

## LOL

### Low-Light Image Enhancement

In many real-world scenarios, images are captured in low-light conditions, leading to poor visibility, high noise, and loss of crucial details. This can severely impact applications such as surveillance, autonomous driving, medical imaging, and photography, where clear and well-lit images are essential.

# LOW-LIGHT IMAGE ENHANCEMENT

GAN

UNET

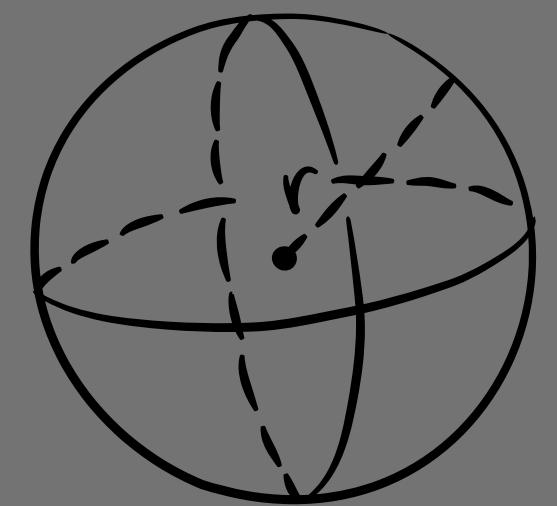
# **GAN**

---

- Composed of a generator (which enhances the low-light image) and a discriminator (which distinguishes real vs. fake enhanced images).
- Learns to generate more realistic, high-quality images.
- Can introduce hallucinations or artifacts.

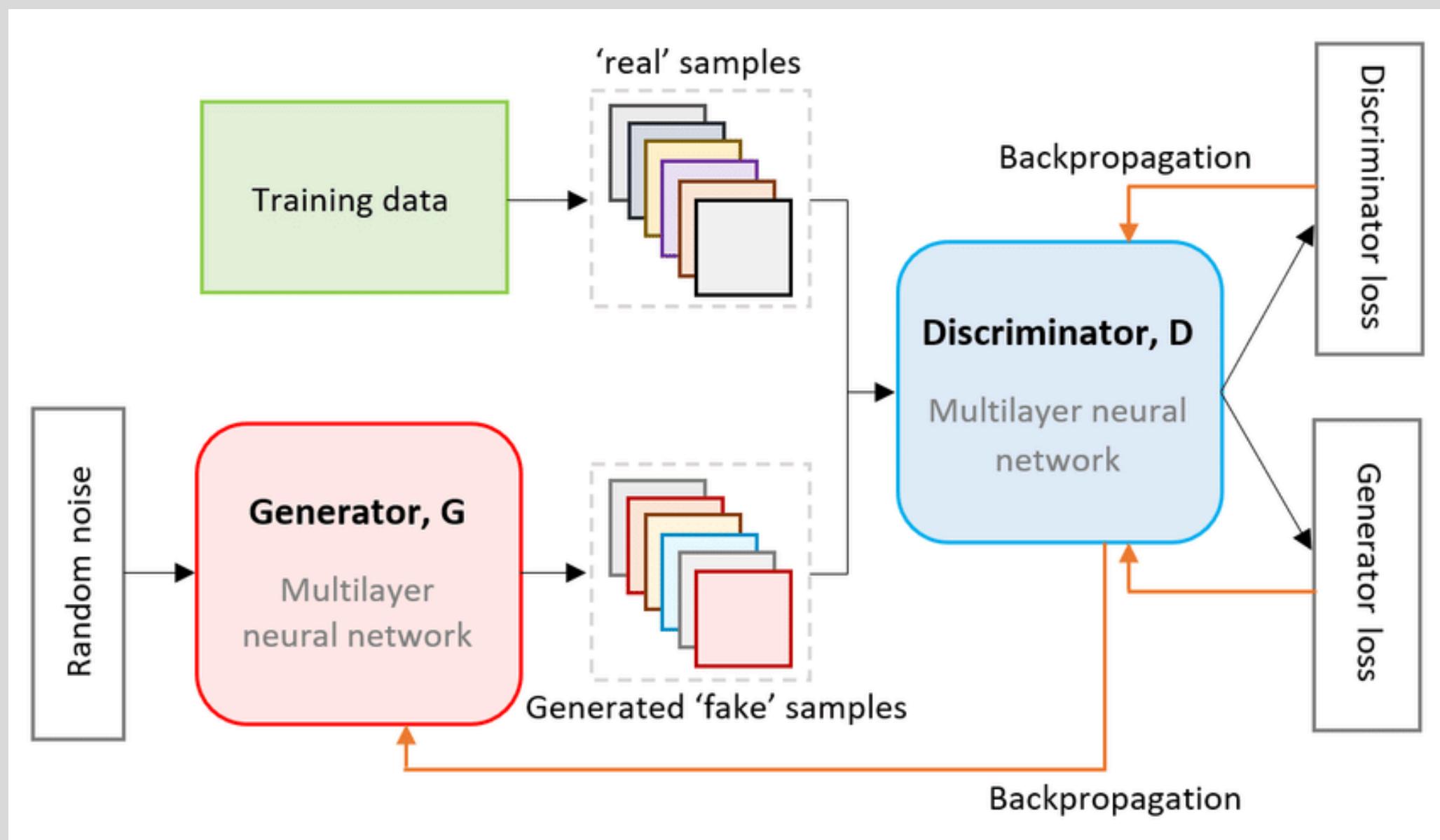
$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$y = mx + b$$



