

view\_frames Result

Recorded at time: 1470765647.767

odom

base\_link

base\_footprint

top\_plate\_link

front\_bumper\_link

imu\_link

inertial\_link

rear\_bumper\_link

top\_chassis\_link

user\_rail\_link

front\_left\_wheel\_link

front\_right\_wheel\_link

rear\_left\_wheel\_link

rear\_right\_wheel\_link

bowler\_link

Broadcaster: /ekf\_localization  
Average rate: 51.175 Hz  
Most recent transform: 1470765647.142 ( 0.624 sec old)  
Buffer length: 0.840 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 51.202 Hz  
Most recent transform: 1470765647.641 ( 0.126 sec old)  
Buffer length: 0.840 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 51.200 Hz  
Most recent transform: 1470765647.641 ( 0.126 sec old)  
Buffer length: 0.840 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 51.201 Hz  
Most recent transform: 1470765647.641 ( 0.126 sec old)  
Buffer length: 0.840 sec

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Average rate: 51.201 Hz  
Most recent transform: 1470765647.641 ( 0.126 sec old)  
Buffer length: 0.840 sec

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Average rate: 51.200 Hz  
Most recent transform: 1470765647.641 ( 0.126 sec old)  
Buffer length: 0.840 sec

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Average rate: 51.200 Hz  
Most recent transform: 1470765647.641 ( 0.126 sec old)  
Buffer length: 0.840 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 11.209 Hz  
Most recent transform: 1470765647.136 ( 0.630 sec old)  
Buffer length: 0.803 sec

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Buffer length: 0.803 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 51.202 Hz  
Most recent transform: 1470765647.641 ( 0.126 sec old)  
Buffer length: 0.840 sec