], where \cos[i][j] = \cos f for L[i] to be matched
    with R[j] and
# Returns: (min cost, match), where L[i] is matched with R[
    match[i]].
# Negate costs for max cost.
# Time: O(N^2M)
def hungarian(G):
    INF = 10 * * 18
    if len(G) == 0:
       return 0, []
    n, m = len(G) + 1, len(G[0]) + 1
    u, v, p = [0]*n, [0]*m, [0]*m
    ans = [0] * (n-1)
    for i in range(1, n):
        p[0], j0 = i, 0
        dist, pre = [INF] \star m, [-1] \star m
        done = [False] * (m+1)
        while True:
            done[j0] = True
            i0, j1, delta = p[j0], 0, INF
            for j in range(1, m):
```

```
if done[j]: continue
               cur = G[i0 - 1][j-1] - u[i0] - v[j]
               if cur < dist[j]:</pre>
                   dist[j], pre[j] = cur, j0
               if dist[j] < delta:</pre>
                   delta, j1 = dist[j], j
           for j in range(0, m):
               if done[j]:
                   u[p[j]] += delta
                   v[j] -= delta
               else:
                   dist[j] -= delta
           j0 = j1
           if p[j0] == 0: break
       while j0:
           j1 = pre[j0]
           p[j0] = p[j1]
           j0 = j1
return -v[0], ans
```

Gauss:

```
# monoid needs to implement
# __add__, __mul__, __sub__, __div__ and isZ
def gauss(A, b, monoid=None):
    def Z(v): return abs(v) < 1e-6 if not monoid else v.isZ()</pre>
   N = len(A[0])
    for i in range(N):
            m = next(j for j in range(i, N) if Z(A[j][i]) ==
    False)
            return None #A is not independent!
       if i != m:
            A[i], A[m] = A[m], A[i]
            b[i], b[m] = b[m], b[i]
        for j in range(i+1, N):
            sub = A[j][i]/A[i][i]
            b[j] = sub*b[i]
            for k in range(N):
                A[j][k] = sub*A[i][k]
    for i in range (N-1, -1, -1):
       for j in range (N-1, i, -1):
            sub = A[i][j]/A[j][j]
            b[i] = sub*b[j]
       b[i], A[i][i] = b[i]/A[i][i], A[i][i]/A[i][i]
```

FFT:

```
import cmath
# A has to be of length a power of 2.

def FFT(A, inverse=False):
    N = len(A)
    if N <= 1:
        return A
    if inverse:
        D = FFT(A) # d_0/N, d_{N-1}/N, d_{N-2}/N, ...
        return map(lambda x: x/N, [D[0]] + D[:0:-1])
    evn = FFT(A[0::2])
    odd = FFT(A[1::2])
    Nh = N//2
    return [evn[k%Nh]+cmath.exp(2j*cmath.pi*k/N)*odd[k%Nh]</pre>
```

```
for k in range(N)]
16
17 # A has to be of length a power of 2.
18 def FFT2(a, inverse=False):
N = len(a)
    j = 0
20
     for i in range(1, N):
21
      bit = N>>1
22
23
         while j&bit:
        j ^= bit
24
           bit >>= 1
25
         j^= bit
26
         if i < j:
27
             a[i], a[j] = a[j], a[i]
28
30
     T. = 2
     MUL = -1 if inverse else 1
      while L <= N:
       ang = 2j*cmath.pi/L * MUL
34
         wlen = cmath.exp(ang)
         for i in range(0, N, L):
35
          w = 1
36
             for j in range (L//2):
                u = a[i+j]
                v = a[i+j+L//2] * w
40
                 a[i+j] = u + v
                 a[i+j+L//2] = u - v
                 w *= wlen
         T. += 2
     if inverse:
         for i in range(N):
           a[i] /= N
47
48
49 def uP(n):
     while n != (n\&-n):
       n += n&-n
52
    return n
54 \# C[x] = sum_{i=0..N} (A[x-i]*B[i])
55 def polymul(A, B):
   sz = 2*max(uP(len(A)), uP(len(B)))
     A = A + [0] \star (sz - len(A))
    B = B + [0] * (sz - len(B))
     fA = FFT(A)
   fB = FFT(B)
     fAB = [a*b for a, b in zip(fA, fB)]
62 C = [x.real for x in FFT(fAB, True)]
63 return C
```

Convex Hull:

```
def convex_hull(pts):
    pts = sorted(set(pts))

    if len(pts) <= 2:
        return pts

    def cross(o, a, b):
        return (a[0] - o[0]) * (b[1] - o[1]) - (a[1] - o[1]) * 29
        (b[0] - o[0])

    lo = []
    for p in pts:
        while len(lo) >= 2 and cross(lo[-2], lo[-1], p) <= 0: 34
        lo.pop()
    lo.append(p)</pre>
```

```
hi = []
for p in reversed(pts):
    while len(hi) >= 2 and cross(hi[-2], hi[-1], p) <= 0:
        hi.pop()
    hi.append(p)

return lo[:-1] + hi[:-1]
```

Chapter 6

17

18

20

Geometry

Distance between two points

Diverse:

import math

```
def dist(p, q):
    return math.hypot(p[0]-q[0], p[1] - q[1])
  # Square distance between two points
  def d2(p, q):
    return (p[0] - q[0]) **2 + (p[1] - q[1]) **2
  # Converts two points to a line (a, b, c),
12 \# ax + by + c = 0
13 # if p == q, a = b = c = 0
  def pts2line(p, q):
   return (-q[1] + p[1],
        q[0] - p[0],
           p[0]*q[1] - p[1]*q[0]
  # Distance from a point to a line,
20 # given that a != 0 or b != 0
  def distl(l, p):
      return (abs(1[0]*p[0] + 1[1]*p[1] + 1[2])
        /math.hypot(1[0], 1[1]))
  # intersects two lines.
  # if parallell, returnes False.
  # lines on format (a, b, c) where ax + by + c == 0
  def line_intersection(11, 12):
   a1,b1,c1 = 11
      a2,b2,c2 = 12
      cp = a1*b2 - a2*b1
      if cp != 0:
          return float (b1*c2 - b2*c1)/cp, float (a2*c1 - a1*c2)/cp
         return False
```

```
# projects a point on a line
def project(1, p):
    a, b, c = 1
    return ((b*(b*p[0] - a*p[1]) - a*c)/(a*a + b*b),
        (a*(a*p[1] - b*p[0]) - b*c)/(a*a + b*b))
# Intersections between circles
def circle_intersection(c1, c2):
    if c1[2] > c2[2]:
       c1, c2 = c2, c1
    x1, y1, r1 = c1
    x2, y2, r2 = c2
    if x1 == x2 and y1 == y2 and r1 == r2:
       return False
    dist2 = (x1 - x2) * (x1-x2) + (y1 - y2) * (y1 - y2)
    rsq = (r1 + r2) * (r1 + r2)
    if dist2 > rsq or dist2 < (r1-r2)*(r1-r2):
        return []
    elif dist2 == rsq:
        cx = x1 + (x2-x1)*r1/(r1+r2)
        cy = y1 + (y2-y1)*r1/(r1+r2)
        return [(cx, cy)]
    elif dist2 == (r1-r2)*(r1-r2):
        cx = x1 - (x2-x1)*r1/(r2-r1)
        cy = y1 - (y2-y1)*r1/(r2-r1)
       return [(cx, cy)]
    d = math.sqrt(dist2)
    f = (r1*r1 - r2*r2 + dist2)/(2*dist2)
    xf = x1 + f*(x2-x1)
    yf = y1 + f*(y2-y1)
    dx = xf-x1
    dy = yf-y1
    h = math.sqrt(r1*r1 - dx*dx - dy*dy)
    norm = abs (math.hypot(dx, dy))
    p1 = (xf + h*(-dy)/norm, yf + h*(dx)/norm)
    p2 = (xf + h*(dy)/norm, yf + h*(-dx)/norm)
    return sorted([p1, p2])
# Finds the bisector through origo
# between two points by normalizing.
def bisector(p1, p2):
    d1 = math.hypot(p1[0], p2[1])
    d2 = math.hypot(p2[0], p2[1])
    return ((p1[0]/d1 + p2[0]/d2),
          (p1[1]/d1 + p2[1]/d2))
# Distance from P to origo
def norm(P):
    return (P[0]**2 + P[1]**2 + P[2]**2)**(0.5)
# Finds ditance between point p
# and line A + t*u in 3D
def dist3D(A, u, p):
    AP = tuple(A[i] - p[i] for i in range(3))
    cross = tuple(AP[i]*u[(i+1)%3] - AP[(i+1)%3]*u[i]
      for i in range(3))
   return norm(cross)/norm(u)
def vec(p1, p2):
   return p2[0]-p1[0], p2[1] - p1[1]
def sign(x):
   if x < 0: return -1
```

return 1 if x > 0 else 0