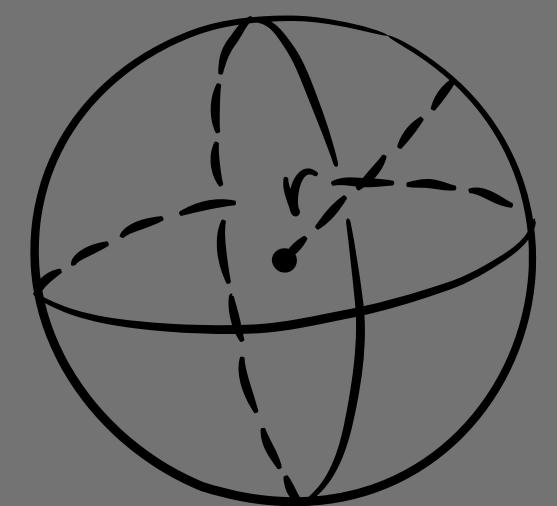
$$\sqrt{V} = \frac{4}{3} \pi r^3$$

# GAN



$$\frac{-b + \sqrt{b^2 - 4ac}}{2a}$$

$$y = mx + b$$



$$\sqrt[3]{\frac{4}{3}\pi r^3}$$

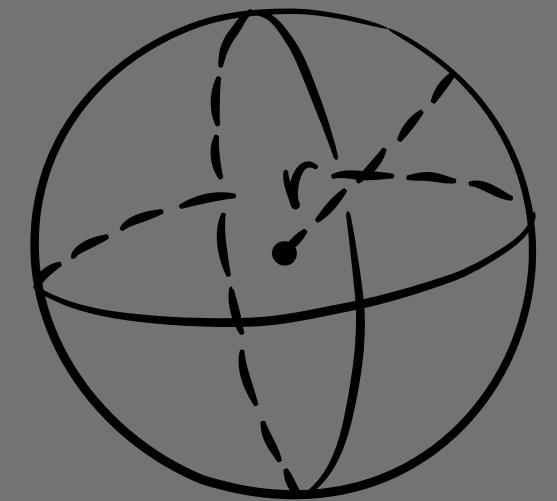
# UNET

---

- Originally designed for biomedical image segmentation.
- Encoder-decoder architecture with skip connections.
- Works as a deterministic model – produces a single output given an input.
- Suitable for pixel-wise regression tasks.

