

# Assignment - 2

Course: Signals, Systems, and Random Processes

Instructor: Himanshu Shekhar

Name: Ekansh Somani

Roll: 20110065

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## Q1

Given following  $x(t)$  with period  $T_0 = 2$ :

$$x(t) = \begin{cases} t^2/2 & 0 \leq t < 1 \\ 0 & \text{otherwise} \end{cases}$$

**a**

Plot the function and it's magnitude line spectra using MATLAB.

```
fs = 100; % sampling frequency = 100 Hz
t = 0 : 1/fs : 10 - 1/fs;
x = repmat([ (t(1:fs).^2)./2, zeros(1, fs)], [1 5]);

figure1 = figure;
axes1 = axes('Parent',figure1);
hold(axes1,'on');
plot(t, x);

title('x(t)')
xlim([0,10]);
ylim([0, 0.5]); % optional to resize axis limits
xlabel('t');
ylabel('x');

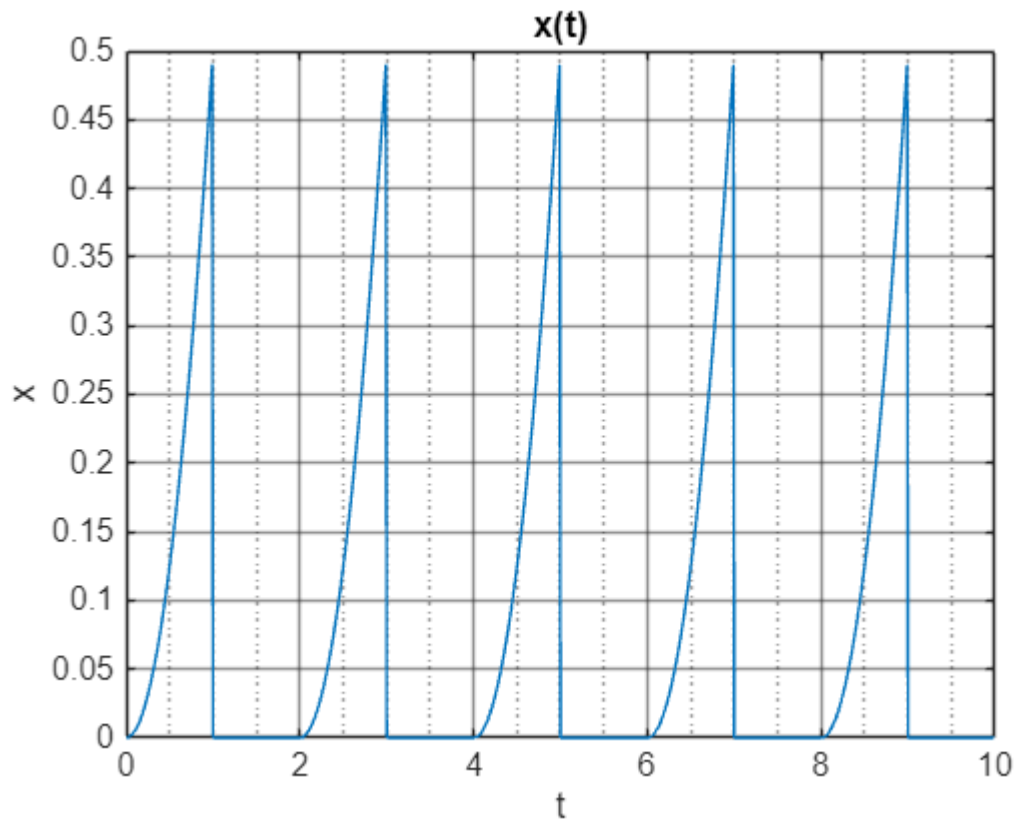
box(axes1,'on');
```

```

grid(axes1,'on');
hold(axes1,'off');
% Set the remaining axes properties
set(axes1,'GridAlpha',0.5,'MinorGridAlpha',0.4,'XMinorGrid','on')

set(gca,'FontSize',12)

```



```

X = fft(x);
X_magnitude = abs(X);
f = (0: length(X)-1) * fs/length(X);

figure2 = figure;
axes2 = axes('Parent',figure2);
hold(axes2,'on');
stem(f, X_magnitude);

title('X-Magnitude Line Spectrum');
xlim([0,10]);
ylim([0, 50]); % optional to resize axis limits
xlabel('f');
ylabel('X_m');

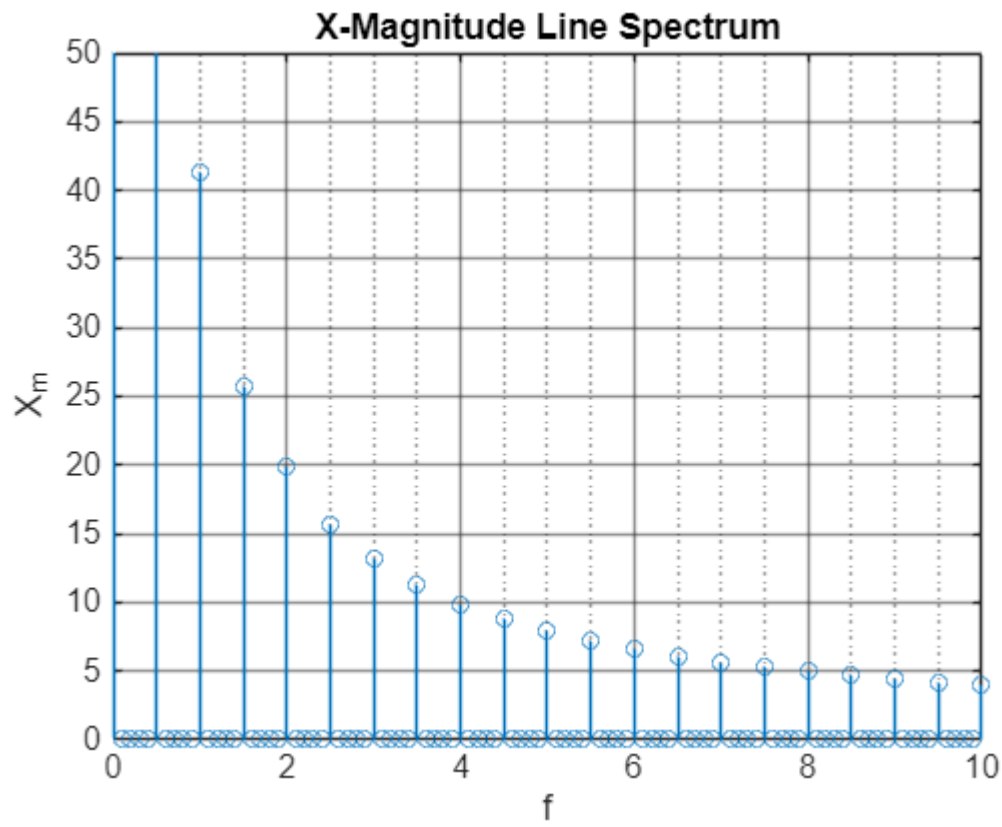
box(axes2,'on');
grid(axes2,'on');
hold(axes2,'off');

% Set the remaining axes properties

