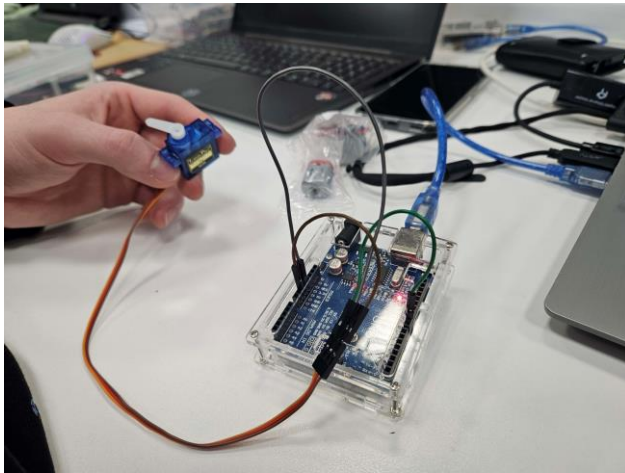
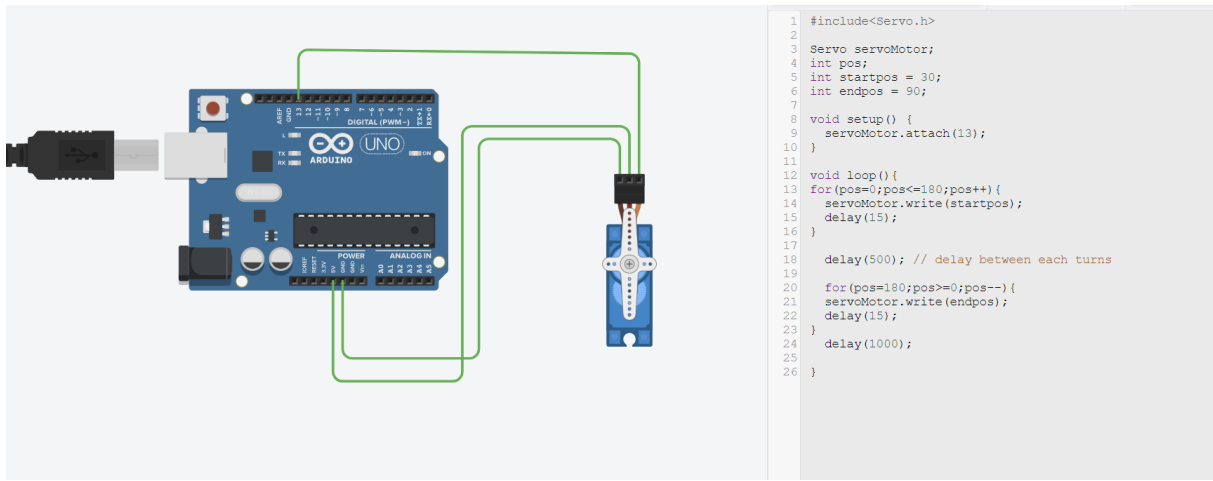


Servo moteur



Moteur pas par pas

```
#include <Stepper.h>

int in1Pin = 11;
int in2Pin = 10;
int in3Pin = 9;
int in4Pin = 8;
int revolution = 4000;

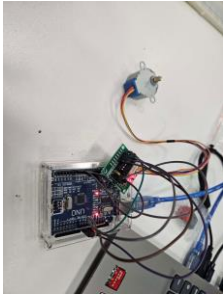
Stepper myStepper = Stepper(revolution, in4Pin, in3Pin, in2Pin, in1Pin);

void setup() {
  // Set the speed to 5 rpm:
  myStepper.setSpeed(5);
}

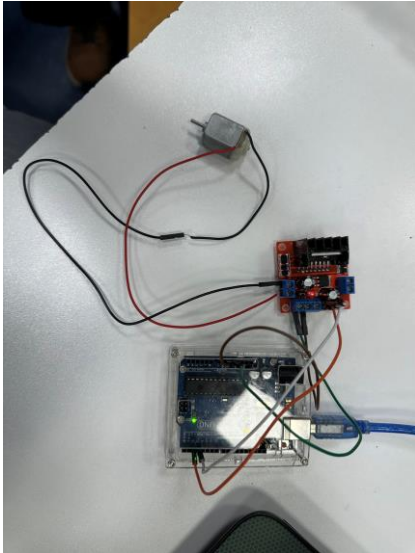
void loop() {

  // Step one revolution in one direction:
  myStepper.step(revolution);
  delay(500);

  // Step one revolution in the other direction:
  myStepper.step(-revolution);
  delay(500);
}
```



Moteur DC



```
int hbridgeIN1 = 2;
int hbridgeIN2 = 3;

void setup() {
  pinMode(hbridgeIN1, OUTPUT);
  pinMode(hbridgeIN2, OUTPUT);
}

void loop() {
  digitalWrite(hbridgeIN1, HIGH);
  delay(1000);
  digitalWrite(hbridgeIN1, LOW);
  digitalWrite(hbridgeIN2, HIGH);
  delay(1000);
  digitalWrite(hbridgeIN2, LOW);
}
```