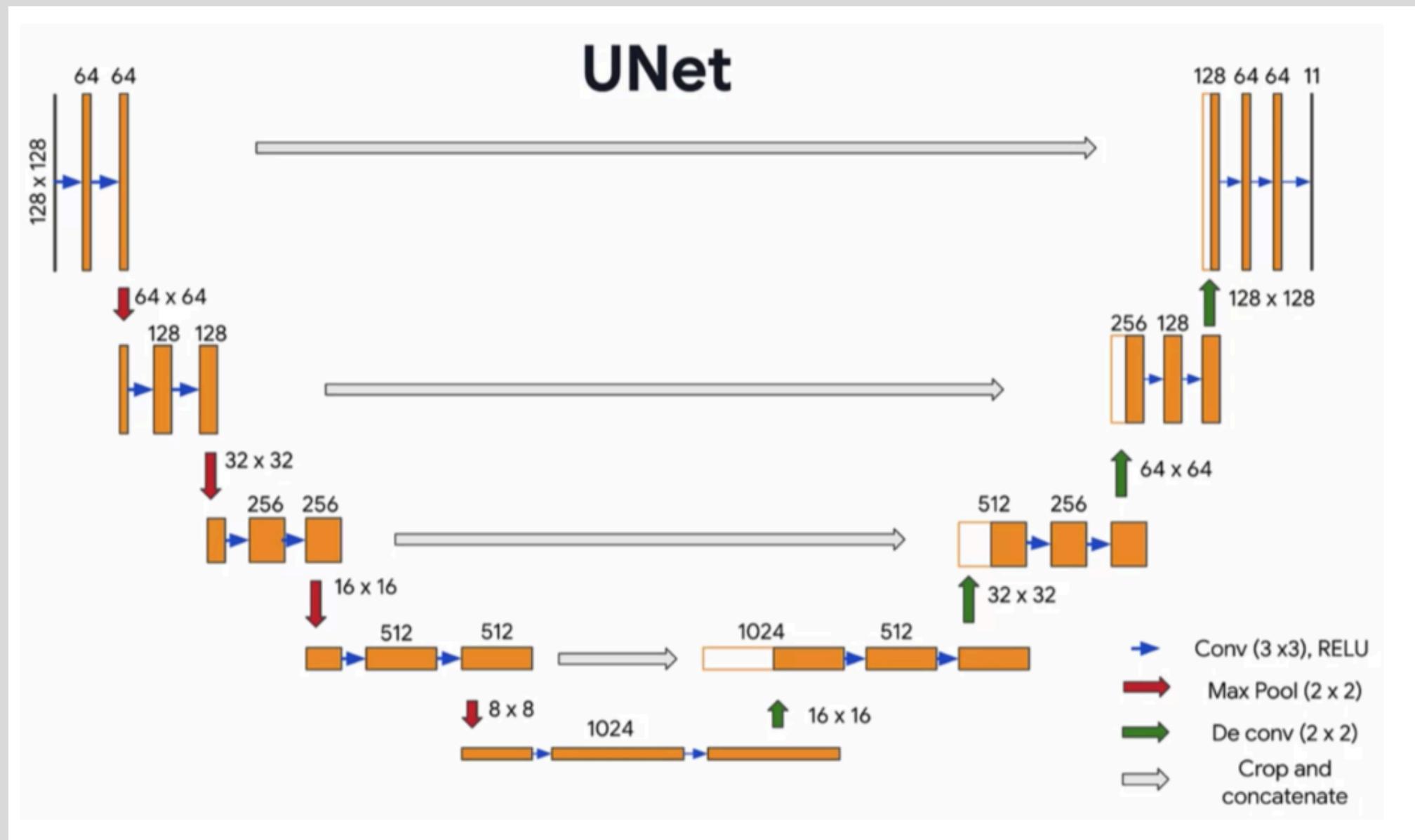
$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$y = mx + b$$



