MA1101R - Linear Algebra I Suggested Solutions

AY19/20 Semester 2

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Question 1

(a) For any $\mathbf{w} \in \text{span}\{\mathbf{u}_1, \mathbf{u}_2\} \cap \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$, we have $w = a_1\mathbf{u}_1 + a_2\mathbf{u}_2 = b_1\mathbf{v}_1 + b_2\mathbf{v}_2 + b_3\mathbf{v}_3$ and so

$$a_1\mathbf{u}_1 + a_2\mathbf{u}_2 - b_1\mathbf{v}_1 - b_2\mathbf{v}_2 - b_3\mathbf{v}_3 = 0.$$

Setting up the augmented matrix and row reducing yields

Thus, a solution to the system is given by span $\{(-1, 1, 0, -3, 1), (2, 3, 1, 0, 0)\}$. This represents **coefficients to the system above, not the vectors themselves**. Set $a_1 = -1$, $a_2 = 1$ and our vector is (-1, -1, -3, 3, -2). Put $a_1 = 2$, $a_2 = 3$ and our vector is (2, -3, -4, -1, 4). Thus $S = \{(-1, -1, -3, 3, -2), (2, -3, -4, -1, 4)\}$.

(b) We aim to solve the system

$$(a_1\mathbf{v}_1 + a_2\mathbf{v}_2 + a_3\mathbf{v}_3) \cdot \mathbf{u}_1 = 8a_1 + 7a_2 + 7a_3 = 0$$

 $(a_1\mathbf{v}_1 + a_2\mathbf{v}_2 + a_3\mathbf{v}_3) \cdot \mathbf{u}_2 = 10a_1 - 7a_2 - 11a_3 = 0.$

Setting up the augmented matrix and row reducing yields

$$\left(\begin{array}{ccc} 8 & 7 & 7 \\ 10 & -7 & -11 \end{array}\right) \xrightarrow{RREF} \left(\begin{array}{ccc} 1 & 0 & -\frac{2}{6} \\ 0 & 1 & \frac{79}{63} \end{array}\right)$$

Thus, the system has a solution given by span $\left\{ \begin{pmatrix} 14 \\ -79 \\ 63 \end{pmatrix} \right\}$. Thus, one such vector is given by $14\mathbf{v}_1 - 79\mathbf{v}_2 + 63\mathbf{v}_3 = (75, 5, -25, -45, -70)$.

Question 2

(a) Using Gram-Schmidt process, we have

$$\begin{array}{lll} \mathbf{u}_1 & = & (5,2,6,-4) = \mathbf{v}_1 \\ \mathbf{u}_2 & = & (-12,-3,-12,6) - \frac{(-12,-3,-12,6) \cdot (5,2,6,-4)}{5^2 + 2^2 + 6^2 + (-4)^2} (5,2,6,-4) \\ & = & \mathbf{v}_2 - 2\mathbf{u}_1 \\ & = & (-2,1,0,-2) \\ \mathbf{u}_3 & = & (2a+3,8a+3,-3a+6,2a-6) - \frac{(2a+3,8a+3,-3a+6,2a-6) \cdot (5,2,6,-4)}{5^2 + 2^2 + 6^2 + (-4)^2} (5,2,6,-4) \\ & - & \frac{(2a+3,8a+3,-3a+6,2a-6) \cdot (-2,1,0,-2)}{(-2)^2 + 1^2 + 0^2 + (-2)^2} (-2,1,0,-2) \\ & = & \mathbf{v}_3 - \mathbf{u}_1 - \mathbf{u}_2 \\ & = & (2a,8a,-3a,2a) \end{array}$$

Provided $a \neq 0$, the required orthonormal basis $T = \{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$ has $\mathbf{w}_1 = \left(\frac{5}{9}, \frac{2}{9}, \frac{2}{3}, \frac{-4}{9}\right), \mathbf{w}_2\left(-\frac{2}{3}, \frac{1}{3}, 0, -\frac{2}{3}\right)$ and $\mathbf{w}_3 = \left(\frac{2}{9}, \frac{8}{9}, \frac{1}{3}, \frac{2}{9}\right)$. If a = 0, then $T = \{\mathbf{w}_1, \mathbf{w}_2\}$ will do.

