

Support Vector machine Optimization:Penalty Methods

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Mathematical Model

Consider the following minimization problem:

$$(P) \begin{cases} \text{Min} & f(x) \\ \text{s.t} & x \in D_R \end{cases}$$

where $D_R = \{x \in \mathbb{R}^n \mid \textcolor{red}{f_i(x)} \leq \textcolor{red}{0} \ i \in I_1, \textcolor{green}{f_i(x)} = \textcolor{green}{0} \ i \in I_2\}$

The Solving of this problem is the solving a suite of unconstraint subproblems, there is three approach as follows:

- **Exterior Penalty Methods:**

sequence of unconstraint subproblems $(PE)_k$: $\text{Min}\{f(x) + r_k PE(x)\} = \text{Min}\{E(r_k, x)\} \rightarrow \textbf{unconstraint optimization}$

- **Interior Penalty Methods : Si $I_2 = \{\emptyset\}$**

sequence of unconstraint subproblems $(PI)_k$: $\text{Min}\left\{f(x) + \frac{1}{r_k} PI(x)\right\} = \text{Min}\{I(r_k, x)\} \rightarrow \textbf{unconstraint optimization}$

- **Mixed Penalty Methods**

sequence of unconstraint subproblems $(PM)_k$: $\text{Min}\{f(x) + M(r_k, t_k)\} = \text{Min}\{M(r_k, t_k, x)\} \rightarrow \textbf{unconstraint optimization}$

$$M(r_k, t_k) = r_k PE(x) + \frac{1}{t_k} PI(x)$$

Exterior Penalty Methods

$$(PE)_k: \text{Min}\{f(x) + r_k PE(x)\}$$

The sequence of values $\{r_k\}$ has the following properties:

- Positivity: $\forall k \ r_k \geq 0$
- Monotonicity : $\forall k \ r_{k+1} \geq r_k$
- Divergence: $\lim_{k \rightarrow \infty} r_k = +\infty$

The Exterior Penalty function is a real value function, $PE: \mathbb{R}^n \rightarrow \mathbb{R}$, with the following properties:

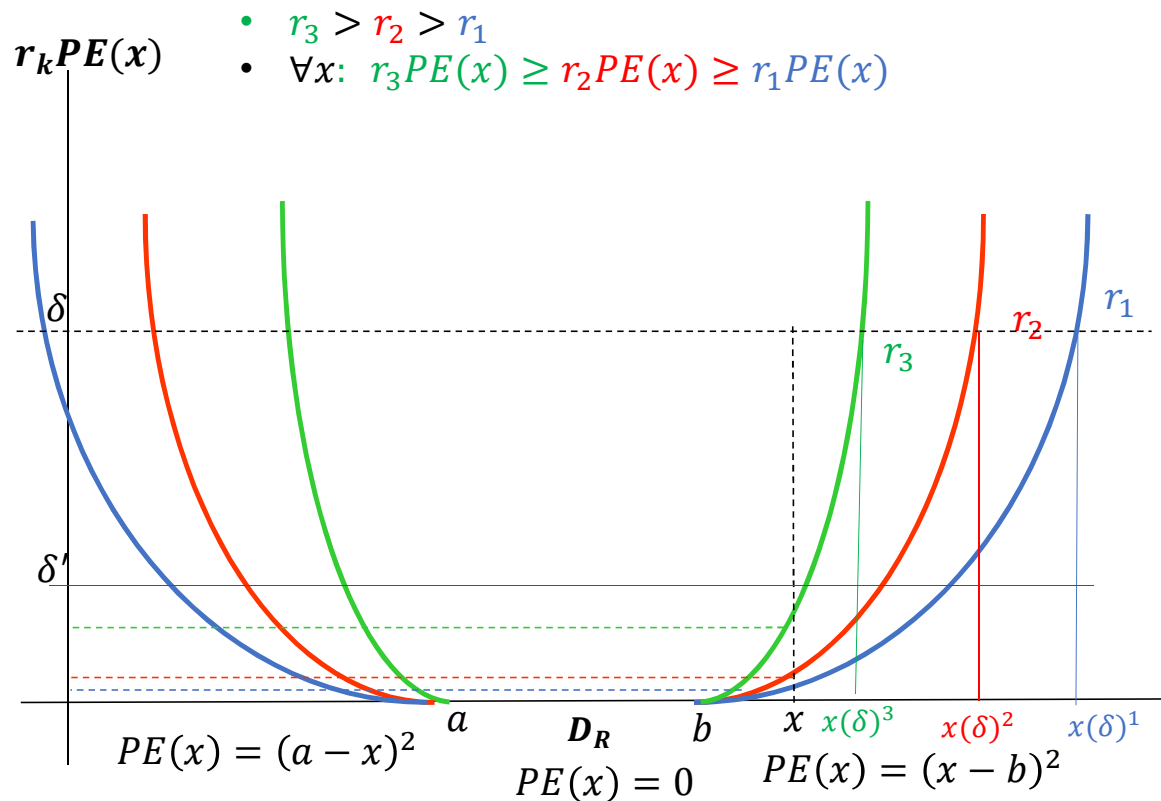
- PE is a continuous function over \mathbb{R}^n
- $\forall x \in \mathbb{R}^n \quad PE(x) \geq 0$
- $PE(x) = 0 \Leftrightarrow x \in D_R (i \in I_1 \ f_i(x) \leq 0, \mathbf{i} \in \mathbf{I_2} \ f_i(x) = 0)$

