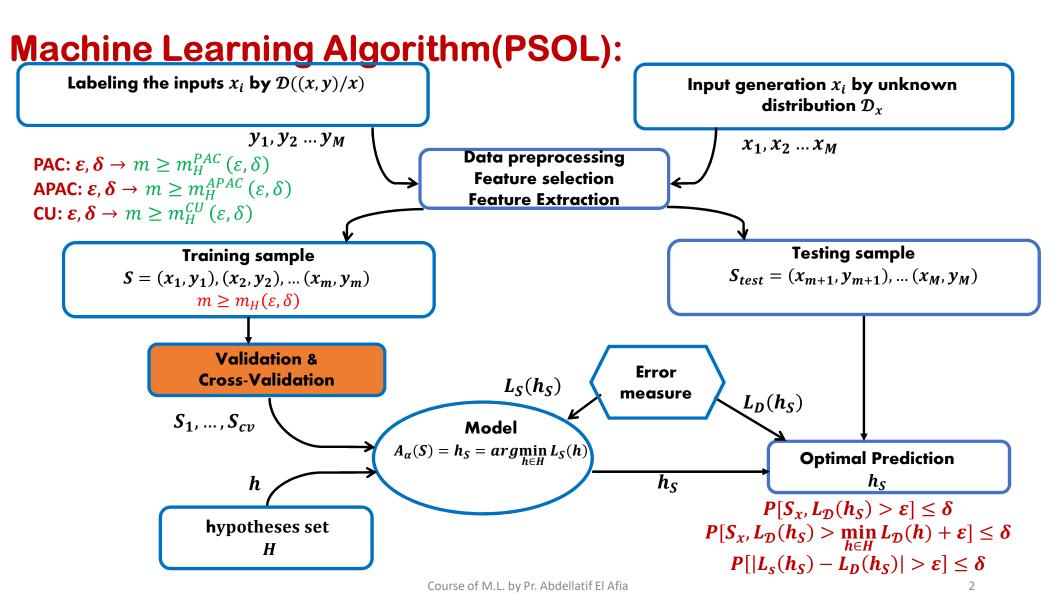
# Part 3: Overfitting-Underfitting

- 1. Validation/Cross-Validation:
  - 1. Validation set
  - 2. Model selection
  - 3. Cross-validation: k-fold method
- 2. Regularization



#### Reminder

#### **Definition: APAC learning model**

H follows agnostic PAC learning, if there exist  $m_H$ :  $(0,1)^2 \to \mathbb{N}$  and  $A_\alpha$ . Having the following property:  $\forall \varepsilon, \delta \in (0,1), \forall \mathcal{D}$  on  $X \times Y$ .

Then, if we run  $A_{\alpha}$  on  $m \ge m_H(\varepsilon, \delta)$  generated (i, i, d) such that S is selected with a probability at least  $(1 - \delta)$ ,  $A_{\alpha}$  will generate the hypothesis  $h_S$  such that:

$$P_{S \sim \mathcal{D}^m} \left[ L_{\mathcal{D}}(h_S) \leq \min_{h \in H} L_{\mathcal{D}}(h) + \varepsilon \right] \geq 1 - \delta \quad \forall \ m \geq m_H(\varepsilon, \delta)$$

In other words:

$$P_{S \sim \mathcal{D}^m} \left[ L_{\mathcal{D}}(h_S) > \min_{h \in H} L_{\mathcal{D}}(h) + \varepsilon \right] \leq \delta \ \forall \ m \geq m_H(\varepsilon, \delta)$$

#### **Motivation**

- If  $L_S(h_S)$  is too big, we have the Underfitting problem. So, we should variate the model's configuration
- Variate the whole model, and select the best one that have the smaller  $L_D(\pmb{h_S})$  .

### **Objective:**

How to select the best Model/Configuration?

#### **Tools:**

- Validation (sufficient training data points)
- Cross-validation (unsufficient training data points).

# Validation & Cross-Validation

#### 1. Validation Set

#### **Definition: Validation**

The validation consists in extracting from the training set another set named: validation set. This is for two objectives :