```

```
set(axes2, 'GridAlpha', 0.5, 'MinorGridAlpha', 0.4, 'XMinorGrid', 'on')
```

```
set(gca, 'FontSize', 12)
```



**b**

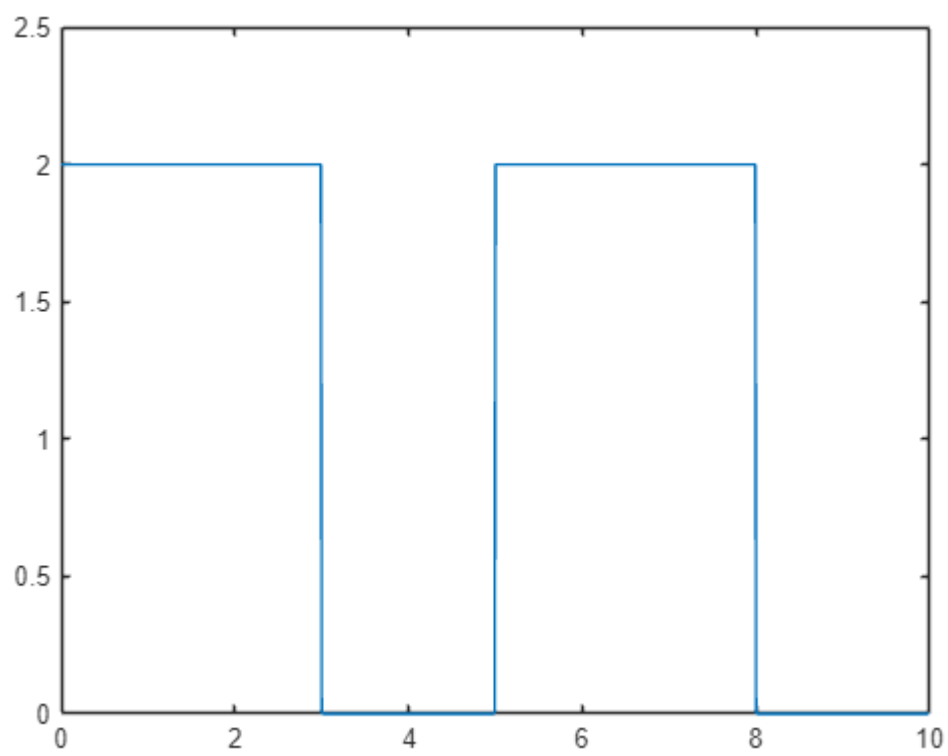
List out the magnitudes of  $3f$ ,  $5f$ , and  $7f$  (where  $f$  is the fundamental frequency of the given signal) components.

$$f_0 = \frac{1}{T_0} = 0.5 \text{ Hz}$$

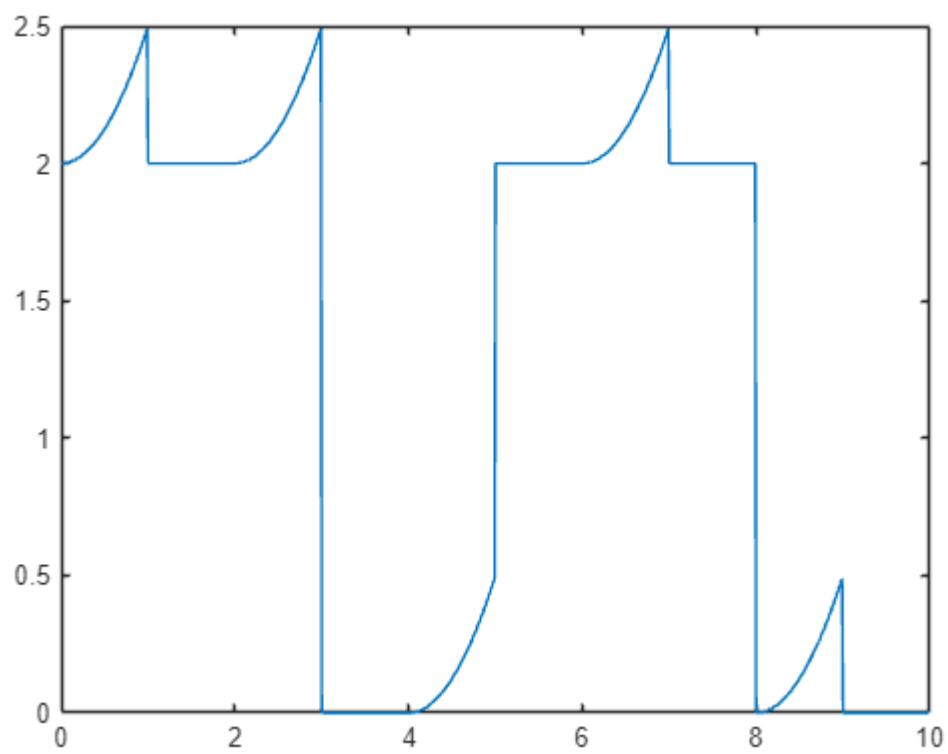
frequency	$3f_0$	$5f_0$	$7f_0$
magnitude	25.6884	15.6442	11.2303

