



Sculptura

Software Engineering project

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Introduction

Main goal

The goal of our project was to create a 3D scanning system of human body

Objectives

- Data acquisition with Kinect
- Alignment methods using OpenCV
- Point Cloud registration improvement
- Color meshing
- GUI implementation

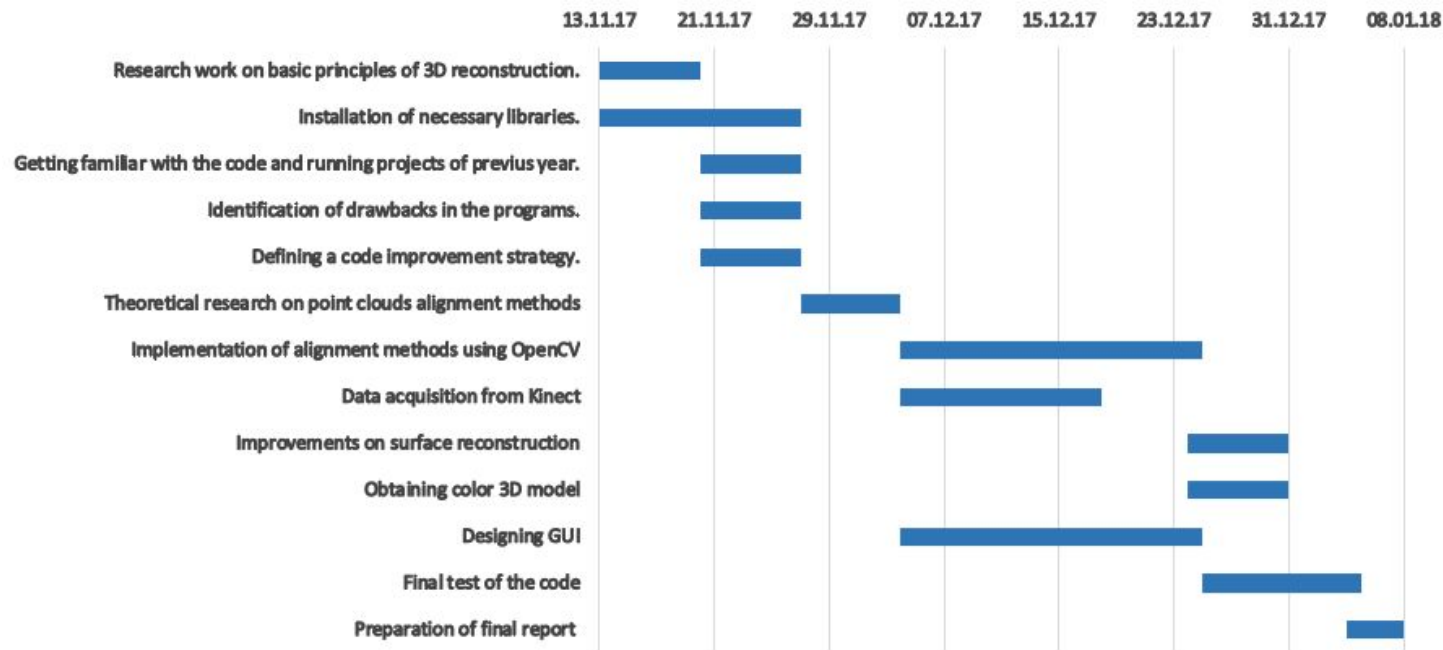