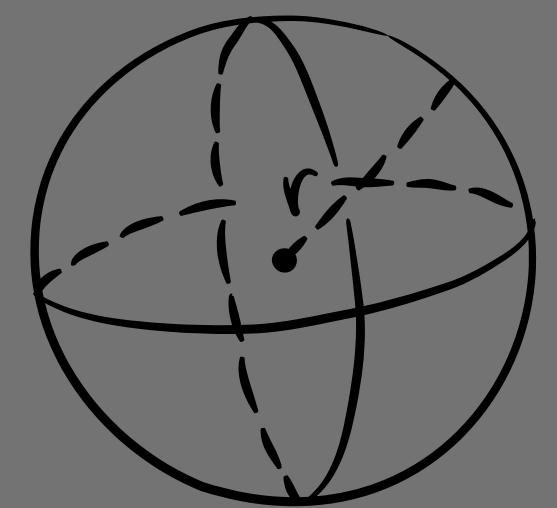
$$V = \frac{4}{3} \pi r^3$$

# UNET



$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

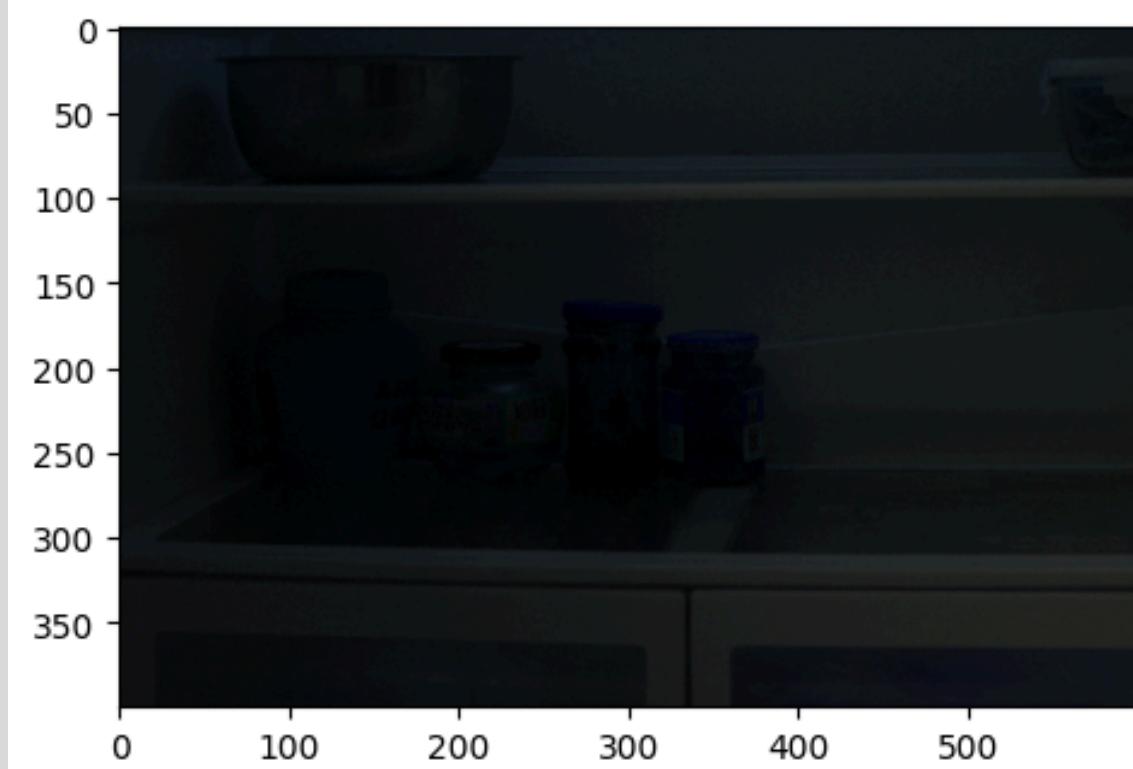
$$y = mx + b$$



$$\sqrt[3]{\frac{4}{3}\pi r^3}$$

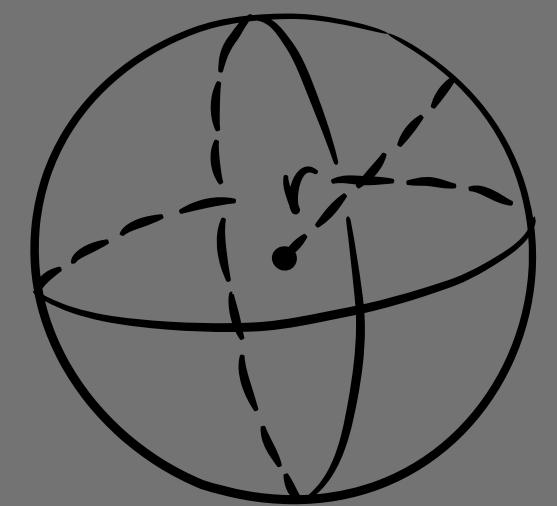
# TRAINING DATA

---



