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> Template

```
#include "bits/stdc++.h"
using namespace std;
typedef long long ll;
#define endl '\n'
#define int ll
#define Hi ios_base::sync_with_stdio(0);
cin.tie(0); cout.tie(0);
///
void magic() {}
signed main() {
 Hi
 int t = 1;
 cin >> t;
 while (t--) magic();
}
   Pragma
#pragma GCC optimize("O3")
#pragma GCC optimize("Ofast,unroll-loops")
#pragma GCC target("avx2,bmi,bmi2,lzcnt,popcnt")
```

#pragma GCC target("avx,avx2,fma")

Custom Hash

```
struct custom_hash {
    static uint64_t splitmix64(uint64_t x) {
        x += 0x9e3779b97f4a7c15;
        x = (x ^ (x >> 30)) * 0xbf58476d1ce4e5b9;
        x = (x ^ (x >> 27)) * 0x94d049bb133111eb;
        return x ^ (x >> 31);
    }
    size_t operator()(uint64_t x) const {
        static const uint64_t FIXED_RANDOM =
        chrono::steady_clock::now().time_since_epoch().co
        unt();
        return splitmix64(x + FIXED_RANDOM);
    }
};
```

Cycle Take All Edges

```
vector<int> res, vis;
vector<vector<pair<int, int>>> adj;

void dfs(int u) {
    while (adj[u].size()) {
        auto [v, i] = adj[u].back();
        adj[u].pop_back();
        if (vis[i])
            continue;
        vis[i] = 1;
        dfs(v);
    }
    res.push_back(u);
}
```

> Path Take All Edges

```
vector<int> res;
vector<vector<int>> adj;
void dfs(int s){
  while(adj[s].size()){
    int u = adj[s].back(); adj[s].pop_back();
    dfs(u);
  }
  res.push_back(s);
}
void check() {
  for(int i = 2; i < n; i++)
    if(in[i] != out[i])
      return "IMPOSSIBLE";
  if(in[1]!= out[1] - 1 || out[n]!= in[n] - 1)
    return "IMPOSSIBLE";
  dfs(1);
  reverse(res.begin(), res.end());
  if(res.size() != m + 1 || res.back() != n) {
    return "IMPOSSIBLE";
  for(auto v:res)
    cout << v << " ";
}
```

De Burijn

```
unordered_map<string, int> id;
string s[MX_SIZE];
int cnt = 1, n, k = 2;
vector<char> a{'0', '1'};
void rec(string cur){
  if(cur.size() == n){
    id[cur] = cnt;
    s[cnt++] = cur;
    return;
  }
  for(int i = 0; i < a.size(); i++)
    rec(cur + a[i]);
}
vector<int> adj[MX_SIZE];
bool vis[MX_SIZE];
string res;
void dfs(int u) {
  for (auto v: adj[u])
    if (!vis[v]) {
      vis[v] = 1;
      dfs(v);
      res.push_back(s[v].back());
    }
}
void makeAdj(){
  int mx = (1 << n);
  for(int i = 1; i \le mx; i++){
    string cur = s[i].substr(1, n - 1);
    for(int j = 0; j < a.size(); j++)
      adj[i].push_back(id[cur + a[j]]);
  }
}
string makeDeBruijn() {
  rec("");
  makeAdj();
  dfs(1);
  s[1].pop_back();
  return res + s[1];
}
```

> Find Cycle

```
int anyCycle = 0;
vector<int> cycle;
void dfs(int u) {
  vis[u] = tc;
  for (auto v: adj[u]) {
    if (anyCycle == tc)
      return;
    if (vis[v] != tc) {
      parent[v] = u;
      dfs(v);
    } else if (v != parent[u]) {
      cycle.push_back(v);
      int current = u;
      while (current != v) {
        cycle.push_back(current);
        current = parent[current];
      }
      cycle.push_back(v);
      anyCycle = tc;
      return;
    }
  }
}
```

> Find Cycle Directed

```
int anyCycle = 0;
vector<int> cycle;
int n, m, in = 1, out = 2;

void dfs(int u) {
    vis[u] = in;
    for (auto v: adj[u]) {
        if (anyCycle == 1)
            return;

        if (vis[v] != in && vis[v] != out ) {
            parent[v] = u;
            dfs(v);
        } else if (vis[v] != out) {
            cycle.push_back(v);
        }
}
```

```
int current = u;
  while (current!= v) {
     cycle.push_back(current);
     current = parent[current];
  }
  cycle.push_back(v);

  anyCycle = 1;
  return;
  }
}

vis[u] = out;
}
```

> Tree Canonical Form

```
string treeCanonicalForm(int u, int par) {
  vector<string> child;

for(auto v : adj[u]){
   if(v == par) continue;
   child.push_back(treeCanonicalForm(v, u));
  }

string cur = "(";
  sort(child.begin(), child.end());
  for(auto it : child)
     cur += it;
  cur += ")";

return cur;
}
```

Tree Canonical BFS

```
string calc(int u, vector<vector<string>> &subCan) {
  string cur = "(";
  sort(subCan[u].begin(), subCan[u].end());
  for (auto it: subCan[u])
    cur += it;
  cur += ")";
  return cur;
}
pair<string, string> treeCanonicalForm(int n) {
  queue<int> leaf;
  vector<int> deg(n + 1, -1);
  int rem = n;
  for (int i = 1; i \le n; i++) {
    if (adj[i].size() <= 1)
      leaf.push(i);
    else
      deg[i] = adj[i].size();
  }
  vector<vector<string>> subCan(n + 1);
  while (rem > 2) {
    int v = leaf.front();
    leaf.pop();
    string cur = calc(v, subCan);
    for (auto u: adj[v]) {
      subCan[u].push_back(cur);
      if(--deg[u] == 1)
        leaf.push(u);
    }
    rem--;
  }
  int v1 = leaf.front();
  leaf.pop();
  int v2 = (leaf.empty()?-1: leaf.front());
  string s1 = calc(v1, subCan);
  string s2 = ((v2 == -1)?"" : calc(v2, subCan));
  if (v2 == -1)
    return make_pair(s1, s2);
  subCan[v1].push_back(s2);
```

```
subCan[v2].push_back(s1);
return {calc(v1, subCan), calc(v2, subCan)};
}
```

```
Tree Diameter void dfsDown(int u, int p) { for (auto v: adj[u]) { if (p == v)
```

```
for (auto v: adj[u]) {
    if (p == v)
      continue;
    dfsDown(v, u);
    if (dpDown[v][0] + 1 > dpDown[u][1])
      dpDown[u][1] = dpDown[v][0] + 1;
    if (dpDown[u][1] > dpDown[u][0])
      swap(dpDown[u][0], dpDown[u][1]);
  }
}
void dfsUp(int u, int p, int level) {
  dpUp[u] = level;
  for (auto v: adj[u]) {
    if (p == v)
      continue;
    int cur;
    if (dpDown[v][0] + 1 != dpDown[u][0])
      cur = dpDown[u][0];
    else
      cur = dpDown[u][1];
    cur = max(cur, dpUp[u]);
    dfsUp(v, u, cur + 1);
  }
}
    > DSU
struct DSU {
  int n, cnt;
  vector<int> parent, size;
  DSU(int sz) {
    n = sz, cnt = 0;
    parent.resize(n);
    size.resize(n);
  }
  void init() {
    for(int u = 0; u < n; ++u) makeSet(u);
```

}

```
void makeSet(int u) {
    if(!size[u]) cnt++;
    parent[u] = u;
    size[u] = 1;
  }
  int find(int u) {
    if(u == parent[u]) return u;
    return parent[u] = find(parent[u]);
  }
  bool merge(int u, int v) {
    int uP = find(u);
    int vP = find(v);
    if(vP == uP) return 0;
    if(size[vP] > size[uP]) swap(uP, vP);
    size[uP] += size[vP];
    parent[vP] = uP;
    --cnt;
    return 1;
 }
};
```

> Bellman

```
struct Edge {
  int from, to, w;
  Edge(): to(0), from(0), w(0) {};
  Edge(int f, int t, int ww): from(f), to(t), w(ww) {};
};
struct Node {
  long long dist;
  int par;
  bool reachCycle;
  Node(): dist(oo), par(-1), reachCycle(0) {};
};
struct bellmanFord {
  int n, m;
  bool negative_cycle = 0;
  vector<Edge> edges;
  vector<Node> node;
  bellmanFord(int nn, int mm, vector<Edge> &e) {
    n = nn, m = mm;
    edges.resize(m);
    node.resize(n + 2);
    edges = e;
  }
  void build(int src, int startCost) {
    node[src].dist = startCost;
    node[src].par = src;
    for (int i = 1; i \le n; ++i) {
      bool exist = 0;
      for (long long j = 0; j < m; ++j) {
        auto [u, v, w] = edges[j];
        if (node[u].dist < oo && node[v].dist >
node[u].dist + w) {
          if (i == n) negative_cycle = 1;
          node[v].dist = node[u].dist + w;
          node[v].par = u;
          exist = 1;
        }
      if (!exist) break;
    }
  }
```

```
void buildReachCycle(int src) {
  vector<long long> oldDist(n + 1);
  for (int i = 1; i <= n; i++)
     oldDist[i] = node[i].dist;

  build(src, oldDist[src]);
  for (int i = 1; i <= n; i++)
     node[i].reachCycle = (oldDist[i] != node[i].dist);
  }
};</pre>
```

> Floyd

```
struct floyd {
  int n;
  vector<vector<int>> dist, par;
  floyd(int sz) {
    n = sz;
    dist = par = vector<vector<int>>(n + 5, vector<int>(n + 5));
  }
  void init() {
    for (int i = 1; i \le n; i++) {
      for (int j = 1; j \le n; j++)
         par[i][j] = i, dist[i][j] = oo;
       dist[i][i] = 0;
    }
  }
  void build() {
    for (int k = 1; k \le n; k++)
      for (int u = 1; u \le n; u++)
         for (int v = 1; v \le n; v++) {
           dist[u][v] = min(dist[u][v], dist[u][k] + dist[k][v]);
           if (dist[u][v] == dist[u][k] + dist[k][v] && k!= v)
             par[u][v] = par[k][v];
         }
  }
  void printPath(int u, int v) {
    if (u != v) printPath(u, par[u][v]);
    cout << v << " ";
  }
  bool isNegativeCycle() {
    for (int i = 1; i <= n; i++)
       if (dist[i][i] < 0)
         return 1;
    return 0;
  }
  bool anyEffectiveNegativeCycle(int u, int v) {
    for (int i = 1; i \le n; i++)
       if (dist[i][i] < 0 && dist[u][i] < oo && dist[i][v] < oo)
         return 1;
    return 0;
  }
};
```

Maximum Matching

```
struct maximumMatching {
  int n, t;
 vector<vector<int>> adj;
 vector<pair<int, int>> matches;
  vector<int> vis, leftAssign, rightAssign, isLeft,
isRight;
  maximumMatching(int nn) {
    n = nn, t = 0;
    adj.assign(n + 1, {});
    vis = isLeft = isRight = vector<int>(n + 1, 0);
    leftAssign = rightAssign = vector<int>(n + 1, -1);
 }
 void matching() { // O(EV)
    if (n == 0) return;
    int maxFlow = 0;
    for (int i = 1; i \le n; i++) {
      if (!isLeft[i]) continue;
      t++;
      if (canMatch(i)) maxFlow++;
    }
    for (int i = 1; i \le n; i++) {
      if (!isRight[i]) continue;
      if (rightAssign[i] != -1)
        matches.push_back({rightAssign[i], i});
    }
  }
  bool canMatch(int u) {
    for (auto v: adj[u])
      if (vis[v] != t) {
        vis[v] = t;
        if (rightAssign[v] == -1 ||
canMatch(rightAssign[v])) {
          rightAssign[v] = u, leftAssign[u] = v;
          return true;
        }
     }
    return false;
  }
```

```
vector<vector<int>> mnPathCvs;
void buildMnPathCvs() {
  for (int i = 1; i <= n; i++) {
     if (rightAssign[i] == -1) {
        vector<int> v(1, i);
        int cur = leftAssign[i];

     while (cur != -1) {
        v.push_back(cur);
        cur = leftAssign[cur];
     }
     mnPathCvs.push_back(v);
     }
   }
}
```

