01.001 - Introduction to Probability and Statistics

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Week 11: First lecture on 03-Apr-2017, Second Lecture on 05-Apr-2017

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Summary of key ideas from week's second lecture

The multivariate normal distribution

The Multivariate Normal Density

The one-dimensional normal distribution with parameters μ, σ^2 generates real numbers $x \in \mathbb{R}^1$ according to the density

$$f(x) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp\left(-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}\right)$$

The multi-variate normal generates **vectors** of real numbers $x \in \mathbb{R}^n$ according to the density

$$f(x) = \frac{1}{(2\pi)^{n/2} det(\Sigma)^{1/2}} \exp\left(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\right)$$

It has as parameters

- 1. mean μ a vector $\mu \in \mathbb{R}^{n \times 1}$
- 2. Covariance matrix Σ a matrix $\Sigma \in \mathbb{R}^{n \times n}$. This matrix must satisfy two properties
 - (a) Σ is symmetric
 - (b) Σ is positive definite.

 $det(\Sigma)$ is the Determinant of a matrix which is equal to the product of all its eigenvalues.

Normal Distribution: Independence and the Covariance matrix

For a joint normal distribution, the covariance matrix allows to see independence relationships. However this holds only for this distribution.

What for is that useful? We can design Σ to encode independences that we want to have in our model - by enforcing (block-wise) zeros in the right positions!

Theorem:

if all X_k are independent from each other, then the covariance matrix is a diagonal matrix, that is

$$\Sigma = \begin{pmatrix} s_1^2 & 0 & \cdots & 0 \\ 0 & s_2^2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & s_n^2 \end{pmatrix}$$

Remember that this is one case that we plotted above.

Proof:

Theorem:

If

- 1. the set of random variables are jointly normally distributed
- 2. and two blocks of variables X_{set1}, X_{set2} are independent, then we have for all pairs of variables (X_{i1}, X_{k2}) such that X_{i1} is from the first set, and X_{k2} from the second set the following observation in the covariance matrix: $\Sigma_{i1,k2} = \Sigma_{k2,i1} = 0$ - that is the entry in i1-th row and k2-th column is zero, and also its mirrored entry in i1-th row and k2-th column.

If

- 1. the set of random variables are jointly normally distributed
- 2. the covariance matrix has zeros, then the corresponding sets are normally distributed

The theorem is best demonstrated by an **Example**: Suppose $X_{set1} = (X_1, X_2, X_3), X_{set2} = (X_4, X_5).$ Then Σ must look like this (* denotes a non-zero entry)

$$\Sigma = \begin{pmatrix} * & * & * & 0 & 0 \\ * & * & * & 0 & 0 \\ * & * & * & 0 & 0 \\ 0 & 0 & 0 & * & * \\ 0 & 0 & 0 & * & * \end{pmatrix}$$

That means: $P(X_1, X_2, X_3, X_4, X_5) = P(X_1, X_2, X_3)P(X_4, X_5)$.

Similarly:

denotes that X_1 and X_3 are independent. This is not of use for the joint distribution $P(X_1, X_2, X_3, X_4, X_5)$, but we know that for the marginal distribution of X_1 and X_3 it holds that: $P(X_1, X_3) =$ $P(X_1)P(X_3)$.

How to see this? Delete from the matrix all those rows and columns that have no 0s, that is: 2,4,5. then we get a 2×2 matrix over variables X_1 , X_3 only that looks like:

$$\Sigma = \begin{pmatrix} [X_1] * & 0 \\ [X_3] & 0 & * \end{pmatrix}$$

That means that in the marginal for (X_1, X_3) we have $P(X_1, X_3) =$ $P(X_1)P(X_3)$.

