# Binding by Oscillatory Dynamics in Neural Architectures for Relational Reasoning

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#### Introduction

Relational reasoning tasks (e.g., same/different judgments or analogies) challenge neural networks due to the lack of explicit binding mechanisms. Inspired by neuroscience, we address the binding problem using oscillatory dynamics, leveraging neural synchrony to dynamically group features. We introduce a relational bottle**neck** to enforce abstract, generalizable relational representations.

#### **Model Architecture**

Our model binds object features through Kuramoto oscillator synchronization:

- Feature Extraction: Object images  $z_i$  encoded by CNN:  $E_i = f_{\theta}(z_i) \in \mathbb{R}^D$ .
- Oscillatory Binding (Kuramoto Dynamics): Features drive oscillators  $\mathbf{x}_{i,d}(t) \in S^{N-1}$  on a unit sphere, evolving as:

$$\dot{\mathbf{x}}_{i,d}(t) = \mathbf{\Omega}_d \mathbf{x}_{i,d}(t) + \mathsf{Proj}_{\mathbf{x}_{i,d}(t)} \left( \mathbf{c}_{i,d} + \sum_{d'} \mathbf{J}_{d,d'}^{\mathsf{IN}} \mathbf{x}_{i,d'}(t) + \sum_{d'} \mathbf{J}_{d,d'}^{\mathsf{OUT}} \mathbf{x}_{3-i,d'}(t) \right)$$

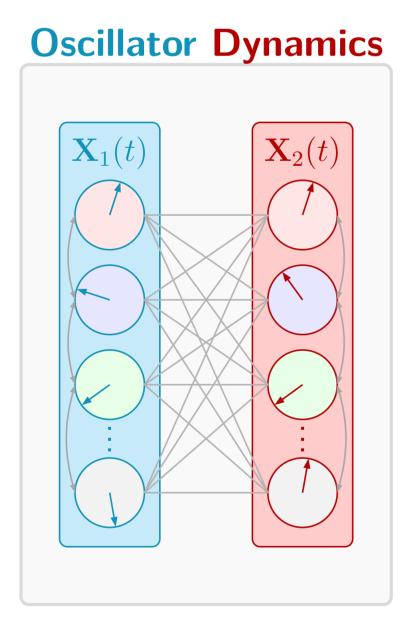
Dynamics include:

- Natural frequency  $(\Omega_d)$ : Skew-symmetric matrices generating intrinsic rotations, ensuring diverse oscillator frequencies and preventing trivial synchronization.
- Conditional input ( $\mathbf{c}_{i,d} = W_d \cdot E_i[d] + \mathbf{b}_d$ ): Encodes object-specific features into oscillator dynamics, guiding task-relevant synchronization patterns.  $W_d$ ,  $\mathbf{b}_d$  are learnable parameters.
- Within-object coupling  $(\mathbf{J}_{d,d'}^{\mathsf{IN}})$ : Synchronizes features within the same object.
- Between-object coupling  $(\mathbf{J}_{dd'}^{OUT})$ : Synchronizes features across different objects.
- Relational Bottleneck: Coherence measures synchronization strength:

$$\rho_d = \|\mathbf{x}_{1,d}(T) + \mathbf{x}_{2,d}(T)\|_2$$

• Classification: Classifier predicts relationship based on coherence signals.

# **Feature Extraction** $\mathsf{CNN}\ f_{ heta}$ $\mathsf{CNN}\ f_{\theta}$ $E_2$ $E_1$



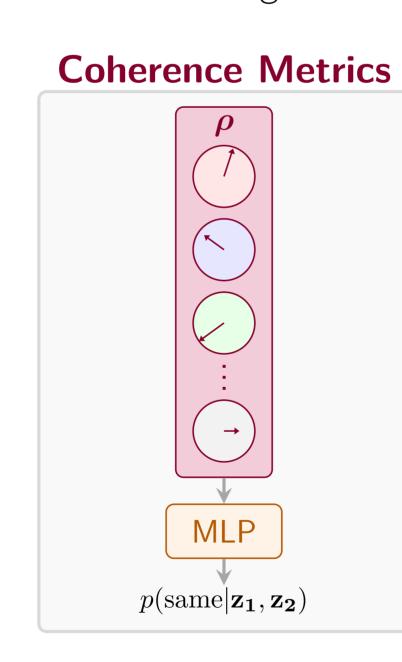


Figure 1. Model architecture overview.