Example:

$$PE(x) = \sum_{i \in I_1} (\text{Max}\{0, f_i(x)\})^2 + \sum_{\mathbf{i} \in \mathbf{I_2}} (\mathbf{f_i(x)})^2$$

- $PE(x) = 0 \Leftrightarrow x \in D_R(i \in I_1 f_i(x) \leq 0, \mathbf{i} \in \mathbf{I}_2 f_i(x) = 0)$
- $x \notin D_R(\exists i \in I_1 f_i(x) > 0, \exists \mathbf{i} \in \mathbf{I}_2 f_i(x) \neq 0) \Leftrightarrow PE(x) > 0$
- $PE(x) = \sum_{i \in I_1} (Max\{0, f_i(x)\})^2 + \sum_{\mathbf{i} \in \mathbf{I}_2} (\mathbf{f}_{\mathbf{i}}(\mathbf{x}))^2$
- $\mathbf{i} \in \mathbf{I}_2, f_i(x) = 0 \Leftrightarrow f_i(x) \leq 0, f_i(x) \geq 0$
- $PE(x) = P(f)(x) = \begin{cases} 0 & \text{if } f(x) \leq 0 \\ f(x)^2 & \end{cases}$
- $PE(x) = Max\{0, f(x)\}$

Exterior Penalty Methods : Example



If $f_1(x) = x - b \leq 0$, $f_2(x) = a - x \leq 0$ then

$$rPE(x) = r(\text{Max}\{0, (a - x)\})^2 + r(\text{Max}\{0, (x - b)\})^2$$

Let

- $\delta > 0$,
- the sequence $\{x(\delta)^k\}$ where $r_k PE(x(\delta)^k) = \delta$

Such that

- if $r_{k+1} > r_k$ then $x(\delta)^{k+1}$ close to D_R than $x(\delta)^k$
- if $\lim_{k \rightarrow \infty} r_k = +\infty$ then the solution of $(PE)_k$ converges to the solution of (P)

