# NATIONAL UNIVERSITY OF SINGAPORE MATHEMATICS SOCIETY

#### PAST YEAR PAPER SOLUTIONS

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## MA3252 Linear and Network Optimization

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## Question 1

(a) (i) Referring to the graph given, we can deduce the constraints of the linear program by determining the region of intersection.

$$L_1: x_1 \ge 0$$

$$L_2: x_2 \ge 5$$

$$L_3: x_1 + x_2 \ge 30$$

$$L_4: x_1 \le 20$$

$$L_5: x_1 - x_2 \ge 0$$

(ii) We want to maximize the following

$$\max c_1 x_1 + c_2 x_2$$

Note that  $c_i > 0$  is the return for each unit of *i*th investment made. Let  $c_1x_1 + c_2x_2 = K$  where  $K \in \mathbb{R}$ . We push this line along the gradient of  $\frac{-c_1}{c_2}$  and we will reach the corner point B. So the best investment option is  $(x_1, x_2) = (20, 20)$ .

(b) Let

$$z = \max\{3|x_1| - 5x_2, |x_2 - 4x_3|\}$$

$$b = \max\{2\max\{x_2, 0\}, |-4x_1 + 2x_2| - 5x_3\}$$

$$c = \max\{x_2, 0\}$$

then we want to

### Question 2

(a) (i) We introduce a slack variable  $s_1$  and an artificial variable y into the standard form of the linear programming.

Choose  $x_B = (s_1, y)' = (0, 0)$ . Note that  $c_B = (0, M)'$ , we obtain the starting  $\bar{c}$ -row as follow:

$$\bar{c} - \text{row} = (c - \text{row}) - 0 \times (s_1 - \text{row}) - M \times (y - \text{row})$$

Basic	$x_1$	$x_2$	$x_3$	$s_1$	y	Solutions
c	1	3	1	0	$\overline{M}$	0
$\overline{c}$	1	3-3M	1-2M	0	0	-6M
$s_1$	1	1	2	1	0	5
y	0	3	2	0	1	6
$\overline{c}$	1	0	-1	0	M-1	-6
$s_1$	1	0	$\frac{4}{3}$	1	$\frac{-1}{3}$	3
$x_2$	0	1	$\frac{2}{3}$	0	$\frac{1}{3}$	2
$\overline{c}$	$\frac{7}{4}$	0	0	$\frac{3}{4}$	$M-\frac{5}{4}$	$\frac{-15}{4}$
$x_3$	$\frac{3}{4}$	0	1	$\frac{3}{4}$	$-\frac{1}{4}$	$\frac{9}{4}$
$x_2$	$\frac{-1}{2}$	1	0	$\frac{-1}{2}$	$\frac{1}{2}$	$\frac{1}{2}$

In the first iteration, we choose  $x_2$  as the entering variable, as 3-3M<1-2M<0. Let i be any variable of the LP, we compute the ratio,  $r_{x_2i}$  where  $r_{x_2i}=|\frac{B^{-1}b_i}{B^{-1}A_2}|$  and we select the min of  $r_{x_2i}$  and variable i as leaving variable. We compute and find out that  $r_{x_2s_1}=5$  and  $r_{x_2y}=2$ . Hence, y will be the leaving variable.

In the second iteration, we choose  $x_3$  as the entering variable, because  $\overline{c_3}$  is the only component with has nonpositive value. We compute the ration,  $r_{x_3i}$  where  $r_{x_3i} = |\frac{B^{-1}b_i}{B^{-1}A_3}|$  and we select the min of  $r_{x_3i}$  and variable i as leaving variable. We compute and find out that  $r_{x_3s_1} = \frac{9}{4}$  and  $r_{x_3x_2} = 3$ . Hence  $s_1$  will be the leaving variable.