Project management

Roles in a team

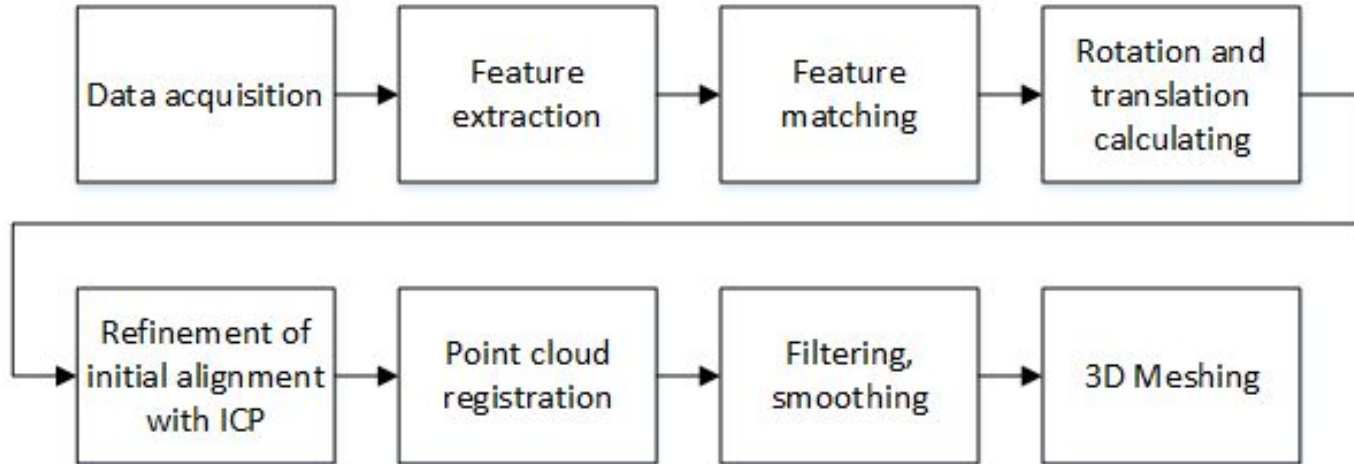
Karim Botros	Kinect data acquisition
Mohamed Ali	Feature operations and point cloud alignment
Elizaveta Genke	3D meshing
Daria Zotova	GUI implementation

Project management

Time management



Software design

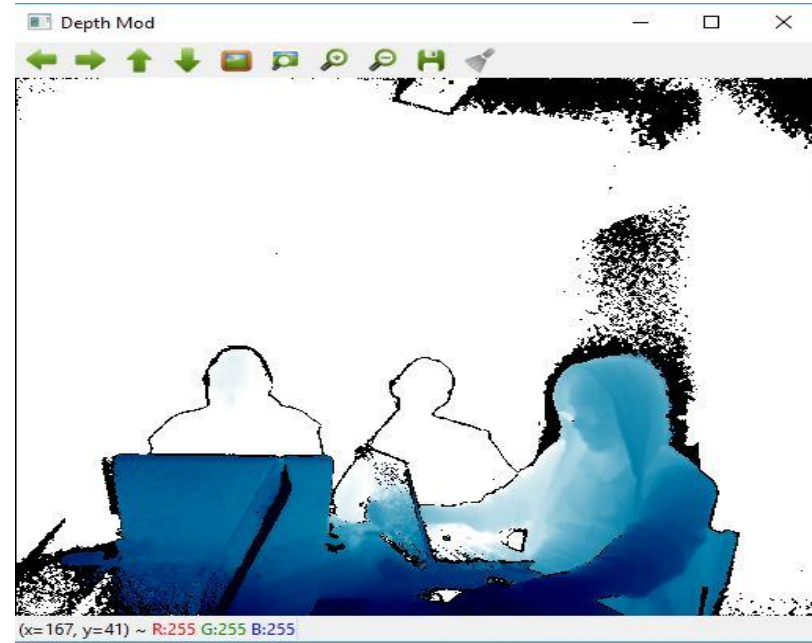
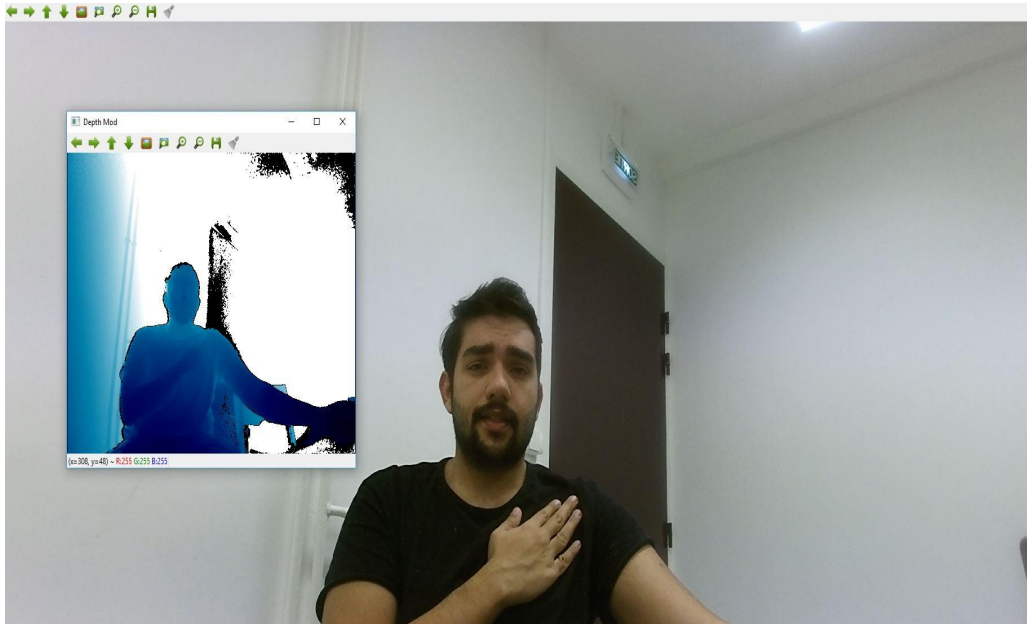