- $f_1(x) = x - b \leq 0 \Rightarrow x \leq b$,
- $f_2(x) = a - x \leq 0 \Rightarrow x \geq a$
- $D_R = [a, b]$
- k : le problème $(PE)_k$
- Soit δ , la suite $\{x(\delta)^k\}$ où $r_k PE(x(\delta)^k) = \delta$
- $\lim_{k \rightarrow +\infty} r_k PE(x(\delta)^k) = 0 \rightarrow \delta \rightarrow 0$
- $\lim_{k \rightarrow +\infty} (PE)_k = (P) \Leftrightarrow f(x^*) = f(x^*) + r_\infty PE(x^*) \quad x^* \in D_R$
- $\lim_{k \rightarrow +\infty} r_k PE(x^k) = 0$
- $PE(x^*) = 0$ car $x^* \in D_R$
- $\sum_{i \in I_1} (\text{Max}\{0, f_i(x)\})^2$

Exterior Penalty Methods : Convergence

The next lemme is used to demonstrate the convergence of the method.
Let's denote by x^k the optimal solution of $\text{Min}\{E(r_k, x)\}$

Lemme 1 :

for any value of k ,

- $E(r_k, x^k) \leq E(r_{k+1}, x^{k+1})$
- $PE(x^k) \geq PE(x^{k+1})$
- $f(x^k) \leq f(x^{k+1})$
- If x^* is an optimal solution of (P) then $\forall k, f(x^*) \geq E(r_k, x^k) \geq f(x^k)$

Theorem 1 :

Let $\{x^k\}$ a sequence of points generated by the Exterior penalty method $(PE)_k$. Any endpoint of this sequence is a solution of (P) .

Exterior Penalty Methods : Algorithm If $I_1 = \{\emptyset\}$

Input :

- $E(r, x) = f(x) + r \sum_{i \in I_2} (f_i(x))^2$
- $x^0, \delta, r_0, \varepsilon_0, \alpha > 1, \beta > 1 \quad \lim_{k \rightarrow \infty} \varepsilon_k = 0$
- $\|\nabla E(r_0, x^0)\| \leq \varepsilon_0$
- $k = 0$
- WHILE($\|\nabla E(r_k, x^k)\| > \delta$) {
 - $r_{k+1} = (r_k)^\alpha$
 - $\varepsilon_{k+1} = (\varepsilon_k)^\beta$ if $\varepsilon_0 < 1$ $\beta > 1$ else $\beta < 1$
 - $\text{Min}\{E(r_{k+1}, y)\}$
 - $y^0 = x^k$
 - $t = 0$
 - WHILE($\|\nabla E(r_{k+1}, y^t)\| > \varepsilon_{k+1}$) {
 - $d^k = -\nabla E(r_{k+1}, y^t)$
 - Déterminer α_t tel que $\alpha_t = \underset{\alpha > 0}{\text{argmin}}\{f(x - \alpha \nabla E(r_{k+1}, y^t))\}$ or inaccurate line search as Armijo rule
 - $y^{t+1} = y^t - \alpha_t \nabla E(r_{k+1}, y^t)$
 - $t = t + 1$ }
 - $x^{k+1} = y^* \quad \|\nabla E(r_{k+1}, x^{k+1})\| \leq \varepsilon_{k+1}$
 - $k = k + 1$
- Fin

$$x^0 = (0,0) \quad r_0 = 2, \delta = 10^{-2}, \alpha = \beta = 2, \quad \varepsilon_0 = 22 \quad \|\nabla E(r_0, x^0)\| \leq \varepsilon_0$$

$$\bullet \text{ } \mathbf{Min} E(r_0, y) = \mathbf{x}^0, \varepsilon_0 = 0,1 \text{ until } \|\nabla E(r_0, y)\| \leq \varepsilon_0$$

$$\bullet (P) \begin{cases} \text{Min} & \frac{1}{2}(x_1^2 + x_2^2) \\ \text{s.t} & x_1 + x_2 = 5 \end{cases}$$