#### **Tasks**

We evaluate on two visual reasoning tasks, using 100 Unicode characters with random scaling/positioning:

- Same/Different: Decide if two objects belong to the same category.
- Relational Match-to-Sample (RMTS): Given a source pair (defining "same" or "different"), choose which of two target pairs matches that relation. This is reasoning about relations of relations.
- Generalization Regimes: Train on  $m \in \{95, 50, 15\}$ icons, test on the remaining  $\{5, 50, 85\}$ .

(a) Same/Different

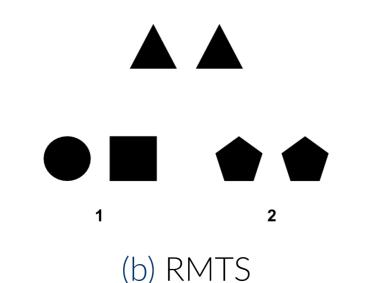


Figure 2. Task Illustrations.

### **Transfer Learning Approach**

- Stage 1: Train the full CNN + Oscillator network on the Same/Different task.
- Stage 2: Freeze CNN and oscillator parameters; extract coherence vectors for each pair and train a new MLP on the RMTS task.

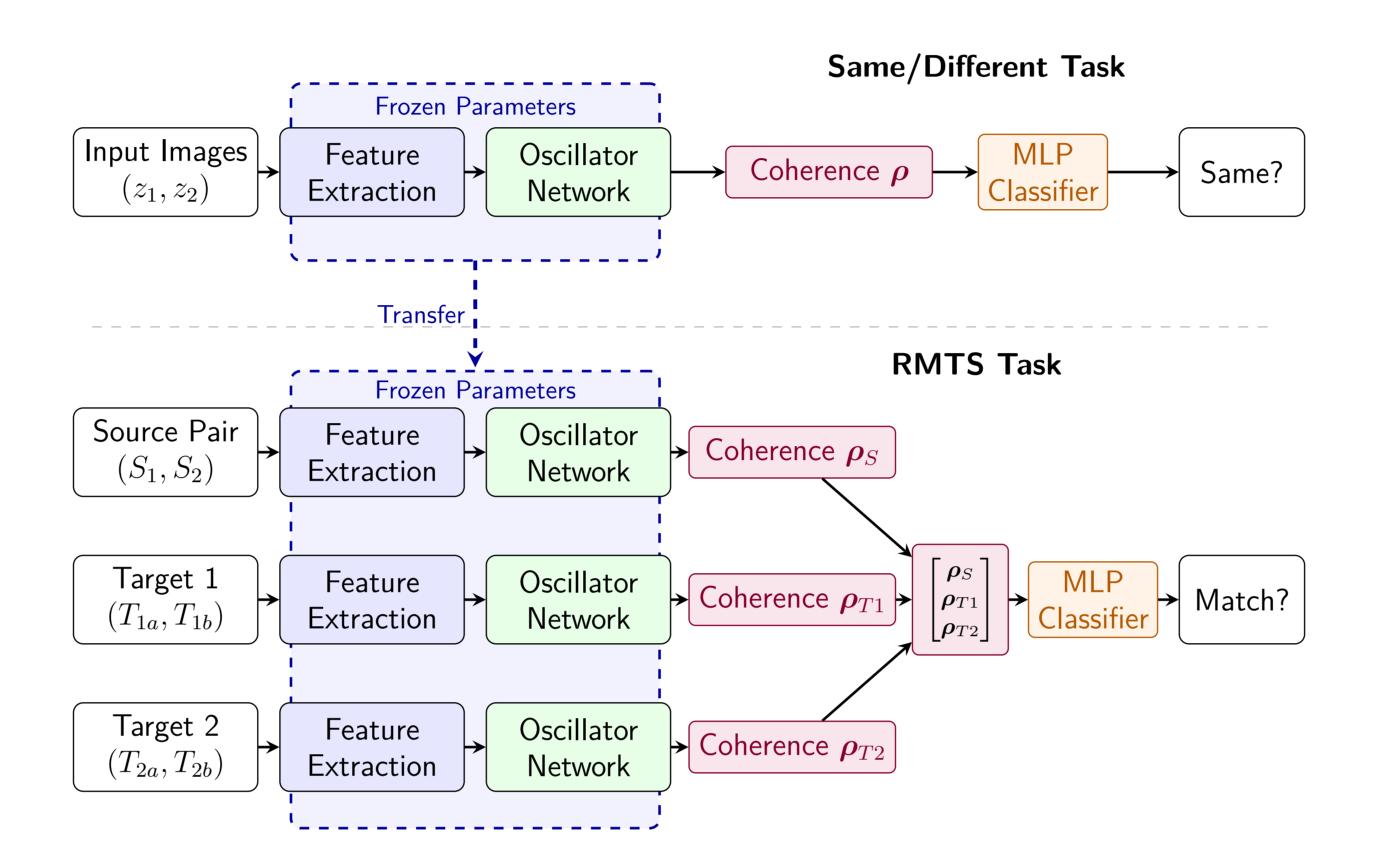
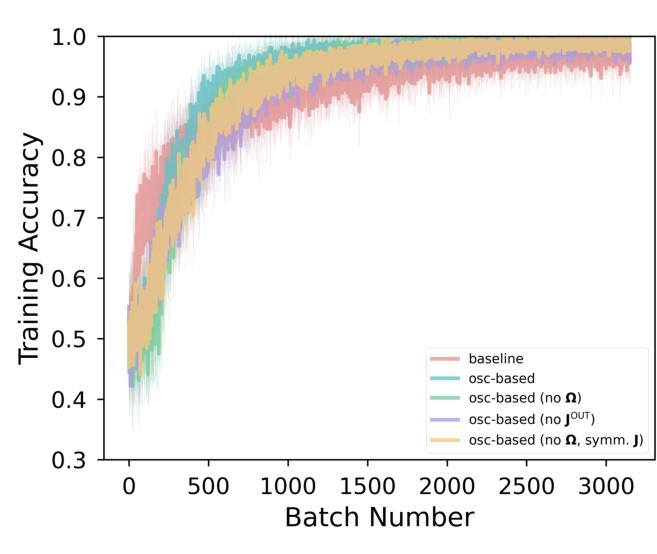
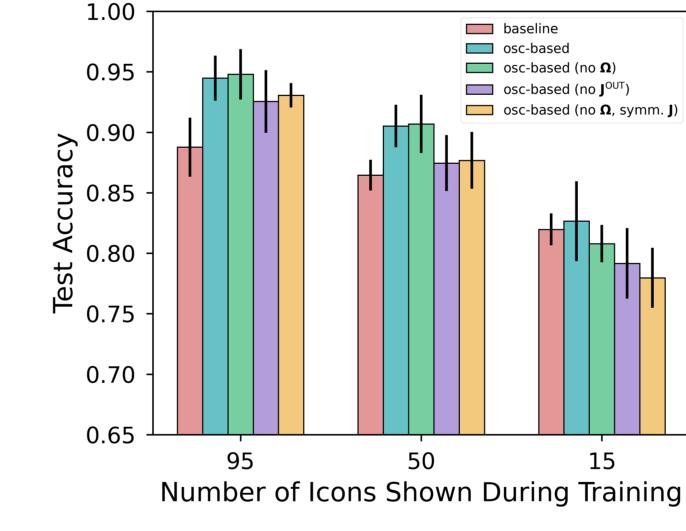