**c**

```
y = repmat([zeros(1, 3*fs) + 2, zeros(1, 2*fs)], [1 2]);
plot(t, y);
ylim([0, 2.5]);
```



```
z = y + x;  
plot(t, z)
```



```

Y_magnitude = abs(fft(y));
Z_magnitude = abs(fft(z));

figure3= figure;
axes3 = axes('Parent',figure3);
hold(axes3,'on');
stem(f, Z_magnitude);

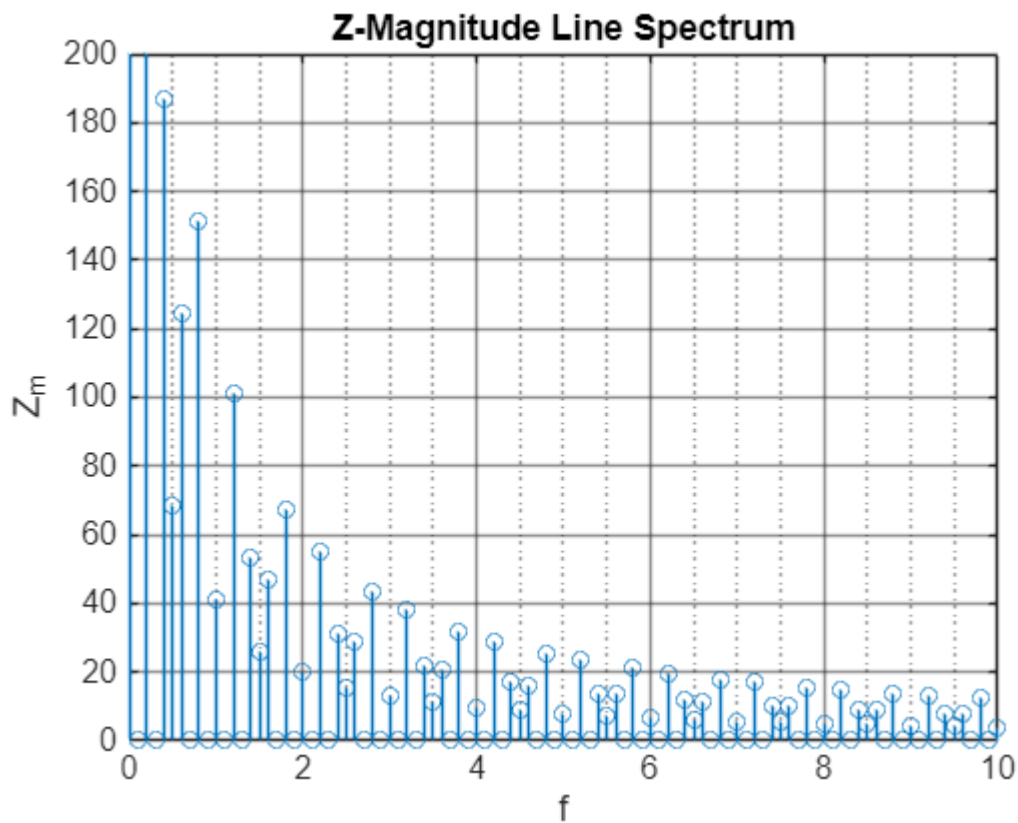
title('Z-Magnitude Line Spectrum');
xlim([0,10]);
ylim([0, 200]); % optional to resize axis limits
xlabel('f');
ylabel('Z_m');

box(axes3,'on');
grid(axes3,'on');
hold(axes3,'off');

% Set the remaining axes properties
set(axes3, 'GridAlpha',0.5, 'MinorGridAlpha',0.4, 'XMinorGrid','on')

set(gca, 'FontSize',12)

```



```

figure4= figure;
axes4 = axes('Parent',figure4);
hold(axes4,'on');

```

```

stem(f, X_magnitude + Y_magnitude);

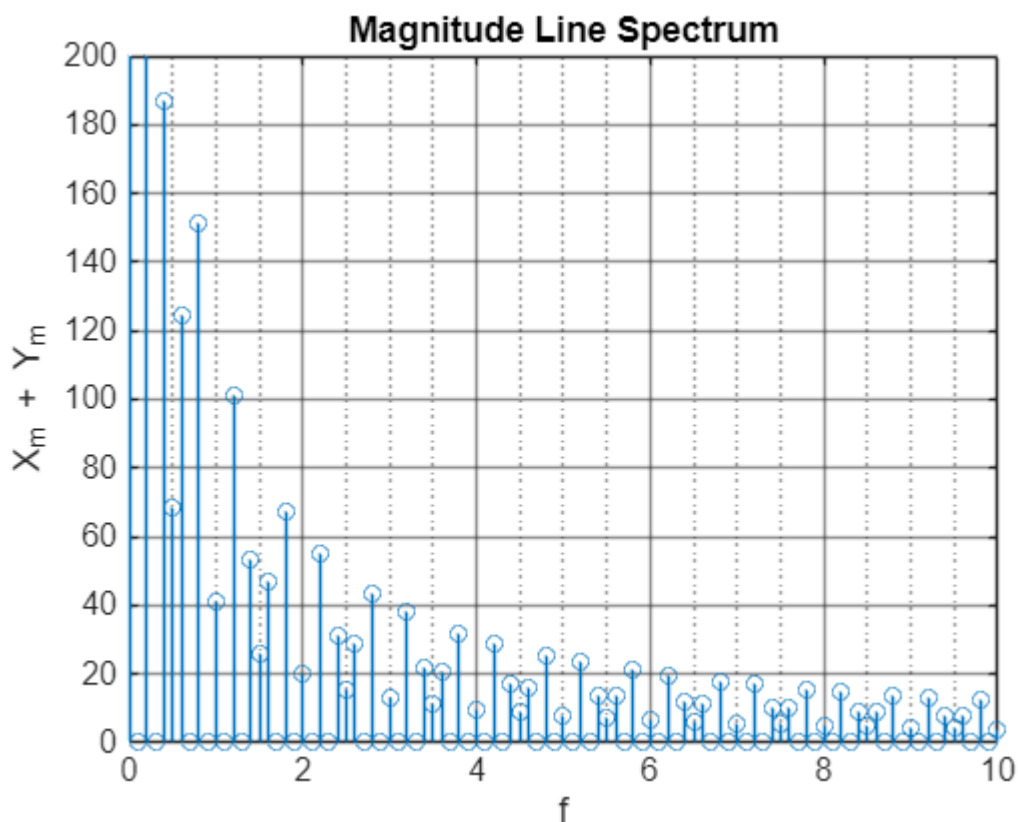
title('Magnitude Line Spectrum');
xlim([0,10]);
ylim([0, 200]); % optional to resize axis limits
xlabel('f');
ylabel('X_m + Y_m');

box(axes4, 'on');
grid(axes4, 'on');
hold(axes4, 'off');

% Set the remaining axes properties
set(axes4, 'GridAlpha',0.5, 'MinorGridAlpha',0.4, 'XMinorGrid', 'on')

set(gca, 'FontSize',12)