Data acquisition

- Principles of work
- Different kinds of data
- No null frame “Safe-Release”



Data acquisition



Point Cloud Registration

Iterative Closest Point (ICP)

- **Given:** Two corresponding point sets (clouds)

$$P = \{\mathbf{p}_1, \dots, \mathbf{p}_n\}$$

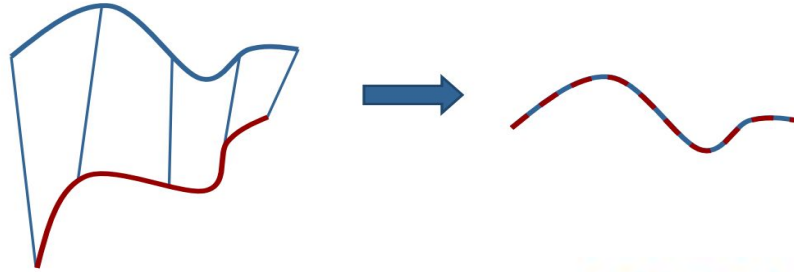
$$Q = \{\mathbf{q}_1, \dots, \mathbf{q}_n\}$$

- **Wanted:** Translation \mathbf{t} and rotation R that minimize the sum of the squared error

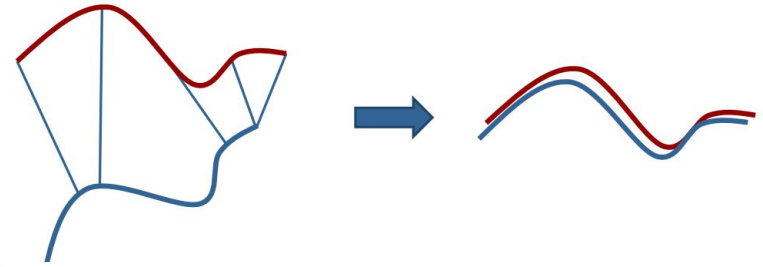
$$E(R, \mathbf{t}) = \frac{1}{n} \sum_{i=1}^n \|\mathbf{p}_i - R\mathbf{q}_i - \mathbf{t}\|^2$$

where \mathbf{p}_i and \mathbf{q}_i are corresponding points

Known Correspondences



Unknown Correspondences



ICP Algorithm

[Besl & McKay, 92]



Selecting Source Points

- Use all points
- Random sampling
- Spatially uniform sub-sampling
- Feature-based sampling

