

EE 213 Computer Organization and Assembly Language

Week # 3, Lecture # 9

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Minds open...



... Laptops closed

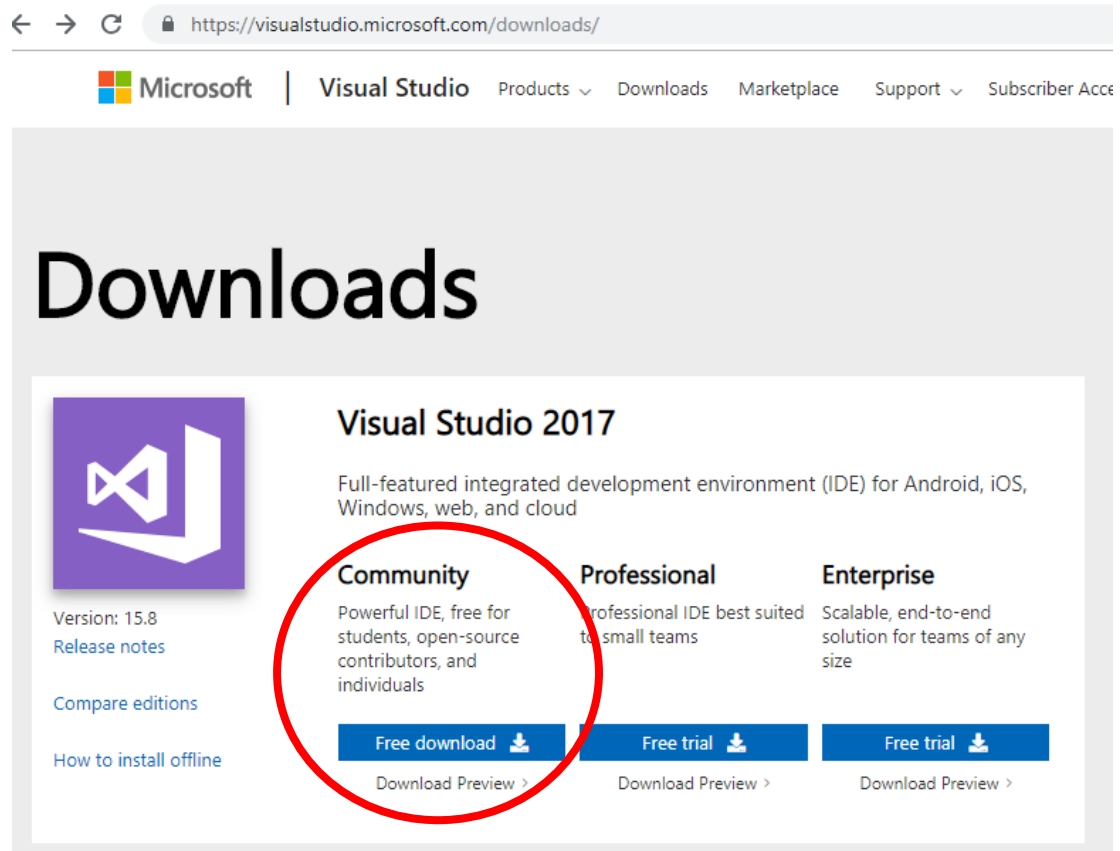


**This presentation helps in delivering the lecture.
Take notes, interact and read text book to learn and gain knowledge.**