- (b) Note that if $\mathbf{v}_1, \mathbf{v}_2$ and \mathbf{v}_3 are linearly dependent, then the length of \mathbf{u}_3 must be 0, which can only happen when a = 0. Thus, for a = 0, the required orthogonal basis is $\{\mathbf{u}_1, \mathbf{u}_2\}$, while for $a \neq 0$, the orthogonal basis is $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$. Hence the possible values for the dimension is $\dim(V) = 2$ or $\dim(V) = 3$.
- (c) Firstly, from (a), we have

$$\begin{array}{rcl} \textbf{u}_1 & = & \textbf{v}_1 \\ \textbf{u}_2 & = & 2\textbf{v}_1 + \textbf{v}_2 \\ \textbf{u}_3 & = & \textbf{v}_1 - \textbf{v}_2 + \textbf{v}_3. \end{array}$$

For the orthonormal basis,

$$\mathbf{w}_{1} = \frac{1}{9}\mathbf{v}_{1}$$

$$\mathbf{w}_{2} = \frac{1}{3}(2\mathbf{v}_{1} + \mathbf{v}_{2})$$

$$\mathbf{w}_{3} = \frac{1}{9a}(\mathbf{v}_{1} - \mathbf{v}_{2} + \mathbf{v}_{3}).$$

Hence, the transition matrix from T to S is given by

$$\mathbf{P}_{S \to T} = \begin{pmatrix} \frac{1}{9} & \frac{2}{3} & \frac{1}{9a} \\ 0 & \frac{1}{3} & -\frac{1}{9a} \\ 0 & 0 & \frac{1}{9a} \end{pmatrix}$$

To find the transition matrix from S to T, we only need to find the inverse of the matrix above.

$$\mathbf{P}_{T \to S} = \left(\begin{array}{ccc} 9 & -18 & -27 \\ 0 & 3 & 3 \\ 0 & 0 & 9a \end{array} \right)$$

(d) Way 1

We first find the projection of (4,7,-9,-5) onto $V := \text{span}\{(5,2,6,-4),(-12,-3,-12,6),(5,11,3,-4)\}$. Using the orthogonal basis found in part (a), we have

$$\begin{array}{lll} \mathrm{Proj}_{V}((4,7,-9,-5)) & = & \frac{(5,2,6,-4)\cdot(4,7,-9,-5)}{5^{2}+2^{2}+6^{2}+(-4)^{2}}(5,2,6,-4) + \frac{(-2,1,0,-2)\cdot(4,7,-9,-5)}{(-2)^{2}+1^{2}+0^{2}+(-2)^{2}}(-2,1,0,-2) \\ & + & \frac{(2,8,-3,2)\cdot(4,7,-9,-5)}{2^{2}+8^{2}+(-3)^{2}+2^{2}}(2,8,-3,2) \\ & = & (0,9,-3,0). \end{array}$$

Now, we aim to solve the system

$$\begin{pmatrix} 5 & -12 & 5 \\ 2 & -3 & 11 \\ 6 & -12 & 3 \\ -4 & 6 & -4 \end{pmatrix} \mathbf{x} = \begin{pmatrix} 0 \\ 9 \\ -3 \\ 0 \end{pmatrix}.$$

Observe that -(5,2,6,-4) + (5,11,3,-4) = (0,9,-3,0), so a least square solution is given by $\mathbf{x} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$.