Same thinking:

$$\Sigma = egin{pmatrix} * & * & 0 & 0 & * \ * & * & * & * & * \ 0 & * & * & * & * \ 0 & * & * & * & * \ * & * & * & * & * \end{pmatrix}$$

How to see this ... lets delete rows/columns 2,5 (because they have no 0 entries). then we obtain this matrix over X_1 , X_3 , X_4

$$\Sigma = \begin{pmatrix} [X_1] * & 0 & 0 \\ [X_3] & 0 & * & * \\ [X_4] & 0 & * & * \end{pmatrix}$$

From here we can see that the block $X_{set1} = (X_1)$ is independent from the block $X_{set2} = (X_3, X_4)$. That means we can say nothing for the joint $P(X_1, X_2, X_3, X_4, X_5)$ but we have for the marginal over variables X_1, X_3, X_4 : $P(X_1, X_3, X_4) = P(X_1)P(X_3, X_4)$. In fact this implies more: you can integrate out any variable in this equation to obtain independencies for lower-dimensional marginal distributions.

$$P(X_1, X_3, X_4) = P(X_1)P(X_3, X_4)$$

implies also:
 $P(X_1, X_3) = P(X_1)P(X_3)$
 $P(X_1, X_4) = P(X_1)P(X_4)$

This shows that the covariance matrix Σ is – for the normal distribution - linked to independence properties between variables of its marginal distributions.

Warning!!!:

If the set of random variables are jointly normally distributed, and the covariance has zeros, then this implies independence. But if only marginal distributions are normally distributed, and the variables have zero covariance, then this does NOT imply independence. The deeper reason is: if variables are marginally normal distributed, it does NOT mean that their joint is a normal distribution.

A counterexample can be given by:

$$X \sim N(0,1)$$
 $Y = uX$, $u \in \{-1, +1\}$, $P(u = -1) = 0.5$

This stuff is fascinating: P(X + Y = 0) = P(X + uX = 0) = 0.5. Does this have a density?

Normal Distribution and Linear transformations

How does the normal distribution changes when $x \sim N(\mu, \Sigma)$ and we transform the random vector $x \in \mathbb{R}^n$ by a linear transformation: $\tilde{x} = Ax + b$ where $A \in \mathbb{R}^{n \times n}$ is an $n \times n$ -Matrix, and $b \in \mathbb{R}^n$ is a vector.

Property:

Suppose $x \sim N(\mu, \Sigma)$, $A \in \mathbb{R}^{n \times n}$ is an $n \times n$ -Matrix, and $b \in \mathbb{R}^n$ is a vector. We have then

$$x$$
 $\sim N(\mu, \Sigma)$ $\Rightarrow y = Ax + b$ $\sim N(A\mu + b, A\Sigma A^{T})$

See worked out example below for how to use this for sampling vectors from a normal distribution with parameters μ , Σ when one can draw only real numbers from the one-dimensional normal distribution N(0,1)

Maximum Likelihood Estimator for the multivariate normal distribution

Its important. See the worked out examples.

We obtain

$$\widehat{\mu} = \frac{1}{n} \sum_{i=1}^{n} x_i$$

$$\widehat{\Sigma} = \frac{1}{n} \sum_{i=1}^{n} (x_i - \mu)(x_i - \mu)^T$$

Note here: $x_i - \mu$ is a $n \times 1$ vector, $(x_i - \mu)^T$ is a $1 \times n$ vector. The matrix product of $n \times 1$ with $1 \times n$ is a $n \times n$ -matrix. So $\widehat{\Sigma} = \dots$ is an equation between two matrices. For a single component of Σ this decomposes into:

$$\widehat{\Sigma}_{k,l} = \frac{1}{n} \sum_{i=1}^{n} (x_{i,k} - \mu_k) (x_{i,l} - \mu_l)$$

where μ_k is the k-th dimension of vector μ , and $x_{i,k}$ is the k-th dimension of vector x_i .

Compare this to the one-dimensional case, where we had $\hat{\mu} =$ $\frac{1}{n}\sum_{i=1}^{n}x_{i}$ - just that in that case we have real numbers and not vectors, and $\sigma^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \widehat{\mu})^2$.

Worked-out examples related to week's second lecture

Suppose you have a random number generator, that can generate one-dimensional random numbers $x \sim N(0,1)$. You want to draw from a multivariate random number distribution $N(\mu, \Sigma)$ in say d = 369 dimensions. How to do that?