```
105 def cross(u, v):
106
      return u[0] * v[1] - u[1] * v[0]
108 def on_segment(p, q, r):
109
       """Check if point q lies on line segment 'pr'"""
      if (q[0] \le max(p[0], r[0]) and q[0] \ge min(p[0], r[0]) and
110
      q[1] \le \max(p[1], r[1]) \text{ and } q[1] \ge \min(p[1], r[1])): 22
112
      return False
113
114
115 def is_segment_intersection(s1, s2):
116
      u = vec(*s1)
117
      v = vec(*s2)
      p1, p2 = s1
118
119
      q1, q2 = s2
120
      # Calculate cross products
122
      d1 = cross(u, vec(p1, q1))
123
      d2 = cross(u, vec(p1, q2))
124
      d3 = cross(v, vec(q1, p1))
      d4 = cross(v, vec(q1, p2))
127
       # Check general case
128
      if d1 != 0 or d2 != 0 or d3 != 0 or d4 != 0:
         return sign(d1) != sign(d2) and sign(d3) != sign(d4)
129
       # Check collinear case
132
       return (on_segment(p1, q1, p2) or on_segment(p1, q2, p2) or43
              on_segment(q1, p1, q2) or on_segment(q1, p2, q2)) 44
```

Chapter 7

Number theory

Primes:

```
1 large_primes = [
2 5915587277,
3 1500450271,
4 3267000013,
5 7574853343,
6 4093082899,
7 9576890767,
8 3628273133,
9 2860486313,
10 5463458053,
11 3367900313,
12 10000000000000001,
13 10**16 + 61,
14 10**17 + 3
```

```
primes = []
   soll = [1]*N
    for p in range(2, N):
       if soll[p]:
           primes.append(p)
            for k in range(p*p, N, p):
               soll[k] = 0
   return primes
def SieveOfEratosthenes(num):
   prime = [True for i in range(num+1)]
    # boolean array
   p = 2
   out = []
    while (p * p \le num):
       if (prime[p] == True):
            # Updating all multiples of p
            for i in range(p * p, num+1, p):
               prime[i] = False
    for p in range(2, num+1):
        if prime[p]:
           out.append(p)
def isPrime(N):
   if N < 2: return False
   if N%2 == 0: return N == 2
    mx = min(int(N**.5) + 2, N)
    for i in range (3, mx, 2):
       if N % i == 0: return False
    return True
def genPrimesFrom(N):
   while True:
       if isPrime(N):
          yield N
       N += 1
def getPrimesFrom(N, cnt):
   itr = genPrimesFrom(N)
    return [next(itr) for _ in range(cnt)]
def is_power_of_two(num):
return num > 0 and (num & (num - 1)) == 0
```

Some useful functions:

def getPrimesBelow(N):

```
return a / math.gcd(a, b) * b
# returns b where (a*b)%MOD == 1
def inv(a, MOD):
return pow(a, -1, MOD)
\# returns g = gcd(a, b), x0, y0,
# where g = x0*a + y0*b
def xgcd(a, b):
    x0, x1, y0, y1 = 1, 0, 0, 1
    while b != 0:
       q, a, b = (a // b, b, a % b)
       x0, x1 = (x1, x0 - q * x1)
       y0, y1 = (y1, y0 - q * y1)
    return (a, x0, y0)
def crt(la, ln):
    assert len(la) == len(ln)
    for i in range(len(la)):
      assert 0 <= la[i] < ln[i]
   prod = 1
    for n in ln:
        assert gcd(prod, n) == 1
   lN = []
    for n in ln:
       1N.append(prod//n)
    for i, a in enumerate(la):
       print(lN[i], ln[i])
        _, Mi, mi = xgcd(lN[i], ln[i])
        x += a*Mi*lN[i]
    return x % prod
# finds x^e mod m
# Or just pow(x, e, m)
def modpow(x, m, e):
   res = 1
    while e:
       if e%2 == 1:
          res = (res*x) % m
       x = (x * x) % m
       e = e//2
    return res
# Divides a list of digits with an int.
# A lot faster than using bigint-division.
def div(L, d):
    r = [0] * (len(L) + 1)
    q = [0] * len(L)
    for i in range(len(L)):
       x = int(L[i]) + r[i] *10
        q[i] = x//d
       r[i+1] = x-q[i]*d
    for i in range (len(L) - 1, 0, -1):
        s.append(q[i]%10)
        q[i-1] += q[i]//10
    while q[0]:
        s.append(q[0]%10)
        q[0] = q[0]//10
    s = s[::-1]
    i = 0
    while s[i] == 0:
      i += 1
```