

ESTIMATION OF ALL PARAMETERS IN THE FRACTIONAL ORNSTEIN-UHLENBECK MODEL UNDER DISCRETE OBSERVATIONS

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ABSTRACT. Let the Ornstein-Uhlenbeck process $(X_t)_{t \geq 0}$ driven by a fractional Brownian motion B^H described by $dX_t = -\theta X_t dt + \sigma dB_t^H$ be observed at discrete time instants $t_k = kh$, $k = 0, 1, 2, \dots, 2n+2$. We propose an ergodic type statistical estimator $\hat{\theta}_n$, \hat{H}_n and $\hat{\sigma}_n$ to estimate all the parameters θ , H and σ in the above Ornstein-Uhlenbeck model simultaneously. We prove the strong consistence and the rate of convergence of the estimator. The step size h can be arbitrarily fixed and will not be forced to go zero, which is usually a reality. The tools to use are the generalized moment approach (via ergodic theorem) and the Malliavin calculus.

1. INTRODUCTION

The Ornstein-Uhlenbeck process $(X_t)_{t \geq 0}$ is described by the following Langevin equation:

$$dX_t = -\theta X_t dt + \sigma dB_t^H, \quad (1.1)$$

where $\theta > 0$ so that the process is ergodic and where for simplicity of the presentation we assume $X_0 = 0$. Other initial value can be treated exactly in the same way. We assume that the process $(X_t)_{t \geq 0}$ is observed at discrete time instants $t_k = kh$ and we want to use the observations $\{X_h, X_{2h}, \dots, X_{(2n+2)h}\}$ to estimate the parameters θ , H and σ that appear in the above Langevin equation simultaneously.

Before we continue let us briefly recall some recent relevant works obtained in literature. Most of the works deal with the estimator of the drift parameter θ . In fact, when the Ornstein-Uhlenbeck process $(X_t)_{t \geq 0}$ can be observed continuously and when the parameters σ and H are assumed to be known, we have the following results :

1. The maximum likelihood estimator for θ defined by θ_T^{mle} is studied [14] (see also the references therein for earlier references), and is proved to be strongly consistent. The asymptotic behavior of the bias and the mean square of θ_T^{mle} is also given. In this paper, a strongly consistent estimator of σ is also proposed.
2. A least squares estimator defined by $\tilde{\theta}_T = \frac{-\int_0^T X_t dX_t}{\int_0^T X_t^2}$ was studied in [3, 7, 8].

It is proved that $\tilde{\theta}_T \rightarrow \theta$ almost surely as $T \rightarrow \infty$. It is also proved that

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when $H \leq 3/4$, $\sqrt{T}(\tilde{\theta}_T - \theta)$ converges in law to a mean zero normal random variable. The variance of this normal variable is also obtained. When $H \geq 3/4$, the rate of convergence is also known [8].

Usually in reality the process can only be observed at discrete times $\{t_k = kh, k = 1, 2, \dots, n\}$ for some fixed observation time lag $h > 0$. In this very interesting case, there are very limited works. Let us only mention two ([9, 13]). To the best of knowledge there is only one work [2] that estimates all the parameters θ , H and σ at the same time, but the observations are assumed to be made continuously.

The diffusion coefficient σ represents the “volatility” and it is commonly believed that it should be computed (hence estimated) by the $1/H$ variations (see [8] and references therein). To use the $1/H$ variations one has to assume the process can be observed continuously (or we have high frequency data). Namely, it is a common belief that σ can only be estimated when one has high frequency data.

In this work, we assume that the process can only be observed at discrete times $\{t_k = kh, k = 1, 2, \dots, n\}$ for some fixed observation time lag $h > 0$ (without the requirement that $h \rightarrow 0$). We want to estimate θ , H and σ simultaneously. The idea we use is the ergodic theorem, namely, we find the explicit form of the limit distribution of $\frac{1}{n} \sum_{k=1}^n f(X_{kh})$ and use it to estimate our parameters. People may naturally think that if we appropriately choose three different f , then we may obtain three different equations to obtain all the three parameters θ , H and σ .

However, this is impossible since as long as we proceed this way, we shall find out that whatever we choose f , we cannot get independent equations. Motivated by a recent work [4], we may try to add the limit distribution of $\frac{1}{n} \sum_{k=1}^n g(X_{kh}, X_{(k+1)h})$ to find all the parameters. However, this is still impossible because regardless how we choose f and g we obtain only two independent equations. This is because regardless how we choose f and g the limits depends only on the covariance of the limiting Gaussians (see Y_0 and Y_h ulteriorly). Finally, we propose to use the following quantities to estimate all the three parameters θ , H and σ :

$$\frac{\sum_{k=1}^n X_{kh}^2}{n}, \quad \frac{\sum_{k=1}^n X_{kh} X_{kh+h}}{n}, \quad \frac{\sum_{k=1}^n X_{kh} X_{kh+2h}}{n}. \quad (1.2)$$

We shall study the strong consistence and joint limiting law of our estimators. The above three series converge to $\mathbb{E}(Y_0^2)$, $\mathbb{E}(Y_0 Y_h)$, and $\mathbb{E}(Y_0 Y_{2h})$ respectively. It should be emphasized that it seems that we cannot use the joint distribution of Y_0, Y_h alone to estimate all the three parameters θ , H and σ , we need to the joint distribution of Y_0, Y_h, Y_{2h} .

The paper is organized as follows. In Section 2, we recall some known results. The construction and the strong consistency of the estimators are provided in Section 3. Central limit theorems are obtained in Section 4. To make the paper more readable, we delay some proofs in Append A. To use our estimators we need the determinant of some functions to be nondegenerate. This is given in Appendix B. Some numerical simulations to validate our estimators are illustrated in Appendix C.

2. PRELIMINARIES

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a complete probability space. The expectation on this space is denoted by \mathbb{E} . The fractional Brownian motion $(B_t^H, t \in \mathbb{R})$ with Hurst parameter

$H \in (0, 1)$ is a zero mean Gaussian process with the following covariance structure:

$$\mathbb{E}(B_t^H B_s^H) = R_H(t, s) = \frac{1}{2}(|t|^{2H} + |s|^{2H} - |t-s|^{2H}), \quad \forall t, s \in \mathbb{R}. \quad (2.1)$$

On stochastic analysis of this fractional Brownian motion, such as stochastic integral $\int_a^b f(t)dB_t^H$, chaos expansion, and stochastic differential equation $dX_t = b(X_t)dt + \sigma(X_t)dB_t^H$ we refer to [1].

For any $s, t \in \mathbb{R}$, we define

$$\langle I_{[0,t]}, I_{[0,s]} \rangle_{\mathcal{H}} = R_H(s, t), \quad (2.2)$$

where $I_{[a,b]}$ denotes the indicate function on $[a, b]$ and we use $I_{[b,a]} = -I_{[a,b]}$ for any $a < b$. We can first extend this scalar product to general elementary functions $f(\cdot) = \sum_{i=1}^n a_i I_{[0,s_i]}(\cdot)$ by (bi-)linearity and then to general function by a limiting argument. We can then obtain the reproducing kernel Hilbert space, denoted by \mathcal{H} , associated with this Gaussian process B_t^H (see e.g. [7] for more details).

Let \mathcal{S} be the space of smooth and cylindrical random variables of the form

$$F = f(B^H(\phi_1), \dots, B^H(\phi_n)), \quad \phi_1, \dots, \phi_n \in C_0^\infty([0, T]),$$

where $f \in C_b^\infty(\mathbf{R}^n)$ and $B^H(\phi) = \int_0^\infty \phi(t)dB_t^H$. For such a variable F , we define its Malliavin derivative as the \mathcal{H} valued random element:

$$DF = \sum_{k=1}^n \frac{\partial f}{\partial x_i}(B^H(\phi_1), \dots, B^H(\phi_n))\phi_i.$$

We shall use the following result in Section 4 to obtain the central limit theorem. We refer to [6] and many other references for a proof.

Proposition 2.1. *Let $\{F_n, n \geq 1\}$ be a sequence of random variables in the space of p th Wiener Chaos, $p \geq 2$, such that $\lim_{n \rightarrow \infty} \mathbb{E}(F_n^2) = \sigma^2$. Then the following statements are equivalent:*

- (i) F_n converges in law to $N(0, \sigma^2)$ as n tends to infinity.
- (ii) $\|DF_n\|_{\mathcal{H}}^2$ converges in L^2 to a constant as n tends to infinity.

