Electrics Eagles

Software Install / Usage

Manual

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For making this tutorial we need:

PC with Windows 7/8/8.1 or 10 installed on it.

As least 4GB RAM

Internet Access

1GB free space on hard drive for PC

Intel Pentium B815 or AMD Equivalent .

7Zip

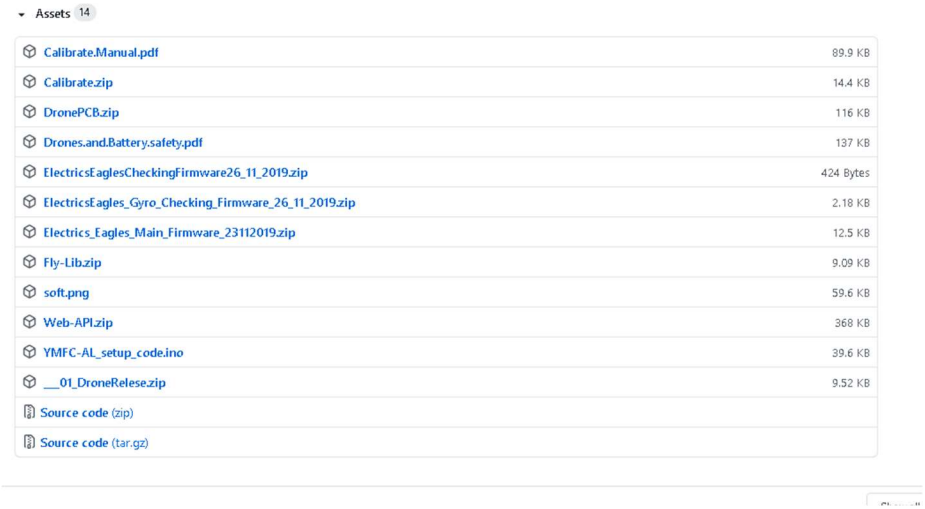
Opera/Chrome/Firefox

PC Skills such as Open browser , unpack files, and Install Programs

Arduino IDE 1.8.12 and higher

A 1 hour 30 minutes free time

Clone all software you need. Do it manually or clone one big pack is doesn`t matter.

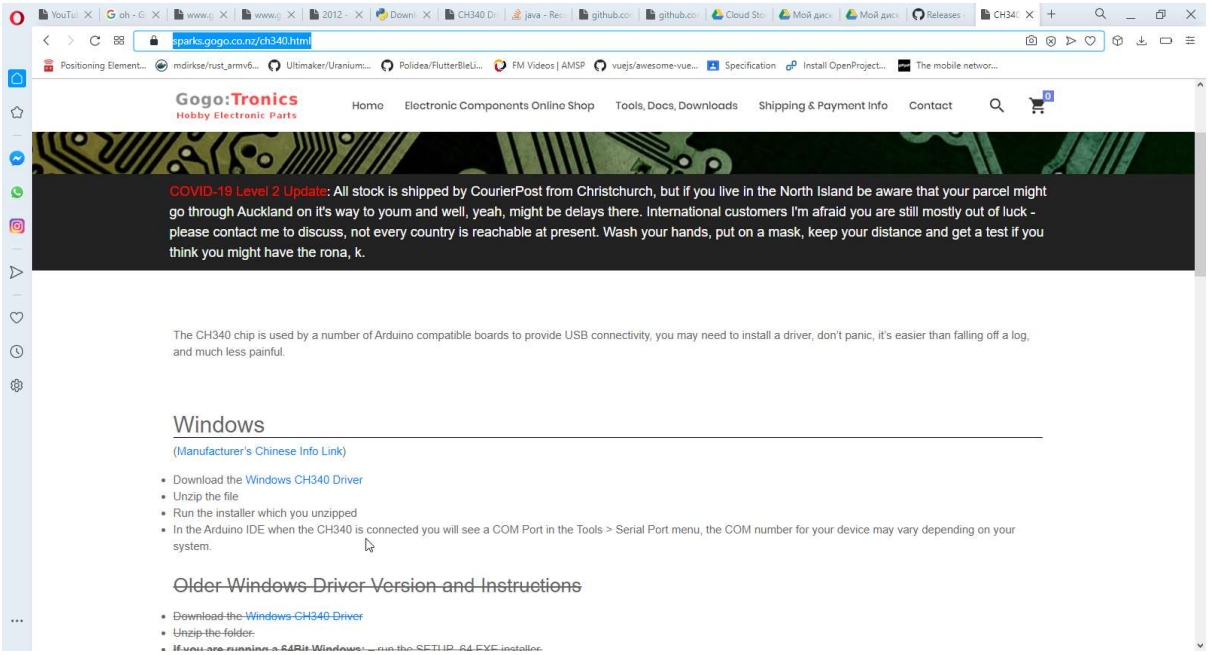


Unpack the big pack if needed.

After it Install the IDE by clicking to ElectricsEaglesIDEV1_Setup_ENG_24_11_2019.exe and the install window will be displayed. Install by Next -> Next -> Finish method.

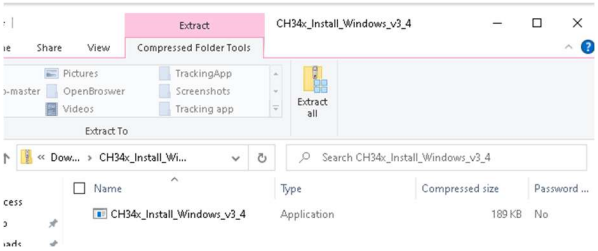
Next is installing CH340 drivers.