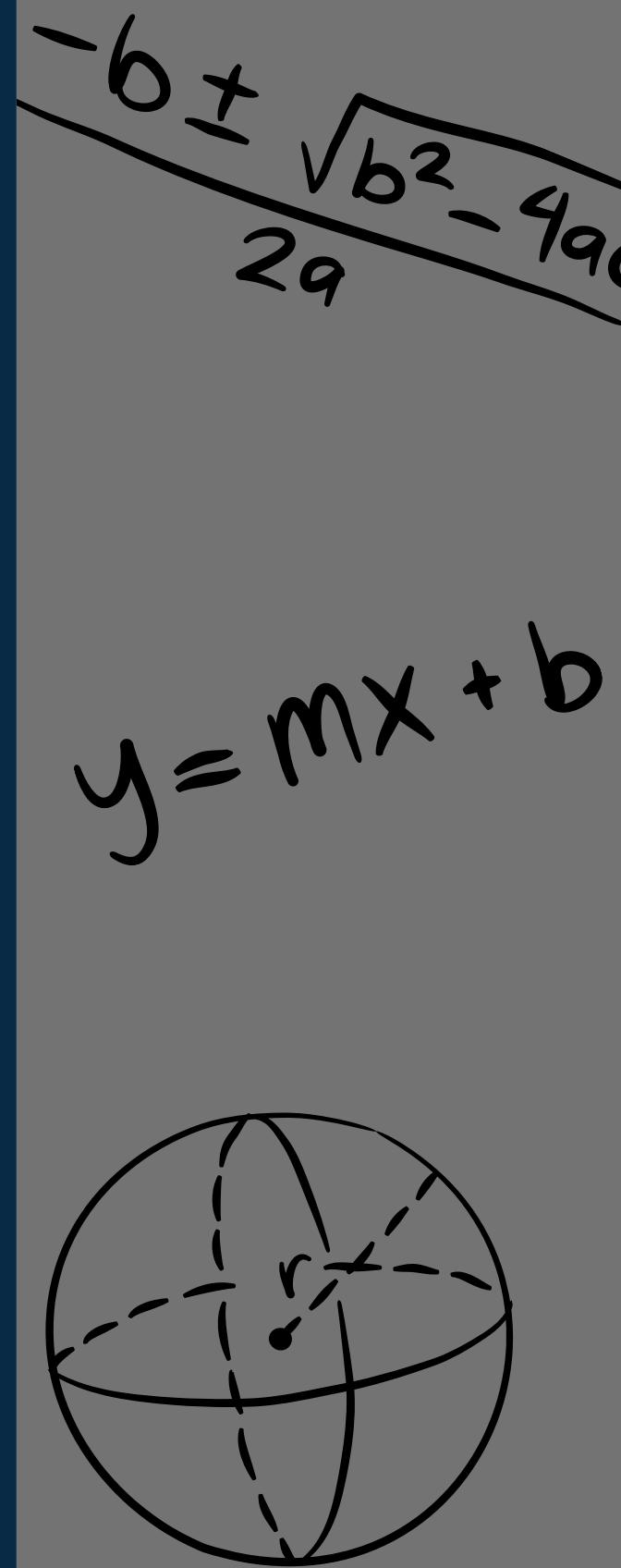
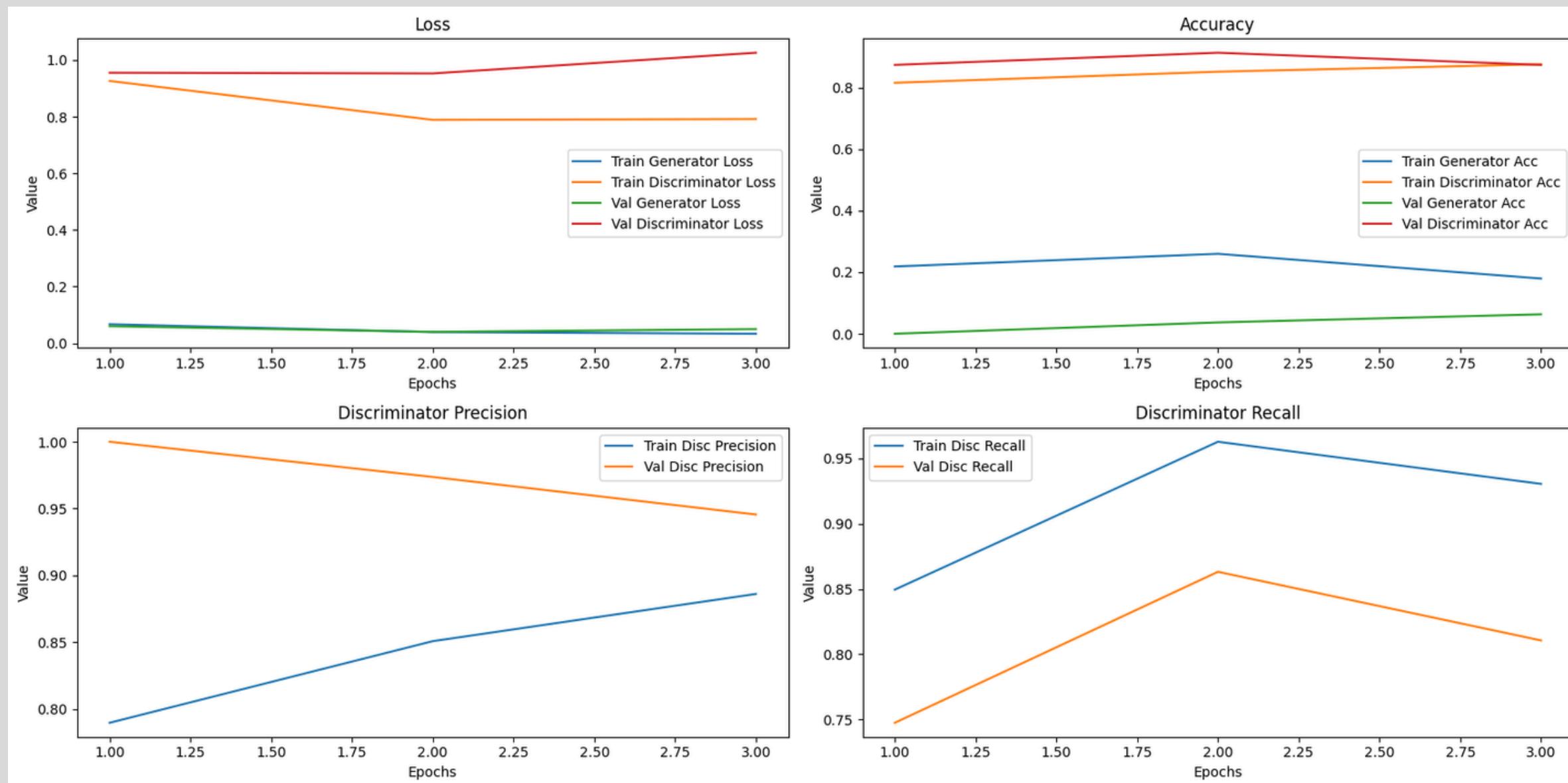
$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$y = mx + b$$



