

OPERATING SYSTEMS CSCI-SHU215

Lesson 08 - Synchronization

Context

Context switching

Multi-concurrent programming

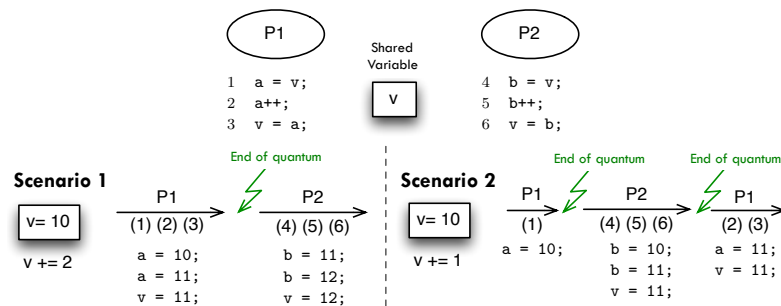
Shared Memory

Modification of a variable value visible by several processes

Consequence: Nondeterministic executions

ie. 2 runs of the same program can produce \neq results

Nondeterminism - Example



Definitions

Critical resource

Resource shared among multiple processes

Consistency \Rightarrow access control (eg. *mutual exclusion*)

Critical Section (CS)

Portion of code that manipulates one or more critical resources

CS execution must be *indivisible*

Indivisibility

Two CSs on a same critical resource must never be executed in parallel

Definitions

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Synchronization

Operation that affects the progress of a set of processes
Establishment of an order of occurrence between types of instructions
eg. *send / receive*
Enforcement of a condition
eg. *rendez-vous, mutual exclusion*

Mutual exclusion

Control mechanism to access CS
Special case of synchronization
Provides exclusive access for **one** process at a time
ie. *no more than one process in CS at any time*

Definitions

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Busy waiting

Repeated execution of a synchronization primitive
Until condition of synchronization is verified
=> CPU greedy!

Deadlock

Two (or more) processes wait for each other to carry out competing actions
=> No escape!



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Mutual Exclusion

Mutual exclusion

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Properties

Safety - No more than one process in CS
Liveness – Eventually, all access requests to the CS get served

Mutual exclusion

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```
EnterCS ();
/* CS Instructions */
LeaveCS ();
```

EnterCS () and LeaveCS () must be indivisible (atomic)

Naive solution

EnterCS () and LeaveCS () = System calls
Hide ITs during execution

Mutual exclusion

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Mechanism 1 – Masking of the Clock IT

Disable timesharing when CS gets executed

EnterCS masks Clock IT

LeaveCS unmask the Clock IT

Wrong answer!

Risk of monopolizing the processor

Excludes all processes

IT Clock mask is internal to the system

Mutual exclusion

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Mechanism 2 – Spinlock

Boolean variable lock

true if the resource is locked

false if the resource is available

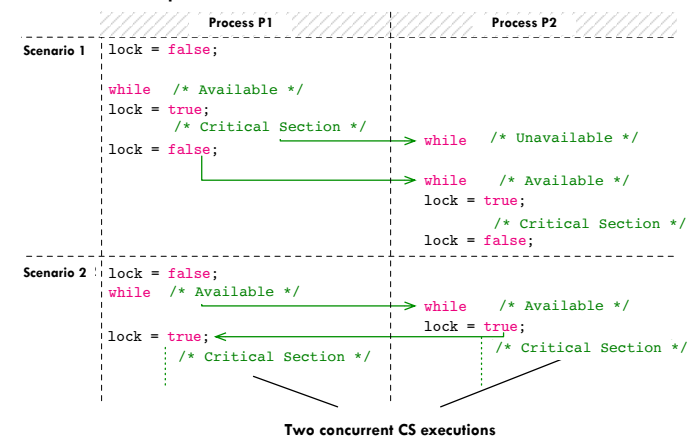
```
bool lock = false;