$$\bullet (PE)_k: \text{Min}\{x_1^2 + x_2^2 + r_k(x_1 + x_2 - 5)^2\}$$

$$\bullet E(r, x) = x_1^2 + x_2^2 + r(x_1 + x_2 - 5)^2$$

$$\bullet \rightarrow \nabla E(r_k, x) = \begin{pmatrix} x_1 + 2r_k(x_1 + x_2 - 5) \\ x_2 + 2r_k(x_1 + x_2 - 5) \end{pmatrix}$$

$$\bullet k = 0$$

$$\bullet \rightarrow \nabla E(r_0, x^0) = \begin{pmatrix} -20 \\ -20 \end{pmatrix} \rightarrow \|\nabla E(r_0, x^0)\| = \sqrt{400} = 20 > \delta = 10^{-2}$$

Interior Penalty Methods

$$(PI)_k: \text{Min} \left\{ f(x) + \frac{1}{r_k} PI(x) \right\} = \text{Min}\{I(r_k, x)\}$$

The sequence of values $\{r_k\}$ has the following properties:

- Positivity: $\forall k \ r_k \geq 0$
- Monotonicity : $\forall k \ r_{k+1} \geq r_k$
- Divergence: $\lim_{k \rightarrow \infty} r_k = +\infty$

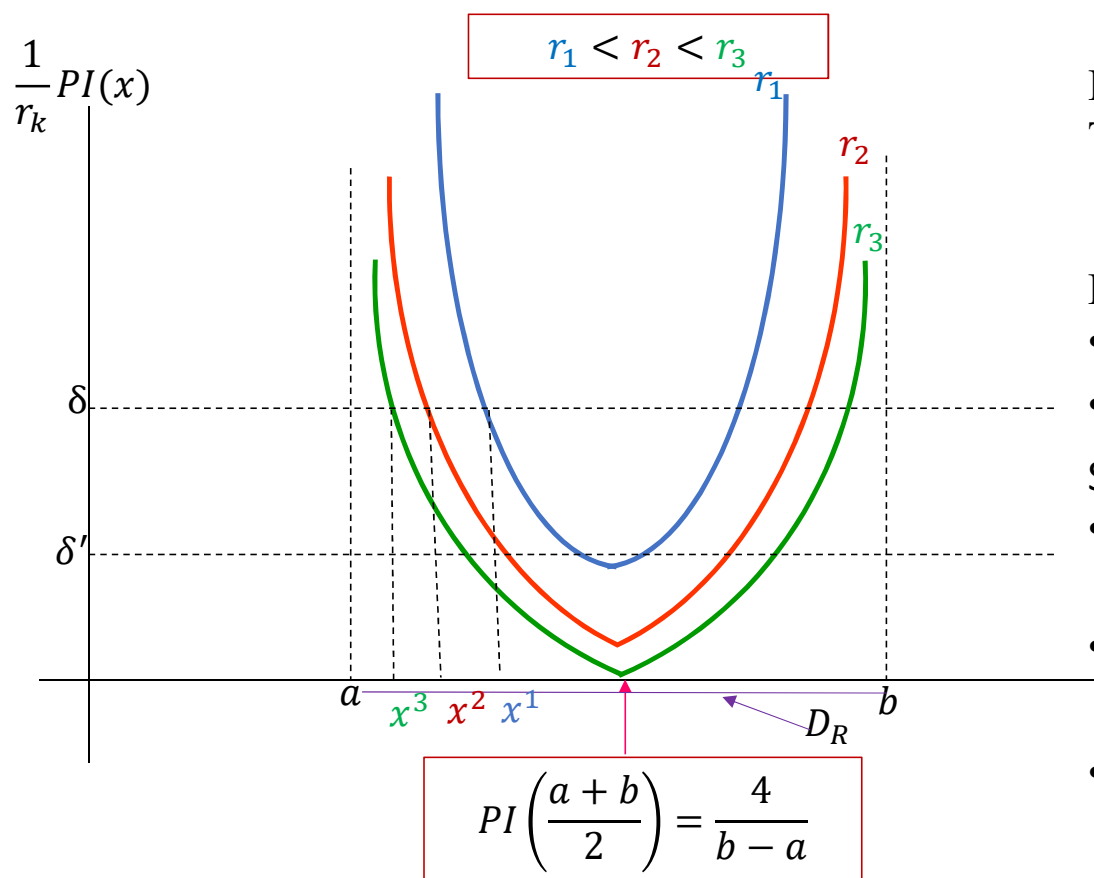
The Interior Penalty function is a real value function, $PI: \mathbb{R}^n \rightarrow \mathbb{R}$, with the following properties:

- PI is a continuous function over \mathbb{R}^n
- $\forall x \in \text{Int}(D_R) \ PI(x) \geq 0$
- $\lim_{x \rightarrow \bar{x}} PI(x) = +\infty$ when $\bar{x} \in \text{Fr}(D_R)$

Example:

- $PI(x) = \sum_{i \in I_1} \frac{-1}{f_i(x)}$
- $PI(x) = -\sum_{i \in I_1} \log(-f_i(x))$

Interior Penalty Methods: example



If $f_1(x) = x - b$, $f_2(x) = a - x$

Then

$$PI(x) = -\frac{1}{a-x} - \frac{1}{x-b}$$

Let

- $\delta > 0$,
- the sequence $\{x(\delta)^k\}$ where $\frac{1}{r_k} PI(x(\delta)^k) = \delta$

Such that:

- if $r_{k+1} > r_k$ then $x(\delta)^{k+1}$ close to D_R than $x(\delta)^k$
- the $\frac{1}{r_k} PI(x)$ curve is closer to the boundaries as x^k increases.
- Note that with each iteration the solution $x^k \in \text{Int}(D_R)$ or this is not very restrictive since if we use an iterative method to solve $(PI)_k$, and if the solution $x^{k-1} \in \text{Int}(D_R)$ then $x^k \in \text{Int}(D_R)$

Interior Penalty Methods: Convergence

The next lemme is used to demonstrate the convergence of the method.

Let's denote by x^k the optimal solution of $\text{Min}\{I(r_k, x)\}$

Lemme 2:

for any value of k ,

- $I(r_k, x^k) \geq I(r_{k+1}, x^{k+1})$
- $PI(x^k) \leq PI(x^{k+1})$
- $f(x^k) \geq f(x^{k+1})$

Theorem 2:

Let $\{x^k\}$ a sequence of points generated by the Interior penalty method. Any endpoint of this sequence is a solution of (P) .

Interior Penalty Methods : Algorithm If $I_2 = \{\emptyset\}$

Input :

- $I(r, x) = f(x) + \frac{1}{r} \sum_{i \in I_1} \frac{-1}{f_i(x)}$ Ou $I(r, x) = f(x) - \frac{1}{r} \sum_{i \in I_1} \log(-f_i(x))$
- $x^0, \delta, r_0, \varepsilon_0, \alpha > 1, \beta > 1 \lim_{k \rightarrow \infty} \varepsilon_k = 0$
- $\|\nabla I(r_0, x^0)\| \leq \varepsilon_0$ solve $x^0 = \operatorname{argmin} I(r_0, y)$ unconstrained optimization
- $k = 0$
- WHILE($\|\nabla I(r_k, x^k)\| > \delta$) {
 - $r_{k+1} = (r_k)^\alpha, \varepsilon_{k+1} = (\varepsilon_k)^\beta$
 - $\operatorname{Min}\{I(r_{k+1}, x)\}$
 - $y^0 = x^k$
 - $t = 0$
 - WHILE($\|\nabla I(r_{k+1}, y^t)\| > \varepsilon_{k+1}$) {
 - $d^k = -\nabla I(r_{k+1}, y^t)$
 - Déterminer α_t tel que $\alpha_t = \operatorname{argmin}_{\alpha > 0} \{f(x - \alpha \nabla I(r_{k+1}, y^t))\}$ or inaccurate line search as Armijo's Algorithm
 - $y^{t+1} = y^t - \alpha_t \nabla I(r_{k+1}, y^t)$
 - $t = t + 1$ }
 - $x^{k+1} = y^*$
 - $k = k + 1$
- Fin

