view_frames Result

Recorded at time: 1563198099.523

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1563198099.523 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1563198099.523 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1563198099.523 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1563198099.523 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1563198099.523 sec old)
Buffer length: 0.000 sec

body

casterFront

casterRear

wheelLeft

wheelRight

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1563198099.523 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1563198099.523 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1563198099.523 sec old)
Buffer length: 0.000 sec

top

casterBallFront

casterBallRear

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1563198099.523 sec old)
Buffer length: 0.000 sec

servoPanNeck

Broadcaster: /pan_tilt
Average rate: 10.204 Hz
Most recent transform: 1563198099.497 (0.026 sec old)
Buffer length: 4.900 sec

servoPan

Broadcaster: /pan_tilt
Average rate: 10.204 Hz
Most recent transform: 1563198099.498 (0.025 sec old)
Buffer length: 4.900 sec

servoTilt

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1563198099.523 sec old)
Buffer length: 0.000 sec

camera