Max Flow (Dinic)

```
// O(v ^ 2 * E)
struct edge {
  int u, v, cap, flow;
};
struct Dinic {
  int n:
  vector<int> dist, par, idEdge, curld;
  vector<vector<int>> adj;
  vector<edge> edges;
  Dinic(int nn) {
    n = nn;
    dist.resize(n + 1);
    adj.resize(n + 1);
    par.resize(n + 1);
    idEdge.resize(n + 1);
    curld.resize(n + 1);
  }
  void addEdge(int u, int v, int c) {
    adj[u].push_back(edges.size());
    edges.push_back({u, v, c, 0});
    adj[v].push_back(edges.size());
    edges.push_back({v, u, 0, 0});
  }
  int flow(int src, int sink) {
    int totalFlow = 0;
    while (isPath(src, sink)) {
      for (int i = 1; i \le n; i++)
        curld[i] = 0;
      while (int newFlow = dfs(src, oo, sink))
        totalFlow += newFlow;
    }
    return totalFlow;
  }
```

```
bool isPath(int src, int sink) {
    for (int i = 1; i \le n; i++)
      dist[i] = oo;
    queue<int>q;
    q.push(src);
    dist[src] = 0;
    while (!q.empty()) {
      int u = q.front();
      q.pop();
      if (u == sink)
        break;
      for (auto idx: adj[u]) {
         auto [\_, v, c, f] = edges[idx];
        if (f < c \&\& dist[v] == oo) {
           dist[v] = dist[u] + 1;
           par[v] = u;
          idEdge[v] = idx;
           q.push(v);
        }
      }
    }
    return dist[sink] < oo;
  }
  int dfs(int u, int flow, int sink) {
    if (!flow)
      return 0;
    if (u == sink)
      return flow;
    for (; curld[u] < adj[u].size(); curld[u]++) {
      int idx = adj[u][curld[u]];
      auto [_, v, c, f] = edges[idx];
      if (dist[v] != dist[u] + 1)
         continue;
      int newFlow = dfs(v, min(flow, c - f), sink);
      if (newFlow) {
         edges[idx].flow += newFlow;
        edges[idx ^ 1].flow -= newFlow;
        return newFlow;
      }
    }
    return 0;
  }
};
```

Max Flow (Karp)

```
struct edge {
  int u, v, cap;
};
struct maxFlow {
  int n;
  vector<int> dist, par, idEdge, vis;
  vector<vector<int>> adj;
  vector<edge> edges;
  maxFlow(int nn) {
    n = nn;
    dist.resize(n + 1);
    adj.resize(n + 1);
    par.resize(n + 1);
    vis.resize(n + 1, 0);
    idEdge.resize(n + 1);
  }
  void addEdge(int u, int v, int c) {
    adj[u].push_back(edges.size());
    edges.push_back({u, v, c});
    adj[v].push_back(edges.size());
    edges.push_back({v, u, 0});
  }
  int flow(int src, int sink) {
    int totalFlow = 0;
    while (isPath(src, sink)) {
      int newFlow = oo;
      int cur = sink;
      while (cur != src) {
        newFlow = min(newFlow,
edges[idEdge[cur]].cap);
        cur = par[cur];
     }
      cur = sink;
      while (cur != src) {
        edges[idEdge[cur]].cap -= newFlow;
        edges[idEdge[cur] ^ 1].cap += newFlow;
        cur = par[cur];
     }
      totalFlow += newFlow;
    }
```

```
return totalFlow;
}
bool isPath(int src, int sink) {
  for (int i = 1; i <= n; i++)
    dist[i] = oo;
  queue<int>q;
  q.push(src);
  dist[src] = 0;
 while (!q.empty()) {
    int u = q.front();
    q.pop();
    if (u == sink)
      break;
    for (auto idx: adj[u]) {
      auto [_, v, c] = edges[idx];
      if (c \&\& dist[v] == oo) {
        dist[v] = dist[u] + 1;
        par[v] = u;
        idEdge[v] = idx;
        q.push(v);
      }
    }
 }
  return dist[sink] < oo;
}
vector<pair<int, int>> res;
void minCutEdges(int src, int sink) {
  dfs(src);
 for (int idx = 0; idx < edges.size(); idx += 2) {
    auto [u, v, c] = edges[idx];
    if (vis[u] && !vis[v]) {
      res.push_back({u, v});
    }
 }
```

```
void dfs(int u) {
    vis[u] = 1;
    for (auto idx: adj[u]) {
      auto [_, v, c] = edges[idx];
      if (c && !vis[v]) {
        dfs(v);
     }
   }
  }
};
    Min Cost Max Flow
struct edge {
  int u, v, cost, cap;
};
struct minCostMaxFlow {
  int n, maxFlow, minCost;
  vector<int> dist, par, idEdge;
  vector<vector<int>> adj;
  vector<edge> edges;
  minCostMaxFlow(int nn) {
    n = nn;
    dist.resize(n + 1, oo);
    adj.resize(n + 1);
    par.resize(n + 1);
    idEdge.resize(n + 1);
  }
  void addEdge(int u, int v, int cost, int cap) {
    adj[u].push_back(edges.size());
    edges.push_back({u, v, cost, cap});
    adj[v].push_back(edges.size());
    edges.push_back({v, u, -cost, 0});
  }
  void flow(int src, int sink) {
    maxFlow = 0, minCost = 0;
    while (true) {
      dijkstra(src);
      if (dist[sink] <= -oo || dist[sink] >= oo)
        break;
      int newFlow = oo;
      int cur = sink;
      while (cur != src) {
```

```
newFlow = min(newFlow,
edges[idEdge[cur]].cap);
        cur = par[cur];
     }
     cur = sink;
     while (cur != src) {
        minCost += newFlow *
edges[idEdge[cur]].cost;
        edges[idEdge[cur]].cap -= newFlow;
        edges[idEdge[cur] ^ 1].cap += newFlow;
        cur = par[cur];
     }
      maxFlow += newFlow;
   }
 }
 void dijkstra(int src) {
   for (int i = 1; i \le n; i++)
      dist[i] = oo;
   dist[src] = 0;
   par[src] = -1;
   vector<br/>bool> inQueue(n + 1, 0);
   queue<int> q;
   q.push(src);
   while (!q.empty()) {
      int u = q.front();
      q.pop();
     inQueue[u] = 0;
     for (auto idx: adj[u]) {
        auto [_, v, w, cap] = edges[idx];
        if (cap > 0 \&\& dist[v] > dist[u] + w) {
          dist[v] = dist[u] + w;
          par[v] = u;
          idEdge[v] = idx;
         if (!inQueue[v]) {
           inQueue[v] = 1;
           q.push(v);
         }
       }
     }
   }
 }
```

➤ Min Cut

```
struct strongWagner {
  vector<vector<int>> adj;
  vector<int> vis, weight, contract;
  int n;
  strongWagner(int nn) {
    n = nn;
    adj.assign(n + 2, {});
    vis.assign(n + 2, {});
    weight.assign(n + 2, {});
    contract.assign(n + 2, {});
    for (int i = 1; i \le n; i++)
      for (int j = 1; j \le n; j++)
        adj[i][j] = 0;
  }
  void addEdge(int x, int y, int v) {
    adj[x][y] += v, adj[y][x] += v;
  }
  int randomMinCut(int &s, int &t) {
    int ret = 0;
    s = t = -1;
    for (int i = 1; i \le n; i++)
      vis[i] = weight[i] = 0;
    for (int i = 1; i \le n; i++) {
      int mx = -00, u = t;
      for (int j = 1; j \le n; j++)
        if (!contract[j] && !vis[j] && weight[j] > mx)
          mx = weight[j], u = j;
      if (u == t) break;
      s = t, t = u, ret = mx;
      vis[u] = 1;
      for (int j = 1; j \le n; j++)
        if (!contract[j] && !vis[j])
          weight[j] += adj[u][j];
    }
    return ret;
  }
```

```
int minCut() {
    for (int i = 1; i \le n; i++)
       contract[i] = 0;
    int ret = oo;
    for (int i = 1; i < n; i++) {
      int s, t;
      int stMinCut = randomMinCut(s, t);
      ret = min(ret, stMinCut);
      if (ret == 0) return ret;
      contract[t] = 1;
      for (int j = 1; j \le n; j++) {
         if (!contract[j]) {
           adj[s][j] += adj[t][j];
           adj[j][s] += adj[j][t];
      }
    }
    return ret;
  }
};
```

> Tarjan (SCC)

```
struct SCCTarjan {
  vector<vector<int>> adj, comps;
  vector<int> inStack, lowLink, compld, dfn;
  stack<int> st;
  int dfnCnt, n;
  SCCTarjan(int nn) {
    adj.resize(nn + 1);
    inStack.resize(nn + 1);
    lowLink.resize(nn + 1);
    dfn.resize(nn + 1, -1);
    compld.resize(nn + 1);
    n = nn;
    dfnCnt = 1;
  }
 void build() {
    for (int i = 1; i \le n; i++)
      if (dfn[i] == -1)
        tarjan(i);
 }
 void tarjan(int u) {
    lowLink[u] = dfn[u] = dfnCnt++;
    inStack[u] = 1;
    st.push(u);
    for (auto v: adj[u]) {
      if (dfn[v] == -1) {
        tarjan(v);
        lowLink[u] = min(lowLink[u], lowLink[v]);
      } else if (inStack[v]) {
        lowLink[u] = min(lowLink[u], dfn[v]);
     }
   }
    if (lowLink[u] == dfn[u]) {
      comps.push_back({});
      int cur = -1;
      while (cur != u) {
        cur = st.top(), st.pop(), inStack[cur] = 0;
        comps.back().push_back(cur);
        compld[cur] = comps.size() - 1;
     }
   }
```

```
vector<int> outDeg, inDeg;
  vector<vector<int>> dagList;
  void computeCompGraph() {
    int compCnt = comps.size();
    int srcCnt = comps.size(), desCnt = comps.size();
    outDeg.resize(compCnt);
    inDeg.resize(compCnt);
    dagList.resize(compCnt);
   for (int u = 1; u \le n; u++) {
     for (auto v: adj[u]) {
       if (compld[u] != compld[v]) {
         dagList[compld[u]].push_back(compld[v]);
         if (!inDeg[compld[v]]++) srcCnt--;
         if (!outDeg[compld[u]]++) desCnt--;
       }
     }
   }
    /* Min edges to convert DAG to one cycle */
   int cnt = max(srcCnt, desCnt);
    if (comps.size() == 1)
     cnt = 0;
    cout << cnt;
 }
};
```

Edges to Make Dag SCC

```
vector<int> vis, id;
int tc = 1;
void dfs(int u, SCCTarjan &scc) {
  vis[u] = tc;
  for (auto v: scc.dagList[u]) {
    if (!vis[v]) dfs(v, scc);
    id[tc] = min(id[vis[v]], id[tc]);
 }
}
void ROOM() {
  int n;
  cin >> n;
  vis.assign(n + 1, 0);
  id.assign(n + 1, 0);
  SCCTarjan scc(n);
  for (int i = 0; i < n; i++) {
    int u;
    cin >> u;
    scc.adj[i + 1].push_back(u);
  }
  scc.build();
  scc.computeCompGraph();
  if (scc.comps.size() == 1)
    return;
  id[tc] = 1;
  for (int i = 0; i < scc.comps.size(); i++)
    if (!vis[i])
      dfs(i, scc), tc++, id[tc] = tc;
  vector<int> can(n + 1);
  vector<int> v;
  for (int i = 0; i < scc.comps.size(); i++) {
    int cur = id[vis[i]];
    if (!can[cur])
      v.push_back(cur);
    can[cur] = 1;
  sort(v.begin(), v.end());
```

```
vector<int> inDags(n + 1, -1), outDags(n + 1, -1);
 vector<int> outs, ins;
 for (int u = 1; u \le n; u++) {
   int i = scc.compld[u];
   int cur = id[vis[i]];
   if (!scc.inDeg[i] && inDags[cur] == -1)
      inDags[cur] = u;
   else if (!scc.inDeg[i])
      ins.push_back(u);
   scc.inDeg[i]++;
   if (!scc.outDeg[i] && outDags[cur] == -1)
      outDags[cur] = u;
   else if (!scc.outDeg[i])
      outs.push_back(u);
   scc.outDeg[i]++;
 }
 for (int i = 0; i < v.size() - 1; i++) {
   int cur1 = v[i], cur2 = v[i + 1];
   cout << outDags[cur1] << " " << inDags[cur2] <<
"\n";
 }
 int cur1 = v.back(), cur2 = v[0];
 cout << outDags[cur1] << " " << inDags[cur2] <<
"\n";
 if (outs.empty() && ins.empty())
   return;
 if (outs.empty())
    outs.push_back(outDags[1]);
 if (ins.empty())
   ins.push_back(inDags[1]);
 while (outs.size() && ins.size()) {
    cout << outs.back() << " " << ins.back() << "\n";
   if (outs.size() == 1 && ins.size() == 1)
      break;
   if (ins.size() != 1)
      ins.pop_back();
   if (outs.size() != 1)
      outs.pop_back();
 }
```