```



## Q2

Say  $x(t)$  is a signal with period  $T_o = 2$  s, and each period has the form of  $u(t) - 2u(t - 1) + u(t - 2)$ .

Approximate  $x(t)$  to  $x'(t)$  with 30 harmonics and plot  $x'(t)$  using MATLAB. Also plot the magnitude line spectrum for  $x'(t)$ .

$$x'(t) = a_0 + \sum_{k=1}^{30} (a_k \cos k\omega_0 t + b_k \sin k\omega_0 t)$$

where,

$$\omega_0 = \frac{2\pi}{T_0} = \pi$$

$$a_0 = \frac{1}{T_0} \int_0^{T_0} x(t) dt$$

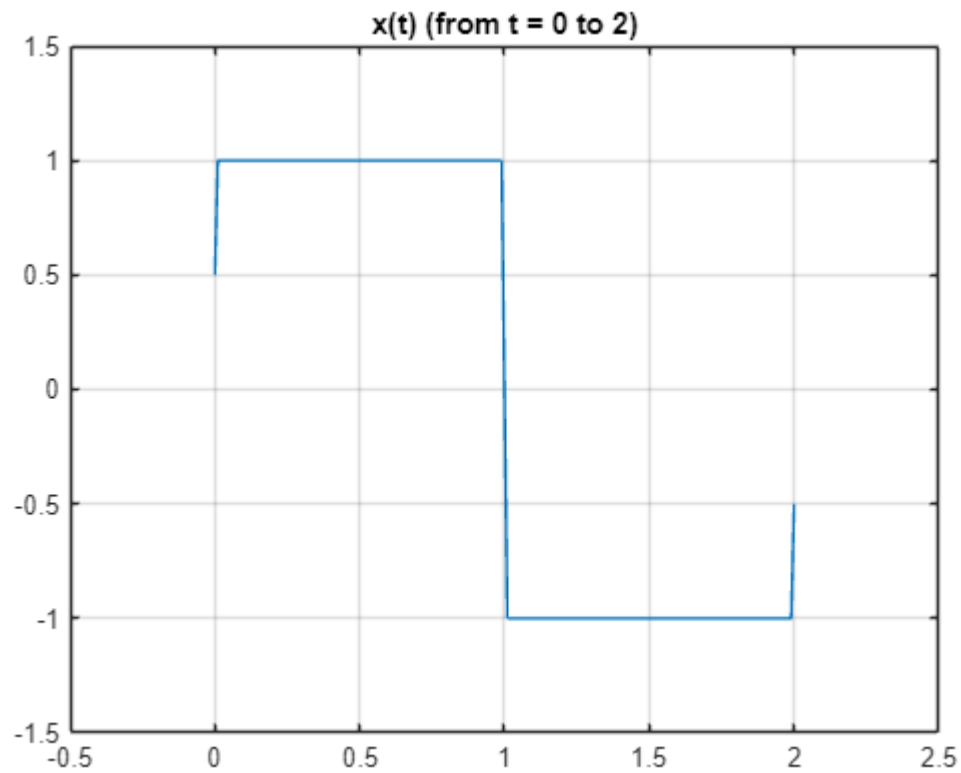
$$a_k = \frac{2}{T_0} \int_0^{T_0} x(t) \cos k\omega_0 t dt$$

$$b_k = \frac{2}{T_0} \int_0^{T_0} x(t) \sin k\omega_0 t dt$$

Let's first try to plot x(t)

```
t = 0:0.01:2; % Define the time vector
u = @(t) heaviside(t); % Define the unit step function

% Define and plot the signal
x = u(t) - 2 * u(t - 1) + u(t - 2);
plot(t, x)
title('x(t) (from t = 0 to 2)');
xlim([-0.5, 2.5]);
ylim([-1.5, 1.5]);
grid on;
```



Based on the above plot, we can say that  $a_0 = 0$ . Now it's a lengthy task to compute all the  $a_k$  and  $b_k$  by hand. So let's have matlab do it for us.

