Behavior With UML

State-charts and components

UML Diagrams

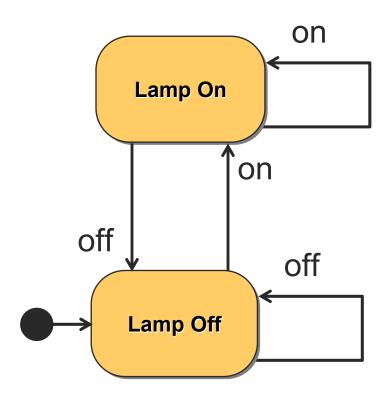
- Requirements capture
 - Use-case diagrams
- Structural view (static aspect of model)
 - Class diagram
 - Object diagram
- Functional view (interaction among objects
 - Sequence diagram
 - Communication diagram
- Behavioral view (object dynamics)
 - Activity diagram
 - State-chart diagram
- Deployment view
 - Composite structure diagram
 - Deployment diagram

Automaton

- A machine whose behavior is not only the consequence of the current input, but also the history of past inputs
- Characterized by an internal state which represents this past history of inputs

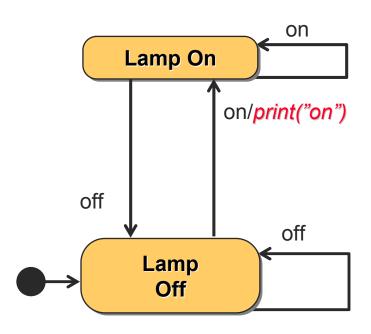
State machine

A graphical representation of an automaton

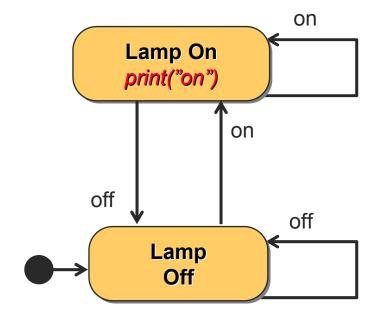


Outputs and Actions

 Outputs can be related to transitions or states



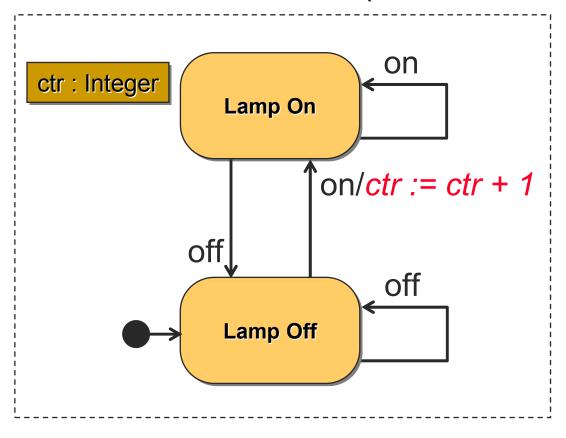
Mealy automaton



Moore automaton

Extended state machines

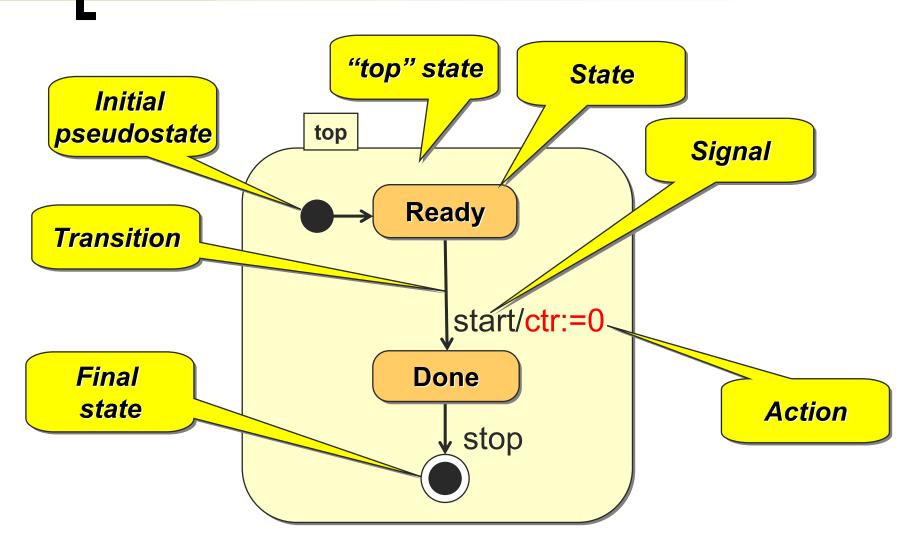
Addition of variables ("extended state")