> Tarjan Bridges

```
struct bridgesTarjan {
  vector<vector<int>> adj;
  vector<pair<int, int>> bridges;
  vector<int> lowLink, dfn;
  int dfnCnt, n;
  bridgesTarjan(int nn) {
    adj.resize(nn + 1);
    lowLink.resize(nn + 1);
    dfn.resize(nn + 1, -1);
    n = nn;
    dfnCnt = 1;
  }
  void build() {
    for (int i = 1; i \le n; i++)
      if(dfn[i] == -1)
        tarjan(i);
    sort(bridges.begin(), bridges.end());
  }
  void tarjan(int u, int par = -1) {
    lowLink[u] = dfn[u] = dfnCnt++;
    for (auto v: adj[u]) {
      if (v == par)
        continue;
      if (dfn[v] == -1) {
        tarjan(v, u);
        lowLink[u] = min(lowLink[u], lowLink[v]);
        if (lowLink[v] == dfn[v])
          bridges.push_back({min(u, v), max(u, v)});
        lowLink[u] = min(lowLink[u], dfn[v]);
      }
    }
 }
};
```

> Tarjan Art

```
struct artPointTarjan {
 vector<vector<int>> adj;
 vector<vector<pair<int, int>>> BCC;
 vector<int> isArtPoint, lowLink, dfn;
 stack<pair<int, int>> st;
 int dfnCnt, n;
 bool root;
 artPointTarjan(int nn) {
    adj.resize(nn + 1);
   lowLink.resize(nn + 1);
   dfn.resize(nn + 1, -1);
   isArtPoint.resize(nn + 1);
   n = nn;
   dfnCnt = 1;
   root = false;
 }
 void build() {
   for (int i = 1; i \le n; i++)
      if (dfn[i] == -1)
        tarjan(i);
 }
```

```
void tarjan(int u, int par = -1) {
    lowLink[u] = dfn[u] = dfnCnt++;
    pair<int, int> edge;
    for (auto v: adj[u]) {
      if (par!= v \&\& dfn[v] < dfn[u])
        st.push({u, v});
      if (dfn[v] == -1) {
        tarjan(v, u);
        lowLink[u] = min(lowLink[u], lowLink[v]);
        if (lowLink[v] >= dfn[u]) {
          if (dfn[u] == 1 \&\& root == false)
            root = true;
          else
            isArtPoint[u] = 1;
          int cnt = 0;
          BCC.push_back({});
          do{
            cnt++;
            edge = st.top();
            st.pop();
            BCC.back().push_back(edge);
          } while (edge.first != u || edge.second != v);
          if (cnt == 1)
            BCC.back().push_back(edge);
        }
      } else if (v != par)
        lowLink[u] = min(lowLink[u], dfn[v]);
    }
  }
};
```

> 2 - SAT

```
struct twoSat {
 vector<int> assignedValue;
 int n;
 twoSat(int nn) {
   n = 2 * nn;
   assignedValue.resize(n + 1, -1);
 }
 int NOT(int u) { return ((1 ^ (u - 1)) + 1); }
 // (0, 1), (1, 0), (1, 1)
 void addEitherOrBoth(int u, int v, SCCTarjan &SCC)
   SCC.adj[NOT(u)].push_back(v);
   SCC.adj[NOT(v)].push_back(u);
 }
 // (0, 1), (1, 0)
 void addEitherNotBoth(int u, int v, SCCTarjan
&SCC) {
   addEitherOrBoth(u, v, SCC);
   addEitherOrBoth(NOT(u), NOT(v), SCC);
 }
 // (1, 1, 1, 1, 1, 0) || (1, 1, 1, 1, 1, 1)
 void addAllExpectAtMostOne(vector<int> &v,
SCCTarjan &SCC){
   cnt += 2;
   addEitherOrBoth(v[0], NOT(cnt), SCC);
   for(int i = 1; i < v.size(); i++){
     cnt += 2;
      addEitherOrBoth(v[i], NOT(cnt), SCC);
      addEitherOrBoth(v[i], cnt - 2, SCC);
      addEitherOrBoth(cnt - 2, NOT(cnt), SCC);
   }
 }
 //(0,0,0,0,0,1)||(0,0,0,0,0,0)
 void addAtMostOne(vector<int> &v, SCCTarjan
&SCC){
   cnt += 2;
   addEitherOrBoth(NOT(v[0]), cnt, SCC);
```

```
for(int i = 1; i < v.size(); i++){
      cnt += 2;
      addEitherOrBoth(NOT(v[i]), cnt, SCC);
      addEitherOrBoth(NOT(v[i]), NOT(cnt - 2), SCC);
      addEitherOrBoth(NOT(cnt - 2), cnt, SCC);
   }
  }
  void forceValue(int u, bool f, SCCTarjan &SCC) {
    if (f)
      SCC.adj[NOT(u)].push_back(u);
      SCC.adj[u].push_back(NOT(u));
  }
  void remove(int u, bool f, SCCTarjan &scc){
    if (f)
      scc.adj[NOT(u)].pop_back();
      scc.adj[u].pop_back();
  }
  bool isSolvable(SCCTarjan &SCC) {
    for (int u = 1; u \le n; u += 2)
      if (SCC.compld[u] == SCC.compld[NOT(u)])
       return false;
    return true;
  }
  void assignValues(SCCTarjan &SCC) {
    vector<int>
compAssignedValue(SCC.comps.size(), -1);
    for (int i = 0; i < SCC.comps.size(); i++) {
      if (compAssignedValue[i] == -1) {
       compAssignedValue[i] = 1;
       int notComp =
SCC.compld[NOT(SCC.compRootNode[i])];
       compAssignedValue[notComp] = 0;
     }
   }
    for (int i = 1; i \le n; i++)
      assignedValue[i] =
compAssignedValue[SCC.compId[i]];
 }
};
```

```
/*

* take u and v from the input

* u = 2 * u - 1

* v = 2 * v - 1

* use them in 2-sat

* cnt = 2 * n - 1

* */
```

LCA (Binary Lifting)

```
struct LCA {
 const int ign = -2e9; // change this
 int n, lg;
 vector<int> depth;
 vector<vector<int>> up, qu;
 vector<vector<pair<int, int>>> adj;
 LCA(vector<vector<pair<int, int>>> &_adj, int root = 1) {
    adj = _adj;
    n = int(adj.size());
    \lg = _{\lg(n)} + 1;
    depth = vector < int > (n + 2);
    up = qu = vector<vector<int>>(n + 2, vector<int>(lg +
1));
    dfs(root, 0);
 }
 void dfs(int u, int p) {
    up[u][0] = p;
    for (int i = 1; i \le \lg; ++i) {
      up[u][i] = up[up[u][i - 1]][i - 1];
      qu[u][i] = max(qu[u][i - 1], qu[up[u][i - 1]][i - 1]);
   }
    for (auto &[ch, w]: adj[u]) {
      if (ch == p)
        continue;
      depth[ch] = depth[u] + 1, qu[ch][0] = w;
      dfs(ch, u);
   }
 }
 int get_kth_ancestor(int a, int k) {
    if (depth[a] < k)
      return -1;
    for (int i = \lg; i >= 0; --i) {
      if (k \ge (1 \le i)) {
        a = up[a][i];
        k = (1 << i);
      }
   }
    return a;
 }
```

```
int get(int a, int dist) {
    if (depth[a] < dist or dist == -1)
      return ign;
    int ret = ign;
    for (int i = \lg; i >= 0; --i) {
      if (dist >= (1 << i)) {
        ret = max(ret, qu[a][i]);
        a = up[a][i];
        dist -= (1 << i);
      }
   }
    ret = max(ret, qu[a][0]);
    return ret;
 }
 int get_max(int a, int b) {
    int c = get_lca(a, b);
    return max(get(a, distance(a, c) - 1), get(b, distance(b,
c) - 1));
 }
  int get_lca(int a, int b) {
    if (depth[a] < depth[b])
      swap(a, b);
    int k = depth[a] - depth[b];
    for (int i = \lg; i >= 0; --i)
      if (k & (1 << i))
        a = up[a][i];
    if (a == b) return a;
   for (int i = \lg; i >= 0; --i) {
      if (up[a][i] != up[b][i]) {
        a = up[a][i];
        b = up[b][i];
      }
   }
    return up[a][0];
 }
  int distance(int a, int b) {
    int c = get_lca(a, b);
    int x = depth[a] - depth[c];
   int y = depth[b] - depth[c];
    return x + y;
 }
```

};

LCA (Euler)

```
struct LCA {
  int n;
  vector<pair<int, int>> tour;
  vector<int> depth, in, par;
  SparseTable<pair<int, int>> table;
  LCA(int sz) {
    n = sz;
    in.resize(n);
    depth.resize(n);
    par.resize(n);
    table = SparseTable<pair<int, int>>(2 * n);
  }
  void dfs(int u, int p, int d, auto &adj) {
    in[u] = (int) tour.size();
    depth[u] = d;
    par[u] = p;
    tour.emplace_back(d, u);
    for (int v: adj[u]) {
      if (v == p) continue;
      dfs(v, u, d + 1, adj);
      tour.emplace_back(d, u);
    }
  }
  void build(auto &adj) {
    dfs(0, 0, 0, adj);
    table.build(tour);
  }
  int get(int u, int v) {
    return table.query(min(in[u], in[v]), max(in[u], in[v])).second;
  }
  int dist(int u, int v) {
    return depth[u] + depth[v] - 2 * depth[get(u, v)];
  }
};
```

> HLD

```
vector<vector<int>> adj;
vector<int> par, depth, pos, sz, heavy, head, val;
int cnt = 0;
void dfs(int u, int p, int d = 0) {
  par[u] = p;
  depth[u] = d;
  sz[u] = 1;
  int mx = 0;
  for (int &v: adj[u]) {
    if (v == p) continue;
    dfs(v, u, d + 1);
    if (sz[v] > mx) heavy[u] = v, mx = sz[v];
    sz[u] += sz[v];
  }
}
void HLD(int u, int hd) {
  if (!u) return;
  head[u] = hd;
  pos[u] = cnt++;
  HLD(heavy[u], hd);
  for (int &v: adj[u])
    if (v != par[u] && v != heavy[u])
      HLD(v, v);
}
int get_path(int u, int v) {
  int a = head[u], b = head[v];
  int res = 0;
  while (a != b) {
    if (depth[a] < depth[b])
      swap(a, b), swap(u, v);
    res = res + query(pos[a], pos[u]);
    u = par[a], a = head[u];
  }
  if (pos[u] > pos[v]) swap(u, v);
  res = res + query(pos[u], pos[v]);
  return res;
}
```

```
int get_subtree(int u) {
  return query(pos[u], pos[u] + sz[u]);
}
// one indexed
// call init(n), dfs(1, 0), HLD(1, 1); in main
void init(int n) {
  ++n, cnt = 0;
  adj.assign(n, {});
  par.assign(n, {});
  depth.assign(n, {});
  pos.assign(n, {});
  sz.assign(n, {});
  heavy.assign(n, {});
  head.assign(n, {});
  val.assign(n, {});
}
```