Mixed Penalty Methods

$$(PM)_k: \text{Min} \left\{ f(x) + r_k PE(x) + \frac{1}{t_k} PI(x) \right\} = \text{Min} \{ M(r_k, t_k, x) \}$$

The sequence of values $\{r_k, t_k\}$ has the following properties:

- Positivity: $\forall k \ r_k \geq 0, \quad t_k \geq 0$
- Monotonicity : $\forall k \ r_{k+1} \geq r_k, \quad t_{k+1} \geq t_k$
- Divergence: $\lim_{k \rightarrow \infty} r_k = +\infty, \lim_{k \rightarrow \infty} t_k = +\infty$

Example:

- $PI(x) = \sum_{i \in I_1} \frac{-1}{f_i(x)}$ ou $PI(x) = -\sum_{i \in I_1} \log(-f_i(x))$
- $PE(x) = \sum_{i \in I_2} (f_i(x))^2$

Mixed Penalty Methods : Convergence

The next lemme is used to demonstrate the convergence of the Mixed Penalty Methods. Let's denote by x^k the optimal solution of $\text{Min}\{M(r_k, t_k, x)\}$

Lemme 3:

for any value of k ,

- $M(r_k, t_k, x^k) \geq M(r_{k+1}, t_{k+1}, x^{k+1})$
- $f(x^k) \geq f(x^{k+1})$

Theorem 3 :

Let $\{x^k\}$ a sequence of points generated by the Mixed Penalty Methods. Any endpoint of this sequence is a solution of (P) .

Mixed Penalty Methods: Algorithm

Entrée :

- $M(r, q, x) = f(x) + \frac{1}{r} \sum_{i \in I_1} \frac{-1}{f_i(x)} + t \sum_{i \in I_2} (f_i(x))^2$ Ou $M(r, t, x) = f(x) - \frac{1}{r} \sum_{i \in I_1} \log(-f_i(x)) + t \sum_{i \in I_2} (f_i(x))^2$
- $x^0, \delta, r_0, t_0, \varepsilon_0, \alpha > 1, \beta > 1, \delta > 1 \lim_{k \rightarrow \infty} \varepsilon_k = 0$
- $\|\nabla I(r_0, t_0, x^0)\| \leq \varepsilon_0 \quad x^0 = \operatorname{argmin} I(r_0, t_0, y)$
- $k = 0$
- WHILE($\|\nabla M(r_k, t_k, x^k)\| > \delta$) {
 - $r_{k+1} = (r_k)^\alpha, t_{k+1} = (t_k)^\delta, \varepsilon_{k+1} = (\varepsilon_k)^\beta$
 - $\operatorname{Min}\{M(r_{k+1}, t_{k+1}, x)\}$ {
 - $y^0 = x^k$
 - $t = 0$
 - WHILE($\|\nabla M(r_{k+1}, t_{k+1}, y^t)\| > \varepsilon_{k+1}$) {
 - $d^t = -\nabla M(r_{k+1}, t_{k+1}, y^t)$
 - Déterminer α_t tel que $\alpha_t = \operatorname{argmin}_{\alpha > 0} \{f(x - \alpha \nabla M(r_{k+1}, t_{k+1}, y^t))\}$
 - $y^{t+1} = y^t - \alpha_t \nabla M(r_{k+1}, t_{k+1}, y^t)$
 - $t = t + 1$ }
 - $x^{k+1} = y^*$
 - $k = k + 1$
- }
- $x^* = x^k \rightarrow \operatorname{RETURN} x^* \rightarrow \operatorname{Fin}$