3. ESTIMATORS OF θ, H AND σ

If $X_0 = 0$, then the solution X_t to (1.1) can be expressed as

$$X_t = \sigma \int_0^t e^{-\theta(t-s)} dB_s^H. \quad (3.1)$$

The associated stationary solution, the solution of (1.1) with the the initial value

$$Y_0 = \int_{-\infty}^0 e^{\theta s} dB_s^H, \quad (3.2)$$

can be expressed as

$$Y_t = \int_{-\infty}^t e^{-\theta(t-s)} dB_s^H = e^{-\theta t} Y_0 + X_t \quad (3.3)$$

and has the same distribution as the limiting normal distribution of X_t (when $t \rightarrow \infty$). Let's consider the following three quantities :

$$\begin{cases} \eta_n = \frac{1}{n} \sum_{k=1}^n X_{kh}^2, \\ \eta_{h,n} = \frac{1}{n} \sum_{k=1}^n X_{kh} X_{kh+h}, \\ \eta_{2h,n} = \frac{1}{n} \sum_{k=1}^n X_{kh} X_{kh+2h}. \end{cases} \quad (3.4)$$

As in [10, Section 1.3.2.2], we have the following ergodic result:

$$\lim_{n \rightarrow \infty} \eta_n = \mathbb{E}(Y_0^2) = \sigma^2 H \Gamma(2H) \theta^{-2H}. \quad (3.5)$$

Now we want to have a similar result for $\eta_{h,n}$. First, let's study the ergodicity of the processes $\{Y_{t+h} - Y_t\}_{t \geq 0}$. According to [11], a centered Gaussian wide-sense stationary process M_t is ergodic if $\mathbb{E}(M_t M_0) \rightarrow 0$ as t tends to infinity. We shall apply this result to $M_t = Y_{t+h} - Y_t, t \geq 0$. Obviously, it is a centered Gaussian stationary process and

$$\mathbb{E}((Y_{t+h} - Y_t)(Y_h - Y_0)) = \mathbb{E}(Y_{t+h} Y_h) - \mathbb{E}(Y_{t+h} Y_0) - \mathbb{E}(Y_t Y_h) + \mathbb{E}(Y_t Y_0).$$

In [5, Theorem 2.3], it is proved that $\mathbb{E}(Y_t Y_0) \rightarrow 0$ as t goes to infinity. Thus, it is easy to see that $\mathbb{E}((Y_{t+h} - Y_t)(Y_h - Y_0)) \rightarrow 0$. Hence, we see that the process $\{Y_{t+h} - Y_t\}_{t \geq 0}$ is ergodic. This implies

$$\frac{\sum_{k=1}^n [Y_{(k+1)h} - Y_{kh}]^2}{n} \xrightarrow{n \rightarrow \infty} \mathbb{E}([Y_h - Y_0]^2).$$

This combined with (3.5) yields the following Lemma.

Theorem 3.1. *Let η_n , $\eta_{h,n}$ and $\eta_{2h,n}$ be defined by (3.4). Then as $n \rightarrow \infty$ we have*

$$\lim_{n \rightarrow \infty} \eta_n = \mathbb{E}(Y_0^2) = \sigma^2 H \Gamma(2H) \theta^{-2H}; \quad (3.6)$$

$$\lim_{n \rightarrow \infty} \eta_{h,n} = \mathbb{E}(Y_0 Y_h) = \sigma^2 \frac{\Gamma(2H+1) \sin(\pi H)}{2\pi} \int_{-\infty}^{\infty} e^{ixh} \frac{|x|^{1-2H}}{\theta^2 + x^2} dx; \quad (3.7)$$

$$\lim_{n \rightarrow \infty} \eta_{2h,n} = \mathbb{E}(Y_0 Y_{2h}) = \sigma^2 \frac{\Gamma(2H+1) \sin(\pi H)}{2\pi} \int_{-\infty}^{\infty} e^{2ixh} \frac{|x|^{1-2H}}{\theta^2 + x^2} dx. \quad (3.8)$$

The explicit expressions of $\mathbb{E}(Y_0 Y_h)$ and $\mathbb{E}(Y_0 Y_{2h})$ are borrowed from [5, Remark 2.4].

From the above theorem we propose the following construction for the estimators of the parameters θ , H and σ .

First let us define

$$\begin{cases} f_1(\theta, H, \sigma) := \sigma^2 H \Gamma(2H) \theta^{-2H}; \\ f_2(\theta, H, \sigma) := \frac{1}{\pi} \sigma^2 \Gamma(2H+1) \sin(\pi H) \int_0^{\infty} \cos(hx) \frac{x^{1-2H}}{\theta^2 + x^2} dx; \\ f_3(\theta, H, \sigma) := \frac{1}{\pi} \sigma^2 \Gamma(2H+1) \sin(\pi H) \int_0^{\infty} \cos(2hx) \frac{x^{1-2H}}{\theta^2 + x^2} dx. \end{cases} \quad (3.9)$$

It is elementary to verify (we fix $h > 0$) that $f_1(\theta, H, \sigma)$, $f_2(\theta, H, \sigma)$, $f_3(\theta, H, \sigma)$ are continuously differentiable functions of $\theta > 0, \sigma > 0$ and $H \in (0, 1)$. and let $f(\theta, H, \sigma) = (f_1(\theta, H, \sigma), f_2(\theta, H, \sigma), f_3(\theta, H, \sigma))^T$ be a vector function defined on $\theta > 0, \sigma > 0$ and $H \in (0, 1)$. Then we set

$$\begin{cases} f_1(\theta, H, \sigma) = \eta_n = \frac{1}{n} \sum_{k=1}^n X_{kh}^2; \\ f_2(\theta, H, \sigma) = \eta_{h,n} = \frac{1}{n} \sum_{k=1}^n X_{kh} X_{kh+h}; \\ f_3(\theta, H, \sigma) = \eta_{2h,n} = \frac{1}{n} \sum_{k=1}^n X_{kh} X_{kh+2h}, \end{cases} \quad (3.10)$$

as a system of three equations for three unknowns (θ, H, σ) . The Jacobian of f , denoted by $J(\theta, H, \sigma)$, is an elementary function whose explicit form can be obtained in a straightforward way. However, this explicit expression is extremely complicated and involves the complicated integrations as well. It is hard to find the range of the parameters analytically so that the determinant of the Jacobian $J(\theta, H, \sigma)$ is not

singular (nonzero). In Appendix B, we shall give a more detailed account for the determinant of the Jacobian $J(\theta, H, \sigma)$ and in particular we shall demonstrate

$$\det(J(\theta, H, \sigma)) \neq 0, \quad \forall (\theta, H, \sigma) \in \mathbb{D}_h, \quad (3.11)$$

where

$$\mathbb{D}_h = \{(\theta, H, \sigma) : 2/h < \theta < 10/h, \quad 0.3 < H < 1, \sigma > 0\}. \quad (3.12)$$

Our approach there is a numerical one. We can try to plot more values to enlarge the domain \mathbb{D}_h . However, we shall not pursue along this direction. By the inverse function theorem, we see that for any point $(\theta_0, H_0, \sigma_0)$ in \mathbb{D}_h , there is a neighbourhood U of $(\theta_0, H_0, \sigma_0)$ and a neighbourhood V of $f(\theta_0, H_0, \sigma_0)$ such that the function f has a continuously differentiable inverse f^{-1} from V to U . From Theorem 3.1 we know that if the true parameter is $(\theta_0, H_0, \sigma_0)$, then $\mathbf{v}_n = (\eta_n, \eta_{h,n}, \eta_{2h,n})$ converges almost surely to $f(\theta_0, H_0, \sigma_0)$ as $n \rightarrow \infty$. This means that there is a $N = N(\omega)$ such that when $n \geq N$, $\mathbf{v}_n = (\eta_n, \eta_{h,n}, \eta_{2h,n}) \in V$. In other words, when n is sufficiently large, the equation (3.10) has a (unique) solution in the neighbourhood of $(\theta_0, H_0, \sigma_0)$.

However, does the equation (3.10) have more than one solution on the domain \mathbb{D}_h ? The global inverse function theorem is much more sophisticated. There are several extension of the Hadamard-Caccioppoli theorem (e.g. [12]). However, it seems that these works can hardly be applied to our situation. It seems impossible to use the determinant alone to determine if a mapping has a global inverse or not. For example, the function $(f(x, y), g(x, y)) = (e^x \cos y, e^x \sin y)$ has a strictly positive determinant on \mathbb{R}^2 . But it is not an injection as a mapping from \mathbb{R}^2 to \mathbb{R}^2 . For this reason we are not going to discuss the uniqueness of the solution to (3.10) on the whole domain \mathbb{D}_h in the present paper.