Segment Tree

```
struct Node {
  int ign = 0, val;
  Node(): val(ign) {};
  Node(int x) : val(x) \{\};
  void set(int x) {
    val = x;
  }
};
#define lNode (x * 2 + 1)
#define rNode (x * 2 + 2)
\#define md (lx + (rx - lx) / 2)
struct Sagara {
  int n;
  vector<Node> node;
  Sagara(int sz) {
    n = 1;
    while (n < sz) n *= 2;
    node.assign(n * 2, Node());
  }
  Node merge(Node &l, Node &r) {
    Node res = Node();
    res.val = l.val + r.val;
    return res;
  }
  void build(vector<int> &v, int x, int lx, int rx) {
    if (rx - lx == 1) {
      if (lx < v.size()) node[x] = Node(v[lx]);
      return;
    }
    build(v, lNode, lx, md);
    build(v, rNode, md, rx);
    node[x] = merge(node[lNode], node[rNode]);
  }
  void build(vector<int> &v) { build(v, 0, 0, n); }
```

```
void set(int &ind, ll &val, int x, int lx, int rx) {
    if (rx - lx == 1) return node[x].set(val);
    if (ind < md) set(ind, val, lNode, lx, md);
    else set(ind, val, rNode, md, rx);
    node[x] = merge(node[lNode], node[rNode]);
  }
  void set(int ind, ll val) { set(ind, val, 0, 0, n); }
  Node query(int &l, int &r, int x, int lx, int rx) {
    if (lx \ge r || rx \le l) return Node();
    if (rx \le r \&\& lx \ge l) return node[x];
    Node L = query(l, r, lNode, lx, md);
    Node R = query(l, r, rNode, md, rx);
    return merge(L, R);
  }
  Node query(int l, int r) {
    return query(l, r, 0, 0, n);
  }
};
```

Lazy Segment Tree

```
struct Node {
  int ign = 0, lazy = 0, val = ign;
  bool isLazy = 0;
  Node() {}
  Node(ll x): val(x) {}
  void add(int x, int lx, int rx) {
    val += x * (rx - lx);
    lazy += x;
    isLazy = 1;
  }
};
#define lNode (x * 2 + 1)
#define rNode (x * 2 + 2)
#define md (lx + (rx - lx) / 2)
struct Sagara {
  int n;
  vector<Node> node;
  Sagara(int sz) {
    n = 1;
    while (n < sz) n *= 2;
    node.assign(n * 2, Node());
  }
  Node merge(Node &I, Node &r) {
    Node res = Node();
    res.val = l.val + r.val;
    return res;
  }
  void propagate(int x, int lx, int rx) {
    if (rx - lx == 1 || !node[x].isLazy) return;
    node[lNode].add(node[x].lazy, lx, md);
    node[rNode].add(node[x].lazy, md, rx);
    node[x].isLazy = node[x].lazy = 0;
  }
```

```
void update(int l, int r, ll val, int x, int lx, int rx) {
    propagate(x, lx, rx);
    if (lx \ge r || rx \le l) return;
    if (lx >= l \&\& rx <= r)
      return node[x].add(val, lx, rx);
    update(l, r, val, lNode, lx, md);
    update(l, r, val, rNode, md, rx);
    node[x] = merge(node[lNode], node[rNode]);
  }
  void update(int l, int r, ll val) { update(l, r, val, 0, 0,
n); }
  Node query(int l, int r, int x, int lx, int rx) {
    propagate(x, lx, rx);
    if (lx >= l \&\& rx <= r) return node[x];
    if (lx \ge r || rx \le l) return Node();
    Node L = query(l, r, lNode, lx, md);
    Node R = query(l, r, rNode, md, rx);
    return merge(L, R);
  }
  Node query(int l, int r) {
    return query(l, r, 0, 0, n);
  }
};
```

Merge Sort Tree

```
struct Node {
  vector<int> v;
  Node() {};
  Node(int x) : v(\{x\}) {};
};
#define lNode (x * 2 + 1)
#define rNode (x * 2 + 2)
\#define md (lx + (rx - lx) / 2)
struct MergeSortSagara {
  vector<Node> node;
  int n;
  MergeSortSagara(int _n) {
    n = 1;
    while (n < _n) n <<= 1;
    node.assign(n * 2, Node());
  }
  Node merge(Node &l, Node &r) {
    Node res;
    int i = 0, j = 0;
    while (i < l.v.size() && j < r.v.size()) {
      if (l.v[i] < r.v[j]) res.v.push_back(l.v[i++]);
      else res.v.push_back(r.v[j++]);
    }
    while (i < l.v.size()) res.v.push_back(l.v[i++]);
    while (j < r.v.size()) res.v.push_back(r.v[j++]);
    return res;
  }
  void build(vector<int> &v, int x, int lx, int rx) {
    if (rx - lx == 1) {
      if (lx < v.size()) node[x] = Node(v[lx]);
      return;
    }
    build(v, lNode, lx, md);
    build(v, rNode, md, rx);
    node[x] = merge(node[lNode], node[rNode]);
  }
  void build(vector<int> &v) { build(v, 0, 0, n); }
```

```
int query(int l, int r, int x, int lx, int rx, int val) {
    if (rx \le l \mid lx \ge r) return 0;
    if (lx \ge l \& rx \le r) return calc(node[x], val);
    return query(l, r, lNode, lx, md, val) + query(l, r,
rNode, md, rx, val);
  }
  int query(int l, int r, int val) {
    return query(l, r, 0, 0, n, val);
  }
  // change this function to match your need
  int calc(Node &no, int val) {
    return greater_than(no, val);
  }
  int less_than(Node &no, int val) {
    return lower_bound(no.v.begin(), no.v.end(), val) -
no.v.begin();
  }
  int greater_than(Node &no, int val) {
    return no.v.size() - less_than(no, val) - equal(no,
val);
  }
  int equal(Node &no, int val) {
    return upper_bound(no.v.begin(), no.v.end(), val)
- lower_bound(no.v.begin(), no.v.end(), val);
 }
};
```

2D Segment Tree

```
struct Node {
  ll ign = 0, val;
  Node(): val(ign) {}
  Node(ll x): val(x) {}
  Node operator+(Node &r) {
    Node res = Node();
    res.val = val + r.val:
    return res;
  }
};
#define lNode (x * 2 + 1)
#define rNode (x * 2 + 2)
\#define md (lx + (rx - lx) / 2)
struct Sagara {
  int n;
  vector<Node> node;
  Sagara(int sz) {
    n = 1;
    while (n < sz) n *= 2;
    node.assign(n * 2, Node());
  }
  void set(int &ind, ll &val, int x, int lx, int rx) {
    if (rx - lx == 1) {
      node[x] = Node(val);
      return;
    }
    if (ind < md) set(ind, val, lNode, lx, md);
    else set(ind, val, rNode, md, rx);
    node[x] = node[lNode] + node[rNode];
  }
  void set(int ind, ll val) {set(ind, val, 0, 0, n);}
  Node get(int &i) {return node[n + i - 1];}
  Node query(int &l, int &r, int x, int lx, int rx) {
    if (lx \ge r \mid | rx \le l) return Node();
    if (rx \le r \&\& lx \ge l) return node[x];
    Node L = query(l, r, lNode, lx, md);
    Node R = query(l, r, rNode, md, rx);
    return L + R;
```

```
}
  Node query(int l, int r) {
    return query(l, r, 0, 0, n);
  }
};
struct Sagara2D {
  vector<Sagara> node;
  int n;
  Sagara2D(int _n, int _m) {
    n = 1;
    while (n < _n) n <<= 1;
    node.assign(n * 2, Sagara(_m));
  }
  void set(int i, int j, int val, int x, int lx, int rx) {
    if (rx - lx == 1)
       return node[x].set(j, val);
    if (i < md) set(i, j, val, lNode, lx, md);
    else set(i, j, val, rNode, md, rx);
    Node L = node[lNode].get(j);
    Node R = node[rNode].get(j);
    node[x].set(j, (L + R).val);
  }
  void set(int i, int j, int val) {
    set(i, j, val, 0, 0, n);
  }
  // r and b are not included
  int query(int t, int b, int l, int r, int x, int lx, int rx) {
    if (rx \le t \mid\mid lx \ge b) return 0;
    if (lx >= t \&\& rx <= b)
       return node[x].query(l, r).val;
    int L = query(t, b, l, r, lNode, lx, md);
    int R = query(t, b, l, r, rNode, md, rx);
    return L + R;
  // top, bottom, right, left
  int query(int t, int b, int r, int l) {
    return query(t, b, r, l, 0, 0, n);
  }
};
```

> PST

```
struct PST {
  // root[query_index] returns the root of the version
of this query
 // L[x], R[x] are the id's of x left and right child
 vector<int> node, L, R, root;
  int n, curr;
  const int ign = 0; // change this accordigly
  PST(int _n, int q) {
    const int LOG = 30;
    n = _n;
    root.reserve(q + 10);
    L.resize(n * LOG);
    R.resize(n * LOG);
    node.resize(n * LOG);
    curr = 0;
 }
  int merge(int lf, int ri) {
    return lf + ri;
 }
  int init(int lx, int rx) {
    int id = curr++;
    if (rx - lx < 2) {
      node[id] = ign;
      return id;
    }
    int md = (lx + rx) / 2;
    L[id] = init(lx, md);
    R[id] = init(md, rx);
    node[id] = merge(node[L[id]], node[R[id]]);
    return id;
 }
 void init() {
    root.push_back(init(0, n));
  }
```

```
int set(int ind, int val, int x, int lx, int rx) {
    if (ind \geq rx || ind \leq lx) return x;
    int id = curr++;
    if (rx - lx < 2) {
      node[id] = val;
      return id;
    }
    int md = (rx + lx) / 2;
    L[id] = set(ind, val, L[x], lx, md);
    R[id] = set(ind, val, R[x], md, rx);
    node[id] = merge(node[L[id]], node[R[id]]);
    return id;
  }
  void set(int ind, int val, int version = -1) {
    if (~version)
       root.push_back(set(ind, val, root[version], 0,
n));
    else
       root.push_back(set(ind, val, root.back(), 0, n));
// work on the latest version
  }
  int query(int l, int r, int x, int lx, int rx) {
    if (rx \le l \mid | lx \ge r) return ign;
    if (rx \le r \&\& lx \ge l) return node[x];
    int md = (lx + rx) / 2;
    return merge(query(l, r, L[x], lx, md), query(l, r,
R[x], md, rx);
  }
  int query(int l, int r, int version = -1) {
    if (~version)
      return query(l, r, root[version], 0, n);
       return query(l, r, root.back(), 0, n);
  }
};
```

Segment Tree Functions

```
// seg tree with hash remember to multiply with inv[I]
in the query
// to get prev go to the right before the left
int next_greater(int l, int r, int val, int x, int lx, int rx) {
  if (lx \ge r \text{ or } l \ge rx) \text{ return -1};
  if (node[x].mx <= val) return -1;
  if (rx - lx == 1) return lx;
  int ans = next_greater(l, r, val, lNode, lx, md);
  if (ans == -1)
    return next_greater(l, r, val, rNode, md, rx);
  return ans;
}
int next_smaller(int l, int r, int val, int x, int lx, int rx) {
  if (lx \ge r \text{ or } l \ge rx) \text{ return -1};
  if (node[x].mn >= val) return -1;
  if (rx - lx == 1) return lx;
  int ans = next_smaller(l, r, val, lNode, lx, md);
  if (ans == -1)
    return next_smaller(l, r, val, rNode, md, rx);
  return ans;
}
int kth_one(int k, int x, int lx, int rx) {
  if (rx - lx == 1)
    return lx;
  if (k < node[lNode].sum)
    return find_kth_one(k, lNode, lx, md);
  return find_kth_one(k - node[lNode].sum, rNode,
md, rx);
}
int kth_one(int k) {
  if(node[0].sum < k) return -1;
  return kth_one(k, 0, 0, n);
}
```

```
// max subarray sum
Node merge(Node &l, Node &r) {
   Node res = Node();
   res.ans = max({l.ans, r.ans, l.suff + r.pre});
   res.pre = max(l.pre, l.sum + r.pre);
   res.suff = max(r.suff, r.sum + l.suff);
   res.sum = r.sum + l.sum;
   return res;
}
```

Iterative Segment Tree

```
const int N = 2e5 + 1; // limit for array size
int t[2 * N];
int m; // array size
void build(vector<int> &v) { // build the tree
  for (int i = 0; i < m; ++i) t[i + m] = v[i];
  for (int i = m - 1; i > 0; --i)
    t[i] = t[i << 1] + t[i << 1 | 1];
}
void modify(int p, int value) {
  for (t[p += m] = value; p > 1; p >>= 1)
    t[p >> 1] = t[p] + t[p ^ 1];
}
int query(int l, int r) { // sum on interval [l, r)
  int res = 0;
  for (l += m, r += m; l < r; l >>= 1, r >>= 1)
    if (l \% 2) res += t[l++];
    if (r \% 2) res += t[--r];
  return res;
}
```