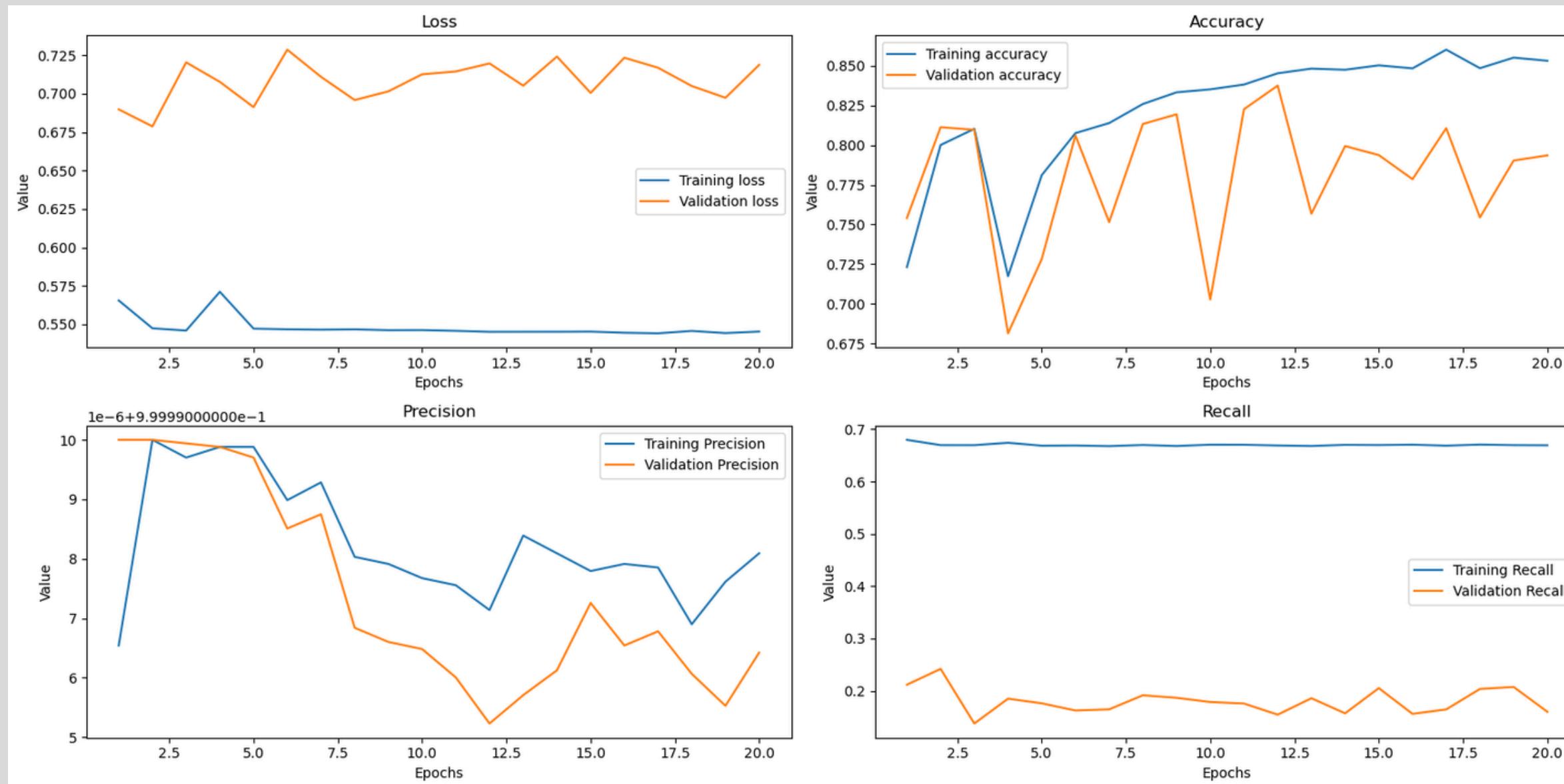
$$V = \frac{4}{3} \pi r^3$$

# GAN TRAINING



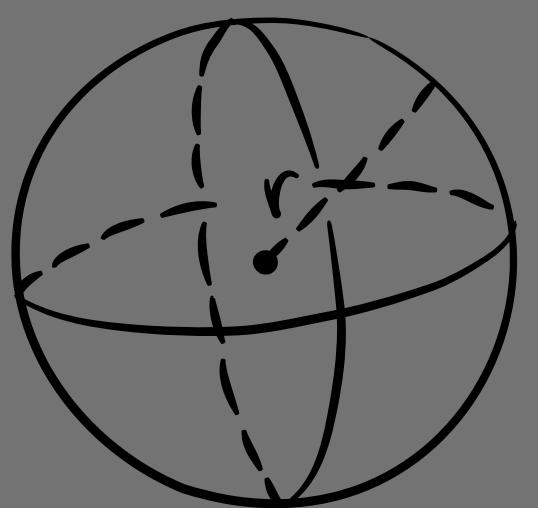
$$\sqrt[3]{\frac{4}{3}\pi r^3}$$

# UNET TRAINING



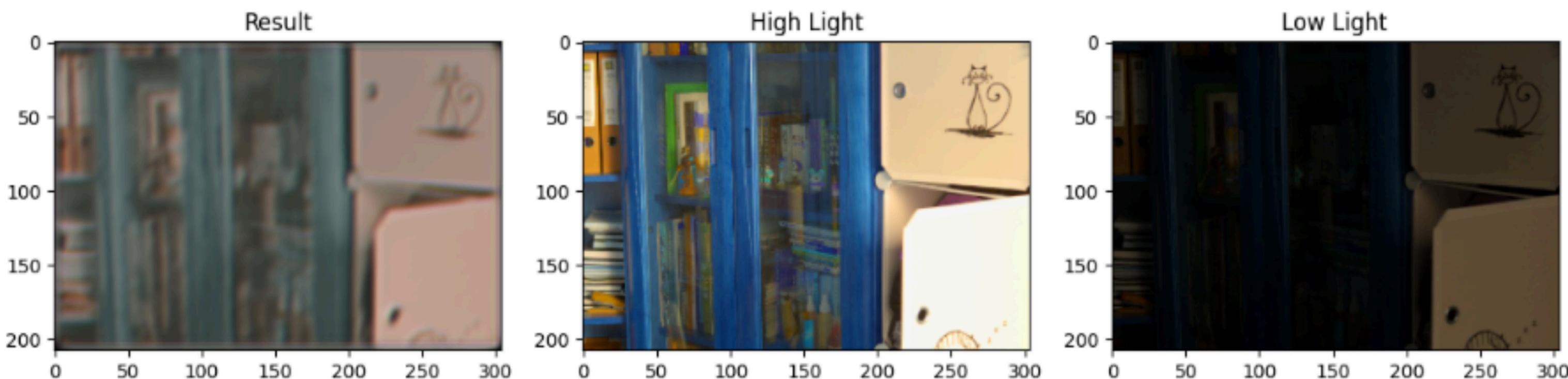
$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$y = mx + b$$