Figure 3. Two-stage transfer learning paradigm.

#### Same/Different Performance





(a) Training accuracy over batches (m = 95)

(a) RMTS training accuracy (m = 95)

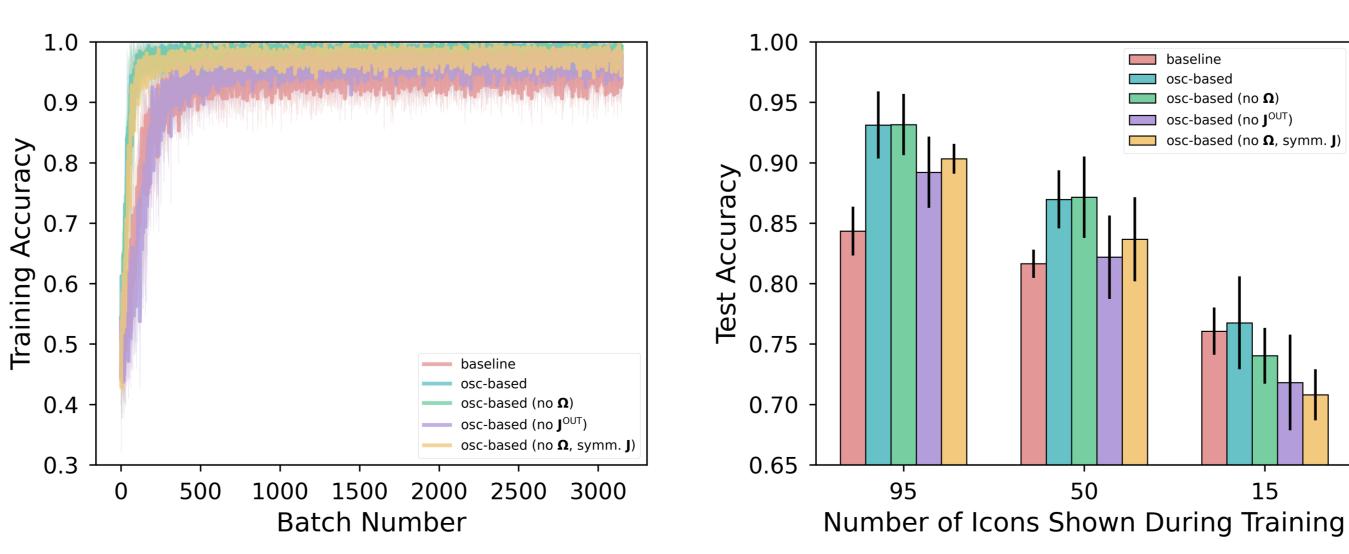
(b) Test accuracy across generalization regimes

osc-based

 $\square$  osc-based (no Ω) osc-based (no J<sup>OUT</sup>)

 $\square$  osc-based (no **Ω**, symm. **J** 

#### **RMTS Performance**



(b) RMTS test accuracy across regimes

### **Energy Minimization**

Under symmetric coupling ( ${f J}={f J}^{ op}$ ) and zero natural frequencies ( ${f \Omega}=0$ ), the Kuramoto network minimizes the Lyapunov energy

$$E = -\frac{1}{2} \sum_{i,j=1}^{2} \mathbf{x}_{i}^{\mathsf{T}} \mathbf{J}_{ij} \mathbf{x}_{j} - \sum_{i=1}^{2} \mathbf{c}_{i}^{\mathsf{T}} \mathbf{x}_{i}$$

$$= -\frac{1}{2} \left( \mathbf{x}_{1}^{\mathsf{T}} \mathbf{J}^{\mathsf{IN}} \mathbf{x}_{1} + \mathbf{x}_{2}^{\mathsf{T}} \mathbf{J}^{\mathsf{IN}} \mathbf{x}_{2} + \mathbf{x}_{1}^{\mathsf{T}} \mathbf{J}^{\mathsf{OUT}} \mathbf{x}_{2} + \mathbf{x}_{2}^{\mathsf{T}} \mathbf{J}^{\mathsf{OUT}} \mathbf{x}_{1} \right) - \left( \mathbf{c}_{1}^{\mathsf{T}} \mathbf{x}_{1} + \mathbf{c}_{2}^{\mathsf{T}} \mathbf{x}_{2} \right).$$

During each integration step, E decreases monotonically. Empirically, "same" input pairs converge to *lower* energy minima than "different" pairs.