Theorem 3.2. *If $(\theta, H, \sigma) \in \mathbb{D}_h$, then when n is sufficiently large the equation (3.10) has a solution in \mathbb{D}_h and in a neighbourhood of (θ, H, σ) the solution is unique denoted by $(\tilde{\theta}_n, \tilde{H}_n, \tilde{\sigma}_n)$. Moreover, $(\tilde{\theta}_n, \tilde{H}_n, \tilde{\sigma}_n)$ converge almost surely to (θ, H, σ) as n tends to infinity.*

We shall use $(\tilde{\theta}_n, \tilde{H}_n, \tilde{\sigma}_n)$ to estimate the parameters (θ, H, σ) . We call $(\tilde{\theta}_n, \tilde{H}_n, \tilde{\sigma}_n)$ the ergodic (or generalized moment) estimator of (θ, H, σ) .

It seems hard to explicitly obtain the explicit solution of the system of equation (3.10). However, it is a classical algebraic equations. There are copious numeric approaches to find the approximate solution. We shall give some validation of our estimators numerically in Appendix C.

4. CENTRAL LIMIT THEOREM

In this section, we shall prove central limit theorem associated with our ergodic estimator $(\tilde{\theta}_n, \tilde{H}_n, \tilde{\sigma}_n)$. We shall prove that $\sqrt{n}(\tilde{\theta}_n - \theta, \tilde{H}_n - H, \tilde{\sigma}_n - \sigma)$ converge in law to a mean zero normal vector.

Let's first consider the random variable F_n defined by

$$F_n = \begin{pmatrix} \sqrt{n}(\eta_n - \mathbb{E}(\eta_n)) \\ \sqrt{n}(\eta_{h,n} - \mathbb{E}(\eta_{h,n})) \\ \sqrt{n}(\eta_{2h,n} - \mathbb{E}(\eta_{2h,n})) \end{pmatrix}. \quad (4.1)$$

Our first goal is to show that F_n converges in law to a multivariate normal distribution using Proposition 2.1. So we consider a linear combination:

$$G_n = \alpha \sqrt{n}(\eta_n - \mathbb{E}(\eta_n)) + \beta \sqrt{n}(\eta_{h,n} - \mathbb{E}(\eta_{h,n})) + \gamma \sqrt{n}(\eta_{2h,n} - \mathbb{E}(\eta_{2h,n})), \quad (4.2)$$

and show that it converges to a normal distribution.

We will use the following Feynman diagram formula [6], where interested readers can find a proof.

Proposition 4.1. *Let X_1, X_2, X_3, X_4 be jointly Gaussian random variables with mean zero. Then*

$$\mathbb{E}(X_1 X_2 X_3 X_4) = \mathbb{E}(X_1 X_2) \mathbb{E}(X_3 X_4) + \mathbb{E}(X_1 X_3) \mathbb{E}(X_2 X_4) + \mathbb{E}(X_1 X_4) \mathbb{E}(X_2 X_3).$$

An immediate consequence of this result is

Proposition 4.2. *Let X_1, X_2, X_3, X_4 be jointly Gaussian random variables with mean zero. Then*

$$\begin{cases} \mathbb{E}[(X_1 X_2 - \mathbb{E}(X_1 X_2))(X_3 X_4 - \mathbb{E}(X_3 X_4))] \\ \quad = \mathbb{E}(X_1 X_3) \mathbb{E}(X_2 X_4) + \mathbb{E}(X_1 X_4) \mathbb{E}(X_2 X_3); & (4.3) \\ \mathbb{E}[(X_1^2 - \mathbb{E}(X_1^2))(X_2 X_3 - \mathbb{E}(X_2 X_3))] = 2 \mathbb{E}(X_1 X_2) \mathbb{E}(X_1 X_3); & (4.4) \\ \mathbb{E}[(X_1^2 - \mathbb{E}(X_1^2))(X_2^2 - \mathbb{E}(X_2^2))] = 2 [\mathbb{E}(X_1 X_2)]^2. & (4.5) \end{cases}$$

Theorem 4.3. *Let $H \in (0, 1/2) \cup (1/2, 1)$. Let X_t be the Ornstein-Uhlenbeck process defined by equation (1.1) and let $\eta_n, \eta_{h,n}, \eta_{2h,n}$ be defined by (3.4). Then*

$$\begin{pmatrix} \sqrt{n}(\eta_n - \mathbb{E}(\eta_n)) \\ \sqrt{n}(\eta_{h,n} - \mathbb{E}(\eta_{h,n})) \\ \sqrt{n}(\eta_{2h,n} - \mathbb{E}(\eta_{2h,n})) \end{pmatrix} \rightarrow N(0, \Sigma), \quad (4.6)$$

where $\Sigma = (\Sigma(i, j))_{1 \leq i, j \leq 3}$ is a symmetric matrix whose elements are given by

$$\begin{cases} \Sigma(1, 1) = \Sigma(2, 2) = \Sigma(3, 3) = 2 [\mathbb{E}(Y_0^2)]^2 + 4 \sum_{m=0}^{\infty} [\mathbb{E}(Y_0 Y_{mh})]^2; & (4.7) \end{cases}$$

$$\begin{cases} \Sigma(1, 2) = \Sigma(2, 1) = \Sigma(2, 3) = \Sigma(3, 2) = 4 \sum_{m=0}^{\infty} \mathbb{E}(Y_0 Y_{mh}) \mathbb{E}(Y_0 Y_{(m+1)h}); & (4.8) \end{cases}$$

$$\begin{cases} \Sigma(1, 3) = \Sigma(3, 1) = 4 \sum_{m=0}^{\infty} \mathbb{E}(Y_0 Y_{2mh}) \mathbb{E}(Y_0 Y_{2mh+2h}). & (4.9) \end{cases}$$

Remark 4.4. (1) It is easy from the following proof to see that all entries $\Sigma(i, j)$ of the covariance matrix Σ are finite.

(2) In an earlier work of Hu and Song it is said [9, Equation (19.19)] that the variance Σ (corresponding to our $\Sigma(1, 1)$ in our notation) is independent of the time lag h . But there was an error on the bound of A_n on [9, page 434, line 14]. So, A_n there does not go to zero. Its limit is re-calculated in this work.

Proof We write

$$\mathbb{E}(G_n^2) = (\alpha, \beta, \gamma) \Sigma_n (\alpha, \beta, \gamma)^T, \quad \Sigma_n = (\Sigma_n(i, j))_{1 \leq i, j \leq 3},$$

where Σ_n is a symmetric 3×3 matrix given by

$$\begin{cases} \Sigma_n(1, 1) = n\mathbb{E}[(\eta_n - \mathbb{E}(\eta_n))^2] ; \\ \Sigma_n(1, 2) = \Sigma_n(2, 1) = n\mathbb{E}[(\eta_n - \mathbb{E}(\eta_n))(\eta_{h,n} - \mathbb{E}(\eta_{h,n}))] ; \\ \Sigma_n(1, 3) = \Sigma_n(3, 1) = n\mathbb{E}[(\eta_n - \mathbb{E}(\eta_n))(\eta_{2h,n} - \mathbb{E}(\eta_{2h,n}))] ; \\ \Sigma_n(2, 2) = n\mathbb{E}[(\eta_{h,n} - \mathbb{E}(\eta_{h,n}))^2] ; \\ \Sigma_n(2, 3) = \Sigma_n(3, 2) = n\mathbb{E}[(\eta_{h,n} - \mathbb{E}(\eta_{h,n}))(\eta_{2h,n} - \mathbb{E}(\eta_{2h,n}))] ; \\ \Sigma_n(3, 3) = n\mathbb{E}[(\eta_{2h,n} - \mathbb{E}(\eta_{2h,n}))^2] . \end{cases}$$

It is easy to observe that

- (1) the limits of $\Sigma_n(1, 1)$, $\Sigma_n(2, 2)$, and $\Sigma_n(3, 3)$ are the same;
- (2) the limits of $\Sigma_n(1, 2)$, and $\Sigma_n(2, 3)$ are the same;
- (3) the limit of $\Sigma_n(1, 3)$ can be obtained from the limit of $\Sigma_n(1, 2)$ by replacing h by $2h$;
- (4) the matrix is symmetric.

Thus, we only need to compute the limits of $\Sigma_n(1, 1)$ and $\Sigma_n(1, 2)$.