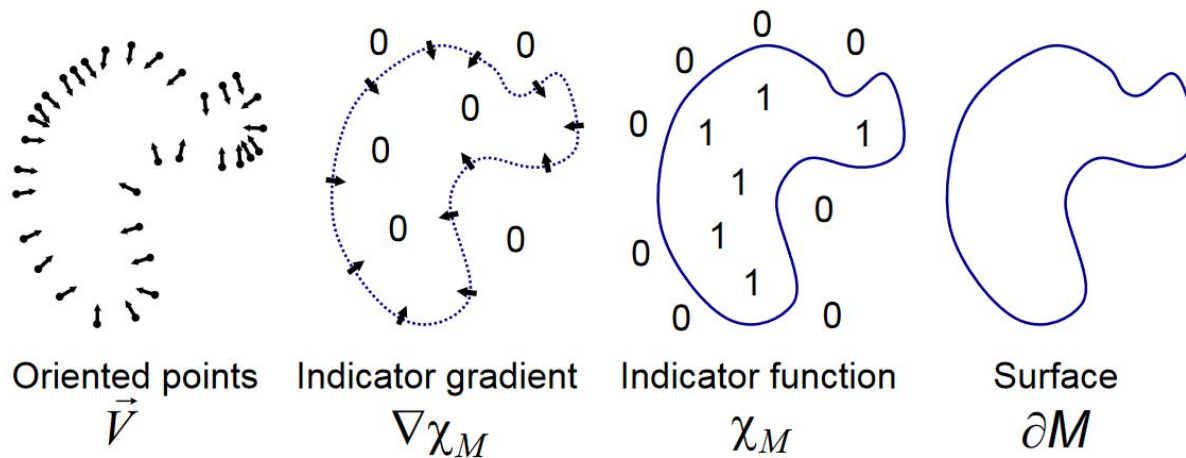


Feature-based Sampling

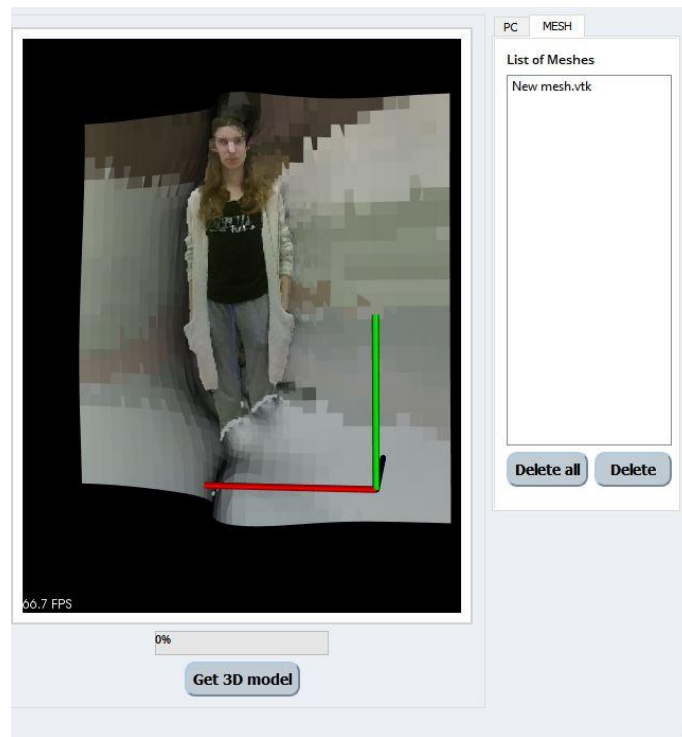
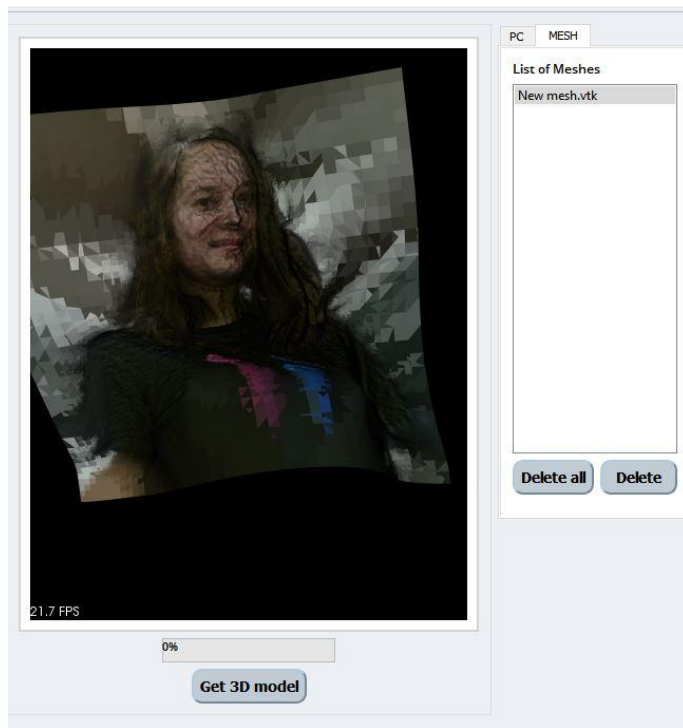
Detect interest points (same as with images)