EnterCS() { while (lock == true);
            lock = true;
            /* CS */
LeaveCS() { lock = false;
```

Mutual exclusion

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Mechanism 2 - Spinlock



Mutual exclusion

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Mechanism 3 – Peterson's algorithm

Mutual exclusion for 2 processes (extensible)

Based on polling and shared variables

flag Array of boolean values shows which processes require the CS
round Integer value indicates the process eligible to access the CS

Code for process *i*

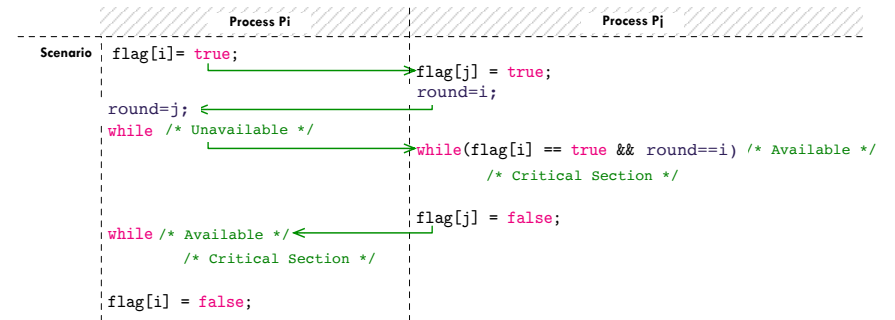
```

EnterCS() [
    flag[i] = true
    round = j
    while (flag[j] == true && round == j)
        /* busy wait */;
    / ** CS ** /
LeaveCS() [ flag[i] = false;
    
```

Mutual exclusion

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Mechanism 3 – Peterson's algorithm



Mutual exclusion

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Mechanism 4 - Test-and-Set

Indivisible block of instructions: assignment & test of a variable value

Based on busy waiting

```

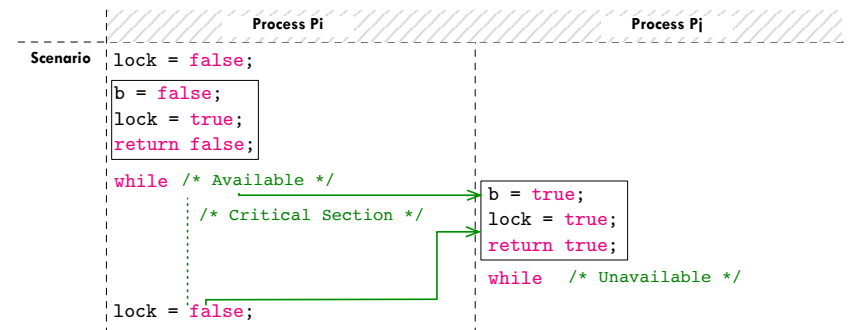
indivisible block
(i.e. masked interrupts)
[
    bool tas(bool v) {
        bool b = v;
        v = true;
        return b;
    }
]

bool lock = false;
EnterCS() [
    busy wait while(tas(lock) == true);
    /* Critical Section */
LeaveCS() [ lock = false;
    