First, we compute the limit of $\Sigma_n(1, 1)$. From the definition (3.4) of η_n and Proposition 4.2, we have

$$\begin{aligned} \Sigma_n(1, 1) &= \frac{1}{n} \sum_{k, k'=1}^n \mathbb{E}[(X_{kh}^2 - \mathbb{E}[(X_{kh})^2])(X_{k'h}^2 - \mathbb{E}[(X_{k'h})^2])] \\ &= \frac{2}{n} \sum_{k, k'=1}^n [\mathbb{E}(X_{kh}X_{k'h})]^2 \end{aligned} \quad (4.10)$$

By Lemma A.2, we see that

$$\Sigma_n(1, 1) \rightarrow \Sigma(1, 1) = 2[\mathbb{E}(Y_0^2)]^2 + 4 \sum_{m=0}^{\infty} [\mathbb{E}(Y_0 Y_{mh})]^2 .$$

This proves (4.7)

Now let consider the limit of $\Sigma_n(1, 2)$. From the definitions (3.4) and from Proposition 4.2 it follows

$$\begin{aligned} \Sigma_n(1, 2) &= \frac{1}{n} \sum_{k, k'=1}^n \mathbb{E}[(X_{kh}^2 - \mathbb{E}[(X_{kh})^2])(X_{k'h}X_{(k'+1)h} - \mathbb{E}[X_{k'h}X_{(k'+1)h}])] \\ &= \frac{2}{n} \sum_{k, k'=1}^n \mathbb{E}(X_{kh}X_{k'h})\mathbb{E}(X_{kh}X_{(k'+1)h}) . \end{aligned} \quad (4.11)$$

By Lemma A.3, we have

$$\Sigma_n(1, 2) \rightarrow 4 \sum_{m=0}^{\infty} \mathbb{E}(Y_0 Y_{mh})\mathbb{E}(Y_0 Y_{(m+1)h}) . \quad (4.12)$$

This proves (4.8). (4.9) is obtained from (4.8) by replacing h by $2h$. This proves

$$\lim_{n \rightarrow \infty} \mathbb{E}(G_n^2) = (\alpha, \beta, \gamma)\Sigma(\alpha, \beta, \gamma)^T . \quad (4.13)$$

using Lemma A.4, we know that $J_n := \langle DG_n, DG_n \rangle_{\mathcal{H}}$ converges to a constant. Then by Proposition 2.1, we know G_n converges in law to a normal random variable.

since G_n converges to a normal for any α , β , and γ , we know by the Cramér-Wold theorem that F_n converges to a mean zero Gaussian random vector, proving the theorem. ■

Now using the delta method and the above Theorem 4.3 we immediately have the following theorem.

Theorem 4.5. *Let $(\theta, H, \sigma) \in \mathbb{D}_h$. Let X_t be the Ornstein-Uhlenbeck process defined by equation (1.1) and let $(\tilde{\theta}_n, \tilde{H}_n, \tilde{\sigma}_n)$ be the ergodic estimator defined by (3.10). Then*

$$\begin{pmatrix} \sqrt{n}(\tilde{\theta}_n - \theta) \\ \sqrt{n}(\tilde{H}_n - H) \\ \sqrt{n}(\tilde{\sigma}_n - \sigma) \end{pmatrix} \xrightarrow{d} N(0, \tilde{\Sigma}),$$

where J denotes the Jacobian matrix of f , studied in Appendix B, Σ is defined in 4.3 and

$$\tilde{\Sigma} = [J(\theta, H, \sigma)]^{-1} \Sigma [J^T(\theta, H, \sigma)]^{-1}. \quad (4.14)$$

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APPENDIX A. DETAILED COMPUTATIONS

First, we need the following lemma.

Lemma A.1. *Let X_t be the Ornstein-Uhlenbeck process defined by (1.1). Then*

$$|\mathbb{E}(X_t X_s)| \leq C(1 \wedge |t - s|^{2H-2}) \leq (1 + |t - s|)^{2H-2}. \quad (\text{A.1})$$

The above inequality also holds true for Y_t .

Proof From [5, Theorem 2.3], we have that

$$\mathbb{E}(Y_s Y_t) \leq C_{H,\theta} |t - s|^{2H-2} \quad \text{for } |t - s| \text{ sufficiently large.} \quad (\text{A.2})$$

But $X_t = Y_t - e^{-\theta t} Y_0$. This combined with (A.2) proves (A.1). ■

Lemma A.2. *Let X_t be defined by (1.1). When $H \in (0, \frac{1}{2}) \cup (\frac{1}{2}, \frac{3}{4})$ we have*

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k,k'=1}^n [\mathbb{E}(X_{kh} X_{k'h})]^2 = [\mathbb{E}(Y_0^2)]^2 + 2 \sum_{m=1}^{\infty} [\mathbb{E}(Y_0 Y_{mh})]^2. \quad (\text{A.3})$$

Proof To simplify notations we shall use X_k, Y_k to represent X_{kh}, Y_{kh} etc. From the relation (3.3) it is easy to see that

$$\begin{aligned} \mathbb{E}(X_k X_{k'}) &= \mathbb{E}(Y_k Y_{k'}) - e^{-\theta k'h} \mathbb{E}(Y_0 Y_k) - e^{-\theta kh} \mathbb{E}(Y_0 Y_{k'}) + e^{-\theta(k+k')h} \mathbb{E}(Y_0^2) \\ &=: \sum_{i=1}^4 I_{i,k,k'}, \end{aligned} \quad (\text{A.4})$$

where $I_{i,k,k'}, i = 1, \dots, 4$, denote the above i -th term.

Let us first consider $\frac{1}{n} \sum_{k,k'=1}^n I_{i,k,k'}^2$ for $i = 2, 3, 4$. First, we consider $i = 2$. By [5, Theorem 2.3], we know that $\mathbb{E}(Y_0 Y_k)$ converges to 0 when $k \rightarrow \infty$. Thus by the Toeplitz theorem, we have

$$\frac{1}{n} \sum_{k,k'=1}^n I_{2,k,k'}^2 = \frac{1}{n} \sum_{k,k'=1}^n e^{-2\theta k'h} [\mathbb{E}(Y_0 Y_k)]^2 \leq C \frac{1}{n} \sum_k [\mathbb{E}(Y_0 Y_k)]^2 \rightarrow 0. \quad (\text{A.5})$$

Exactly in the same way we have

$$\frac{1}{n} \sum_{k,k'=1}^n I_{3,k,k'}^2 \rightarrow 0. \quad (\text{A.6})$$

When $i = 4$, we have easily

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k,k'=1}^n I_{4,k,k'}^2 = \frac{1}{n} \sum_{k,k'=1}^n e^{-2\theta(k+k')h} [\mathbb{E}(Y_0^2)]^2 \rightarrow 0. \quad (\text{A.7})$$

Now we have

$$\begin{aligned} \frac{1}{n} \sum_{k,k'=1}^n [\mathbb{E}(X_k X_{k'})]^2 &= \frac{1}{n} \sum_{i,j=1}^4 \sum_{k,k'=1}^n I_{i,k,k'} I_{j,k,k'} \\ &= \frac{1}{n} \sum_{k,k'=1}^n I_{1,k,k'}^2 + \frac{1}{n} \sum_{i \neq 1, \text{ or } j \neq 1} \sum_{k,k'=1}^n I_{i,k,k'} I_{j,k,k'}. \end{aligned}$$

When one of the i or j is not equal to 1, we have by the Hölder inequality

$$\frac{1}{n} \sum_{k,k'=1}^n |I_{i,k,k'} I_{j,k,k'}| \leq \left(\frac{1}{n} \sum_{k,k'=1}^n I_{i,k,k'}^2 \right)^{1/2} \left(\frac{1}{n} \sum_{k,k'=1}^n I_{j,k,k'}^2 \right)^{1/2}$$

which will go to 0 if we can show $\frac{1}{n} \sum_{k,k'=1}^n I_{1,k,k'}^2, n = 1, 2, \dots$ is bounded. In fact, we have

$$\begin{aligned} \frac{1}{n} \sum_{k,k'=1}^n I_{1,k,k'}^2 &= \frac{1}{n} \sum_{k,k'=1}^n [\mathbb{E}(Y_k Y_{k'})]^2 \\ &= \frac{1}{n} \sum_{k,k'=1}^n [\mathbb{E}(Y_0 Y_{|k'-k|})]^2 \\ &= \mathbb{E}(Y_0^2) + \frac{2}{n} \sum_{m=1}^{n-1} (n-m) [\mathbb{E}(Y_0 Y_m)]^2 \\ &= [\mathbb{E}(Y_0^2)]^2 + 2 \sum_{m=1}^{n-1} [\mathbb{E}(Y_0 Y_m)]^2 - \frac{2}{n} \sum_{m=1}^{n-1} m [\mathbb{E}(Y_0 Y_m)]^2. \quad (\text{A.8}) \end{aligned}$$

By Lemma A.1 for Y_t or an expression of $\mathbb{E}(Y_0 Y_m)$ given in [5, Theorem 2.3]:

$$\mathbb{E}(Y_0 Y_m) = \frac{1}{2} \sigma^2 \sum_{n=1}^N \theta^{-2n} (\Pi_{k=0}^{2n-1} (2H - k)) m^{2H-2n} + O(m^{2H-2N-2}).$$

This means $\mathbb{E}(Y_0 Y_m) = O(m^{2H-2})$ as $m \rightarrow \infty$, which in turn means that $[\mathbb{E}(Y_0 Y_m)]^2 = O(m^{4H-4})$. Hence, for $H < \frac{3}{4}$, $\sum_{m=0}^{n-1} \mathbb{E}(Y_0 Y_m)^2$ converges as n tends to infinity.