> Sparse Table

```
template<class T>
struct SparseTable {
  // change mxLog
  static const int mxLog = 21;
  vector<array<T, mxLog>> table;
  vector<int> lg;
  int n;
  SparseTable(int sz) {
    n = sz;
    table.resize(n + 1);
    \lg.resize(n + 1);
    for (int i = 0; i <= n; ++i) lg[i] = _lg(i);
  }
  void build(vector<T> &v) {
    for (int i = 0; i < n; ++i) table[i][0] = v[i];
    for (int j = 1; j < mxLog; ++j)
      for (int i = 0; i + (1 << j) - 1 < n; ++i)
        table[i][j] = merge(table[i][j - 1], table[i + (1 <<
(j - 1))[j - 1];
  }
  T merge(T &l, T &r) { return min(l, r); }
  T query(int l, int r) {
    int j = \lg[r - l + 1];
    return merge(table[l][j], table[r - (1 << j) + 1][j]);
  }
};
```

➢ BIT

```
struct FenwickTree {
  vector<ll> bit;
  int n;
  void updateBit(int ind, ll val) {
    for (; ind < n; ind = ind | (ind + 1))
       bit[ind] += val;
  }
  FenwickTree(int _n) {
    n = _n + 1;
    bit.assign(n, 0);
  }
  void updateRange(int l, int r, ll val) {
    updateBit(l, val);
    updateBit(r + 1, -val);
  }
  ll query(int r) {
    ll ret = 0;
    for (; r \ge 0; r = (r \& (r + 1)) - 1)
      ret += bit[r];
    return ret;
  }
  ll prefix(int l, int r) { return query(r) - query(l - 1); }
};
```

Ordered Set

```
#include<ext/pb_ds/assoc_container.hpp>
#include<ext/pb_ds/tree_policy.hpp>

using namespace __gnu_pbds;

template<typename T>
    using ordered_set = tree<T, null_type, less<T>, rb_tree_tag, tree_order_statistics_node_update>;

void myErase(ordered_set<int> &t, int v) {
    int rank = t.order_of_key(v);
    ordered_set<int>::iterator it = t.find_by_order(rank);
    t.erase(it);
}
```

➤ Convex Hull

```
struct Line {
  mutable ll k, m, p;
  bool operator<(const Line &o) const { return k < o.k;
}
  bool operator < (ll x) const \{ return p < x; \}
};
struct HullDynamic: multiset<Line, less<>> {
  // (for doubles, use inf = 1/.0, div(a,b) = a/b)
  const ll inf = 2e18;
  ll div(ll a, ll b) { // floored division
    return a / b - ((a ^ b) < 0 && a % b);
 }
  bool isect(iterator x, iterator y) {
    if (y == end()) {
      x - p = inf;
      return false;
    if (x->k == y->k) x->p = x->m > y->m ? inf : -inf;
    else x->p = div(y->m - x->m, x->k - y->k);
    return x->p>=y->p;
  }
```

```
void add(ll k, ll m) { // k is the slope
    auto z = insert({k, m, 0}), y = z++, x = y;
    while (isect(y, z)) z = erase(z);
    if (x != begin() && isect(--x, y)) isect(x, y =
    erase(y));
    while ((y = x) != begin() && (--x)->p >= y->p)
        isect(x, erase(y));
}

ll query(ll x) {
    assert(!empty());
    auto l = *lower_bound(x);
    return l.k * x + l.m;
}
};
```

Matrix

```
template<class T>
struct Matrix {
  int n, m;
  vector<vector<T>> a;
  Matrix(int _n, int _m) {
    n = _n, m = _m;
    a.assign(n, vector<T>(m));
  }
  Matrix operator*(const Matrix &b) {
    int r = n, c = b.m, k = m;
    Matrix res(r, c);
    for (int i = 0; i < r; ++i)
      for (int j = 0; j < c; ++j)
        for (int o = 0; o < k; ++o)
          res.a[i][j] = add(res.a[i][j], mul(a[i][o],
b.a[o][j], MOD), MOD);
    return res;
 }
  friend Matrix power(Matrix mat, ll p) {
    Matrix ret(mat.n, mat.n);
    for (int i = 0; i < mat.n; ++i)
      ret.a[i][i] = 1;
    while (p) {
      if (p & 1) ret = ret * mat;
      mat = mat * mat, p >>= 1;
    }
    return ret;
  }
};
```

➤ BIT 2D

```
// this supports update rect and get a single cell
struct BIT2D {
  int n, m;
  vector<vector<int>> bit;
  BIT2D(int _n, int _m) {
    n = _n + 5, m = _m + 5;
    bit.assign(n, vector<int>(m));
  }
  void updateY(int x, int ind, ll val) {
    for (; ind < m; ind |= (ind + 1))
       bit[x][ind] += val;
  }
  void update(int x, int y, int val) {
    for (; x < n; x | = (x + 1))
       updateY(x, y, val);
  }
  // pass it left, right, top, bottom, value
  void updateRect(int l, int r, int t, int b, ll val) {
    update(t, l, val);
    update(t, r + 1, -val);
    update(b + 1, l, -val);
    update(b + 1, r + 1, val);
  }
  int getY(int x, int ind) {
    int v = 0;
    for (; ind \geq 0; ind = (ind & (ind + 1)) - 1)
      v += bit[x][ind];
    return v;
  }
  int get(int x, int y) {
    int v = 0;
    for (; x \ge 0; x = (x & (x + 1)) - 1)
      v += getY(x, y);
    return v;
  }
};
```

> MO Algorithm

```
struct Query {
  int l, r, ind;
};
struct MO {
  int n, sq, l, r;
  ll curr;
  vector<int>v;
  MO(vector<int> &_v) {
    V = V;
    n = v.size();
    sq = sqrt(n) + 1;
    curr = 0;
  };
  void add(int i) {}
  void del(int i) {}
  void move(int &lq, int &rq) {
    while (r < rq) add(++r);
    while (l < lq) del(l++);
    while (l > lq) add(--l);
    while (r > rq) del(r--);
  }
  void solve(vector<Query> &qu) {
    sort(qu.begin(), qu.end(), [&](auto &lf, auto ri) {
      if (lf.l / sq == ri.l / sq)
        return lf.r < ri.r;
      return lf.l/sq < ri.l/sq;
    });
    l = qu[0].l, r = qu[0].l;
    add(l);
    vector<int> res(qu.size());
    for (auto &[lq, rq, iq]: qu) {
      move(lq, rq);
      res[iq] = curr;
    }
    for (int &i: res) cout << i << endl;
  }
};
```

> MO with Updates

```
const int N = 2e5 + 5, SQ = 3500;
struct query {
  int l, r, idx, uldx;
  bool operator<(const query &other) const {
    if (l/SQ != other.l/SQ)
      return l / SQ < other.l / SQ;
    if (r / SQ != other.r / SQ)
      return r / SQ < other.r / SQ;
    return uldx < other.uldx;
  }
};
struct update {
  int idx, val, old;
};
int a[N], ans[N], frq[N], cnt[N];
void add(int idx) {}
void remove(int idx) {}
void upd(update &u, int l, int r) {
  if (u.idx \ge l \& u.idx \le r)remove(u.idx);
  a[u.idx] = u.val;
  if (u.idx \ge l \&\& u.idx \le r)add(u.idx);
}
void cancel(update &u, int l, int r) {
  if (u.idx \ge l \& u.idx \le r)remove(u.idx);
  a[u.idx] = u.old;
  if (u.idx \ge l \& u.idx \le r)add(u.idx);
}
void mo(vector<query> &v, vector<update> &u) {
  int l = 0, r = -1;
  int cur = 0;
  for (auto &q: v) {
    while (cur < q.uldx)upd(u[cur++], l, r);
    while (cur > q.uldx)cancel(u[--cur], l, r);
    while (r < q.r)add(++r);
    while (l > q.l)add(--l);
    while (r > q.r) remove(r--);
    while (l < q.l)remove(l++);
    while (cnt[ans[q.idx]])ans[q.idx]++;
  }
}
```

Bitmasks

```
int count_numbers_has_ith_bit(int n, int k) {
  ++n;
  int d = (1LL << (k + 1)), p = (1LL << k);
  return n / d * p + max(0LL, n % d - p);
}
int highest_bit(int x) {
  int t = 63 - __builtin_clzll(x);
  return (1LL << t);
}
int lowest_bit(int x) {
  int t = __builtin_ctzll(x);
  return (1LL << t);
}
// loop through submasks
for (int j = mask; j; j = (j - 1) \& mask) {
}
int xor_range(int n) { // from 1 to n
  if (n \% 4 == 0) return n;
  if (n % 4 == 1) return 1;
  if (n \% 4 == 2) return n + 1;
  return 0;
}
int odd_xor(int n) {
  if (n \% 2 == 0)
    return ((xor_range(n)) ^ (2LL * xor_range(n / 2LL)));
  else
    return ((xor_range(n)) ^ (2LL * xor_range((n - 1LL) /
2LL)));
}
int odd_xor_range(int l, int r) {
  return odd_xor(l - 1) ^ odd_xor(r);
}
int even_xor_range(int l, int r) {
  int xor_r = 2LL * xor_range(r / 2LL);
  int xor_l = 2LL * xor_range((l - 1LL) / 2LL);
  return (xor_l ^ xor_r);
}
```

> XOR of all subarrays

```
int calcSubArrayXORSum(vector<int> &arr) {
  int n = arr.size();
  int sum = 0;
  int multiplier = 1;
  for (int i = 0; i < 30; i++) {
    int oddCount = 0;
    bool isOdd = 0;
    for (int j = 0; j < n; j++) {
      if ((arr[i] & (1 << i)) > 0)
        isOdd = (!isOdd);
      if (isOdd)
        oddCount++;
    }
    for (int j = 0; j < n; j++) {
      sum += (multiplier * oddCount);
      if ((arr[j] & (1 << i)) > 0)
        oddCount = (n - j - oddCount);
    }
    multiplier *= 2;
  }
  return sum;
}
```

> SOS DP

```
const int B = 20;
const int M = 1 \ll B;
// subset contribute to its superset
void forward(vector<int> &dp) {
  for (int i = 0; i < B; ++i)
    for (int m = 0; m < M; ++m)
      if (m & (1 << i))
        dp[m] += dp[m ^ (1 << i)];
}
// superset contribute to its subset
void forwardRev(vector<int> &dp) {
  for (int i = 0; i < B; ++i)
    for (int m = M - 1; \sim m; --m)
      if (m \& (1 << i))
        dp[m ^ (1 << i)] += dp[m];
}
// remove subset contribution from superset
void backward(vector<int> &dp) {
  for (int i = 0; i < B; ++i)
    for (int m = M - 1; \sim m; --m)
      if (m & (1 << i))
        dp[m] = dp[m ^ (1 << i)];
}
// remove superset contribution from subset
void backwardRev(vector<int> &dp) {
  for (int i = 0; i < B; ++i)
    for (int m = 0; m < M; ++m)
      if (m \& (1 << i))
        dp[m ^ (1 << i)] -= dp[m];
}
```

XOR of all subarrays multiplied by length

```
int calcSubArrayXORSum(vector<int> arr) {
  int n = arr.size();
  int sum = 0;
  int multiplier = 1;
  for (int i = 0; i < 30; i++) {
    int oddCount = 0;
    bool isOdd = 0;
    int tot = 0;
    for (int j = 0; j < n; j++) {
      if ((arr[j] & (1 << i)) > 0)
        isOdd = (!isOdd);
      if (isOdd) {
        oddCount++;
        tot += j + 1;
      }
    }
    for (int j = 0; j < n; j++) {
      sum += ((multiplier % mod) * (tot % mod)) %
mod;
      sum %= mod;
      if ((arr[i] & (1 << i)) > 0) {
        oddCount = (n - j - oddCount);
        tot = (n - j) * (n - j + 1) / 2 - tot;
        tot -= oddCount;
      } else
        tot -= oddCount;
    multiplier *= 2;
  return sum;
}
```