Way 2

Solving for $\mathbf{A}^T \mathbf{A} x = \mathbf{A}^T b$, we get the augmented matrix,

$$\begin{pmatrix} 81 & -162 & 81 & 0 \\ -162 & 333 & -153 & 9 \\ 81 & -153 & 171 & 90 \end{pmatrix} \xrightarrow{RREF} \begin{pmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix}$$

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Question 3

(a) We have

$$\begin{pmatrix} 1 & -2 & 1 & 3 \\ 1 & -1 & 0 & 4 \\ 1 & 0 & -1 & 5 \end{pmatrix} \xrightarrow{R_2 - R_1} \begin{pmatrix} 1 & -2 & 1 & 3 \\ 0 & 1 & -1 & 1 \\ 0 & 2 & -2 & 2 \end{pmatrix} \xrightarrow{R_1 + 2R_2} \begin{pmatrix} 1 & 0 & -1 & 5 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Hence, a basis for the row space is given by $\{(1,0,-1,5),(0,1,-1,1)\}$.

On the other hand, a basis for the null space is given by $\{(1,1,1,0)^T, (-5,-1,0,1)^T\}$

(b) For any matrix A, denote the row space and null space of A by R(A) and N(A) respectively. For any subspace W, define

$$W^{\perp} = \{ \mathbf{v} \in \mathbb{R}^n : \mathbf{v} \cdot \mathbf{u} = 0 \ \forall \ \mathbf{u} \in W \}.$$

We first show that $(R(\mathbf{A}))^{\perp} = N(\mathbf{A})$. Indeed, we have

$$\mathbf{u} \in N(\mathbf{A}) \quad \Longleftrightarrow \quad \mathbf{A}\mathbf{u} = \mathbf{0}$$

$$\iff \quad \text{for any row } \mathbf{a} \text{ of } \mathbf{A}, \ \mathbf{a} \cdot \mathbf{u} = 0.$$

$$\iff \quad \mathbf{u} \in (R(\mathbf{A}))^{\perp}.$$

Observe that the column space of A^T is equal to the row space of A. Thus, we have

$$N(\mathbf{B}) = R(\mathbf{A}) \implies R(\mathbf{B}) = (N(\mathbf{B}))^{\perp} = (R(\mathbf{A}))^{\perp} = N(\mathbf{A}).$$

Hence, it suffices to pick the matrix $\mathbf{B} = \begin{pmatrix} -5 & -1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix}$.

For completeness sake, we verify that the matrix $\begin{pmatrix} -5 & -1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix}$ works. Indeed, we have

$$\begin{pmatrix} -5 & -1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ -1 \\ 5 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \text{ and } \begin{pmatrix} -5 & -1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

The proof is complete.

Question 4

(a) We first find the characteristic polynomial of A. We have

$$\det(\mathbf{A} - x\mathbf{I}_3) = \begin{pmatrix} \frac{5}{2} - x & 1 & -2\\ 1 & 1 - x & -1\\ 2 & 1 & -\frac{3}{2} - x \end{pmatrix} \\
= \begin{pmatrix} \frac{5}{2} - x \end{pmatrix} \left((1 - x) \left(-\frac{3}{2} - x \right) - (-1) \times 1 \right) - 1 \left(1 \left(-\frac{3}{2} - x \right) - (-1) \times 2 \right) \\
+ (-2)(1 \times 1 - 2(1 - x)) \\
= -x^3 + 2x^2 - \frac{5}{4}x + \frac{1}{4} \\
= -\frac{1}{4}(2x - 1)^2(x - 1).$$

By right, the characteristic polynomial have 1 as the coefficient of the highest term. The characteristic polynomial of **A** is $c(x) = \frac{1}{4}(2x-1)^2(x-1)$. Thus, the eigenvalues of **A** are $\frac{1}{2}$ and 1. A matrix which has the same characteristic polynomial is

$$\begin{pmatrix}
\frac{1}{2} & 0 & 0 \\
0 & \frac{1}{2} & 0 \\
0 & 0 & 1
\end{pmatrix}$$
(1)