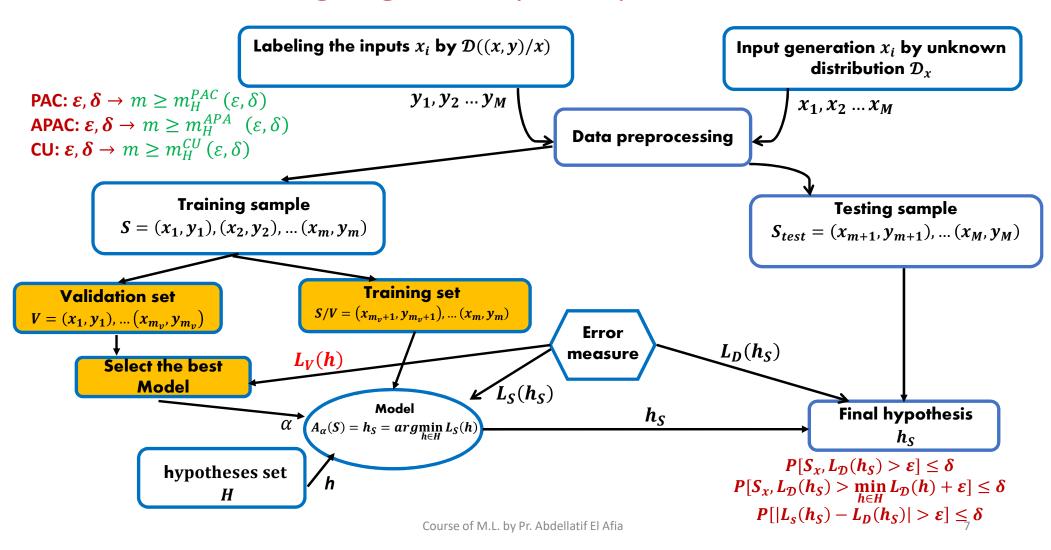
- Select the best model (algorithm or hyper-parameter).
- Better estimation of the generalization error.

Let's consider the following validation set:

$$V = (x_1, y_1), ..., (x_{m_v} y_{m_v})$$

Whose data points are sampled according to the distribution  ${\cal D}$  independently from the  ${\cal m}$  data of the training set.

## Machine Learning Algorithm(PSOL): Validation set



#### 1. Validation Set

#### Theorem:

Consider the hypothesis h and the cost function belonging to [0,1]. So  $\forall \delta \in [0,1]$ :

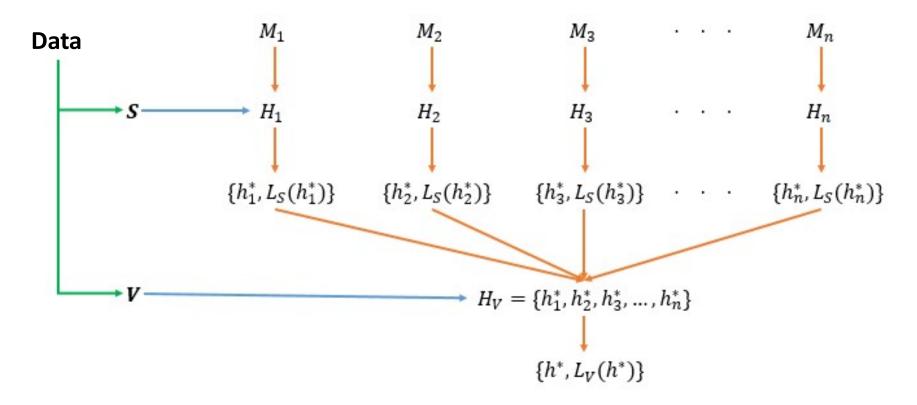
$$P_{V \sim D^{m_v}} \left[ |L_V(h) - L_D(h)| \le \varepsilon = \sqrt{\frac{\log\left(\frac{2}{\delta}\right)}{2m_v}} \right] \ge 1 - \delta$$

#### Notice : $|H| \cong \infty$

- This generalization bound doesn't depend neither on the learning algorithm nor on the training set.
- The generalization bound of the validation set is better than that of the training set:

$$L_D(h) - L_S(h) \leq \sqrt{C \frac{d_{VC}(H) + log(\frac{1}{\delta})}{m}}$$

With: C is a constant.



 $Model = \{learning \ algorithm; hyperparameters\}$ 

If  $h^* \in H_i$  so  $M_i$  is the best model, with i = 1, ..., n.

## Theorem : $|H_V| < \infty$

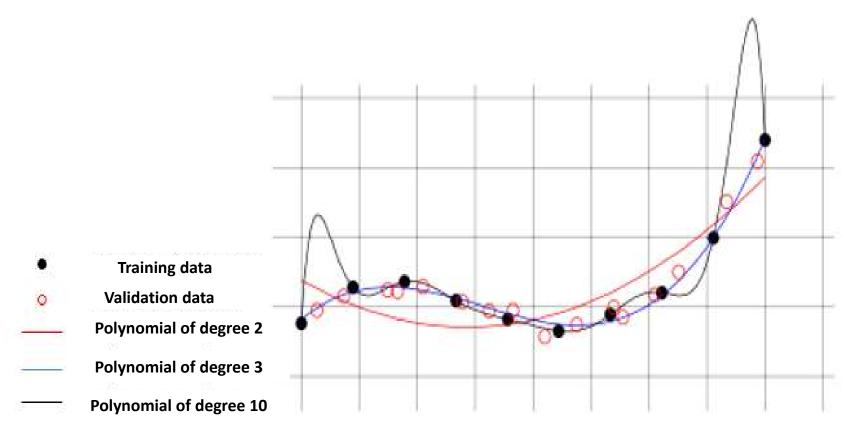
Let's consider the hypothesis set  $H_V = \{h_1^*, h_2^*, \dots, h_n^*\}$  and the cost function belonging to [0,1]. Let's consider the validation set V of size  $m_v$  sampled independently from  $H_V$ . So  $\forall \delta \in [0,1]$  and  $\forall h^* \in H_V$ :

$$P_{V \sim D^{m_v}} \left[ |L_V(h^*) - L_D(h^*)| \le \varepsilon = \sqrt{\frac{\log\left(\frac{2|H_V|}{\delta}\right)}{2m_v}} \right] \ge 1 - \delta$$

#### **Notice:**

The generalization bound based on the validation set is better than that of the training set under the condition that the size of  $H_V$  is small.