In the third iteration, notice that  $\bar{\mathbf{c}} > 0$ . So we have an optimal solution

$$\mathbf{x} = (x_1 \ x_2 \ x_3 \ s_1) = (0 \ \frac{1}{2} \ \frac{9}{4} \ 0)$$

(ii)

max 
$$5p_1 + 6p_2$$
  
st.  $p_1 \le 1$   
 $p_1 + 3p_2 \le 3$   
 $2p_1 + 2p_2 \le 1$   
 $p_1 \le 0, p_2$  free

(iii) Complementary Slackness theorem states that let x and p be feasible solutions to the primal problem and dual problem respectively. The vector x and p are optimal solutions for the two respective problems if and only if

$$p_i(\mathbf{a_i'x} - b_i) = 0 \quad \forall i$$
$$(c_j - \mathbf{p'A_j})x_j = 0 \quad \forall j$$

By applying the above theorem, we substitute the value of  $\mathbf{x}$  into the following equations,

$$x_1(p_1 - 1) = 0$$

$$x_2(p_1 + 3p_2 - 3) = 0 \Rightarrow 2p_1 + 6p_2 = 6$$

$$x_3(2p_1 + 2p_2 - 1) = 0 \Rightarrow 2p_1 + 2p_2 = 1$$

$$p_2 = \frac{5}{4} \quad p_1 = \frac{-3}{4}$$

(b) ( $\Longrightarrow$ ) Assume (1) is true, then  $\exists x \in \mathbb{R}^n$  such that Ax = b. For any  $y \in \mathbb{R}^n$  st. A'y = 0. we have

$$y'b = y'Ax$$

$$= (y'A)(x)$$

$$= 0'x$$

$$= 0 \neq 1$$

which  $y'b = 0 \neq 1$ , a contradiction.

( $\Leftarrow$ ) Let **z** be a vector in  $\mathbb{R}^m$  which satisfies  $\mathbf{A}'\mathbf{y} = \mathbf{0}$  and  $\mathbf{z}'\mathbf{b} = 1$ . So we have  $\mathbf{z}'\mathbf{A} = \mathbf{0}$  as (1)  $\mathbf{z}'\mathbf{b} = 1$  as (2).  $\forall \mathbf{x} \in \mathbb{R}^n$ , we consider the following equation

$$\mathbf{z'}\mathbf{A}\mathbf{x} = \mathbf{0} \quad (3)$$

Suppose  $\exists \mathbf{x} \in \mathbb{R}^n$  such that  $\mathbf{A}\mathbf{x} = \mathbf{b}$ , then from (3),  $\mathbf{z}'\mathbf{A}\mathbf{x} = \mathbf{0} \Rightarrow \mathbf{z}'\mathbf{b} = \mathbf{0}$ , which contradicts (2). Thus when *Alternative* 2 holds, *Alternative* 1 cannot hold.

### Question 3

(i) We complete the tableau From the above tableau, we can deduce  $\mathbf{B}^{-1}$ . Note that  $x_3, x_4, x_5$ 

Basic	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	Solution
$\overline{c}$	0	0	0	$\delta$	1	-7
$x_1$	1	0	0	-1	0	3
$x_3$	0	0	1	$\gamma$	3	eta
$x_2$	0	1	0	$\alpha$	-4	1

is the initial basic variables. So we know that

$$B^{-1} = \left( \begin{array}{ccc} A_3 & A_4 & A_5 \\ \end{array} \right) = \left( \begin{array}{ccc} 0 & -1 & 0 \\ 1 & \gamma & 3 \\ 0 & \alpha & -4 \end{array} \right)$$

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(ii) 
$$\underline{c'} - \underline{c'_B}B^{-1}A \ge 0$$

$$c_4 - (c_1 \quad c_2 + \epsilon \quad c_3)B^{-1}A_4 \ge 0 \Leftrightarrow \overline{c_4} - (0 \quad \epsilon \quad 0)B^{-1}A_4 \ge 0$$

$$c_5 - (c_1 \quad c_2 + \epsilon \quad c_3)B^{-1}A_5 \ge 0 \Leftrightarrow \overline{c_5} - (0 \quad \epsilon \quad 0)B^{-1}A_5 \ge 0$$

$$\delta - (0 \quad \epsilon \quad 0) = \begin{pmatrix} -1 \\ \gamma \\ \alpha \end{pmatrix} = \delta - \epsilon \gamma \ge 0 \Rightarrow \epsilon \ge \frac{\delta}{\gamma}$$

$$1 - (0 \quad \epsilon \quad 0) = \begin{pmatrix} 0 \\ 3 \\ -4 \end{pmatrix} = 1 - 3\epsilon \ge 0 \Rightarrow \epsilon \le \frac{1}{3}$$

(iii) Given  $\beta = 0$ , we have the following table

Basic	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	Solution
$\overline{c}$	0	0	0	δ	1	-7
$x_1$	1	0	0	-1	0	3
$x_3$	0	0	1	$\gamma$	3	0
$x_2$	0	1	0	$\alpha$	-4	1

to make sure the current basic feasible solution is optimal. We have  $\delta \geq 0$  so that  $\underline{c} > \underline{0}$ . Note that also this optimal solution might be a degenerate optimal solution.