(b) To find the eigenspace E_1 , we solve the system

$$\begin{pmatrix} \frac{3}{2} & 1 & -2 & | & 0 \\ 1 & 0 & -1 & | & 0 \\ 2 & 1 & -\frac{5}{2} & | & 0 \end{pmatrix} \xrightarrow{2R_1} \begin{pmatrix} 3 & 2 & -4 & | & 0 \\ 1 & 0 & -1 & | & 0 \\ 4 & 2 & -5 & | & 0 \end{pmatrix} \xrightarrow{-R_2 + R_3} \begin{pmatrix} 3 & 2 & -4 & | & 0 \\ 1 & 0 & -1 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \xrightarrow{-3R_2 + R_1} \begin{pmatrix} 0 & 2 & -1 & | & 0 \\ 1 & 0 & -1 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}.$$

It follows that $E_1 = \operatorname{span} \left\{ \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \right\}$.

(c) As for the eigenspace $E_{\frac{1}{2}}$, we have

$$\begin{pmatrix} 2 & 1 & -2 & 0 \\ 1 & \frac{1}{2} & -1 & 0 \\ 2 & 1 & -2 & 0 \end{pmatrix} \xrightarrow{-\frac{1}{2}R_1 + R_2} \begin{pmatrix} 2 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Hence, we have $E_{\frac{1}{2}} = \operatorname{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 2 \\ 0 \end{pmatrix} \right\}$

(d) We have

$$\begin{pmatrix} 2 & 1 & -1 \\ 1 & 0 & 2 \\ 2 & 1 & 0 \end{pmatrix}^{-1} \mathbf{A} \begin{pmatrix} 2 & 1 & -1 \\ 1 & 0 & 2 \\ 2 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{2} \end{pmatrix} =: D.$$

Then,

$$\lim_{n \to \infty} D^n = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

Since

$$\mathbf{A} = \begin{pmatrix} 2 & 1 & -1 \\ 1 & 0 & 2 \\ 2 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 2 & 1 & -1 \\ 1 & 0 & 2 \\ 2 & 1 & 0 \end{pmatrix}^{-1},$$

we have

$$\lim_{n \to \infty} \mathbf{A}^n = \lim_{n \to \infty} (\mathbf{P} \mathbf{D} \mathbf{P}^{-1})^n = \lim_{n \to \infty} \mathbf{P} \mathbf{D}^n \mathbf{P}^{-1} = \mathbf{P} \left(\lim_{n \to \infty} \mathbf{D}^n \right) \mathbf{P}^{-1} = P \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} P^{-1} = \begin{pmatrix} 4 & 2 & -4 \\ 2 & 1 & -2 \\ 4 & 2 & -4 \end{pmatrix}.$$

Question 5

(a) Clearly, $\mathbf{0} \in V$.

For
$$\mathbf{a} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ 0 \end{pmatrix}$$
, $\mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \\ 0 \end{pmatrix} \in V$ and a scalar $c \in \mathbb{R}$ we have

$$c\mathbf{a} + \mathbf{b} = c \begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ 0 \end{pmatrix} + \begin{pmatrix} b_1 \\ b_2 \\ b_3 \\ 0 \end{pmatrix} = \begin{pmatrix} ca_1 \\ ca_2 \\ ca_3 \\ 0 \end{pmatrix} + \begin{pmatrix} b_1 \\ b_2 \\ b_3 \\ 0 \end{pmatrix} = \begin{pmatrix} ca_1 + b_1 \\ ca_2 + b_2 \\ ca_3 + b_3 \\ 0 \end{pmatrix} \in V.$$

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Thus, *V* is a subspace of \mathbb{R}^4 .

A basis for
$$V$$
 is given by $\left\{ \begin{pmatrix} 1\\0\\0\\0 \end{pmatrix}, \begin{pmatrix} 0\\1\\0\\0 \end{pmatrix}, \begin{pmatrix} 0\\0\\1\\0 \end{pmatrix} \right\}$.