Solution:

We know: If we draw $x_i \sim N(0,1) = f(x_i \mid$ 0,1), then the vector

$$x = (x_1, ..., x_n) \sim \prod_{i=1}^n f(x_i \mid 0, 1)$$

= $N(0, I)$

where *I* is the $d \times d$ identity matrix. We know from the theorem about the normal distribution and linear transformations that:

$$x \sim N(0,1) \Rightarrow Ax + b \sim N(b, AIA^T) = N(b, AA^T)$$

We need

$$b = \mu$$
, $\Sigma = AA^T$

So we must choose

- (a) $b = \mu$
- (b) A such that $\Sigma = AA^T$.

Usually, you cannot do that by pen and paper except when Σ is diagonal. To our rescue scipy.linalg (and weka for Java, GNU GSL, eigen3 for C/C++ and many other libraries) has matrix decomposition functions that do right this kind of decomposition. The solution A is not unique. you can multiply it with any rotation matrix R ($RR^T = I$), then AR is also a solution because of

$$AR(AR)^T = ARR^TA^T = AIA^T = AA^T = \Sigma$$

2. Suppose a vectors $x \in \mathbb{R}^2$ are drawn from $N(\mu, \Sigma)$ with

$$\mu = \begin{pmatrix} 3 \\ -2 \end{pmatrix}$$

$$\Sigma = \begin{pmatrix} 6 & 2 \\ 2 & 5 \end{pmatrix}$$

What is the distribution of the transformed vectors Ax + b such that

$$b = \begin{pmatrix} -1\\2 \end{pmatrix}$$
$$A = \begin{pmatrix} 1 & 5\\3 & 2 \end{pmatrix}$$

Solution:

Its a matrix-vector/matrix-matrix multiplication task.

Remember:

$$(Av)_k = \sum_{i=1}^n A_{ki}v_i$$
$$(AB)_{kl} = \sum_{i=1}^n A_{ki}B_{il}$$

We have the result parameters being:

$$\widetilde{\mu} = A\mu + b$$

$$\widetilde{\Sigma} = A\Sigma A^T$$

$$\widetilde{\mu} = A\mu + b$$

$$= \begin{pmatrix} 1 & 5 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} 3 \\ -2 \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} 1 \cdot 3 + 5 \cdot -2 \\ 3 \cdot 3 + 2 \cdot -2 \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} -8 \\ 7 \end{pmatrix}$$

Equally

$$A\Sigma A^{T} = \begin{pmatrix} 1 & 5 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} 6 & 2 \\ 2 & 5 \end{pmatrix} \begin{pmatrix} 1 & 3 \\ 5 & 2 \end{pmatrix}$$
$$= \begin{pmatrix} 16 & 27 \\ 22 & 16 \end{pmatrix} \begin{pmatrix} 1 & 3 \\ 5 & 2 \end{pmatrix}$$
$$= \begin{pmatrix} 151 & 102 \\ 102 & 98 \end{pmatrix}$$

3. Suppose we have a set of vector-valued random variables (X_1, \ldots, X_n) , $X_i \sim N(\mu, \Sigma)$, where we restrict Σ to be a diagonal matrix, that is

$$\Sigma = \begin{pmatrix} s_1^2 & 0 & \cdots & 0 \\ 0 & s_2^2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & s_n^2 \end{pmatrix}$$

Find the maximum likelihood estimator for μ and Σ .

Solution:

Lets rewrite the density for a diagonal covariance matrix. We have

$$det(\Sigma) = \prod_{i=1}^{n} s_{i}^{2}$$

$$(\Sigma^{-1})_{lr} = \begin{cases} \frac{1}{s_{l}^{2}} & \text{if } l = r \\ 0 & \text{otherwise} \end{cases}$$

$$f(x) = \frac{1}{(2\pi)^{n/2} det(\Sigma))^{1/2}} \exp\left(-\frac{1}{2}(x-\mu)^{T} \Sigma^{-1}(x-\mu)\right)$$

$$= \frac{1}{(2\pi)^{n/2} \prod_{l=1}^{n} |s_{l}|} \exp\left(-\frac{1}{2}(x-\mu)^{T} \Sigma^{-1}(x-\mu)\right)$$

