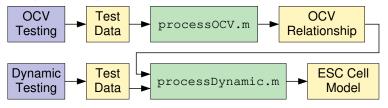
Creating the model



- Figure depicts overall process for creating an ESC cell model
- Blue boxes = laboratory processes; yellow boxes = data files; green boxes = processing by Octave/MATLAB functions



- In this lesson, you will learn the main details of processDynamic.m
- I recommend that you study this alongside notes for Lessons 2.3.1 through 2.3.2

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2.3.3: Introducing Octave code to determine dynamic part of an ECM

Preliminary comments (1)



```
% function processDynamic
% PROCESSDYNAMIC assumes that specific cell test scripts have been run to gen-
% erate the input data structure having fields for time, step, current, voltage,
\% chgAh, and disAh for each script run. The results from three scripts are
\% required at every temperature. The steps in each script file are assumed to be:
   Script 1 (thermal chamber set to test temperature):
     Step 1: Rest @ 100% SOC to acclimatize to test temperature
     Step 2: Discharge @ 1C to reach ca. 90% SOC
%
    Step 3: Repeatedly execute dynamic profiles (and possibly
              intermediate rests) until SOC is around 10%
  Script 2 (thermal chamber set to 25 degC):
     Step 1: Rest ca. 10% SOC to acclimatize to 25 degC
     Step 2: Discharge to min voltage (ca. C/3)
%
     Step 3: Rest
     Step 4: Constant voltage at vmin until current small (ca. C/30)
%
     Steps 5-7: Dither around vmin
    Step 8: Rest
```

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2.3.3: Introducing Octave code to determine dynamic part of an ECM

Preliminary comments (2)



```
Script 3 (thermal chamber set to 25 degC):
     Step 2: Charge @ 1C to max voltage
      Step 3: Rest
      Step 4: Constant voltage at vmax until current small (ca. C/30)
      Steps 5-7: Dither around vmax
      Step 8: Rest
\% All other steps (if present) are ignored by PROCESSDYNAMIC. The time step
% between data samples must be uniform -- we assume a 1s sample period in this code
% The inputs:
\% - data: An array, with one entry per temperature to be processed.
          One of the array entries must be at 25 degC. The fields of
          "data" are: temp (the test temperature), script1,
          script 2, and script 3, where the latter comprise data
          collected from each script. The sub-fields of these script
          structures that are used by PROCESSDYNAMIC are the vectors:
          current, voltage, chgAh, and disAh
\% - model: The output from processOCV, comprising the OCV model
% - numpoles: The number of R-C pairs in the model
\% - doHyst: 0 if no hysteresis model desired; 1 if hysteresis desired
```



Preliminary comments (3); function header



```
% The output:
% - model: A modified model, which now contains the dynamic
          fields filled in.
function model = processDynamic(data, model, numpoles, doHyst)
 global bestcost
 % used by fminbnd later on
 options=optimset('TolX',1e-8,'TolFun',1e-8,'MaxFunEval',100000, ...
    'MaxIter',1e6, 'Jacobian', 'Off'); % for later optimization
 % Step 1: Determine coulombic efficiency and capacity
% Code omitted here. See Lesson 2.2.5 for similar code + description
```

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2.3.3: Introducing Octave code to determine dynamic part of an ECM

Compute OCV, subtract from v|k|



```
% Step 2: Compute OCV for "discharge portion" of test
for k = 1:length(data),
  etaParam = model.etaParam(k);
                                 % retrieve eta for this test
  etaik = data(k).script1.current; % modify current using eta
  etaik(etaik<0) = etaParam*etaik(etaik<0);</pre>
  data(k).Z = 1 - cumsum([0,etaik(1:end-1)])*1/(data(k).Q*3600); % SOC
  data(k).OCV = OCVfromSOCtemp(data(k).Z(:),alltemps(k),model); % OCV
end % OCV is actually subtracted from voltage later on...
% Step 3: Set up optimization, optimize!
model.GParam = NaN(1,numTemps); % "gamma" hysteresis parameter
model.MOParam = NaN(1,numTemps); % "MO" hysteresis parameter
model.MParam = NaN(1,numTemps); % "M" hysteresis parameter
model.ROParam = NaN(1,numTemps); % "RO" ohmic resistance parameter
model.RCParam = NaN(numTemps, numpoles); % time const.
model.RParam = NaN(numTemps, numpoles); % Rk
```