- (iv) If at any iteration, the constraint coefficients  $B^{-1}A_j$  of a nonbasic variable  $x_j$  are all non-positive, the solution space is unbounded in that direction. If, the reduced cost  $\overline{c_j}$  of that nonbasic variable is negative (respectively positive) in the minimization (respectively maximization) problem, then the objective value is also unbounded.
  - To have a feasible solution,  $\beta \geq 0$ . To make sure  $x_4$  is chosen as entering variable,  $\delta < 0$ ,  $\gamma \geq 0$  and  $\alpha \leq 0$ . In particular, if  $\beta > 0$ , then  $\gamma \leq 0$ . If  $\beta = 0$ , then  $\gamma$  is free.
- (v) To have the primal problem infeasible,  $\beta < 0$ . Then to ensure dual problem is feasible,  $\delta > 0$  and  $\gamma < 0$ .

#### Question 4

(a) (i)

$$\begin{array}{ll} \max & 100P + 75T - 20L \\ st. & P \geq 20 \\ & T \geq 5 \\ & 0.3P + 0.5T \leq 100 \quad \Rightarrow 3P + 5T \leq 100 \\ & L \leq 250 \\ & 0.5P + T \leq L \\ & 0.6P + 0.8T \leq 40 \end{array}$$

(ii) Yes, the company should accept the offer. Referring to the sensitivity report, note that the Shadow Price for raw material is \$ 30. Hence, the net profit will be \$ 10.

$$2 \times 30 - 50 = 10$$

- (iii) Note that the constraints of T is tight. Considering the Shadow Price for T, the increase in shadow price is  $2 \times -\$ 95 = -\$ 190$ . Hence they will lose extra \$ 190 of profit.
- (b) Let  $S = {\mathbf{A}\mathbf{x} = b}$  be the feasible region for a standard LP problem. We try to study the property of Ax.

$$Ax = \begin{cases} a_{11}x_1 + \dots + a_{1i}x_i^+ + a_{1i}x_i^- + \dots + a_{1n}x_n = b_1 \\ \vdots & \vdots \\ a_{m1}x_1 + \dots + a_{mi}x_i^+ + a_{mi}x_i^- + \dots + a_{mn}x_n = b_m \end{cases}$$

By observations, the coefficients of  $x_i^+$  and  $x_i^-$  are not equal for each row.

To prove the statement, we assume to the contrary that there exists a step of the simplex method that 2 of the variables  $x_i^+, x_i^-$  is equal to zero.

Basic	$x_1$	 $x_i^+$	··· · <u>c'_B</u> B	$x_i^-$	 $x_n$	Solution
$\overline{c}$		$\underline{c'_B}B^{-1}b$				
$x_{i_1}$						
:	:	:		:	:	:
$x_i^+$						
:	$B^{-1}A_1$	 $B^{-1}A_i$		$B^{-1}A_i$	 $B^{-1}A_n$	$B^{-1}b$
$x_i^-$						
:	:	:		:	:	:
$x_{i_m}$						

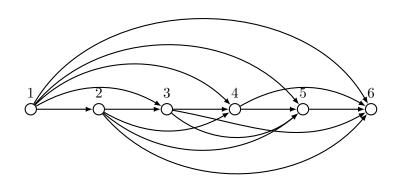
Note that  $B^{-1}b > \mathbf{0}$  for a feasible solution. So we will have  $x_i^+, x_i^-$  both not equal to zero. So,  $x_i^+$  and  $x_i^-$  must be both basic variables. However, notice from the above tableau that the columns for both  $x_i^+$  and  $x_i^-$  are identical.

Considering A, the matrix consisting only the columns of basic variables, we find out that A is a singular matrix, since there are 2 columns which are identical. Since A is singular, we obtain a contradiction. Therefore, in each step of the simplex method, at most one of the variables  $x_i^+, x_i^-$  is not equal to zero.