Suffix Array

```
struct SuffixArray {
  int n;
  vector<int> suff, lcp, c;
  SuffixArray(int sz) {
    n = sz + 1;
    suff.resize(n);
    lcp.resize(n);
    c.resize(n);
  }
  void countingSort(vector<int> &p) {
    vector<int> cnt(n), pos(n), newP(n);
    for (int i: c)
      cnt[i]++;
    for (int i = 1; i < n; ++i)
      pos[i] = pos[i - 1] + cnt[i - 1];
    for (int i: p)
      newP[pos[c[i]]++] = i;
    swap(p, newP);
  }
  void build(string &s) {
    s += '$';
    vector<pair<char, int>> a(n);
    for (int i = 0; i < n; ++i)
      a[i] = {s[i], i};
    sort(a.begin(), a.end());
    vector<int> p(n);
    for (int i = 0; i < n; ++i)
      p[i] = a[i].second;
    for (int i = 1; i < n; ++i)
      c[a[i].second] = c[a[i - 1].second] + (a[i].first !=
a[i - 1].first);
```

```
int k = 0;
    while ((1 << k) < n) {
      int bit = 1 << k;
      for (int i = 0; i < n; ++i)
         p[i] = (p[i] - bit + n) \% n;
       countingSort(p);
      vector<int> newC(n);
      for (int i = 1; i < n; ++i) {
         int currL = p[i], currR = (p[i] + bit) \% n;
         int preL = p[i - 1], preR = (p[i - 1] + bit) \% n;
         bool add = (c[currL] != c[preL]) || (c[currR] !=
c[preR]);
         newC[p[i]] = newC[p[i-1]] + add;
      }
      c = newC;
       ++k;
    }
    suff = p;
    // Build LCP
    k = 0:
    for (int i = 0; i < n - 1; ++i) {
      int pi = c[i];
      int j = p[pi - 1];
      while (s[i + k] == s[j + k])
         ++k;
      lcp[pi] = k;
      k = max(int(0), k - 1);
    }
  }
};
```

Hashing

```
mt19937
rng(chrono::steady_clock::now().time_since_epoch()
#define getrand(l, r) uniform_int_distribution<long
long>(l, r)(rng)
struct Hash {
 // everything is zero indexed
  int mod, base, st, N;
  vector<int> pw, inv;
 // st is the start char, _N is the max size of the string
  Hash(int _st = 'a', int _N = 1e6) {
    st = _st - 1;
    N = N + 1;
    pw.resize(N);
    inv.resize(N);
    gen();
    pre();
 }
 void gen() {
    auto check = [](int x) {
      for (int i = 2; i * i <= x; ++i)
        if (!(x % i)) return false;
      return true;
    };
    mod = getrand(1e8, 2e9);
    base = getrand(30, 120);
    while (!check(mod))--mod;
 }
  void pre() {
    int inv_pw = inverse(base, mod);
    pw[0] = inv[0] = 1;
   for (int i = 1; i < N; ++i) {
      pw[i] = mul(pw[i - 1], base, mod);
      inv[i] = mul(inv[i - 1], inv_pw, mod);
   }
  }
  int push_back(int h, char a, int len) {
    return add(h, mul(a - st, pw[len], mod), mod);
 }
  int push_front(int h, char a) {
    return add(a - st, mul(h, base, mod), mod);
 }
```

```
int concat(int l, int r, int szLeft) {
    return add(l, mul(r, pw[szLeft], mod), mod);
  }
  vector<int> build(string &s) {
    int sz = s.size();
    vector<int> res(sz);
    res[0] = s[0] - st;
    for (int i = 1; i < sz; ++i)
      res[i] = push_back(res[i - 1], s[i], i);
    return res;
  }
  // [l, r] l & r are included
  int getSubstring(int l, int r, vector<int> &hash) {
    int res = hash[r];
    if (l) res = add(res, -hash[l - 1], mod);
    return mul(res, inv[l], mod);
  }
  bool is_palindrome(int l, int r, vector<int> &hsh,
vector<int> &hshRev) {
    int rev_l = hsh.size() - r - 1;
    int rev_r = hsh.size() - l - 1;
    return getSubstring(l, r, hsh) ==
getSubstring(rev_l, rev_r, hshRev);
 }
  // get Hash of path on tree
  void dfs(int u, int p, int l = 0) {
    hsh[u] = h.push_back(hsh[p], c[u], l);
    hshRev[u] = h.push_front(hshRev[p], c[u]);
    v[u] = l;
    par[u] = p;
    for (int &v: adj[u])
      if (v != p) dfs(v, u, l + 1);
  }
  int getTreePath(int u, int v, int lc) {
    int u_lc = add(hshRev[u], -mul(hshRev[lc],
pw[lvl[u] - lvl[lc]], mod), mod);
    int lc_v = add(hsh[v], -hsh[par[lc]], mod);
    lc_v = mul(lc_v, inv[lvl[lc]], mod);
    return concat(u_lc, lc_v, lvl[u] - lvl[lc]);
 };
};
```

Trie & Aho-Corasick

```
// mx char
const int MX = 26;
struct Trie {
  struct Node {
    array<int, MX> nxt;
    vector<int> pat;
    int f = 0;
    Node() { nxt.fill(-1); }
  };
  vector<Node> node;
  int start = 'a';
  Trie() {
    node.resize(1);
  }
  void add(string &s, int &i) {
    int v = 0;
    for (char ch: s) {
      int c = ch - start;
      if (node[v].nxt[c] == -1) {
        node[v].nxt[c] = node.size();
        node.emplace_back();
      }
      v = node[v].nxt[c];
    }
    node[v].pat.push_back(i);
  }
};
```

```
struct AhoCorasick: public Trie {
  AhoCorasick(vector<string> &pat) {
    for (int i = 0; i < pat.size(); ++i)
      add(pat[i], i);
    build();
  }
  int move(int &curr, int &c) {
    int f = node[curr].f;
    while (node[f].nxt[c] == -1 \&\& f) f = node[f].f;
    return node[f].nxt[c] == -1 ? 0 : node[f].nxt[c];
  }
  void build() {
    queue<int>q;
    for (int i = 0; i < MX; i++) {
      if (~node[0].nxt[i])
        q.push(node[0].nxt[i]);
    }
    while (!q.empty()) {
      int curr = q.front();
      q.pop();
      for (int i = 0; i < MX; i++) {
        int nxt = node[curr].nxt[i];
        if (nxt == -1) continue;
        int f = move(curr, i);
        node[nxt].f = f;
        for (auto &j: node[f].pat)
          node[nxt].pat.push_back(j);
        q.push(nxt);
      }
    }
 }
};
```

Manacher

```
struct manacher {
  string s;
  vector<int>p;
  manacher(string &in) {
    s = manacher_string(in);
    int n = s.size();
    p.assign(n, 0);
    for (int i = 0, l = 0, r = -1, k; i < n; ++i) {
      if (i > r)
         k = 1;
       else
         k = min(p[l + (r - i)], r - i) + 1;
      while (i - k \ge 0 \&\& i + k < n \&\& s[i - k] == s[i + k])
         ++k;
      if (i - k == -1 || i + k == n || s[i - k] != s[i + k])
         --k;
       p[i] = k;
      if (i + k > r)
        l = i - k, r = i + k;
    }
  }
  string manacher_string(string &in) {
    int n = in.size();
    string t(2 * n + 1, '#');
    for (int i = 1, j = 0; i < 2 * n + 1; i += 2, ++j)
      t[i] = in[j];
    return t;
  }
  bool is_palindrome(int l, int r) {
    int L = 2 * l + 1;
    int R = 2 * r + 1;
    int mid = (L + R) / 2;
    return p[mid] >= mid - L;
  }
```

> Z Algorithm

```
vector<int> get_z_table(string &txt) {
  int n = int(txt.size());
  int l = 0, r = 0, k;
  vector<int> z table(n);
  for (int i = 1; i < n; ++i) {
    if (i > r) {
       l = r = i;
       while (r < n \text{ and } txt[r - l] == txt[r]) {
      }
       z_{table[i]} = r - l, --r;
    } else {
       k = i - l;
       if (z_{table}[k] < r - i + 1) {
         z_table[i] = z_table[k];
      } else {
         l = i:
         while (r < n \text{ and } txt[r - l] == txt[r]) {
           ++r;
         z_table[i] = r - l, r--;
      }
    }
  }
  return z_table;
}
vector<int> z_table(string &txt, string &pat) {
  string concat = pat + "|" + txt;
  int l = int(concat.size());
  vector<int> Z = get_z_table(concat);
  int d = int(pat.size()) + 1;
  vector<int> z_table(int(txt.size()));
  for (int i = d; i < l; ++i)
    z_{table[i - d] = Z[i];
  z_table.front() = 0;
  return z_table;
}
```

≻ KMP

```
vector<int> buildPI(string &pat) {
  int m = pat.size();
  vector<int> pi(m);
  for (int i = 1, c = 0; i < m; i++) {
    while (c > 0 \&\& pat[c] != pat[i])
      c = pi[c - 1];
    if (pat[c] == pat[i]) pi[i] = ++c;
    else pi[i] = c;
  }
  return pi;
}
void KMP(string &s, string &pat, vector<int> &id) {
  int n = s.size(), m = pat.size();
  vector<int> pi = buildPI(pat);
  for (int i = 0, c = 0; i < n; i++) {
    while (c > 0 \&\& pat[c] != s[i])
      c = pi[c - 1];
    if (pat[c] == s[i])
      C++;
    if (c == m) {
      id.push_back(i - m + 1);
      c = pi[c - 1];
    }
 }
}
```

> Arithmetic Progression

```
pair<vector<int>, vector<int>> build(vector<int> &v) {
   int n = v.size();
   vector<int> suff(n + 2), s(n + 2);
   for (int i = n - 1; i >= 0; --i) {
      suff[i] = suff[i + 1] + v[i];
      s[i] = s[i + 1] + suff[i];
   }
   return {suff, s};
}

int get(int l, int r, vector<int> &suff, vector<int> &s) {
   int res = s[l] - s[r + 1];
   res -= (r - l + 1) * suff[r + 1];
   return res;
}
```

Merge Segments

```
void merge(vector<pair<int, int>> &vc) {
  sort(vc.begin(), vc.end());
  vector<int> start, end;
  int st = vc[0].first, en = vc[0].second;
  for (int i = 1; i < vc.size(); i++) {
    if (vc[i].first <= en) en = max(en, vc[i].second);
    else {
      start.push_back(st);
      end.push_back(en);
      st = vc[i].first;
      en = vc[i].second;
    }
  }
  start.push_back(st);
  end.push_back(en);
}
```

Number of mod in range

```
// count number of y such that y%n = x (0 -> l)
int f(int l, int n, int x) {
  int cnt = (l / n) + (l % n >= x);
  return cnt;
}
```

Kadane on Matrix

```
int kadane(vector<int> &v) {
  int s = 0, mx = -00;
  for (int &i: v) {
    s += i;
    mx = max(s, mx);
    s = max(0ll, s);
  }
  return mx;
}
int maxSubmatrixSum(vector<vector<int>> &A) {
  int r = A.size();
  int c = A[0].size();
  int **pre = new int *[r];
  for (int i = 0; i < r; i++) {
    pre[i] = new int;
    for (int j = 0; j < c; j++)
       pre[i][j] = 0;
  }
  for (int i = 0; i < r; i++) {
    for (int j = 0; j < c; j++) {
       pre[i][j] = A[i][j];
      if (i)
         pre[i][j] += pre[i][j - 1];
    }
  }
  int maxSum = -oo;
  for (int i = 0; i < c; i++) {
    for (int j = i; j < c; j++) {
      vector<int> v;
      for (int k = 0; k < r; k++) {
         int el = pre[k][j];
         if (i) el -= pre[k][i - 1];
         v.push_back(el);
      }
      maxSum = max(maxSum, kadane(v));
    }
  }
  return maxSum;
}
```

2D Prefix Sum

```
// g is one indexed!!!
vector<vector<int>> g(n+1, vector<int>(m+1));

for(int i = 1; i <= n; i++)
    for(int j = 1; j <= m; j++)
        g[i][j] = g[i][j-1] + mat[i-1][j-1];

for(int j = 1; j <= m; j++)
    for(int i = 1; i <= n; i++)
        g[i][j] += g[i-1][j];

while(q--) {
    int a, b, c, d; cin >> a >> b >> c >> d;
    cout << g[c][d] + g[a - 1][b - 1] - g[a - 1][d] - g[c][b - 1]
<< endl;
}</pre>
```