A bit of theory

- An extended (Mealy) state machine is defined by:
 - A set of input signals (input alphabet)
 - A set of output signals (output alphabet)
 - A set of states
 - A set of transitions
 - Triggering signal
 - Action
 - A set of extended state variables
 - An initial state designation
 - A set of final states (if terminating automaton)

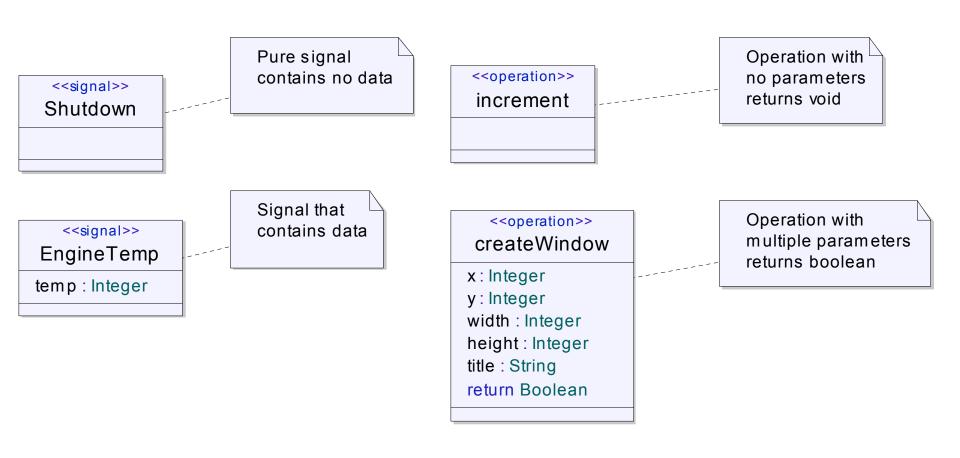
Basic State-chart Diagram



Event-driven Behavior

- Also called *reactive* behavior
- An event is a type of observable behavior
 - Interactions
 - Synchronous (operation call)
 - Asynchronous (signal transmission/reception)
 - Time events
 - Interval expiry
 - Calendar/clock times
 - Change events
 - Change in value of some entity (change events)
- Event Instance: an instance of an event of a certain type
 - Occurs at a particular instance of time, has no duration

Signals and Operations



The Behavior of What?

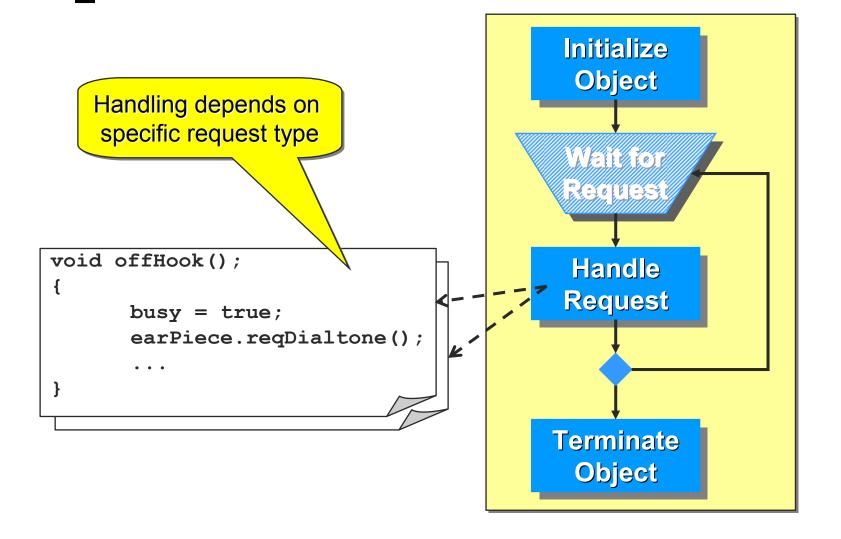
- In principle, anything that manifests eventdriven behavior
 - There is no support currently in UML for modeling continuous behavior
- In practice:
 - The behavior of individual objects
 - Object interactions
- The dynamic semantics of UML state machines are currently mainly specified for the case of active objects