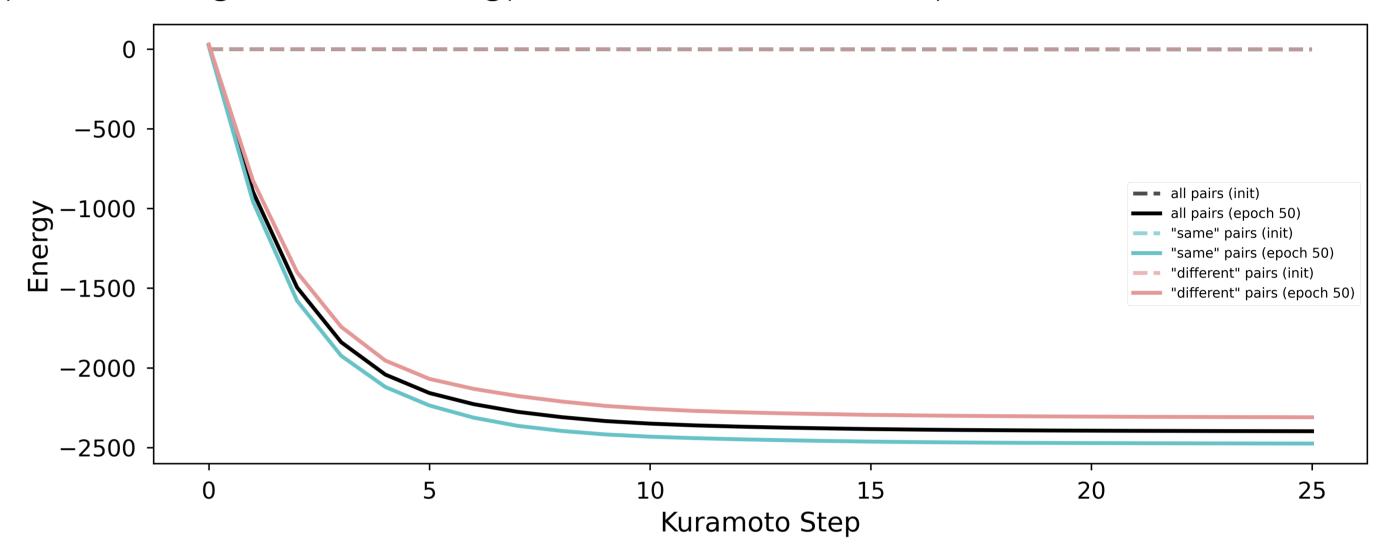
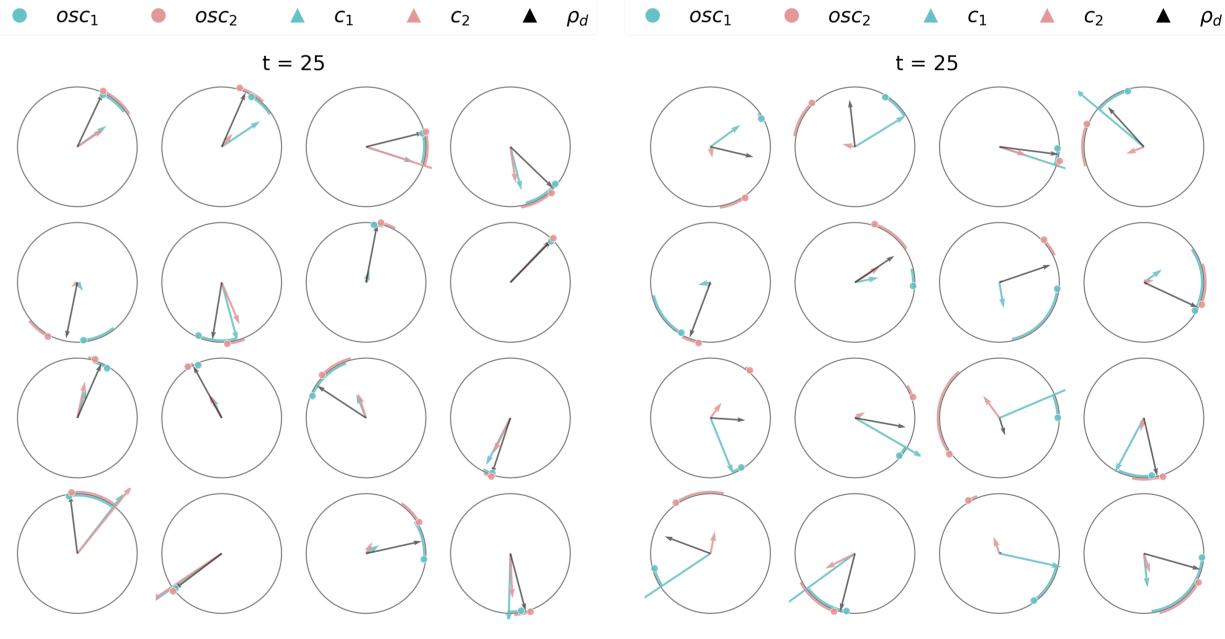


Figure 6. Average energy trajectory for "same" vs "different" pairs over T=25 steps.

## **Oscillator State Dynamics**

- ullet Initialization: All D oscillators begin with random phases on the circle.
- Trained "Same" Pair: For every dimension d, the two corresponding oscillators lock in phase—i.e. they overlap as tight pairs on the circle.
- Trained "Different" Pair: Only shared-feature dimensions phase-lock; others remain asynchronous, producing a mix of tight and dispersed pairs.



(a) "Same" pair oscillators (epoch 50)

(b) "Different" pair oscillators (epoch 50)

Figure 7. All D oscillator phases at t=T for sample "same" vs. "different" pairs.

#### References

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