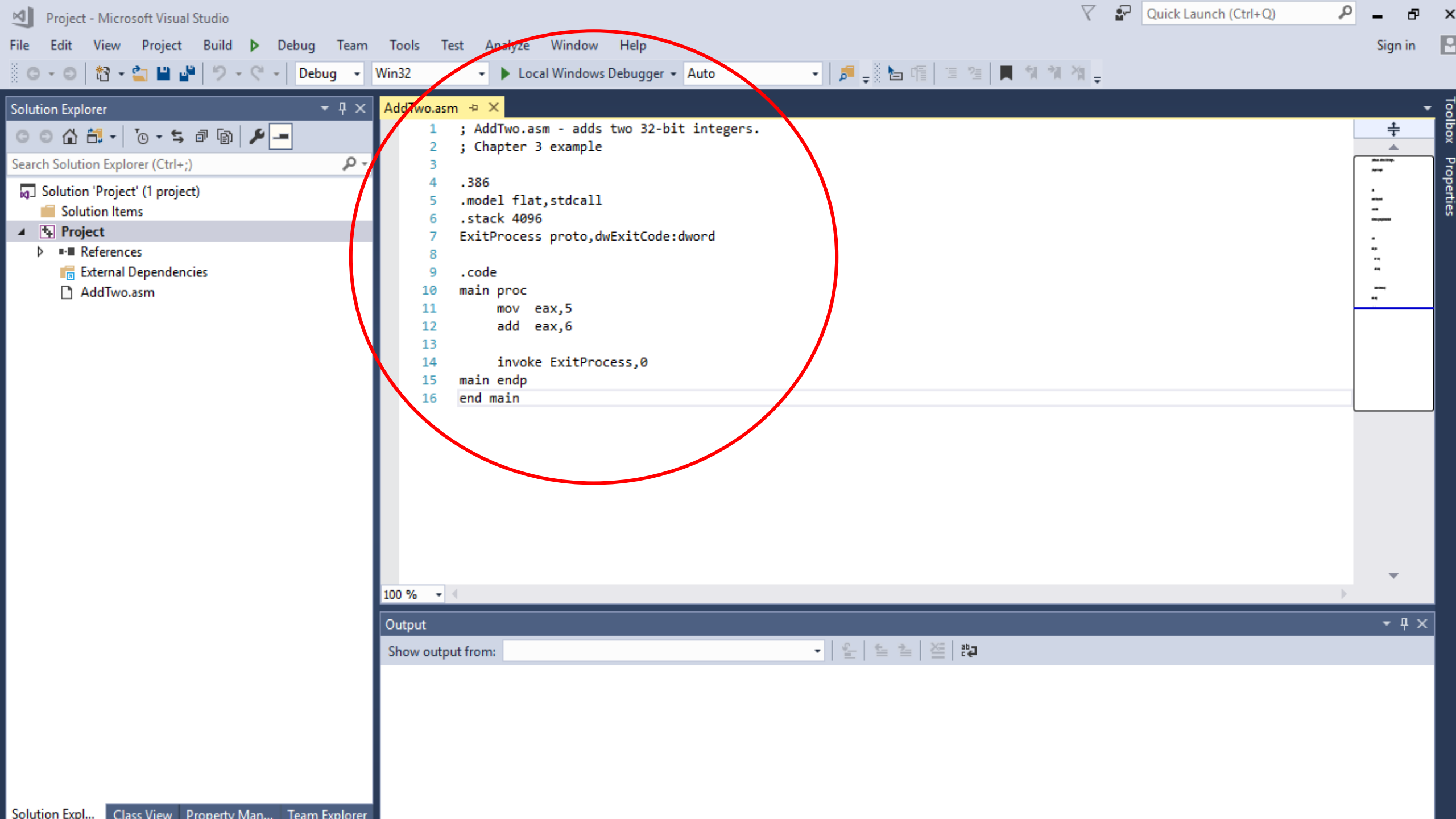
Today's Topics

- Homework: Visual Studio 2017 installation and assemble Irvine code
- Writing Assembly Programs

Install VS 2017 and Try x86 Assembly @ home



- Getting Started with MASM and Visual Studio 2017
<http://kipirvine.com/asm/gettingStartedVS2017/index.htm>



```
1 ; AddTwo.asm - adds two 32-bit integers.  
2 ; Chapter 3 example  
3  
4 .386  
5 .model flat,stdcall  
6 .stack 4096  
7 ExitProcess proto,dwExitCode:dword  
8  
9 .code  
10 main proc  
11     mov     eax,5  
12     add     eax,6  
13  
14     invoke ExitProcess,0  
15 main endp  
16 end main
```

Chapter # 2

2.7 Key Terms

32-bit mode	instruction pointer	data bus	programmable parallel port
64-bit mode	interrupt flag	data cache	protected mode
address bus	Level-1 cache	device drivers	random access memory (RAM)
application programming interface (API)	Level-2 cache	direction flag	read-only memory (ROM)
arithmetic logic unit (ALU)	machine cycle	dynamic RAM	real-address mode
auxiliary carry flag	memory storage unit	EFLAGS register	registers
basic program execution registers	MMX registers	extended destination index	segment registers
BIOS (basic input–output system)	motherboard	extended physical addressing	sign flag
bus	motherboard chipset	extended source index	single-instruction, multiple-data (SIMD)
cache	operating system (OS)	extended stack pointer	static RAM
carry flag	overflow flag	fetch-decode-execute	status flags
central processor unit (CPU)	parity flag	flags register	system management mode (SMM)
clock	PCI (peripheral component interconnect)	floating-point unit	Task Manager
clock cycle	PCI express	general-purpose registers	virtual-8086 mode
clock generator	process	instruction decoder	wait states
code cache	process ID	instruction execution cycle	XMM registers
control flags	programmable interrupt controller (PIC)	instruction queue	zero flag
control unit	programmable interval timer/counter		

3.1.1 First Assembly Language Program

```
1: main PROC
2:     mov eax,5           ; move 5 to the eax register
3:     add eax,6           ; add 6 to the eax register
4:
5:     INVOKE ExitProcess,0 ; end the program
6: main ENDP
```

Let's go through the program one line at a time: Line 1 starts the **main** procedure, the entry point for the program. Line 2 places the integer 5 in the **eax** register. Line 3 adds 6 to the value in **EAX**, giving it a new value of 11. Line 5 calls a Windows service (also known as a function) named **ExitProcess** that halts the program and returns control to the operating system. Line 6 is the ending marker of the main procedure.