Active Classes

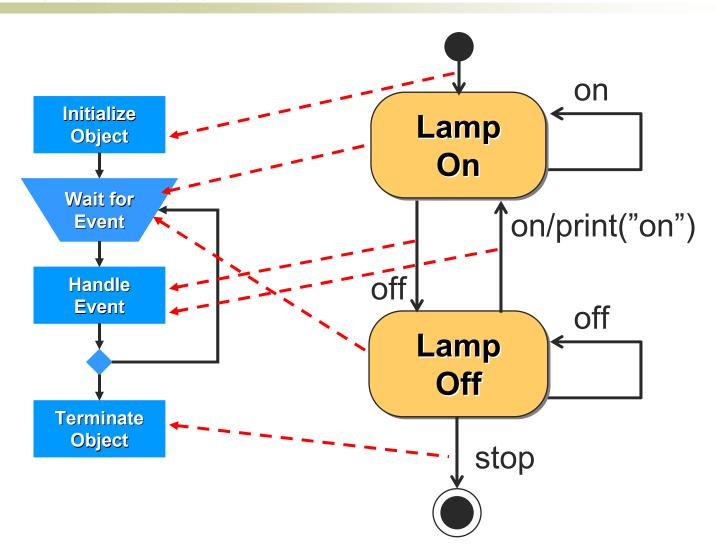
- An active class in UML is one that
 - Starts execution of its behavior as soon as an object of it is created
 - Does not cease until either
 - The behavior defined for it is completed
 - It is terminated by another object
 - So it is also referred to as having its own thread of control
- The points at which an object of an active class responds to communication is determined solely by its behavior and not by the invoking object
- Presentation
 - An active class is shown by a class box with additional vertical bars on the sides