Montonic Stack

```
vector<int> nextGreater(vector<int> &v) {
  int n = v.size();
  vector<int> res(n, n);
  stack<int> st;
  for (int i = 0; i < n; ++i) {
    if (st.empty() || v[i] \le v[st.top()]) st.push(i);
    else {
      res[st.top()] = i;
      st.pop(), --i;
    }
  }
  return res;
vector<int> prevGreater(vector<int> &v) {
  int n = v.size();
  vector<int> res(n, -1);
  stack<int> st;
  for (int i = n - 1; i \ge 0; --i) {
    // you may need to remove the equal
    if (st.empty() || v[i] \le v[st.top()]) st.push(i);
    else {
      res[st.top()] = i;
      st.pop(), ++i;
    }
  }
  return res;
```

> STL Compare

```
struct compare {
  // right is the top -> pq
  // left is the begin -> set, map
  // return false if equal
  bool operator()(# a, # b) const {
  }
};
```

Minimum Swaps

```
int cost(vector<int>& from, vector<int>& to) {
    int n = int(from.size());

    vector<int, int> mp;
    ordered_set<int> st;
    for (int i = 0; i < n; ++i) {
        st.insert(i);
        mp[from[i]] = i;
    }

    int ret = 0;
    for (int i = 0; i < n; ++i) {
        ret += st.order_of_key(mp[to[i]]);
        st.erase(mp[to[i]]);
    }

    return ret;
}</pre>
```

Mod Operations & Comb

```
// make sure a & b < mod
int add(int a, int b, int mod) {
  ll res = (ll) a + b;
  if (res >= mod) res -= mod;
  if (res < 0) res += mod;
  return res;
}
int mul(int a, int b, int mod) {
  return (1LL * a * b) % mod;
}
int power(int a, int b, int mod) {
  int ret = 1;
  while (b) {
    if (b & 1) ret = 1ll * ret * a % mod;
    a = 111 * a * a % mod, b >>= 1;
  }
  return ret;
}
int inverse(int b, int mod) {
  return power(b, mod - 2, mod);
}
struct Comb {
  vector<int> fact; // pre process fact inv too :)
  Comb(int n) {
    fact.assign(n + 5, 1);
    for (int i = 1; i \le n; ++i) fact[i] = mul(i, fact[i - 1]);
  }
  int nPr(int n, int r) {
    return n < r? 0: mul(fact[n], inverse(fact[n - r]));
  }
  int nCr(int n, int r) {
    return mul(nPr(n, r), inverse(fact[r]));
 }
};
```

Linear Sieve

```
// pr is all the primes, low[x] is the lowest prime of x
vector<int> pr, low;
void Sieve(int n) {
  low.assign(n + 1, 0);
  for (int i = 2; i \le n; ++i) {
    if (!low[i]) {
      low[i] = i;
       pr.push_back(i);
    }
    for (int &j: pr) {
      if (j > low[i] || i * j > n) break;
      low[j * i] = j;
    }
  }
}
```

Segmented Sieve

```
vector<bool> segmentedSieve(int L, int R) {
  // generate all primes up to sqrt(R)
  int lim = sqrtl(R);
  vector<bool> mark(lim + 1, false);
  vector<int> primes;
  for (int i = 2; i \le \lim_{i \to \infty} ++i) {
    if (!mark[i]) {
       primes.emplace_back(i);
      for (int j = i * i; j <= lim; j += i)
         mark[j] = true;
    }
  vector<bool> isPrime(R - L + 1, true);
  for (int i: primes)
    for (int j = max(i * i, (L + i - 1) / i * i); j <= R; j += i)
      isPrime[j - L] = false;
  if (L == 1)
    isPrime[0] = false;
  return isPrime;
}
```

Count Divisors up to 1e18

```
N = input()
primes = array containing primes till 10^6
ans = 1
for all p in primes :
            if p*p*p > N:
                  break
            count = 1
            while N divisible by p:
                  N = N/p
                  count = count + 1
            ans = ans * count
if N is prime:
            ans = ans * 2
else if N is square of a prime:
            ans = ans * 3
else if N != 1:
            ans = ans * 4
```

> Int128

```
__int128 read() {
  _int128 x = 0, f = 1;
  char ch = getchar();
  while (ch < '0' || ch > '9') {
    if (ch == '-') f = -1;
    ch = getchar();
  }
  while (ch \geq= '0' && ch \leq= '9') {
    x = x * 10 + ch - '0';
    ch = getchar();
  }
  return x * f;
}
void print(__int128 x) {
  if (x < 0) {
    putchar('-');
    \chi = -\chi;
  }
  if (x > 9) print(x / 10);
  putchar(x % 10 + '0');
}
```

Prime Tester

```
typedef unsigned long long ull;
ull modmul(ull a, ull b, ull M) {
  ll ret = a * b - M * ull(1.L / M * a * b);
  return ret + M * (ret < 0) - M * (ret >= (ll)M);
ull modpow(ull b, ull e, ull mod) {
  ull ans = 1;
  for (; e; b = modmul(b, b, mod), e \neq 2)
    if (e & 1) ans = modmul(ans, b, mod);
  return ans;
}
bool isPrime(ull n) {
  if (n < 2 || n \% 6 \% 4 != 1) return (n | 1) == 3;
  ull A[] = \{2, 325, 9375, 28178, 450775, 9780504,
1795265022},
      s = _builtin_ctzll(n-1), d = n >> s;
  for (ull a : A) {
    ull p = modpow(a\%n, d, n), i = s;
    while (p!= 1 && p!= n - 1 && a % n && i--)
      p = modmul(p, p, n);
    if (p != n-1 \&\& i != s) return 0;
  }
  return 1;
}
```

> Sieve up to 1e9

```
vector<int> sieve(const int N, const int Q = 17, const
int L = 1 << 15) {
  static const int rs[] = \{1, 7, 11, 13, 17, 19, 23, 29\};
  struct P {
    P(int p) : p(p) {}
    int p;
    int pos[8];
  };
  auto approx_prime_count = [](const int N) -> int {
    return N > 60184? N / (log(N) - 1.1)
             : max(1., N / (log(N) - 1.11)) + 1;
  };
  const int v = sqrt(N), vv = sqrt(v);
  vector<bool> isp(v + 1, true);
  for (int i = 2; i \le vv; ++i)
    if (isp[i]) {
      for (int j = i * i; j <= v; j += i) isp[j] = false;
    }
  const int rsize = approx_prime_count(N + 30);
  vector<int> primes = {2, 3, 5};
  int psize = 3;
  primes.resize(rsize);
  vector<P> sprimes;
  size_t pbeg = 0;
  int prod = 1;
  for (int p = 7; p \le v; ++p) {
    if (!isp[p]) continue;
    if (p \le Q) prod *= p, ++pbeg, primes[psize++] = p;
    auto pp = P(p);
    for (int t = 0; t < 8; ++t) {
      int j = (p \le Q) ? p : p * p;
      while (j % 30 != rs[t]) j += p << 1;
      pp.pos[t] = j / 30;
    }
    sprimes.push_back(pp);
  }
  vector<unsigned char> pre(prod, 0xFF);
  for (size_t pi = 0; pi < pbeg; ++pi) {
    auto pp = sprimes[pi];
    const int p = pp.p;
    for (int t = 0; t < 8; ++t) {
      const unsigned char m = \sim (1 << t);
      for (int i = pp.pos[t]; i < prod; i += p) pre[i] &= m;
    }
  }
  const int block_size = (L + prod - 1) / prod * prod;
```

```
vector<unsigned char> block(block_size);
  unsigned char *pblock = block.data();
  const int M = (N + 29) / 30;
  for (int beg = 0; beg < M; beg += block_size, pblock -
= block size) {
    int end = min(M, beg + block_size);
    for (int i = beg; i < end; i += prod)
      copy(pre.begin(), pre.end(), pblock + i);
    if (beg == 0) pblock[0] &= 0xFE;
    for (size_t pi = pbeg; pi < sprimes.size(); ++pi) {
      auto &pp = sprimes[pi];
      const int p = pp.p;
      for (int t = 0; t < 8; ++t) {
        int i = pp.pos[t];
        const unsigned char m = \sim (1 << t);
        for (; i < end; i += p) pblock[i] &= m;
        pp.pos[t] = i;
      }
    }
    for (int i = beg; i < end; ++i)
      for (int m = pblock[i]; m > 0; m \&= m - 1)
        primes[psize++] = i * 30 + rs[__builtin_ctz(m)];
  }
  while (psize > 0 && primes[psize - 1] > N) --psize;
  primes.resize(psize);
  return primes;
}
```

Math Formulas & Theoroms

9.
$$\sum_{i=1}^{n} \frac{i}{2^{i}} = 2^{-n}(-n + 2^{n+1} - 2)$$

Sum

$$\sum_{i=1}^{n} i b^{i} = \frac{b (n b^{n+1} - (n+1) b^{n} + 1)}{(b-1)^{2}}$$

```
summation from 1 to r with step (sum of numbers divisible by step in range)

ll calc(int 1, int r, int step) {
    --1;
    ll sum = 1ll * step * (r / step) * ((r / step) + 1) / 2LL;
    sum -= 1ll * step * (l / step) * ((l / step) + 1) / 2LL;
    return sum;
}
```

For two coprime positive integers m and n, that largest number that cannot be written as am + bn (cannot be made by adding up m and n) will be m*n - m - n.

Cayley's formula is the number of spanning trees of N nodes which is equal to N^{N-2}

Number of spanning trees in complete bipartite graph $G_{X,Y}$ is : $X^{Y-1} \times Y^{X-1}$

Such that

X: is the number of nodes in the first set.

Y: is the number of nodes in the second set.

int SumOfOddCubes(int n) {return n * n * (2 * n * n - 1);} int SumOfOddSquares(int n) {return n * (2 * n + 1) * (2 * n - 1) / 3;} int SumOfEvenCubes(int n) {return 2 * n * n * (n + 1) * (n + 1);} int SumOfEvenSquares(int n) {return 2 * n * (n + 1) * (2 * n + 1) / 3;}

$$\sum_{k=1}^{n} k = \frac{1}{2} (n^{2} + n)$$

$$\sum_{k=1}^{n} k^{2} = \frac{1}{6} (2 n^{3} + 3 n^{2} + n)$$

$$\sum_{k=1}^{n} k^{3} = \frac{1}{4} (n^{4} + 2 n^{3} + n^{2})$$

$$\sum_{k=1}^{n} k^{4} = \frac{1}{30} (6 n^{5} + 15 n^{4} + 10 n^{3} - n)$$

$$\sum_{k=1}^{n} k^{5} = \frac{1}{12} (2 n^{6} + 6 n^{5} + 5 n^{4} - n^{2})$$

$$\sum_{k=1}^{n} k^{6} = \frac{1}{42} (6 n^{7} + 21 n^{6} + 21 n^{5} - 7 n^{3} + n)$$

$$\sum_{k=1}^{n} k^{7} = \frac{1}{24} (3 n^{8} + 12 n^{7} + 14 n^{6} - 7 n^{4} + 2 n^{2})$$

$$\sum_{k=1}^{n} k^{8} = \frac{1}{90} (10 n^{9} + 45 n^{8} + 60 n^{7} - 42 n^{5} + 20 n^{3} - 3 n)$$

$$\sum_{k=1}^{n} k^{9} = \frac{1}{20} (2 n^{10} + 10 n^{9} + 15 n^{8} - 14 n^{6} + 10 n^{4} - 3 n^{2})$$

$$\sum_{k=1}^{n} k^{10} = \frac{1}{66} (6 n^{11} + 33 n^{10} + 55 n^{9} - 66 n^{7} + 66 n^{5} - 33 n^{3} + 5 n).$$

• The number of factors of n is:
$$\tau(n) = \prod_{i=1}^{k} (\alpha_i + 1),$$

• Sum of factors of n:
$$\sigma(n) = \prod_{i=1}^{k} (1 + p_i + ... + p_i^{\alpha_i}) = \prod_{i=1}^{k} \frac{p_i^{\alpha_i + 1} - 1}{p_i - 1},$$

• The product of factors :
$$\mu(n) = n^{\tau(n)/2}$$

> Theorem (Fermat).

Every prime of the form 4k +1 is the sum of two squares. A positive integer n is the sum of two squares if and only if all prime factors of the form 4k - 1 have an even exponent in the prime- factorization of n.

Legendre's three-square theorem

Let n be a natural number. $n=x^2+y^2+z^2$ is solvable in non-negative number $\iff n$ is not of the following form: $4^a(8b+7)$

Lagrange's four-square theorem

Every natural number can be represented as a sum of four non-negative integer squares.