Notice that for $H < \frac{3}{4}$, $m \mathbb{E}(Y_0 Y_m)^2 = O(m^{4H-3}) \rightarrow 0$ as $m \rightarrow \infty$. By Toeplitz theorem we have

$$\frac{1}{n} \sum_{m=0}^{n-1} m [\mathbb{E}(Y_0 Y_m)]^2 \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

Thus, $\frac{1}{n} \sum_{k,k' > k} [\mathbb{E}(Y_k Y_{k'})]^2$ converges to $[\mathbb{E}(Y_0^2)]^2 + 2 \sum_{m=1}^{\infty} [\mathbb{E}(Y_0 Y_m)]^2$ as n tends to infinity. ■

Lemma A.3. *Let X_t be defined by (1.1). When $H \in (0, \frac{1}{2}) \cup (\frac{1}{2}, \frac{3}{4})$ we have*

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k,k'=1}^n \mathbb{E}(X_{kh} X_{k'h}) \mathbb{E}(X_{kh} X_{(k'+1)h}) = 2 \sum_{m=0}^{\infty} \mathbb{E}(Y_0 Y_{mh}) \mathbb{E}(Y_0 Y_{(m+1)h}). \quad (\text{A.9})$$

Proof We continue to use the notations in Lemma A.2.

$$\begin{aligned} \mathbb{E}(X_k X_{k'}) &= \sum_{i=1}^4 I_{i,k,k'}, \\ \mathbb{E}(X_k X_{k'+1}) &= \sum_{i=1}^4 I_{i,k,k'+1}, \end{aligned} \quad (\text{A.10})$$

where $I_{i,k,k'}$, $i = 1, \dots, 4$, is defined in (A.5). As in the proof of Lemma A.2, we have

$$\begin{aligned} \lim_{n \rightarrow \infty} \sum_{k,k'=1}^n \mathbb{E}(X_k X_{k'}) \mathbb{E}(X_k X_{k'+1}) &= \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k,k'=1}^n \mathbb{E}(Y_k Y_{k'}) \mathbb{E}(Y_k Y_{k'+1}) \\ &= \frac{1}{n} \sum_{k,k'=1}^n \mathbb{E}(Y_0 Y_{|k'-k|}) \mathbb{E}(Y_0 Y_{|k'+1-k|}) \\ &= \frac{1}{n} \sum_{m=0}^{n-1} (n-m) \mathbb{E}(Y_0 Y_m) \mathbb{E}(Y_0 Y_{m+1}) + \frac{1}{n} \sum_{m=1}^{n-1} (n-m) \mathbb{E}(Y_0 Y_m) \mathbb{E}(Y_0 Y_{m-1}) \end{aligned}$$

Now we can use the same argument as in proof of Lemma A.2 to obtain

$$\lim_{n \rightarrow \infty} \sum_{k,k'=1}^n \mathbb{E}(X_k X_{k'}) \mathbb{E}(X_k X_{k'+1}) = 2 \sum_{m=0}^{\infty} \mathbb{E}(Y_0 Y_m) \mathbb{E}(Y_0 Y_{m+1}),$$

proving the lemma. ■

Let G_n be defined by (4.2) in Section 4. Its Malliavin derivative is given by

$$\begin{aligned} DG_n &= \frac{1}{\sqrt{n}} 2\alpha \sum_{k=1}^n X_k DX_k + \frac{1}{\sqrt{n}} \beta \sum_{k=1}^n (X_k DX_{k+1} + X_{k+1} DX_k) \\ &\quad + \frac{1}{\sqrt{n}} \sum_{k=1}^n \gamma (X_k DX_{k+2} + X_{k+2} DX_k). \end{aligned} \quad (\text{A.11})$$

Lemma A.4. Define the sequence of random variables $J_n := \langle DG_n, DG_n \rangle_{\mathcal{H}}$. Then

$$\lim_{n \rightarrow \infty} \mathbb{E} [J_n - \mathbb{E}(J_n)]^2 = 0. \quad (\text{A.12})$$

Proof It is easy to see that J_n is a linear combination of terms of the following forms (with the coefficients being a quadratic forms of α, β, γ):

$$\begin{aligned} \tilde{J}_n &:= \frac{1}{n} \sum_{k',k=1}^n \langle DX_{k_1}, DX_{k'_1} \rangle_{\mathcal{H}} X_{k_2} X_{k'_2} \\ &= \frac{1}{n} \sum_{k',k=1}^n \mathbb{E}(X_{k_1} X_{k'_1}) X_{k_2} X_{k'_2}, \end{aligned} \quad (\text{A.13})$$

where k_1, k_2 may take $k, k+1, k+2$, and k'_1, k'_2 may take $k', k'+1, k'+2$. For example, one term is to take $k_1 = k_2 = k$ and $k'_1 = k'+1, k'_2 = k'$ which corresponds to the product:

$$\begin{aligned} &\langle \frac{1}{\sqrt{n}} 2\alpha \sum_{k=1}^n X_k DX_k, \frac{1}{\sqrt{n}} \beta \sum_{k=1}^n (X_k DX_{k+1}) \rangle \\ &= \frac{2\alpha\beta}{n} \sum_{k',k=1}^n \mathbb{E}(X_k X_{k'+1}) X_k X_{k'} =: 2\alpha\beta \tilde{J}_{0,n}. \end{aligned} \quad (\text{A.14})$$

We will first give a detail argument to explain why

$$\mathbb{E} [\tilde{J}_{0,n} - \mathbb{E}(\tilde{J}_{0,n})]^2 \rightarrow 0$$

and then we outline the procedure that similar claims hold true for any terms in (A.13). Note that $\mathbb{E}(\tilde{J}_{0,n})$ will not converge to 0.

From the Proposition 4.2 it follows

$$\begin{aligned} \mathbb{E} \left[\tilde{J}_{0,n} - \mathbb{E}(\tilde{J}_{0,n}) \right]^2 &= \frac{1}{n^2} \sum_{k,k',j,j'=1}^n \mathbb{E}(X_k X_{k'+1}) \mathbb{E}(X_j X_{j'+1}) \mathbb{E}(X_k X_j) \mathbb{E}(X_{k'} X_{j'}) \\ &\quad + \frac{1}{n^2} \sum_{k,k',j,j'=1}^n \mathbb{E}(X_k X_{k'+1}) \mathbb{E}(X_j X_{j'+1}) \mathbb{E}(X_k X_{j'}) \mathbb{E}(X_{k'} X_j) \\ &=: I_{1,n} + I_{2,n} . \end{aligned}$$

using (A.1) we have

$$\begin{aligned} I_{1,n} &\leq \frac{1}{n^2} \sum_{k,k',j,j'=1}^n (1 + |k' - k|)^{2H-2} (1 + |j' - j|)^{2H-2} \\ &\quad (1 + |j - k|)^{2H-2} (1 + |k' - j'|)^{2H-2} ; \\ I_{2,n} &\leq \frac{1}{n^2} \sum_{k,k',j,j'=1}^n (1 + |k' - k|)^{2H-2} (1 + |j' - j|)^{2H-2} \\ &\quad (1 + |j' - k|)^{2H-2} (1 + |k' - j|)^{2H-2} . \end{aligned}$$

Now it is elementary to see that $I_{1,n} \rightarrow 0$ and $I_{2,n} \rightarrow 0$ when $n \rightarrow \infty$.

Now we deal with the general term

$$\tilde{J}_{1,n} := \frac{1}{n} \sum_{k',k=1}^n \mathbb{E}(X_{k_1} X_{k'_1}) X_{k_2} X_{k'_2}$$

in (A.13), where k_1, k_2 may take $k, k+1, k+2$, and k'_1, k'_2 may take $k', k'+1, k'+2$.