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#### Question 5

(a)



Referring to the graph above, we set the vertex i be the starting of ith year. Let  $V = \{1, 2, 3, 4, 5, 6\}$  and  $E = \{(i, j) : 1 \le i < j \le 6\}$ . We define the cost,  $c_{ij}$  as

$$c_{ij} = \begin{cases} 40 + 20 + 40 & = 60 & \text{if } j - i = 1 \\ 40 + 20 + 40 + 30 & = 90 & \text{if } j - i = 2 \\ 40 + 20 + 40 + 30 + 40 & = 130 & \text{if } j - i = 3 \\ 40 + 20 + 40 + 30 + 40 + 60 & = 190 & \text{if } j - i = 4 \\ 40 + 20 + 40 + 30 + 40 + 60 + 70 & = 260 & \text{if } j - i = 5 \end{cases}$$

We can then model this problem as a minimum cost problem, where

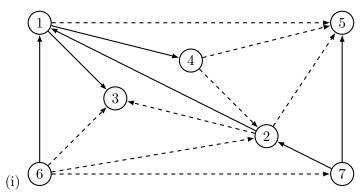
$$\min \sum_{(i,j)\in E} c_{ij}x_{ij}$$

$$st. \sum_{j\in O(i)} x_{ij} - \sum_{j\in I(i)} x_{ji} = \begin{cases} 0 & \text{if } i \neq 1, 6\\ 1 & \text{if } i \neq 1\\ -1 & \text{if } i = 6 \end{cases}$$

$$x_{ij} \geq 0 \quad \forall (i,j) \in E$$

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(b)



We try to compute  $p_i = c_{ij} - p_j$ . Let  $p_6 = 0$ , then

$$p_6 - p_1 = 56 \Rightarrow p_1 = -56$$
  
 $p_1 - p_3 = 48 \Rightarrow p_3 = -104$ 

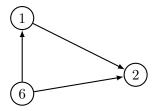
$$p_1 - p_4 = 28 \Rightarrow p_4 = -84$$

$$p_2 - p_1 = 7 \Rightarrow p_2 = -49$$

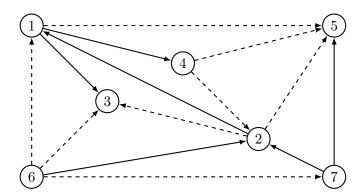
$$p_7 - p_2 = 33 \Rightarrow p_7 = 82$$

$$p_7 - p_5 = 19 \Rightarrow p_5 = 63$$

Then we compute  $\overline{c_{ij}} = c_{ij} - (p_i - p_j)$ , and we find out that  $\overline{c_{62}} = 48 - (0 - (-49)) = -1 < 0$  while other  $\overline{c_{ij}} > 0$ , then we choose arc (6,2) to enter. By considering the following graph,



we find the value of  $\theta^* = 9$  and decides that arc (6,1) leaves. After this iteration, we obtain a new graph,



We try to use the similar method as above to compute  $p_i = c_{ij} - p_j$ . Let  $p_6 = 0$ , then

$$p_{6} - p_{2} = 48 \Rightarrow p_{2} = -48$$

$$p_{7} - p_{2} = 33 \Rightarrow p_{7} = -15$$

$$p_{7} - p_{5} = 19 \Rightarrow p_{5} = -34$$

$$p_{2} - p_{1} = 7 \Rightarrow p_{1} = -55$$

$$p_{1} - p_{3} = 48 \Rightarrow p_{3} = -103$$

$$p_{1} - p_{4} = 28 \Rightarrow p_{4} = -83$$

Then we compute  $\overline{c_{ij}} = c_{ij} - (p_i - p_j)$ , and we find out that  $\forall (i,j)$  arc in this graph,  $\overline{c_{ij}} > 0$ , then we conclude that this dual solution is optimal. By Complementary Slackness Theorem, the prime solution is optimal as well. Hence we have

(ii) Note that  $\epsilon$  is small enough so that it will not affect the optimal solutions. Now, considering the flow of the optimal solution's graph, an extra flow of  $\epsilon$  flow passes through (6,2), incurring an extra cost of  $c_{62} \times \epsilon$ . Then the extra flow of  $\epsilon$  passes through (2,1), incurring an extra cost of  $c_{21} \times \epsilon$ . Since  $\epsilon$  flows out at node 1, there is no further cost incurred. Hence the change in value of the optimal cost is

$$\delta$$
 in optimal cost =  $\epsilon \times (c_{62} + c_{21}) = 55\epsilon$ 

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