If $n = 4^a(8b + 7)$, applying Lagrange's four-square theorem return 4.

Otherwise answer could be 1, 2 or 3.

Counting

Combinatorics

▼ nPr

$$rac{!n}{!(n-r)}$$

▼ nCr

$$\frac{nPr}{!r} = \frac{!n}{!r*!(n-r)}$$

Recurrance relation

$$\binom{n}{r} = \binom{n-1}{r-1} + \binom{n-1}{r}$$

▼ Stars and Bars

the number of ways to distribute n balls in k boxes suppose you have k - 1 bars that and you want to place them between the balls

$$\binom{n+k-1}{k-1}$$

▼ Lucas Theorem

$$egin{pmatrix} m \ n \end{pmatrix} \equiv \prod_{i=0}^k inom{m_i}{n_i} \pmod{p},$$

- mi is the coefficient of the number m after converting it to base p (the digits it self)
- ni is the coefficient of the number n after converting it to base p (the digits it self)

▼ Hockey Stick Identity

$$\sum_{k=r}^{n} \binom{k}{r} = \binom{n+1}{r+1}$$

Derangements

the number of ways to shuffle a set consisting of n elements no element stays in his initial position

$$D(n) = (n-1) * (D(n-1) + D(n-2))$$

Counting Tricks

1. Dearrangements:

- NcR = N-1cR + N-1cR-1
- 3. stars and bars:

N balls, K baskets: N+K-1 c K-1

if no basket can have 0 balls: N-1 c K-1

we can multiply this by N! to get all permutations of it

- 4. The last digit in the a^b is repeated every 4 times
- 5. To choose things in increasing order -> use combinations
- 6. Lattice grid -> number of ways to go from (x1, y1) to (x2, y2)
 - a. (x2+y2) (x1+y1) C (x2 x1)
- 7. If we can repeat choosing the element we must use stars and bars not combination (bars represent the switch between element and the other).
- 8. Number of multisets [with size(k)] that have numbers from 0 to n (n+1 numbers)

9.
$$\sum_{i=1}^{n} \frac{i}{2^i} = 2^{-n}(-n + 2^{n+1} - 2)$$

10. Arithmetic progression:

$$S_n = \frac{n}{2}[2a + (n-1)d].$$

This formula can be simplified as:
$$S_n = \frac{n}{2}[a+a+(n-1)d].$$

$$= \frac{n}{2}(a+a_n).$$

$$= \frac{n}{2}(\text{initial term} + \text{last term}).$$

For a geometric Progression a, ar, ar², ar³ ...

nth Term,

$$a_n = r a_{n-1}$$

· Sum of n terms

$$S_n = \begin{cases} \frac{\alpha(r^n-1)}{r-1} \text{ ,when } r \neq 1 \\ n\alpha \text{ ,when } r \neq 1 \end{cases} \quad S_n = \begin{cases} \frac{\alpha}{1-r} \text{ ,When } |r| < 1. \\ \text{diverges ,When } |r| \geq 1. \end{cases}$$

```
> FFT
```

```
using cd = complex<double>;
const double PI = acos(-1);
void fft(vector<cd> & a, bool invert) {
  int n = a.size();
  for (int i = 1, j = 0; i < n; i++) {
    int bit = n >> 1;
    for (; j & bit; bit >>= 1)
      i ^= bit;
    j ^= bit;
    if (i < j)
      swap(a[i], a[j]);
  }
  for (int len = 2; len <= n; len <<= 1) {
    double ang = 2 * PI / len * (invert ? -1 : 1);
    cd wlen(cos(ang), sin(ang));
    for (int i = 0; i < n; i += len) {
      cd w(1);
      for (int j = 0; j < len / 2; j++) {
        cd u = a[i+j], v = a[i+j+len/2] * w;
        a[i+j] = u + v;
        a[i+j+len/2] = u - v;
        w *= wlen;
      }
    }
  }
  if (invert) {
    for (cd & x : a)
      x = n;
  }
}
vector<int> multiply(vector<int> const& a,
vector<int> const& b) {
  vector<cd> fa(a.begin(), a.end()), fb(b.begin(),
b.end());
  int n = 1;
  while (n < a.size() + b.size())
    n <<= 1;
  fa.resize(n);
  fb.resize(n);
  fft(fa, false);
```

```
fft(fb, false);
  for (int i = 0; i < n; i++)
    fa[i] *= fb[i];
  fft(fa, true);
  vector<int> result(n);
  for (int i = 0; i < n; i++)
    result[i] = round(fa[i].real());
  return result;
}
```

> FFTMOD

```
#define rep(aa, bb, cc) for(int aa = bb; aa < cc;aa++)
#define sz(a) (int)a.size()
typedef complex<double> C;
typedef vector<double> vd;
void fft(vector<C>& a) {
  int n = sz(a), L = 31 - _builtin_clz(n);
  static vector<complex<long double>> R(2, 1);
  static vector<C> rt(2, 1); // (^ 10% faster if double)
  for (static int k = 2; k < n; k *= 2) {
    R.resize(n); rt.resize(n);
    auto x = polar(1.0L, acos(-1.0L) / k);
    rep(i,k,2*k) rt[i] = R[i] = i&1 ? R[i/2] * x : R[i/2];
  }
  vi rev(n);
  rep(i,0,n) rev[i] = (rev[i/2] | (i \& 1) << L) / 2;
  rep(i,0,n) if (i < rev[i]) swap(a[i], a[rev[i]]);
  for (int k = 1; k < n; k *= 2)
    for (int i = 0; i < n; i += 2 * k) rep(j,0,k) {
        // Cz = rt[j+k] * a[i+j+k]; // (25\% faster if hand-
rolled) /// include-line
        auto x = (double *)&rt[j+k], y = (double
*)&a[i+j+k];
                /// exclude-line
        C z(x[0]*y[0] - x[1]*y[1], x[0]*y[1] + x[1]*y[0]);
/// exclude-line
        a[i + j + k] = a[i + j] - z;
        a[i + j] += z;
      }
}
template<int M> vi convMod(const vi &a, const vi &b)
  if (a.empty() || b.empty()) return {};
  vi res(sz(a) + sz(b) - 1);
  int B=32-__builtin_clz(sz(res)), n=1<<B,
cut=int(sqrt(M));
```

```
vector<C> L(n), R(n), outs(n), outl(n);
  rep(i,0,sz(a)) L[i] = C((int)a[i] / cut, (int)a[i] % cut);
  rep(i,0,sz(b)) R[i] = C((int)b[i] / cut, (int)b[i] % cut);
  fft(L), fft(R);
  rep(i,0,n) {
    int j = -i \& (n - 1);
    outl[j] = (L[i] + conj(L[j])) * R[i] / (2.0 * n);
    outs[j] = (L[i] - conj(L[j])) * R[i] / (2.0 * n) / 1i;
  }
  fft(outl), fft(outs);
  rep(i,0,sz(res)) {
    ll\ av = ll(real(outl[i])+.5),\ cv = ll(imag(outs[i])+.5);
    ll\ bv = ll(imag(outl[i])+.5) + ll(real(outs[i])+.5);
    res[i] = ((av % M * cut + bv) % M * cut + cv) % M;
  }
  return res;
}
    > NTT
const int mod = 998244353;
const int root = 31;
const int root_1 = 128805723;
const int root_pw = 1 << 23;
// make the size of (a) power of 2
void fft(vector<int> &a, bool invert) {
  int n = a.size();
  // reversal bit sort
  for (int i = 1, j = 0; i < n; i++) {
    int bit = n >> 1;
    for (; j & bit; bit >>= 1)
      i ^= bit;
    j ^= bit;
    if (i < j)
      swap(a[i], a[j]);
  }
  for (int len = 2; len <= n; len <<= 1) {
    int wlen = invert ? root 1 : root;
    for (int i = len; i < root_pw; i <<= 1)
      wlen = 1ll * wlen * wlen % mod;
```

```
for (int i = 0; i < n; i += len) {
      int w = 1;
      for (int j = 0; j < len / 2; j++) {
        int u = a[i + j], v = 1ll * a[i + j + len / 2] * w %
mod;
        a[i + j] = u + v;
        if (a[i + j] \ge mod) a[i + j] = mod;
        a[i + j + len / 2] = u - v;
        if (a[i+j+len/2] < 0) a[i+j+len/2] += mod;
        w = 1ll * w * wlen % mod;
      }
    }
  }
  if (invert) {
    int n_1 = power(n, mod - 2);
    for (int &x: a)
      x = 111 * x * n_1 % mod;
  }
}
vector<int> multiply(vector<int> const &a,
vector<int> const &b) {
  vector<int> fa = a, fb = b;
  int n = 1;
  while (n < a.size() + b.size())
    n <<= 1;
  fa.resize(n), fb.resize(n);
  fft(fa, false);
  fft(fb, false);
  for (int i = 0; i < n; i++)
    fa[i] = 1ll * fa[i] * fb[i] % mod;
  fft(fa, true);
  fa.resize(a.size() + b.size());
  return fa;
}
vector<int> power(vector<int> &a, int b) {
  vector<int> res{1};
  while (b) {
    if (b & 1) res = multiply(res, a);
    a = multiply(a, a), b >>= 1;
  }
  return res;
}
```

> phi function

```
// phi[p] = p - 1
// phi[p^k] = p^k - p^(k - 1)
// phi[a * b] = phi[a] * phi[b]
// sum:[d|n] phi[d] = n
// a^{(phi[m])} = 1 \% m
// a^(n) = a^(n % phi[m]) % m
long long phi(long long n) {
  long long ans = n;
  for (int p = 2; 1LL * p * p \le n; p++) {
    if (n \% p == 0) {
      while (n \% p == 0) {
         n = p;
      }
      ans -= ans / p;
    }
  }
  if (n > 1) {
    ans -= ans / n;
  }
  return ans;
}
const int N = #;
int phi[N];
void calc_phi() {
  for (int i = 1; i < N; i++) {
    phi[i] = i;
  }
  for (int i = 2; i < N; i++) {
    if (phi[i] == i) {
      for (int j = i; j < N; j += i) {
         phi[j] -= phi[j] / i;
      }
    }
  }
}
```

extended eculidian

```
// x * a + y * b = g
// x = x0 + b/g * t
// y = y0 - a/g * t
int gcd(int a, int b, int&x, int&y) {
  x = 1, y = 0;
  int x1 = 0, y1 = 1, a1 = a, b1 = b;
  while (b1) {
    int q = a1 / b1;
    tie(x, x1) = make_tuple(x1, x - q * x1);
    tie(y, y1) = make_tuple(y1, y - q * y1);
    tie(a1, b1) = make_tuple(b1, a1 - q * b1);
  }
  return a1;
}
// extended (a, m, x, y) -> inverse of a
if (g!=1) {
cout << "No solution!";
} else {
x = (x \% m + m) \% m;
cout << x << endl;
}
vector<int> invs(vector<int> a, int mod) {
  int n = int(a.size());
  vector<int> ret(n);
  int v = 1;
  for (int i = 0; i != n; ++i) {
    ret[i] = v;
    v = 1LL * v * a[i] % mod;
  auto [x, y] = extended_gcd(v, mod);
  x = (x \% mod + mod) \% mod;
  for (int i = n - 1; i \ge 0; --i) {
    ret[i] = 1LL * x * ret[i] % mod;
    x = 1LL * x * a[i] % mod;
  }
  return ret;
}
```

Mobius

```
mobius[1] = -1;
for (int i = 1; i < VALMAX; i++) {
    if (mobius[i]) {
        mobius[i] = -mobius[i];
        for (int j = 2 * i; j < VALMAX; j += i) {
            mobius[j] += mobius[i];
        }
    }
}

Pascal
struct pascal_triangel {
    vector<vector<int>> nCr:
```

struct pascal_triangel { vector<vector<int>> nCr; pascal_triangel(int n) { nCr = vector<vector<int>>(n + 1, vector<int>(n + 1)); }

```
nCr[0][0] = 1;
for (int i = 1; i <= n; i++) {
    nCr[i][0] = 1;
}
for (int i = 1; i <= n; i++) {
    for (int j = 1; j <= i; j++) {
        // mod overflow
        nCr[i][j] = nCr[i - 1][j] + nCr[i - 1][j - 1];
    }
}
}</pre>
```

pascal_triangel g(#);