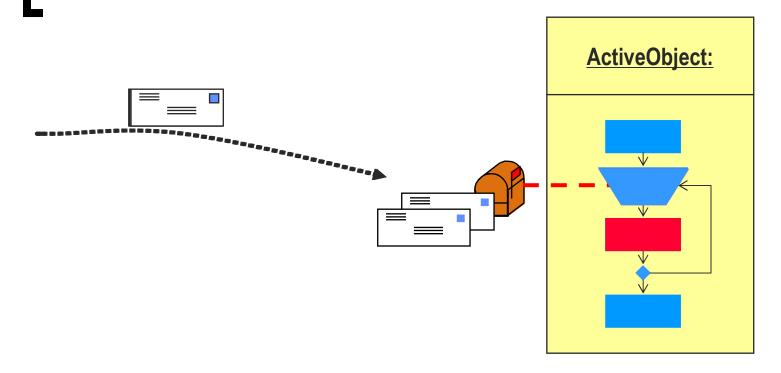
Object Behavior Model



Object Behavior and State Machines



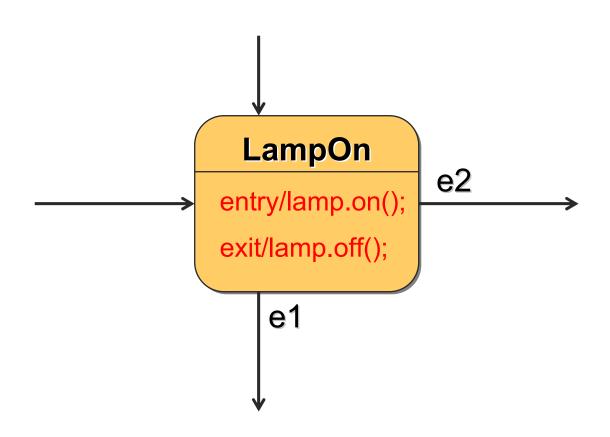
Dynamic Semantics of Active Objects



Run-to-completion model

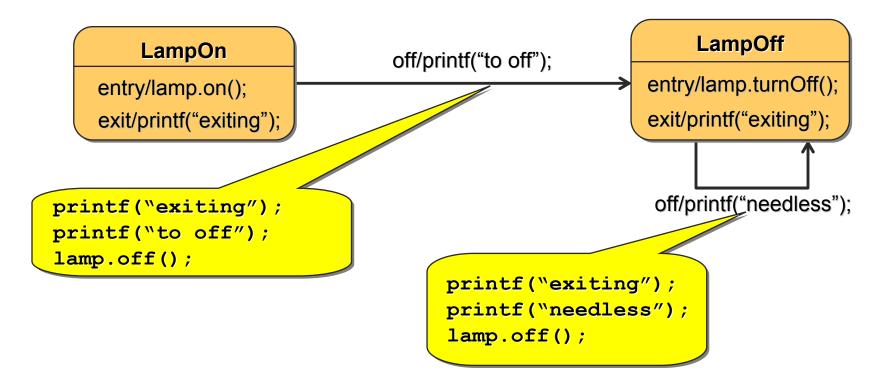
- Serialized event handling
- Eliminates internal concurrency
- Minimal context switching overhead

State entry and exit actions



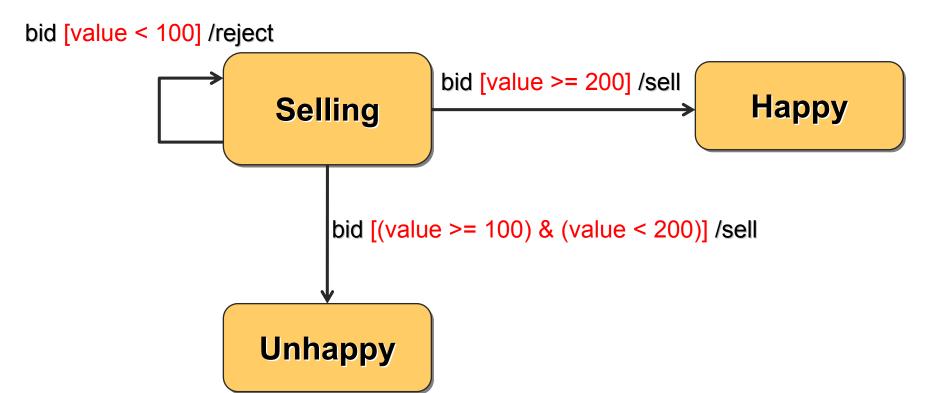
Order of actions

- Exit actions prefix transition actions
- Entry actions postfix transition actions