$$= \frac{1}{(2\pi)^{n/2} \prod_{l=1}^{n} |s_{l}|} \exp\left(-\frac{1}{2} \sum_{l=1}^{n} \sum_{r=1}^{n} (x_{l} - \mu_{l})^{T} \Sigma_{lr}^{-1}(x_{r} - \mu_{r})\right)$$

$$= \frac{1}{(2\pi)^{n/2} \prod_{l=1}^{n} |s_{l}|} \exp\left(-\frac{1}{2} \sum_{l=1}^{n} (x_{l} - \mu_{l})^{T} \Sigma_{ll}^{-1}(x_{l} - \mu_{l})\right)$$

$$= \frac{1}{(2\pi)^{n/2} \prod_{l=1}^{n} |s_{l}|} \exp\left(-\frac{1}{2} \sum_{l=1}^{n} \frac{1}{s_{l}^{2}}(x_{l} - \mu_{l})^{2}\right)$$

The log-likelihood of it for one sample *x* becomes (under assumption $s_l > 0$, so that $|s_1| = s_1$):

$$-\log((2\pi)^{n/2}) - \log(\prod_{l=1}^{n} |s_{l}|) - \frac{1}{2} \sum_{l=1}^{n} \frac{1}{s_{l}^{2}} (x_{l} - \mu_{l})^{2}$$

$$= -\log((2\pi)^{n/2}) - \sum_{l=1}^{n} \log(s_{l}) - \frac{1}{2} \sum_{l=1}^{n} \frac{1}{s_{l}^{2}} (x_{l} - \mu_{l})^{2}$$

Now lets assume that we have samples $x^{(1)}, \ldots, x^{(S)}$ (with the k-th dimension of sample $x^{(i)}$ being: $x_k^{(i)}$). Then the log likelihood for the dataset

becomes

$$-\sum_{i=1}^{S} \left(\sum_{l=1}^{n} \log(s_l) - \frac{1}{2} \sum_{l=1}^{n} \frac{1}{s_l^2} (x_l^{(i)} - \mu_l)^2 \right)$$

$$= -S \sum_{l=1}^{n} \log(s_l) - \frac{1}{2} \sum_{i=1}^{S} \sum_{l=1}^{n} \frac{1}{s_l^2} (x_l^{(i)} - \mu_l)^2$$

Its derivative for the *l*-th dimension of the mean μ_l is:

$$-\frac{1}{2} \sum_{i=1}^{S} \frac{1}{s_l^2} (-2) \cdot (x_l^{(i)} - \mu_l)^1 = 0$$

$$\frac{1}{s_l^2} \sum_{i=1}^{S} (x_l^{(i)} - \mu_l) = 0$$

$$\sum_{i=1}^{S} (x_l^{(i)} - \mu_l) = 0$$

$$\sum_{i=1}^{S} x_l^{(i)} = S\mu_l$$

$$\mu_l = \frac{1}{S} \sum_{i=1}^{S} x_l^{(i)}$$

Writing this in vector notation this yields:

$$\mu = \frac{1}{S} \sum_{i=1}^{S} x^{(i)}$$

Its derivative for the *l*-th dimension of the

variance diagonal s_l is:

$$-S\frac{1}{s_{l}} - \frac{1}{2} \sum_{i=1}^{S} (-2) \cdot \frac{1}{s_{l}^{3}} (x_{l}^{(i)} - \mu_{l})^{2} = 0 \mid \cdot s_{l}^{3}$$

$$\Leftrightarrow -Ss_{l}^{2} + \sum_{i=1}^{S} (x_{l}^{(i)} - \mu_{l})^{2} = 0$$

$$\Leftrightarrow \sum_{i=1}^{S} (x_{l}^{(i)} - \mu_{l})^{2} = Ss_{l}^{2}$$

$$\Leftrightarrow s_{l}^{2} = \frac{1}{S} \sum_{i=1}^{S} (x_{l}^{(i)} - \mu_{l})^{2}$$

This is the variance estimate for the *l*-th dimension of the data if it would have been treated as a separate dimension.