$$x'(t) = \sum_{k=1}^{30} (a_k \cos k\pi t + b_k \sin k\pi t)$$

where,

$$a_k = \int_0^2 x(t) \cos k\pi t \, dt$$

$$b_k = \int_0^2 x(t) \sin k\pi t \, dt$$

```
x = @(t) u(t) - 2 * u(t - 1) + u(t - 2);

a_k = @(k) integral(@(t) x(t).*cos(k*pi*t), 0, 2);
b_k = @(k) integral(@(t) x(t).*sin(k*pi*t), 0, 2);

a = zeros(1, 30);
b = zeros(1, 30);
for k = 1:30
    a(k) = a_k(k);
    b(k) = b_k(k);
end
```

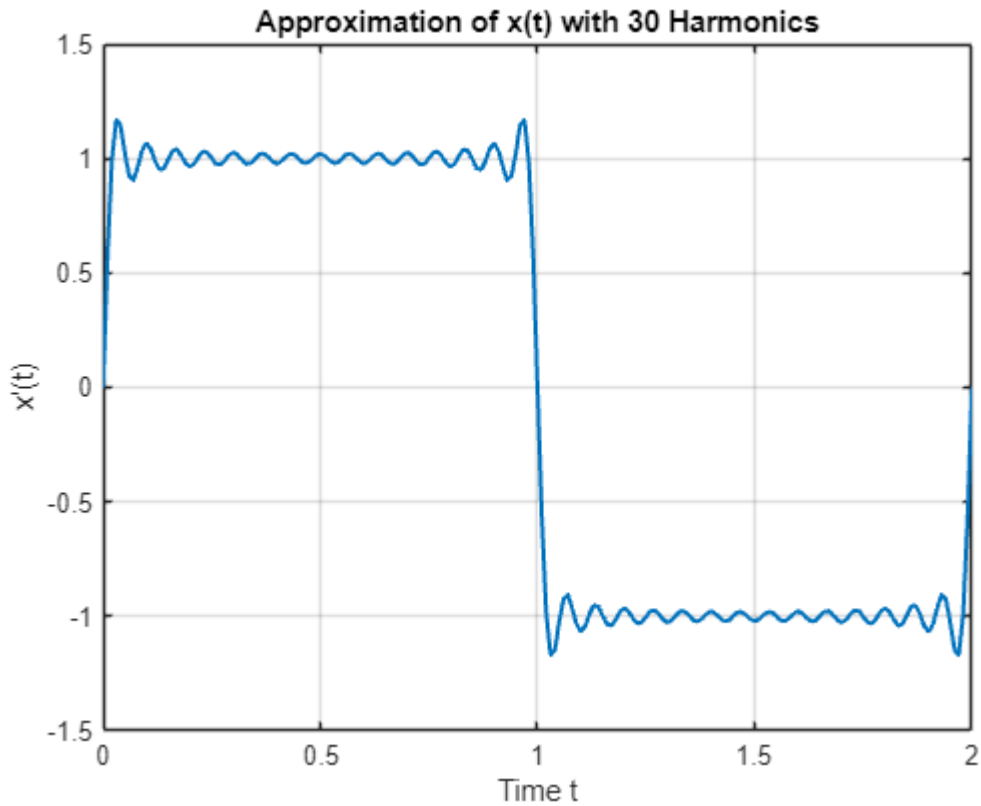


```
% Create a table for a_k and b_k
disp(table((1:30)', a', b', 'VariableNames', {'k', 'a_k', 'b_k'}));
```

k	a_k	b_k
1	1.9429e-16	1.2732
2	2.0817e-17	1.0235e-16
3	2.2204e-16	0.42441
4	6.9389e-18	-2.8796e-16
5	-4.2934e-17	0.25465
6	-1.7174e-16	-2.2204e-16
7	4.1286e-16	0.18189
8	1.1796e-16	-4.1633e-16
9	3.0531e-16	0.14147
10	1.1796e-16	4.5797e-16
11	6.6093e-16	0.11575
12	-3.1919e-16	3.1398e-16
13	-8.3267e-17	0.097942
14	-1.2143e-17	-8.3267e-17
15	7.7369e-16	0.084883
16	2.7582e-16	7.3726e-17
17	1.4225e-16	0.074896
18	-1.0061e-16	-8.4134e-17
19	2.8623e-16	0.067013
20	1.1276e-17	-4.1633e-17
21	-3.4044e-17	0.06063
22	6.6353e-16	-1.0061e-16
23	2.8449e-16	0.055358
24	6.3578e-16	-6.9389e-18
25	3.1832e-16	0.05093
26	-1.0408e-17	-2.5327e-16
27	-7.867e-16	0.047157
28	-3.5735e-16	1.5959e-16
29	-1.0408e-16	0.043905
30	3.5041e-16	-5.3256e-16

```
x_t_prime = zeros(size(t)); % Start with the a0 term
for k = 1:30
    x_t_prime = x_t_prime + a(k) * cos(k * pi * t) + b(k) * sin(k * pi * t);
end

figure;
plot(t, x_t_prime, 'LineWidth', 1.5);
xlabel('Time t');
ylabel('x''(t)');
title('Approximation of x(t) with 30 Harmonics');
grid on;
```



### Q3

Convert the following continuous-time signals into discrete-time signals using the sampling theorem. Make sure that there is no aliasing.

**a**

$$x(t) = 1 + \text{sinc}(300\pi t)$$

$$x[n] = 1 + \text{sinc}(300\pi T_s n)$$

$$f_m = \frac{\omega_m}{2\pi} = 150$$

$$T_s = \frac{1}{f_s} = \frac{1}{2f_m} = \frac{1}{2 * 150} = 1/300$$

$$x[n] = 1 + \text{sinc}(\pi n) \quad \text{where, } n \in \mathbb{Z}$$

**b**

$$x(t) = 1 + \cos(2000\pi t) + \sin(4000\pi t)$$

$$f_m = \frac{\omega_m}{2\pi} = 2000$$

$$T_s = \frac{1}{2f_m} = \frac{1}{4000}$$

$$x[n] = x(nT_s) = 1 + \cos\left(\pi \frac{n}{2}\right) + \sin(\pi n) \quad \text{where, } n \in \mathbb{Z}$$