```

Mutual exclusion

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Mechanism 4 - Test-and-Set



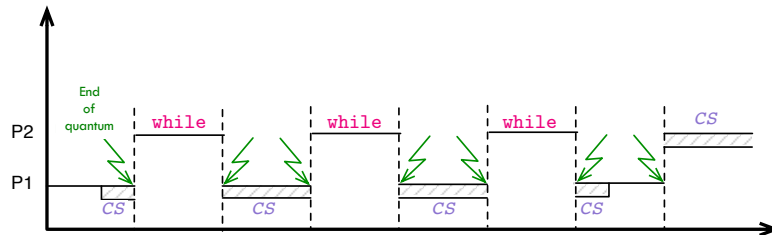
Mutual exclusion

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Performance issue raised by busy waiting

busy waiting consumes CPU time

=> solutions without busy waiting are more effective



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Semaphores

Semaphores

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Principle (Dijkstra)

Synchronization mechanism

- ▣ solves mutual exclusion
- ▣ structure managed by the system and shared between processes
- ▣ no busy waiting

Shared structure

- ▣ a queue contains all blocked processes awaiting access
- ▣ a counter
 - value initialized to the total number of available accesses (≥ 0)
 - value ≥ 0 # of accesses available before blocking
 - value < 0 # of processes stuck in the queue

Semaphores

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Mechanism

- ▣ Request access (P - *proberen* or "*procure*")
 - ▣ Decrement counter
 - ▣ If counter < 0 , then block calling process and insert it in the queue
- ▣ Release access (V - *verhogen* or "*vacate*")
 - ▣ Increment counter
 - ▣ If counter ≤ 0 , then extract a process from the queue and unblock it

P and V are indivisible blocks of code (masked ITs)

P can be blocking, V is never blocking

block, unblock, and queue insertion/extraction are implicit

Semaphores

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Main drawback

Frankly *counter intuitive*

Deadlock

Two processes P and Q are blocked
P waits for Q to release its access
&
Q waits for P to release its access

Famine

One process is blocked, waiting for a release that will never happen

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Classic synchronization problems

Classic synchronization problems

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- Mutual exclusion
- Barrier
- Producer / Consumer
- Reader / Writer
- Swimming pool
- Dining philosophers
- Banker
- Elevator
- Smokers
- ...

Classic problems

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Mutual exclusion

□ Problem

Allow no more than one process to access the CS at any time

□ Semaphore implementation

```
init (MUTEX, 1);  
P (MUTEX);  
/ ** CS ** /  
V (MUTEX);
```

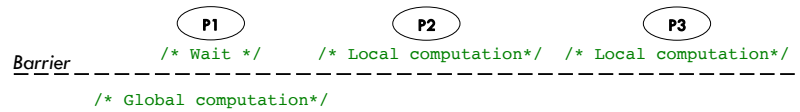
Classic problems

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Barrier

□ Problem

Force a process to wait until all others have carried out their action



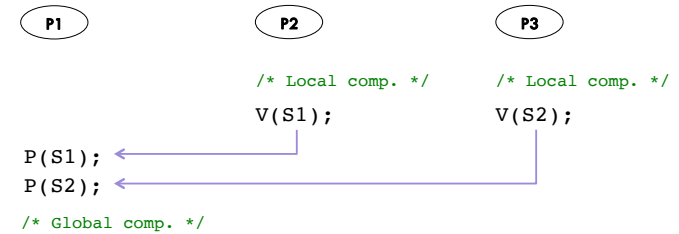
Classic problems

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Barrier

□ Implementation

init(S1, 0); init (S2, 0);

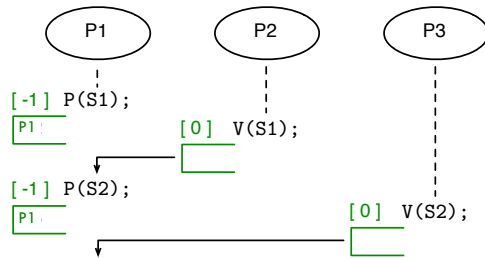


Classic problems

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Barrier

□ Example scenario 1

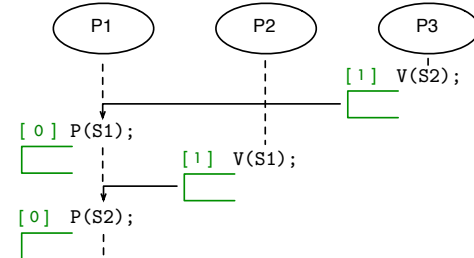


Classic problems

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Barrier

□ Example scenario 2



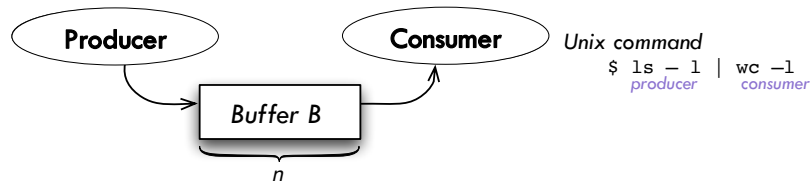
Classic problems

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Producer / Consumer (aka. Bounded Buffer)

□ Problem

Exchange of data in a shared buffer



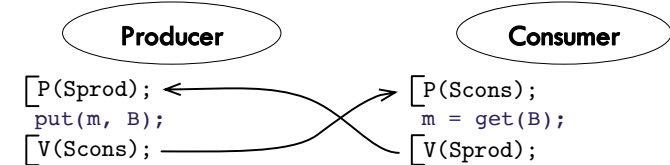
Classic problems

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Producer / Consumer

□ Implementation (single value buffer)