We use Proposition 4.2 to obtain

$$\begin{aligned} \mathbb{E} \left[\tilde{J}_{1,n} - \mathbb{E}(\tilde{J}_{1,n}) \right]^2 &= \frac{1}{n^2} \sum_{k,k',j,j'=1}^n \mathbb{E}(X_{k_1} X_{k'_1}) \mathbb{E}(X_{j_1} X_{j'_1}) \mathbb{E}(X_{k_2} X_{j_2}) \mathbb{E}(X_{k'_2} X_{j'_2}) \\ &\quad + \frac{1}{n^2} \sum_{k,k',j,j'=1}^n \mathbb{E}(X_{k_1} X_{k'_1}) \mathbb{E}(X_{j_1} X_{j'_1}) \mathbb{E}(X_{k_2} X_{j'_2}) \mathbb{E}(X_{k'_2} X_{j_2}) \\ &=: \tilde{I}_{1,n} + \tilde{I}_{2,n} , \end{aligned}$$

where k_1, k_2 may take $k, k+1, k+2$, and k'_1, k'_2 may take $k', k'+1, k'+2$, j_1, j_2 may take $j, j+1, j+2$, and j'_1, j'_2 may take $j', j'+1, j'+2$. using (A.1) we have

$$\begin{aligned} \tilde{I}_{1,n} &\leq \frac{1}{n^2} \sum_{k,k',j,j'=1}^n (1 + |k' - k|)^{2H-2} (1 + |j' - j|)^{2H-2} \\ &\quad (1 + |j - k|)^{2H-2} (1 + |k' - j'|)^{2H-2} ; \\ \tilde{I}_{2,n} &\leq \frac{1}{n^2} \sum_{k,k',j,j'=1}^n (1 + |k' - k|)^{2H-2} (1 + |j' - j|)^{2H-2} \\ &\quad (1 + |j' - k|)^{2H-2} (1 + |k' - j|)^{2H-2} . \end{aligned}$$

Now it is elementary to see that $\tilde{I}_{1,n} \rightarrow 0$ and $\tilde{I}_{2,n} \rightarrow 0$ when $n \rightarrow \infty$. ■

APPENDIX B. DETERMINANT OF THE JACOBIAN OF f

The goal of this section is to compute the determinant of the Jacobian of

$$f(\theta, H, \sigma) = \begin{cases} \frac{1}{\pi} \sigma^2 \Gamma(2H+1) \sin(\pi H) \int_0^\infty \frac{x^{1-2H}}{\theta^2+x^2} dx; \\ \frac{1}{\pi} \sigma^2 \Gamma(2H+1) \sin(\pi H) \int_0^\infty \cos(hx) \frac{x^{1-2H}}{\theta^2+x^2} dx; \\ \frac{1}{\pi} \sigma^2 \Gamma(2H+1) \sin(\pi H) \int_0^\infty \cos(2hx) \frac{x^{1-2H}}{\theta^2+x^2} dx, \end{cases} \quad (\text{B.1})$$

(we use the integral form of the first component of f to simplify the computation of the determinant).

The Jacobian matrix of f is equivalent (their determinants are up to a sign) to $J = (C_1, C_2, C_3)$, where the column vectors are given by

$$C_1 = \begin{pmatrix} 2\sigma\Gamma(2H+1) \sin(\pi H) \int_0^\infty \frac{x^{1-2H}}{\theta^2+x^2} dx \\ 2\sigma\Gamma(2H+1) \sin(\pi H) \int_0^\infty \cos(hx) \frac{x^{1-2H}}{\theta^2+x^2} dx \\ 2\sigma\Gamma(2H+1) \sin(\pi H) \int_0^\infty \cos(2hx) \frac{x^{1-2H}}{\theta^2+x^2} dx \end{pmatrix};$$

$$C_2 = \begin{pmatrix} -2\theta\sigma^2\Gamma(2H+1) \sin(\pi H) \int_0^\infty \frac{x^{1-2H}}{(\theta^2+x^2)^2} dx \\ -2\theta\sigma^2\Gamma(2H+1) \sin(\pi H) \int_0^\infty \cos(hx) \frac{x^{1-2H}}{(\theta^2+x^2)^2} dx \\ -2\theta\sigma^2\Gamma(2H+1) \sin(\pi H) \int_0^\infty \cos(2hx) \frac{x^{1-2H}}{(\theta^2+x^2)^2} dx \end{pmatrix};$$

and $C_3 = C_{3,1} + C_{3,2} + C_{3,3}$, where

$$C_{3,1} = \begin{pmatrix} \sigma^2\Gamma(2H+1) \sin(\pi H) \int_0^\infty -2\log(x) \frac{x^{1-2H}}{\theta^2+x^2} dx \\ \sigma^2\Gamma(2H+1) \sin(\pi H) \int_0^\infty -2\log(x) \cos(hx) \frac{x^{1-2H}}{\theta^2+x^2} dx \\ \sigma^2\Gamma(2H+1) \sin(\pi H) \int_0^\infty -2\log(x) \cos(2hx) \frac{x^{1-2H}}{\theta^2+x^2} dx \end{pmatrix};$$

$$C_{3,2} = \begin{pmatrix} \sigma^2\pi\Gamma(2H+1) \cos(\pi H) \int_0^\infty \frac{x^{1-2H}}{\theta^2+x^2} dx \\ \sigma^2\pi\Gamma(2H+1) \cos(\pi H) \int_0^\infty \cos(hx) \frac{x^{1-2H}}{\theta^2+x^2} dx \\ \sigma^2\pi\Gamma(2H+1) \cos(\pi H) \int_0^\infty \cos(2hx) \frac{x^{1-2H}}{\theta^2+x^2} dx \end{pmatrix};$$

and

$$C_{3,3} = \begin{pmatrix} \sigma^2\partial_H\Gamma(2H+1) \sin(\pi H) \int_0^\infty \frac{x^{1-2H}}{\theta^2+x^2} dx \\ \sigma^2\partial_H\Gamma(2H+1) \sin(\pi H) \int_0^\infty \cos(hx) \frac{x^{1-2H}}{\theta^2+x^2} dx \\ \sigma^2\partial_H\Gamma(2H+1) \sin(\pi H) \int_0^\infty \cos(2hx) \frac{x^{1-2H}}{\theta^2+x^2} dx \end{pmatrix}.$$

By the linearity of the determinant, we have

$$\det(J) = \det(C_1, C_2, C_{3,1}) + \det(C_1, C_2, C_{3,2}) + \det(C_1, C_2, C_{3,3})$$

It is easy to see that $\det(C_1, C_2, C_{3,2}) = \det(C_1, C_2, C_{3,3}) = 0$ (C_1 is a proportional to $C_{3,2}$ and to $C_{3,3}$). Therefore

$$\det(J) = \det(C_1, C_2, C_{3,1}). \quad (\text{B.2})$$

Notice that

$$\det(C_1, C_2, C_{3,1}) = -4\theta\sigma^5\Gamma^3(2H+1) \sin^3(\pi H) \det(M), \quad (\text{B.3})$$

where

$$M = \begin{pmatrix} \int_0^\infty \frac{x^{1-2H}}{(\theta^2+x^2)} dx & \int_0^\infty \frac{x^{1-2H}}{(\theta^2+x^2)^2} dx & \int_0^\infty -2\log(x) \frac{x^{1-2H}}{\theta^2+x^2} dx \\ \int_0^\infty \cos(hx) \frac{x^{1-2H}}{(\theta^2+x^2)} dx & \int_0^\infty \cos(hx) \frac{x^{1-2H}}{(\theta^2+x^2)^2} dx & \int_0^\infty -2\log(x) \cos(hx) \frac{x^{1-2H}}{\theta^2+x^2} dx \\ \int_0^\infty \cos(2hx) \frac{x^{1-2H}}{(\theta^2+x^2)} dx & \int_0^\infty \cos(2hx) \frac{x^{1-2H}}{(\theta^2+x^2)^2} dx & \int_0^\infty -2\log(x) \cos(2hx) \frac{x^{1-2H}}{\theta^2+x^2} dx \end{pmatrix}$$

Since $\theta > 0$, $\sigma > 0$, $\sin(\pi H) > 0$ and $\Gamma(2H + 1) > 0$ (for $H \in (0, 1)$), $\det(J) = 0$ if and only if $\det(M) = 0$.