3.1.9 Directives

A *directive* is a command embedded in the source code that is recognized and acted upon by the assembler. Directives do not execute at runtime, but they let you define variables, macros, and procedures. They can assign names to memory segments and perform many other housekeeping tasks related to the assembler. Directives are not, by default, case sensitive. For example, `.data`, `.DATA`, and `.Data` are equivalent.

The following example helps to show the difference between directives and instructions. The `DWORD` directive tells the assembler to reserve space in the program for a doubleword variable. The `MOV` instruction, on the other hand, executes at runtime, copying the contents of `myVar` to the `EAX` register:

```
myVar  DWORD 26  
mov    eax, myVar
```

Although all assemblers for Intel processors share the same instruction set, they usually have different sets of directives. The Microsoft assembler's `REPT` directive, for example, is not recognized by some other assemblers.

Defining Segments One important function of assembler directives is to define program sections, or *segments*. Segments are sections of a program that have different purposes. For example, one segment can be used to define variables, and is identified by the `.DATA` directive:

```
.data
```

The `.CODE` directive identifies the area of a program containing executable instructions:

```
.code
```

The `.STACK` directive identifies the area of a program holding the runtime stack, setting its size:

```
.stack 100h
```

Appendix A contains a useful reference for directives and operators.

3.1.10 Instructions

An *instruction* is a statement that becomes executable when a program is assembled. Instructions are translated by the assembler into machine language bytes, which are loaded and executed by the CPU at runtime. An instruction contains four basic parts:

- Label (optional)
- Instruction mnemonic (required)
- Operand(s) (usually required)
- Comment (optional)

This is how the different parts are arranged:

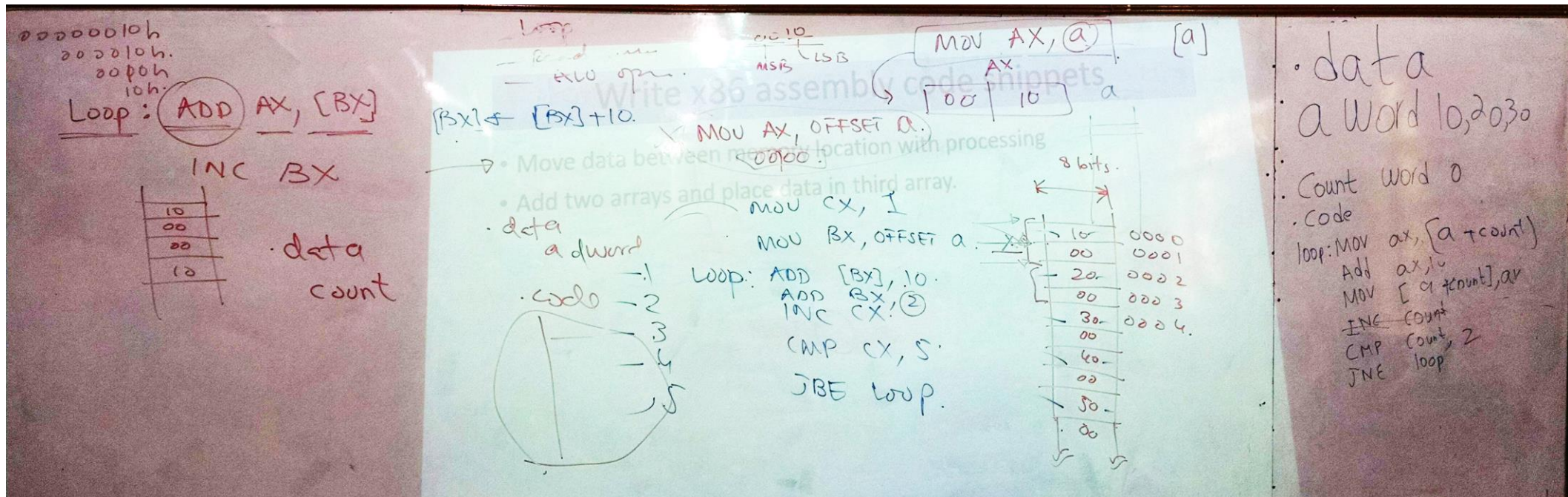
```
[label:] mnemonic [operands] [;comment]
```

Mnemonic	Description
MOV	Move (assign) one value to another
ADD	Add two values
SUB	Subtract one value from another
MUL	Multiply two values
JMP	Jump to a new location
CALL	Call a procedure

Example	Operand Type
96	<i>Integer literal</i>
2 + 4	Integer expression
eax	Register
count	Memory

Write x86 assembly code snippets

- Add 10 to existing elements to memory



Write x86 assembly code snippets

- Add two arrays and place data in third array.

```
.data
```

```
array1 dword 50 dup (10)
```

```
array2 dword 50 dup (20)
```

```
array3 dword 50 dup (?)
```

- Write manipulation code yourself.