Real-time Stream Simulation & Event Trigger

Vivek's Computer Vision based stream event trigger

Simulates a real-time stream, performing detection on every third frame and triggering an alert if three or more people appear on the screen (three's a crowd!). The alerts are logged in a JSON file with timestamps, and are also plotted with a timeline of alert occurences. The alerts are overlayed and the output visuals are exported.

Pre-requisites:- Rename the short video to 'input_video.mp4' in the current directory, and create two folders: 'output_video' and 'output_images' in the directory you run your code from

Install the necessary packages

```
!pip install opencv-python
!pip install ultralytics
!pip install matplotlib
```

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```

Importing the libraries

```
from ultralytics import YOLO
import cv2
import json
import matplotlib.pyplot as plt
from google.colab.patches import cv2 imshow
```

Loading the yolov10 model, the video, and defining integers and lists

```
model = YOLO('yolov10n.pt')
#loading video
video_path = '/content/StreamSim/input_video.mp4'
cap = cv2.VideoCapture(video_path)  # use cv2.VideoCapture('cam.no.') for streaming
fnc = con_cot/cv2_CAD_DBOD_EDS)  # cot_tho_fnc_of_tho_video
```

```
TpS = cap.get(cvz.car_rkur_rrs)
                                         # get the Tps of the video
frame_skip = 3
                                         # number of skipped frames
frame_index = 0
                                         # integer defining the number of the frame every
scale_percent = 50
                                         # percetage the video will be resized to
all_detections = []
                                         # stores detected labels, box-coordinates, conf.
                                         # stores the timestamps of people detected
time_list = []
people_count_list =[]
                                         # stores the number of people detected
Main Loop:
ret = True
while ret:
   ret, frame = cap.read()
    if ret:
        results = model.track(frame, persist = True)
                                                                                      # detec
        frame_ = results[0].plot()
                                                                        # plots the detected
        height, width, _ = frame_.shape
                                                                           # resizing the ir
        new_height = int(height * scale_percent / 100)
        new_width = int(width * scale_percent / 100)
        resized = cv2.resize(frame_,(new_width,new_height), interpolation=cv2.INTER_AREA)
        if frame_index % frame_skip == 0:
                                                                              # executes eve
            frame_detections = []
                                                                                        # stc
            person_detected = 0
                                                                             # stores number
            for r in results:
                                                                      # loop stores objects
                for box in r.boxes:
                    cls_id = int(box.cls)
                    label = model.model.names[cls_id]
                    conf = float(box.conf)
                    if (label == 'person') & (conf > 0.5): # if person is detected & confic
                        person_detected += 1
                        if person_detected >=3:
                                                              # if more than 3 people, store
                            detection_time = frame_index / fps
                            frame_detections.append([label, detection_time, conf])
                            time_list.append(detection_time)
                            people_count_list.append(person_detected)
            if frame_detections:
                                                                                # If more th
                frame_json = {
                    "frame number": frame_index,
                    "time (seconds)": detection_time,
                    "frame detections": frame_detections
                all_detections.append(frame_json)
                                                                                       # upda
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