**c**

$$x(t) = 10 \sin 40\pi t \cos 300\pi t = 5 \sin 340\pi t - 5 \sin 260\pi t$$

$$f_m = \frac{340\pi}{2\pi} = 170$$

$$T_s = \frac{1}{2 * 170} = \frac{1}{340}$$

$$x[n] = x(nT_s) = 10 \sin \frac{2}{17} \pi n \cos \frac{15}{17} \pi n = 5 \sin \pi n - 5 \sin \frac{13}{17} \pi n$$

where,  $n \in Z$

## Q4

Find out the FT of the given signal in MATLAB without using the FFT built-in function and plot the phase and magnitude graph for the given signal. Compare your results with the built-in function FFT.

$$x = \sin 30\pi t + \sin 80\pi t$$

$$X(\omega) = \sum_0^T x(t)e^{j\omega t}$$

```
t = 0:1/100:10-1/100; % Time vector
x = sin(2*pi*15*t) + sin(2*pi*40*t); % Signal

X = zeros([1 20]);
omega_0 = 10*pi;
for k = 1:20
    Angle = k * omega_0 * t;
    X(k) = x * (cos(Angle) + 1i*sin(Angle))';
end

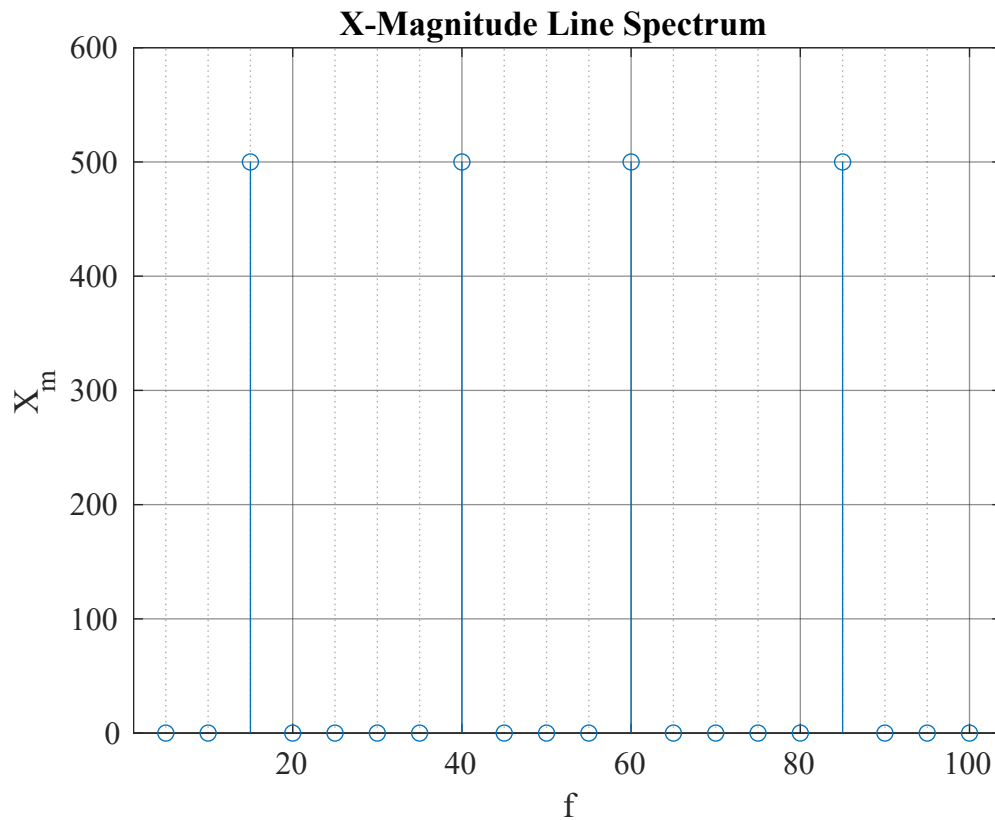
f = 5:5:100;

figure1 = figure;
axes1 = axes('Parent',figure1);
hold(axes1,'on');
stem(f, abs(X))
title('X-Magnitude Line Spectrum');
% xlim([0,10]);
% ylim([0, 50]); % optional to resize axis limits
xlabel('f');
ylabel('X_m');

box(axes1,'on');
grid(axes1,'on');
hold(axes1,'off');

% Set the remaining axes properties
set(axes1,'GridAlpha',0.5,'MinorGridAlpha',0.4,'XMinorGrid','on')
```

```
set(gca, 'FontSize',12)
```