The determinant $\det(J)$ or the determinant $\det(M)$ depends also on h . To remove this dependence, we write $M = (M_{ij})_{1 \leq i, j \leq 3}$, where

$$\begin{aligned} M_{11} &= \int_0^\infty h^{2H} \frac{x^{1-2H}}{(h^2\theta^2 + x^2)} dx, & M_{12} &= \int_0^\infty h^{2H+2} \frac{x^{1-2H}}{(h^2\theta^2 + x^2)^2} dx \\ M_{13} &= \int_0^\infty -2h^{2H} \log\left(\frac{x}{h}\right) \frac{x^{1-2H}}{h^2\theta^2 + x^2} dx, & M_{21} &= \int_0^\infty h^{2H} \cos(x) \frac{x^{1-2H}}{(h^2\theta^2 + x^2)} dx \\ M_{22} &= \int_0^\infty h^{2H+2} \cos(x) \frac{x^{1-2H}}{(h^2\theta^2 + x^2)^2} dx, & M_{23} &= \int_0^\infty -2h^{2H} \log\left(\frac{x}{h}\right) \cos(x) \frac{x^{1-2H}}{h^2\theta^2 + x^2} dx \\ M_{31} &= \int_0^\infty h^{2H} \cos(2x) \frac{x^{1-2H}}{(h^2\theta^2 + x^2)} dx, & M_{32} &= \int_0^\infty h^{2H+2} \cos(2hx) \frac{x^{1-2H}}{(h^2\theta^2 + x^2)^2} dx \\ M_{33} &= \int_0^\infty -2h^{2H} \log\left(\frac{x}{h}\right) \cos(2x) \frac{x^{1-2H}}{h^2\theta^2 + x^2} dx \end{aligned}$$

Since $\log(\frac{x}{h}) = \log(x) - \log(h)$, the determinant of M is equal to h^{6H+2} multiply the determinant of the following matrix:

$$N = \begin{pmatrix} \int_0^\infty \frac{x^{1-2H}}{(h^2\theta^2 + x^2)} dx & \int_0^\infty \frac{x^{1-2H}}{(h^2\theta^2 + x^2)^2} dx & \int_0^\infty -2 \log(x) \frac{x^{1-2H}}{h^2\theta^2 + x^2} dx \\ \int_0^\infty \cos(x) \frac{x^{1-2H}}{(h^2\theta^2 + x^2)} dx & \int_0^\infty \cos(x) \frac{x^{1-2H}}{(h^2\theta^2 + x^2)^2} dx & \int_0^\infty -2 \log(x) \cos(x) \frac{x^{1-2H}}{h^2\theta^2 + x^2} dx \\ \int_0^\infty \cos(2x) \frac{x^{1-2H}}{(h^2\theta^2 + x^2)} dx & \int_0^\infty \cos(2x) \frac{x^{1-2H}}{(h^2\theta^2 + x^2)^2} dx & \int_0^\infty -2 \log(x) \cos(2x) \frac{x^{1-2H}}{h^2\theta^2 + x^2} dx \end{pmatrix}$$

Namely, the determinant $\det(J)$ is a negative number multiplied by the determinant $\det(N)$. Denote $\theta' = h\theta$. The determinant of N a function of two variables only: θ' and H . The plot in Fig 1 shows that $\det(N)$ is positive for $H \in (0.03, 1)$ and $\theta' \in (2, 10)$. Combining this with (B.2)-(B.3), we see that on

$$\mathbb{D}_h = \{H > 0.03, 2 < \theta h < 10, \sigma > 0\} \quad (\text{B.4})$$

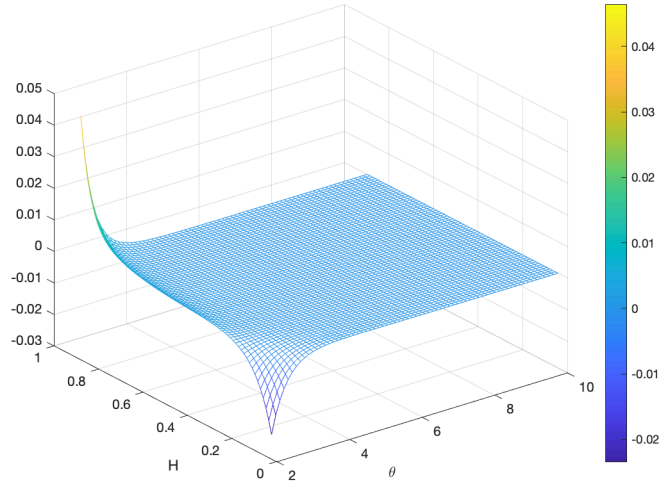
$\det(J)$ is strictly negative hence is not singular.

APPENDIX C. NUMERICAL RESULTS

For all the experiments, we take $h = 1$.

C.1. Strong consistency of the estimators. In this subsection, we illustrate the almost-sure convergence by plotting different trajectories of the estimators. We observe that when $\log_2(n) \geq 14$, the estimators become very close to the true parameter.

However, since our estimators are random (they depend on the sample $\{X_{kh}\}_{k=1}^n$), what's important to see in these figures is the deviations from the true parameter we are estimating. Even if three trajectories are not enough to make statements about the variance, the figures predict that the variance of $\tilde{\theta}_n$ is very high compared to the other estimators (see Fig 2 and Fig 3) and that, for H close to 0 (see Fig 4), the deviations of \tilde{H}_n increase.

FIGURE 1. Determinant of M for $H \in (0, 1)$ and $\theta \in (2, 10)$

C.2. Mean and standard deviation/Asymptotic behavior of the estimators. It is important to check the mean and deviation of our estimators. For example, a large variance implies a large deviation and therefore a “weak” estimator. That is why we plotted the mean and variance of our estimators for $n = 2^{12}$ over 100 samples.

As we observe, the standard deviation (s.d) of $\tilde{\theta}_n$ is larger than the s.d of $\tilde{\sigma}_n$ which is larger than the s.d of \tilde{H}_n (see table 1 and table 2). Notice also that the s.d of \tilde{H}_n increases as H decreases.

In [9], the variance of the θ estimator is proportional to θ^2 . In our case, it is difficult to compute the variances of our estimators (they depend on the matrix Σ

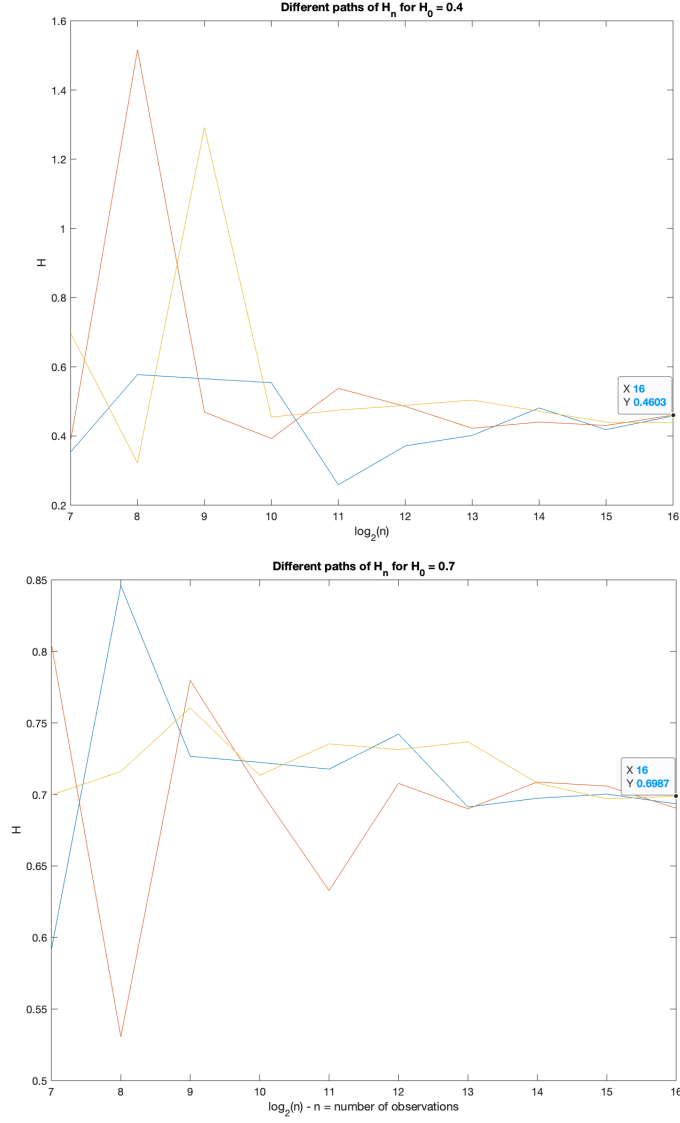
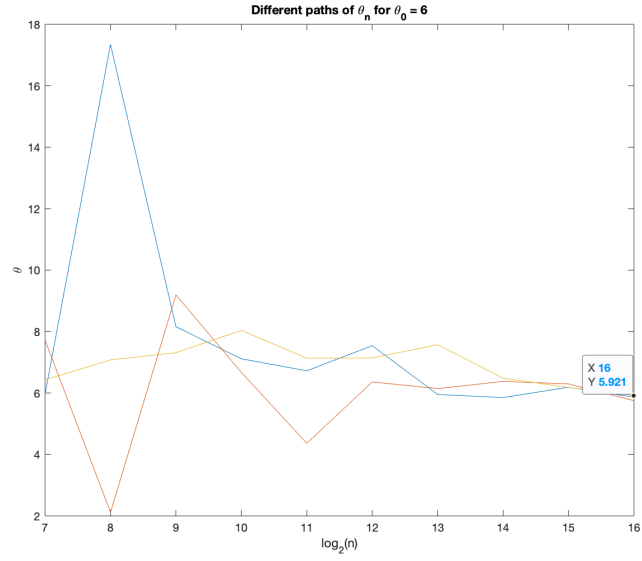
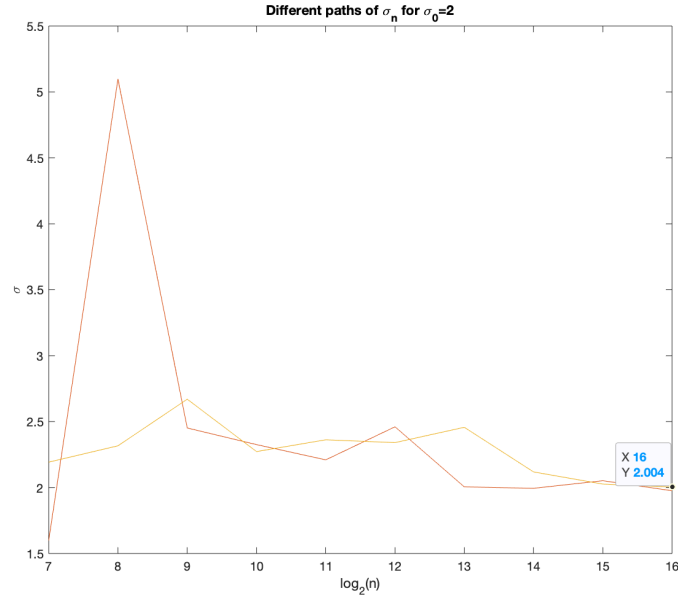