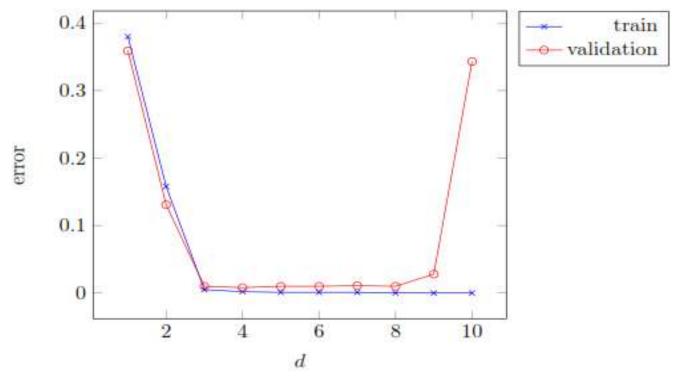
#### What is the best polynomial?



#### **Definition:**

The model selection curve presents the training error and the validation error in function of

the model complexity.



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#### **Definition**: k-Fold cross-validation

The training set is partitioned on k subsets (folds) of size  $\frac{m_H(\varepsilon,\delta)=m}{k}$ .

For each subset  $S_i$  i=1,...,k, the algorithm  $A_{\alpha}$  is trained on the union of the remaining subsets, then the estimation of the validation error of  $A_{\alpha}(h)$  is made on  $S_i$ .

Finally, the total validation error of the model is the mean of all validation errors of the subsets  $S_i$ .

#### **Definition: Leave-one-out cross-validation**

Leave-one-out cross-validation is a particular case of the k-Fold cross-validation with k=1.

```
ALGORITHM: « k-Fold Cross Validation »
INPUT: Training set : S = \{(x_1, y_1), ..., (x_m, y_m)\}
             Parameter values set : Θ
             Learning Model A
             Integer k
BEGIN:
        Partition S into S_1, \dots, S_k
        FOREACH \theta \in \Theta
               FOR i = 1 ... k
                       h_{i,\theta} = A(S \setminus S_i; \theta)
                       Compute the error estimation L_{S_i}(h_{i,\theta})
               ENDFOR
               error(\theta) = \frac{1}{k} \sum_{i=1}^{k} L_{S_i}(h_{i,\theta})
END
OUTPUT: Optimal parameter: \theta^* = \operatorname{argmin}_{\theta \in \Theta} (\operatorname{error}(\theta))
               Optimal hypothesis : h_{\theta^*} = A(S; \theta^*)
```

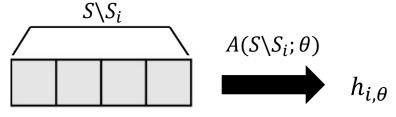
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Example: k = 5

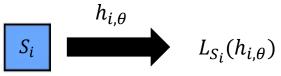
• Partition S into 5 subsets  $S_1, ..., S_5$ 

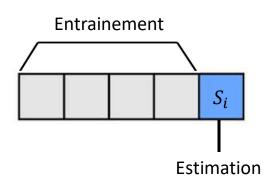


- For each i = 1, ..., 5:
  - The training is done on the set  $S \setminus S_i$

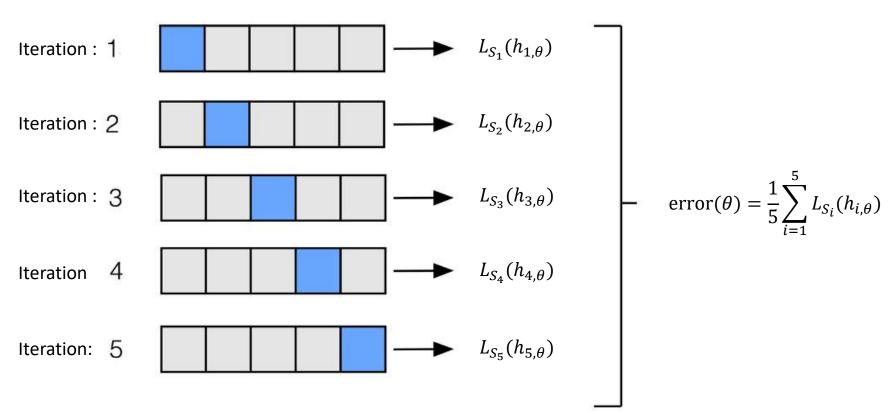


• The error estimation  $L_{S_i}(h_{i,\theta})$  is done on  $S_i$ :





• For  $\forall i=1,\ldots,5$ :  $m_{\mathcal{S}_i} < m_H = m$ 



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