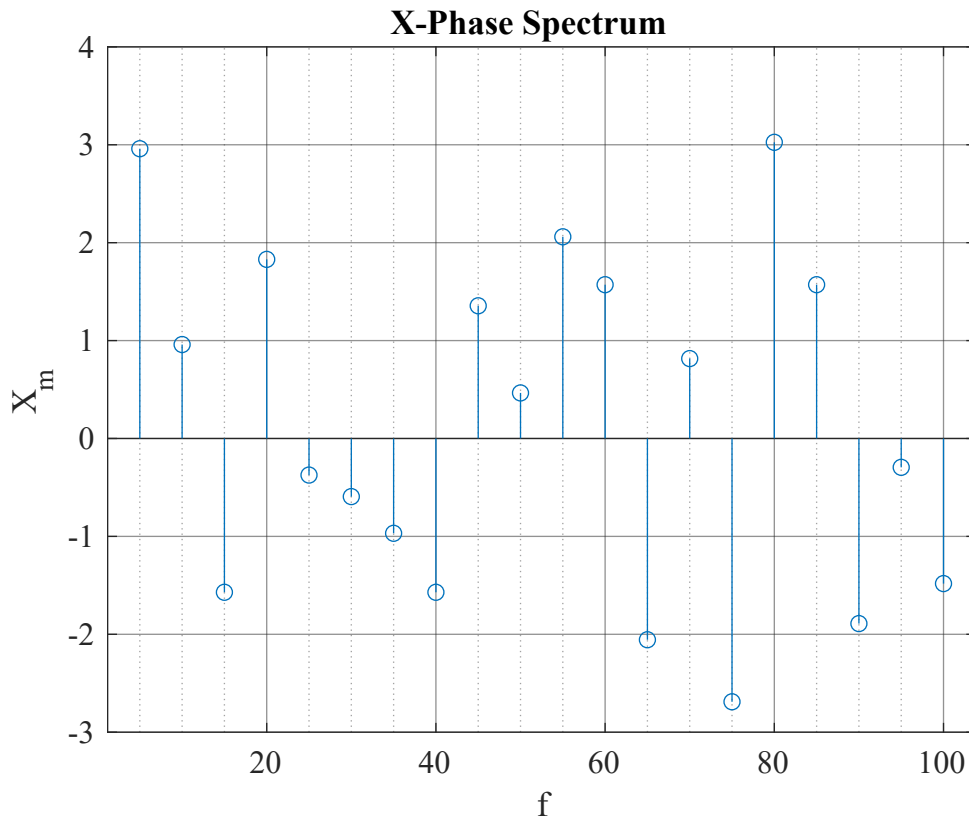


```
figure2 = figure;
axes2 = axes('Parent',figure2);
hold(axes2,'on');
stem(f, angle(X))
title('X-Phase Spectrum');
% xlim([0,10]);
% ylim([0, 50]); % optional to resize axis limits
xlabel('f');
ylabel('X_m');

box(axes2,'on');
grid(axes2,'on');
hold(axes2,'off');

% Set the remaining axes properties
set(axes2,'GridAlpha',0.5,'MinorGridAlpha',0.4,'XMinorGrid','on')

set(gca, 'FontSize',12)
```



## Q5

Consider the following signal:

$$x(t) = r(t+1) - 2r(t) + r(t-1)$$

$$y(t) = \frac{dx}{dt}$$

**a**

Obtain  $X(\Omega)$  and  $Y(\Omega)$ , plot their magnitude and phase spectrums, and comment whether  $X(\Omega)$  and  $Y(\Omega)$  are real or imaginary.

$$\begin{aligned}
 X(\Omega) &= \int_{-\infty}^{+\infty} x(t)e^{j\Omega t} dt \\
 &= \int_{-\frac{3}{2}}^{-\frac{1}{2}} e^{j\Omega t} dt + \int_{\frac{1}{2}}^{\frac{3}{2}} e^{j\Omega t} dt - \int_{-\frac{1}{2}}^{\frac{1}{2}} e^{j\Omega t} dt \\
 &= \frac{1}{j\Omega} (e^{3/2 j\Omega} + 2e^{-1/2 j\Omega} - 2e^{1/2 j\Omega} - e^{-3/2 j\Omega}) \\
 Y(\Omega) &= \int_{-\infty}^{+\infty} \frac{dx}{dt} e^{j\Omega t} dt \\
 &= e^{j\Omega t} x(t) \Big|_{-\infty}^{+\infty} - j\Omega \int_{-\infty}^{+\infty} x(t) e^{j\Omega t} dt \\
 &= -j\Omega * X(\Omega)
 \end{aligned}$$

```

omega = -50:0.1:50;
Y = - exp(1.5i .* omega) - 2 * exp(-0.5i .* omega) + 2 * exp(0.5i .* omega) +
exp(-1.5i .* omega);
X = Y./ (-1i * omega);

```

```

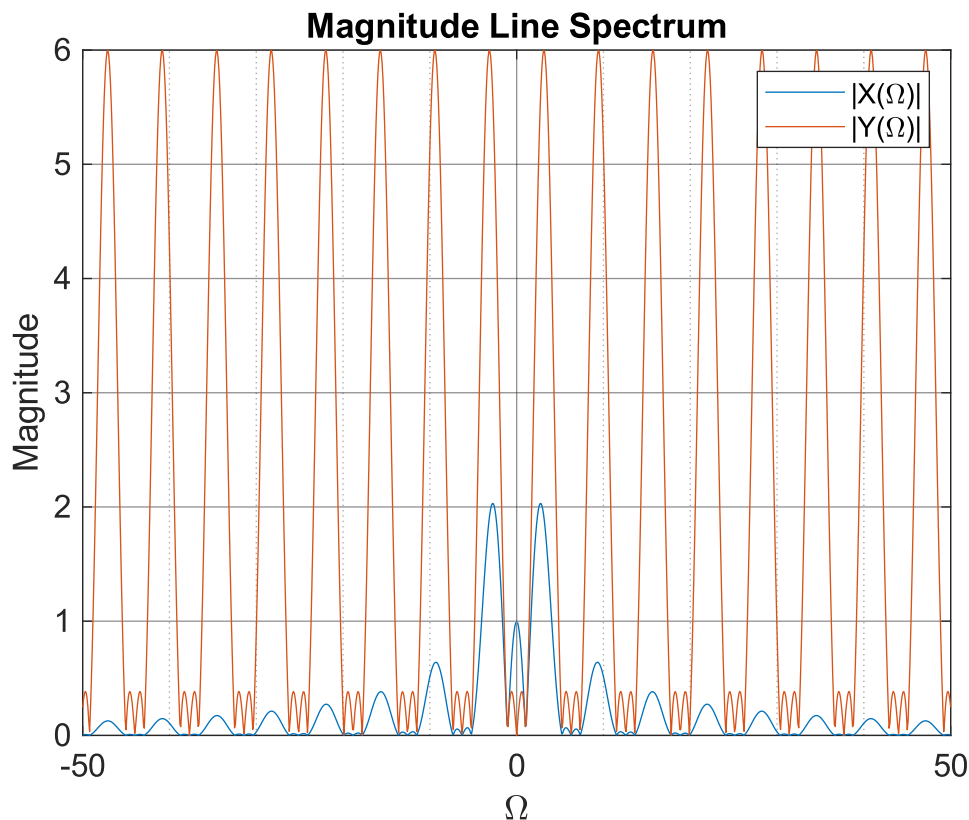
figure1 = figure;
axes1 = axes('Parent',figure1);
hold(axes1,'on');
plot(omega, abs(X), 'DisplayName', '|X(\Omega)|')
plot(omega, abs(Y), 'DisplayName', '|Y(\Omega)|')
title('Magnitude Line Spectrum');
% xlim([0,10]);
% ylim([0, 50]); % optional to resize axis limits
xlabel('\Omega');
ylabel('Magnitude');
legend

box(axes1,'on');
grid(axes1,'on');
hold(axes1,'off');

% Set the remaining axes properties
set(axes1,'GridAlpha',0.5,'MinorGridAlpha',0.4,'XMinorGrid','on')

set(gca,'FontSize',12)