```
init (sprod, 1); init (SCons, 0);
```



Classic problems

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Reader / Writer

□ Problem

Share data in a file

Access constraints

Either N simultaneous read accesses (no write)

Or a single write access (no read)

Classic problems

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Reader / Writer

□ Implementation (Imperfect: possibility of famine)

1 semaphore to enforce file access

1 shared counter (init 0)

stores the current number of read accesses

1 mutex to protect the shared counter

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POSIX Semaphores

Programming with semaphores

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2 types of POSIX semaphores:

- **Named** semaphores
 - ▣ Scope: all processes of the system
 - ▣ Basic primitives: **sem_open**, **sem_close**, **sem_unlink**, **sem_post**, **sem_wait**
- **Unnamed** semaphores (*memory-based*)
 - ▣ Scope: process with filiation, only threads in linux
 - ▣ **Requires a memory space that is shared between processes / threads**
 - ▣ Basic primitives: **sem_init**, **sem_destroy**, **sem_post**, **sem_wait**

Included in the pthread library

```
$ gcc -Wall -o myprog monprog.c -lpthread
```

Named semaphore creation

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```
#include <semaphore.h>
sem_t* sem_open(const char *name, int oflag, mode_t mode, int value);
```

Creates or opens the semaphore called *name*

- ▣ *oflag*
 - O_RDONLY**, **O_WRONLY**, **O_RDWR** : read/write permissions
 - O_CREAT** : create semaphore if it does not exist
 - O_EXCL** : error if **O_CREAT** & semaphore already exists
- ▣ *mode* read/write/execute permissions (**O_CREAT**)
- ▣ *value* initial value of the counter (**O_CREAT**)

Returns a pointer to the semaphore, NULL on error

Ex: Creation of a semaphore initialized with value 10

```
sem_t * s;
s = sem_open ( "mysem", O_CREAT | O_RDWR, 0600, 10);
```

Semaphore operations

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"P"

```
int sem_wait(sem_t* sem);
```

There is a "P" non-blocking ...

```
int sem_trywait(sem_t* sem);
```

"V"

```
sem_post(sem_t* sem);
```

Return -1 on error, 0 otherwise

Closing / Destruction

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Named semaphore

1) Close the semaphore

```
int sem_close(sem_t* sem);
```

2) Destroy the semaphore

```
int sem_unlink(const char *name);
```

Sample code with a named semaphore

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```
-
int main () {
    * sem_t smutex;
    /* Creation of a semaphore mutex initialized to 1 */
    if ((smutex = sem_open ("mysem" O_CREAT | O_EXCL | O_RDWR, 0666, 1)) == SEM_FAILED) {
        if (errno != EEXIST) {
            perror ("sem_open"); exit (1);
        }
        /* Semaphore already created, open without O_CREAT */
        smutex = sem_open("mysem", O_RDWR);
    }

    /* P * on smutex /
    sem_wait (smutex);

    /* V * smutex /
    sem_post (smutex);

    /* Close the semaphore */
    sem_close (smutex);

    /* Destroy the semaphore */
    sem_unlink ("mysem");
    return 0;
}
```