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2.3.3: Introducing Octave code to determine dynamic part of an ECM

The code that invokes the optimizations



■ The following code invokes the optimizations (discussed on following slides)

```
for theTemp = 1:numTemps,
   fprintf('Processing temperature %d\n',model.temps(theTemp));
   bestcost = Inf;
   if doHyst,
      model.GParam(theTemp) = abs(fminbnd(@(x) optfn(x,data,...
                                  model, model.temps(theTemp),...
                                  doHyst),1,250,options));
      model.GParam(theTemp) = 0; theGParam = 0;
      % call optfn to display plots, if desired
     optfn(theGParam,data,model,model.temps(theTemp),doHyst);
   end
   % set final model fields
   [~, model] = minfn(data, model, model.temps(theTemp), doHyst);
return % from processDynamic
```

Function to be minimized by optimization



- optfn is nested function called by fminbnd.m to optimize γ
- It can also update plots of best parameter values found to date

```
% This function has the correct syntax to be invoked by fminbnd.m to optimize
\% the model parameter values (esp. gamma), returning the rms model error "cost"
function cost=optfn(theGParam,data,model,theTemp,doHyst)
 global bestcost
 model.GParam(model.temps == theTemp) = abs(theGParam);
  [cost,model] = minfn(data,model,theTemp,doHyst);
 if cost < bestcost ,</pre>
   bestcost = cost;
   disp('Best ESC model values yet!');
   % You can plot some things here if you want to
return
```

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2.3.3: Introducing Octave code to determine dynamic part of an ECM

Given γ , find best model parameter values (1)



- minfn is the function that does most of the work
- Given OCV and γ , find the remaining parameter values

```
% Using an assumed value for gamma (already stored in the model), find
\% optimum values for remaining cell parameters, and compute the RMS
% error between true and predicted cell voltage
function [cost, model] = minfn(data, model, theTemp, doHyst)
 alltemps = [data(:).temp];
 ind = find(alltemps == theTemp); numfiles = length(ind);
 rmserr = zeros(1, numfiles);
 G = abs(getParamESC('GParam', theTemp, model));
 Q = abs(getParamESC('QParam',theTemp,model));
 eta = abs(getParamESC('etaParam',theTemp,model));
 RC = getParamESC('RCParam', theTemp, model);
 numpoles = length(RC);
```

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2.3.3: Introducing Octave code to determine dynamic part of an ECM

Given γ , find best model parameter values (2)



- minfn is the function that does most of the work
- Given OCV and γ , find the remaining parameter values

```
for thefile = 1:numfiles;
   ik = data(ind(thefile)).script1.current(:);
   vk = data(ind(thefile)).script1.voltage(:);
   tk = (1:length(vk))-1;
   etaik = ik; etaik(ik<0) = etaik(ik<0)*eta;</pre>
   h=0*ik; sik = 0*ik;
   fac=exp(-abs(G*etaik/(3600*Q)));
   for k=2:length(ik),
    h(k)=fac(k-1)*h(k-1)-(1-fac(k-1))*sign(ik(k-1));
     sik(k) = sign(ik(k));
     if abs(ik(k)) < Q/100, sik(k) = sik(k-1); end
```

Given γ , find best model parameter values (3)



- minfn is the function that does most of the work
- \blacksquare Given OCV and γ , find the remaining parameter values

```
% First modeling step: Compute error with model = OCV only
vest1 = data(ind(thefile)).OCV; verr = vk - vest1;
% Second modeling step: Compute time constants in "A" matrix
A = SISOsubid(-diff(verr), diff(etaik), numpoles);
eigA = eig(A); eigAr = eigA + 0.001*randn(size(eigA));
eigA(eigA ~= conj(eigA)) = abs(eigAr(eigA ~= conj(eigA)));
eigA(eigA<0) = abs(eigA(eigA<0)); eigA(eigA>1) = 1./eigA(eigA>1);
RCfact = sort(eigA); RCfact = RCfact(end-numpoles+1:end);
RC = -1./log(RCfact);
\% Simulate the R-C filters to find R-C currents
vrcRaw = dlsim(diag(RCfact),1-RCfact,eye(numpoles),zeros(numpoles,1),etaik);
```