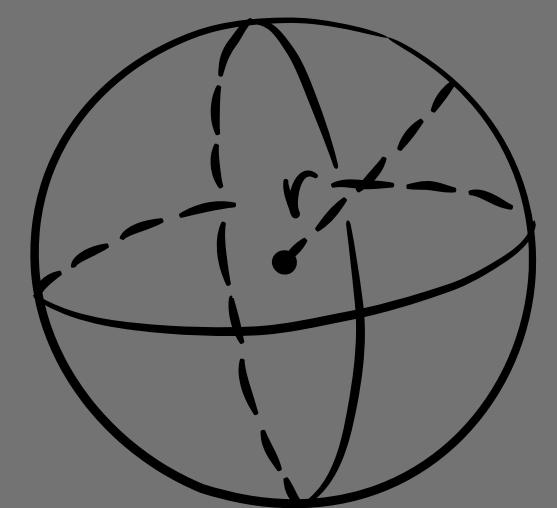
$$\sqrt[3]{\frac{4}{3}\pi r^3}$$

# GAN RESULTS



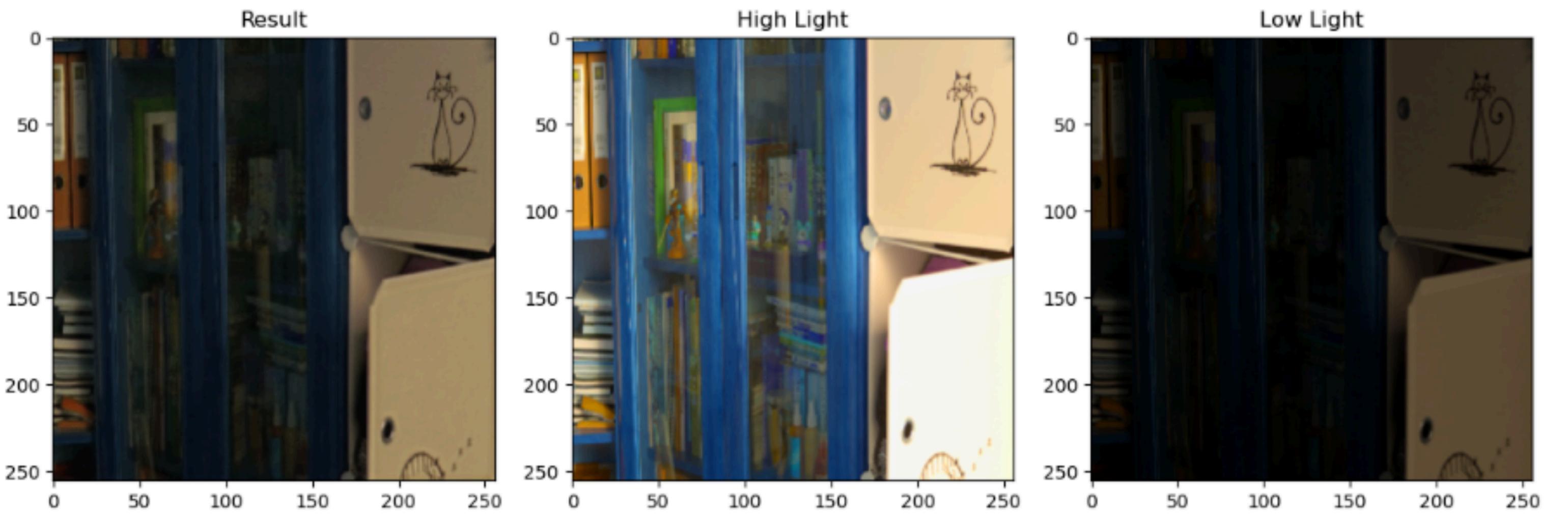
$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$y = mx + b$$



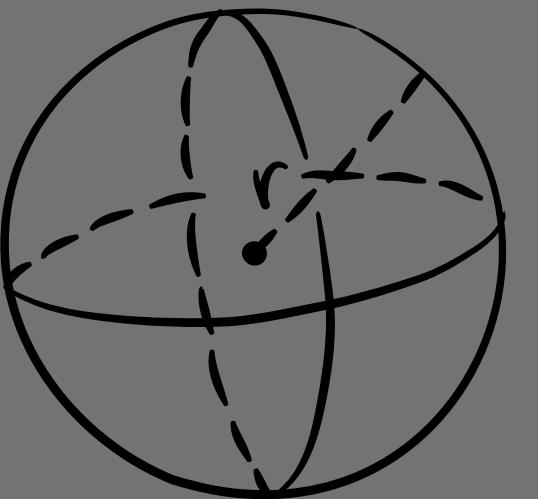
$$\sqrt[3]{V} = \frac{4}{3} \pi r^3$$

# UNET RESULTS



$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$y = mx + b$$



$$\sqrt[3]{\frac{4}{3}\pi r^3}$$