FIGURE 2. Convergence of \widetilde{H}_n for $H = 0.7$ and $H = 0.4$ ($\theta = 6, \sigma = 2$)

(see Theorem 4.3) and the Jacobian of the function f (see equation (3.9)), however we should probably expect something similar which could explain the gap in the variances since the values of θ are usually bigger than the values taken by σ or H .

Having access to 100 estimates of each parameter, we are also able to plot the distributions of our estimators to show that they effectively have a Gaussian nature (4.5). (Fig 5, Fig 6 and Fig 7).

FIGURE 3. Convergence of $\widetilde{\theta}_n$ for $\theta = 6, H = 0.7, \sigma = 2$ FIGURE 4. Convergence of $\widetilde{\sigma}_n$ for $\theta = 6, H = 0.7, \sigma = 2$

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TABLE 1. $H = 0.7, \theta = 6$ and $\sigma = 2$

	Mean	Standard deviation
\widetilde{H}_n	0.704	0.0221
$\widetilde{\theta}_n$	6.2983	0.8288
$\widetilde{\sigma}_n$	2.0921	0.2117

TABLE 2. $H = 0.4, \theta = 6$ and $\sigma = 2$

	Mean	Standard deviation
\widetilde{H}_n	0.4392	0.0531
$\widetilde{\theta}_n$	6.832	1.3227
$\widetilde{\sigma}_n$	2.4785	0.3833

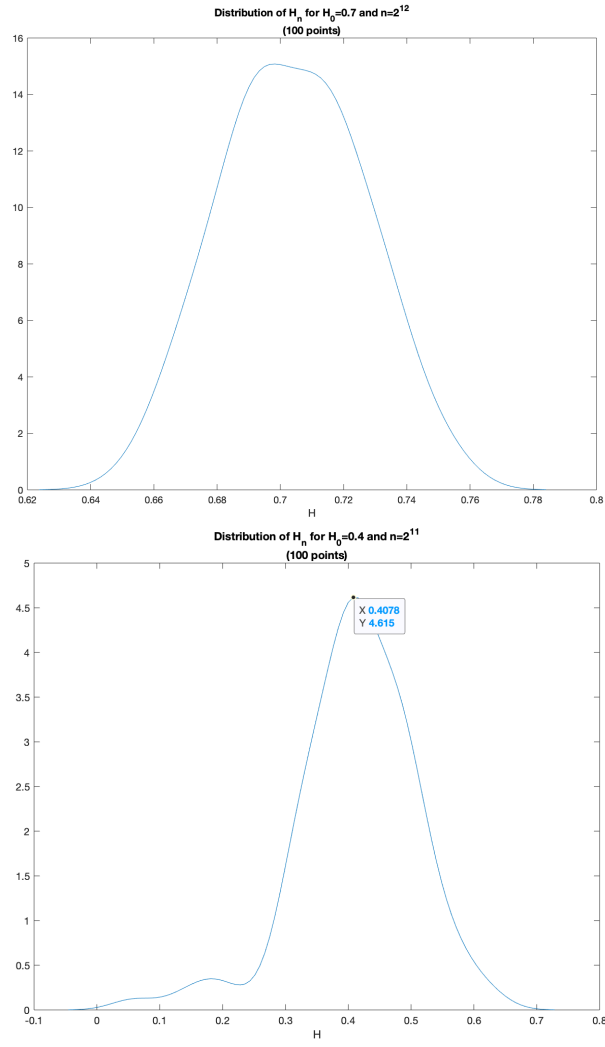
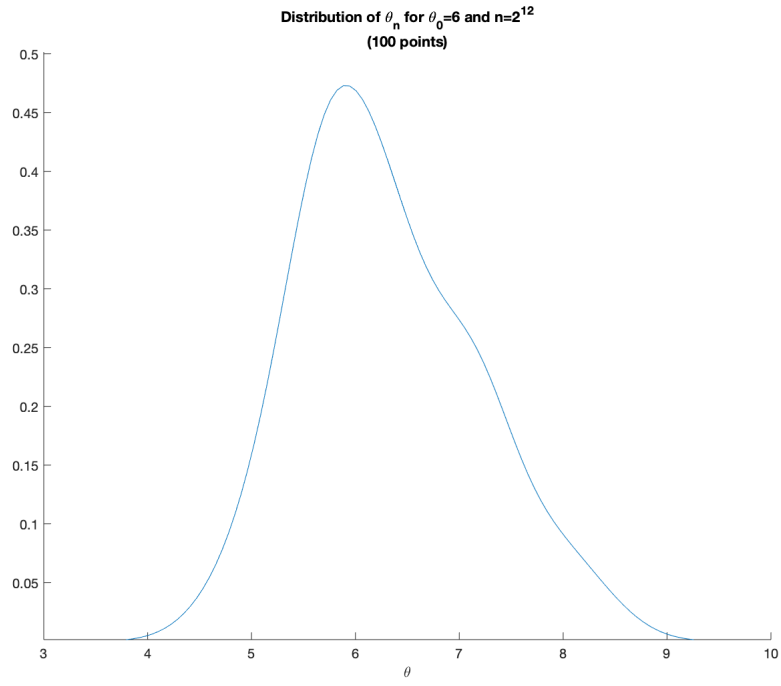
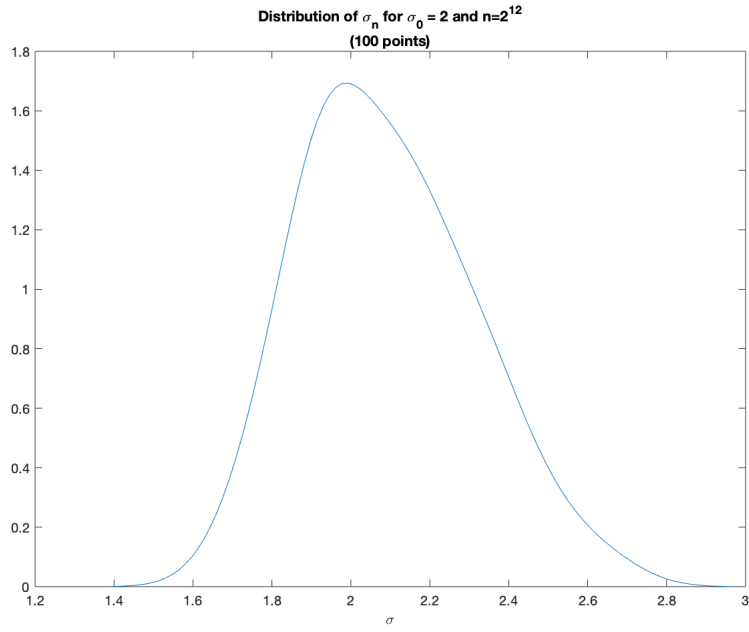


FIGURE 5. Distribution of \widetilde{H}_n for $H = 0.7$ and $H = 0.4$ while $\theta = 6, \sigma = 2$

FIGURE 6. Distribution of $\widetilde{\theta}_n$ for $\theta = 6, H = 0.7, \sigma = 2$ FIGURE 7. Distribution of $\widetilde{\sigma}_n$ for $\theta = 6, H = 0.7, \sigma = 2$