- Decrease the number of correspondences
- Increase efficiency and accuracy
- Requires pre-processing

3D meshing



3D meshing

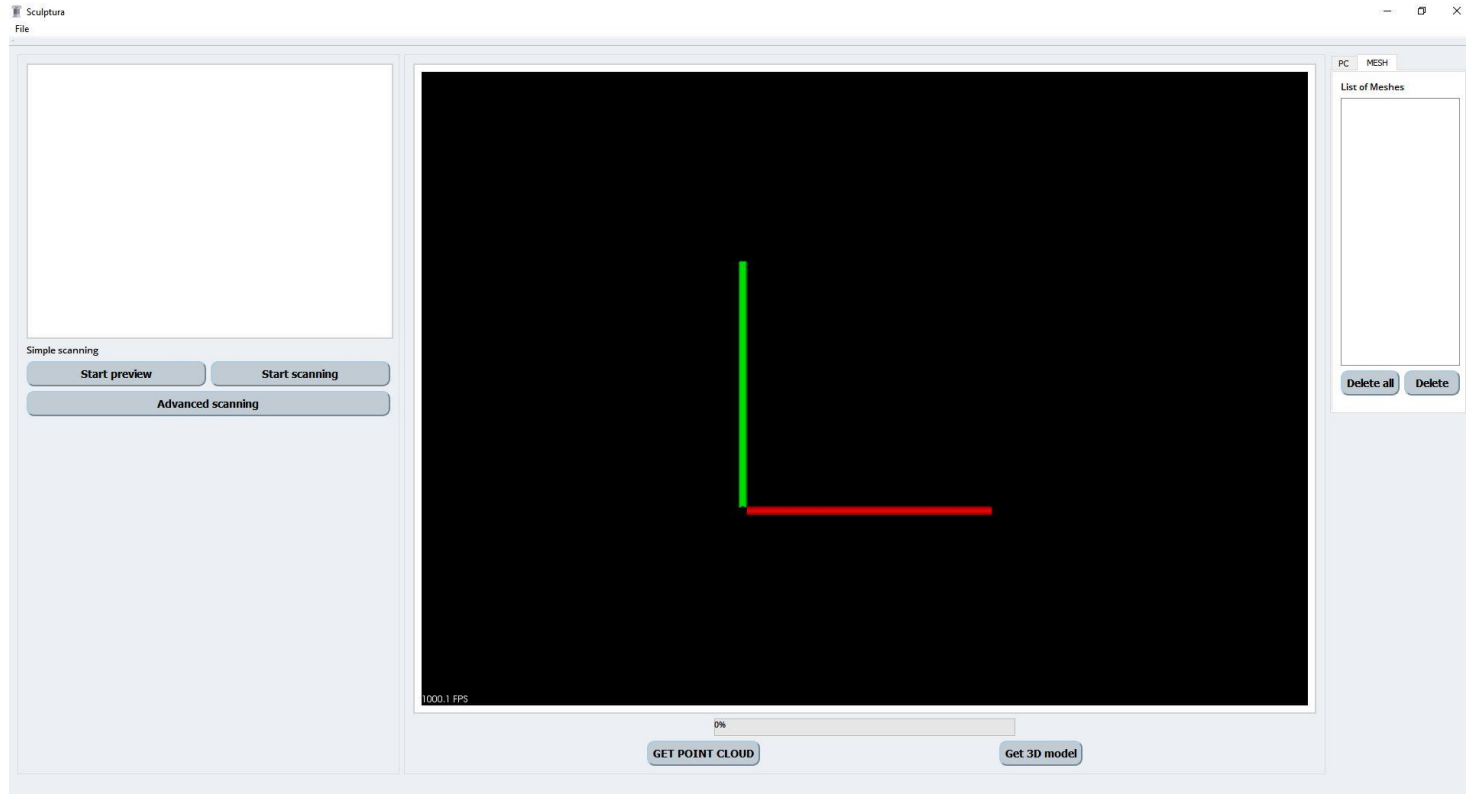


GUI implementation

Requirements

- Implementation in Qt Designer
- Simplicity of usage
- Usability in Software Design
- Minimum interactions to get final result

GUI implementation



Thank you for your attention.