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2.3.3: Introducing Octave code to determine dynamic part of an ECM

Given γ , find best model parameter values (4)



- minfn is the function that does most of the work
- Given OCV and γ , find the remaining parameter values

```
% Third modeling step: Hysteresis parameters
if doHyst,
 H = [h,sik,-etaik,-vrcRaw];
 W = lsqnonneg(H,verr); % or, W = H\verr;
 M = W(1); M0 = W(2); R0 = W(3); Rfact = W(4:end)';
else
 H = [-etaik, -vrcRaw];
 W = H\verr;
 M=0; M0=0; R0 = W(1); Rfact = W(2:end)';
end
ind = find(model.temps == data(ind(thefile)).temp,1);
model.RCParam(ind,:) = RC'; model.RParam(ind,:) = Rfact';
model.ROParam(ind) = RO;
```

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2.3.3: Introducing Octave code to determine dynamic part of an ECM

Given γ , find best model parameter values (5)



- minfn is the function that does most of the work
- \blacksquare Given OCV and γ , find the remaining parameter values

```
vest2 = vest1 + M*h + M0*sik - R0*etaik - vrcRaw*Rfact';
   verr = vk - vest2;
   \% Compute RMS error only on data roughly in 5% to 95% SOC
   v1 = OCVfromSOCtemp(0.95,data(ind(thefile)).temp,model);
   v2 = OCVfromSOCtemp(0.05,data(ind(thefile)).temp,model);
   N1 = find(vk < v1,1,'first'); N2 = find(vk < v2,1,'first');
   if isempty(N1), N1=1; end; if isempty(N2), N2=length(verr); end
   rmserr(thefile) = sqrt(mean(verr(N1:N2).^2));
 end % for thefile = 1:numfiles
 cost=sum(rmserr);
 fprintf('RMS error = %0.2f(mV)\n',cost*1000);
 if isnan(cost), stop, end
return % end of minfn
```

Table of model fields (1)



■ The following table lists fields in the model data structure

Identifier field

An identifying string storing a name for the cell type name

Fields pertaining to the OCV versus SOC relationship

Vector of OCV versus SOC at 0 °C [V]

OCVrel Vector of change in OCV versus SOC per °C [V/°C]

SOC SOC vector at which OCVO and OCVrel are stored

Vector of SOC versus OCV at 0 °C (unitless) SOCO

SOCrel Vector of change in SOC versus OCV per °C [1/°C] OCV OCV vector at which SOCO and SOCrel are stored

(continued...)

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2.3.3: Introducing Octave code to determine dynamic part of an ECM

Table of model fields (2)



Fields in the model data structure (continued)

Fields pertaining to the dynamic relationship

temps Temperatures at which dynamic parameters stored [°C]

QParam Capacity *Q* at each temperature [Ah]

etaParam Coulombic efficiency η at each temperature (unitless)

GParam Hysteresis "gamma" parameter γ (unitless)

MParam Hysteresis *M* parameter [V]

MOParam Hysteresis M_0 parameter [V]

ROParam Series resistance parameter R_0 [Ω]

The R–C time constant parameter R_iC_i [s] RCParam Resistance R_i of the R–C parameter $[\Omega]$ RParam

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2.3.3: Introducing Octave code to determine dynamic part of an ECM

Summary



- In this lesson, you have seen Octave/MATLAB code to optimize model parameter values
 - Coulombic efficiency and capacity calculated directly from data, allowing computation of OCV
 - Subspace system identification method finds R–C time constants
 - \Box Line-search algorithm optimizes hysteresis rate constant γ
 - □ All other values found via least-squares fitting
- Code should match theory in earlier lessons quite closely