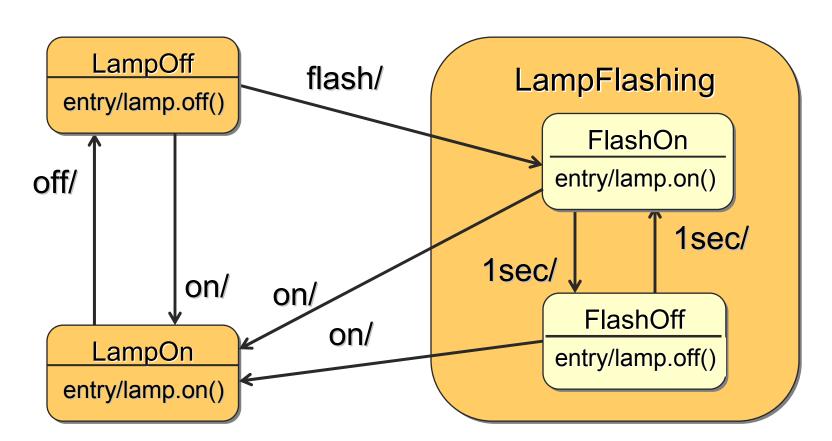
Guards

- Boolean predicates on transitions
- Must be side-effects free

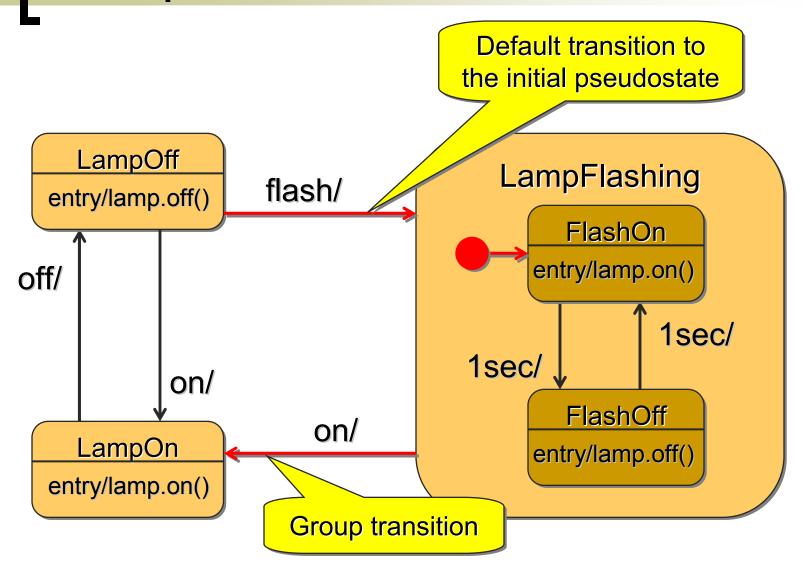


Hierarchical State Machines

- Gradual attack on complexity
- States decomposed into state machines

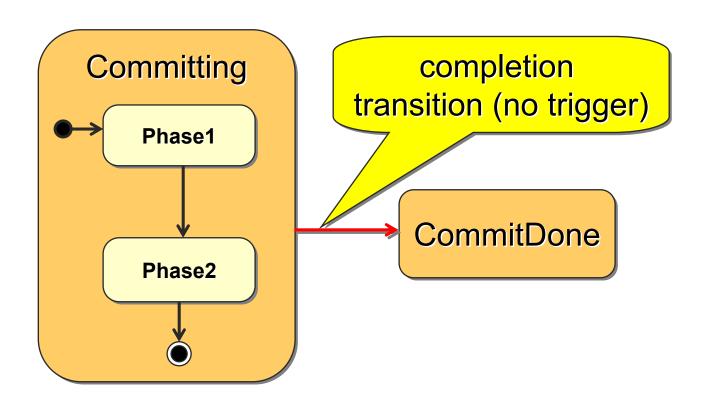


Group Transitions



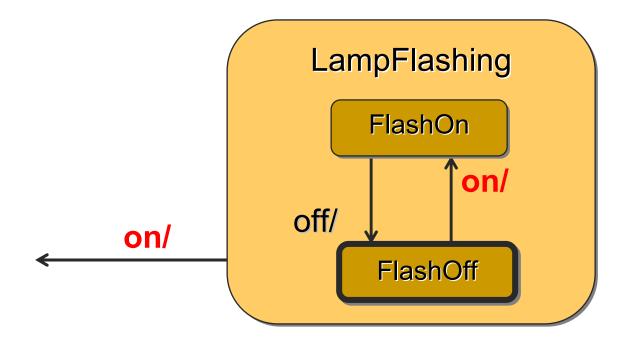
Completion Transitions

 Triggered automatically when a nested state machine reaches the final state

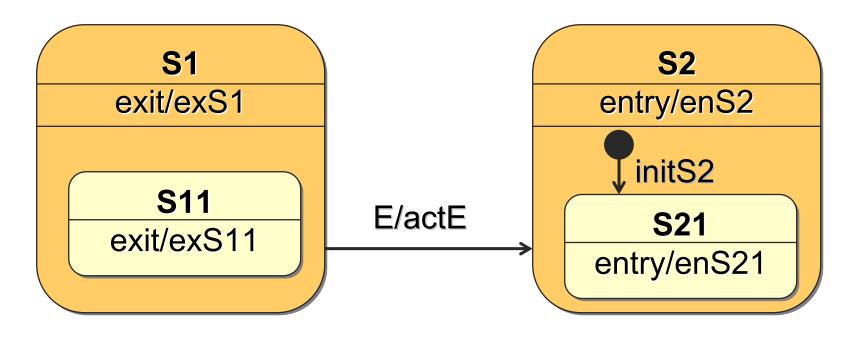


Triggering Rules

- Two or more transitions may have same trigger
 - Innermost takes precedence
 - Event is discarded whether or not a transition is triggered



Order of Actions (Complex Case)



The sequence of actions is as follows:

exS11 ⇒ exS1 ⇒ actE ⇒ enS2 ⇒ initS2 ⇒ enS21