```



```

figure2 = figure;
axes2 = axes('Parent',figure2);
hold(axes2,'on');
scatter(omega, angle(X), 'DisplayName', 'arg(X(\Omega))')

```

```

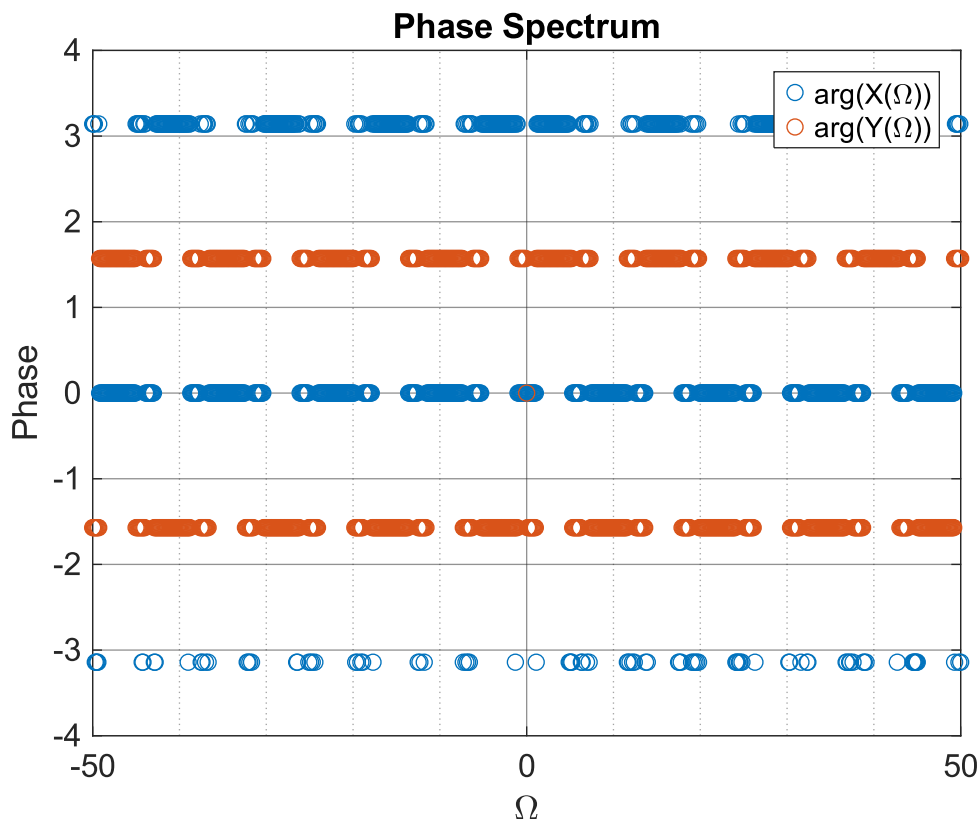
scatter(omega, angle(Y), 'DisplayName', 'arg(Y(\Omega))')
title('Phase Spectrum');
% xlim([0,10]);
% ylim([0, 50]); % optional to resize axis limits
xlabel('\Omega');
ylabel('Phase');
legend

box(axes2,'on');
grid(axes2,'on');
hold(axes2,'off');

% Set the remaining axes properties
set(axes2,'GridAlpha',0.5,'MinorGridAlpha',0.4,'XMinorGrid','on')

set(gca,'FontSize',12)

```



We could already tell from the derived equations that  $X(\Omega)$  and  $Y(\Omega)$  were  $90^\circ$  out of phase. Based on the above phase spectrum now, it is clear that the phase of  $X(\Omega)$  is either  $0$ ,  $+\pi$ , or  $-\pi$ . Thus  $X(\Omega)$  is real, and  $Y(\Omega)$  is imaginary.

**b**

**Determine from the above spectra which of these two signals are smoother. Use MATLAB integration function `int` to find the fourier transforms. Plot  $20 \log_{10} |Y(\Omega)|$  and  $20 \log_{10} |X(\Omega)|$  and decide. Would**

you say in general that computing the derivative of a signal generates high frequencies or possible discontinuities.

We can easily conclude based on the magnitude line spectra that  $x(t)$  is much smoother than  $y(t)$ . The reason being that magnitude of high frequencies in it's spectra is significantly lower due to  $X(\Omega)$  being a decaying function of  $\Omega$ . It implies components of  $x(t)$  are mainly low frequency sine and cosine waves while  $y(t)$  has a lot of high frequency components. Thus,  $y(t)$  would fluctuate a lot more than  $x(t)$  and would seem noisy/less smooth in comparison to  $x(t)$ .

```
figure1 = figure;
axes1 = axes('Parent',figure1);
hold(axes1,'on');
plot(omega, 20.*log10(abs(X)), 'DisplayName', '20 log_{10}|X(\Omega)|')
plot(omega, 20.*log10(abs(Y)), 'DisplayName', '20 log_{10}|Y(\Omega)|')
title('Magnitude Line Spectrum');
% xlim([0,10]);
% ylim([0, 50]); % optional to resize axis limits
xlabel('\Omega');
ylabel('log(Magnitude)');
legend
```