(b)
$$\mathbf{A} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}.$$

- (c) rank(A) = 3, nullity(A) = 3 rank(A) = 3 3 = 0.
- (d) Take $\mathbf{B} = \mathbf{A}^T$. The matrix \mathbf{B} is not unique. In fact, for any $\mathbf{u} \in \mathbb{R}^3$, the matrix $(\mathbf{I}_3 \ \mathbf{u})$ satisfies the relation. For instance, take $\mathbf{u} = (-1, 0, 1)$. Put $\mathbf{B} = \begin{pmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix}$. Then $\mathbf{B}\mathbf{A} = \mathbf{I}_3$.
- (e) Note that $4 = \text{rank}(\mathbf{I}_4) = \text{rank}(\mathbf{AD}) \le \text{rank}(\mathbf{A}) = 3$, which is a contradiction.

Question 6

(a) Note that we have

$$c_{\mathbf{A}}(x) = \det(\mathbf{I_3} - x\mathbf{A}) = \begin{pmatrix} x - 2 & a & b \\ 0 & x - c & d \\ 0 & 0 & x - e \end{pmatrix} = (x - 2)(x - c)(x - e)$$

and so x = 2 is an eigenvalue of **A**. In particular, $e_1 = (1,0,0)^T$ is an eigenvector associated with 2.

(b) Way 1:

By Vieta's formula, the product of roots of the polynomial is -18. It follows that $\frac{-18}{2 \times 9} = -1$ is a root of the polynomial too.

Way 2:

c(x) = (x-2)(x-c)(x-e). Either c or e must be 9. WLOG, put e = 9. To get 18 as the constant term, c = -1, which means that -1 is a root of c(x).

Since the characteristic polynomial has three distinct roots, the dimension of the union of the eigenspaces must be ≥ 3 . Since the union of the eigenspaces cannot exceed dim = 3, this forces the dimension of the union of the eigenspaces to be 3 and A must be diagonalizable.

Question 7

(a) Since S is an orthonormal basis of V, it follows from triangle inequality that

$$||\mathbf{v}|| = ||c_1\mathbf{u}_1 + c_2\mathbf{u}_2 + \dots + c_k\mathbf{u}_k||$$

$$\leq |c_1| ||\mathbf{u}_1|| + |c_2| ||\mathbf{u}_2|| + \dots + |c_k| ||\mathbf{u}_k||$$

$$= |c_1| + |c_2| + \dots + |c_k|.$$

(b) Write

$$||v|| = ||c_1\mathbf{u}_1 + c_2\mathbf{u}_2 + \dots + c_k\mathbf{u}_k|| = \sqrt{c_1^2 + c_2^2 + \dots + c_k^2}.$$

Then, it follows that $||v||^2 = c_1^2 + c_2^2 + \dots + c_k^2$ and so for each positive integer $1 \le i \le k$, we have $c_i^2 \le ||v||^2$, which implies that $|c_i| \le ||v|| \le 1$. Hence, $|c_i| \le 1$.

(d) We will prove the result from part (d) only because the proof for part (c) is similar. From part (b), we have

$$||\mathbf{A}\mathbf{v}|| = ||\mathbf{A}(c_1\mathbf{u}_1 + c_2\mathbf{u}_2 + \dots + c_k\mathbf{u}_k)||$$

$$\leq |c_1| ||\mathbf{A}\mathbf{u}_1|| + |c_2| ||\mathbf{A}\mathbf{u}_2|| + \dots + |c_k| ||\mathbf{A}\mathbf{u}_k||$$

$$\leq ||\mathbf{v}|| (||\mathbf{A}\mathbf{u}_1|| + ||\mathbf{A}\mathbf{u}_2|| + \dots + ||\mathbf{A}\mathbf{u}_k||)$$

$$= M||\mathbf{v}||.$$

Setting $||v|| \le 1$ gives the result for (c).