Go to https://sparks.gogo.co.nz/ch340.html

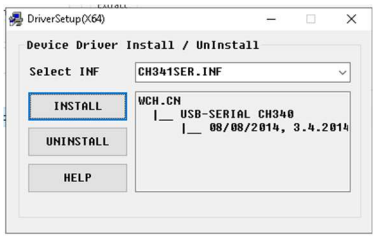


Click Windows CH340 Driver.

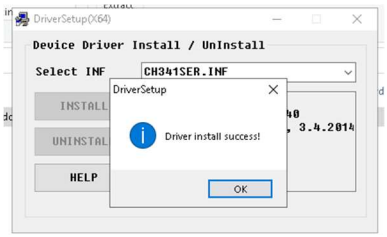
Unzip file and Run CH340_Install_Windows :



Press Install :

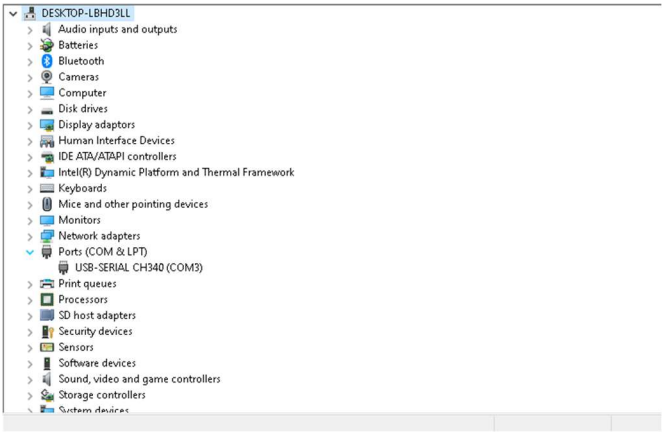


Wait while success window displayed:



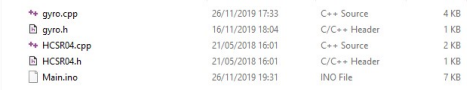
Reconnect the Drone to PC

If all done correct the new COM Port should be detected.

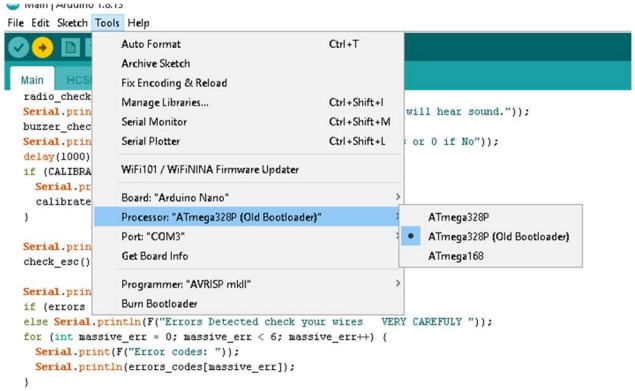


Next step is unpack the ElectricsEaglesCheckingFirmware26_11_2019.zip .

Open the Main.ino file via Arduino IDE



Select Correct Arduino IDE Board and after it press Ctrl+U to upload code.

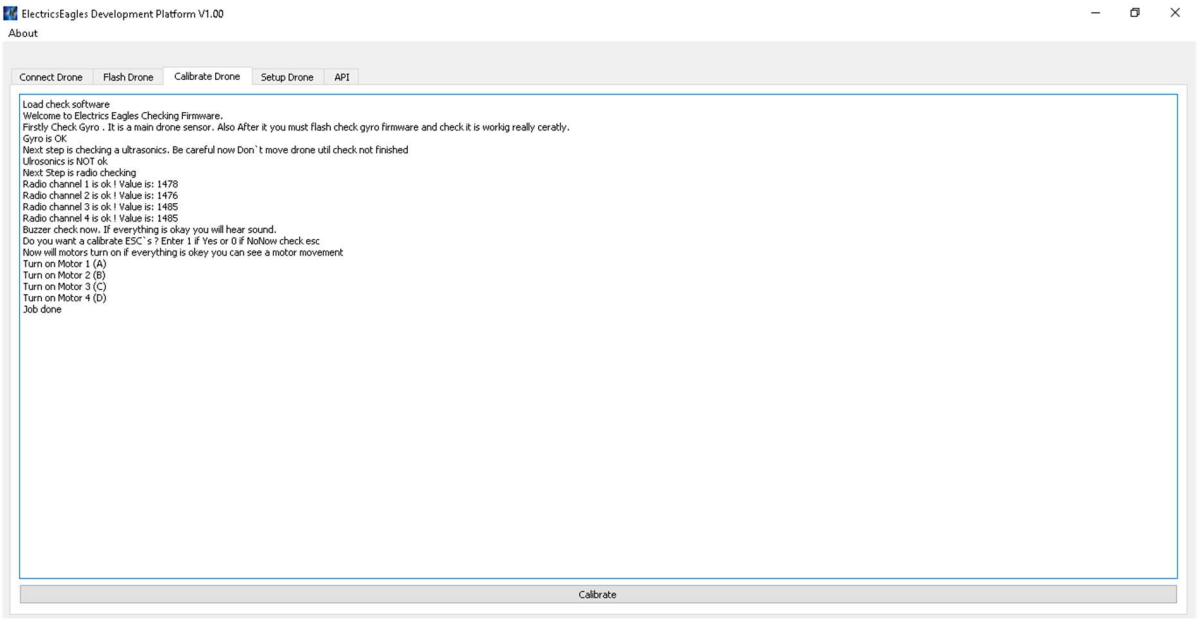


After Uploading code disconnect the Drone from computer.

After open Electrics Eagles IDE and select connect options and press connect .

(Options COM-Port Watch in Device Manager) (Baudrate:9600)

After It go to Calibrate Drone option and press Calibrate option. Let your drone stationary and wait.

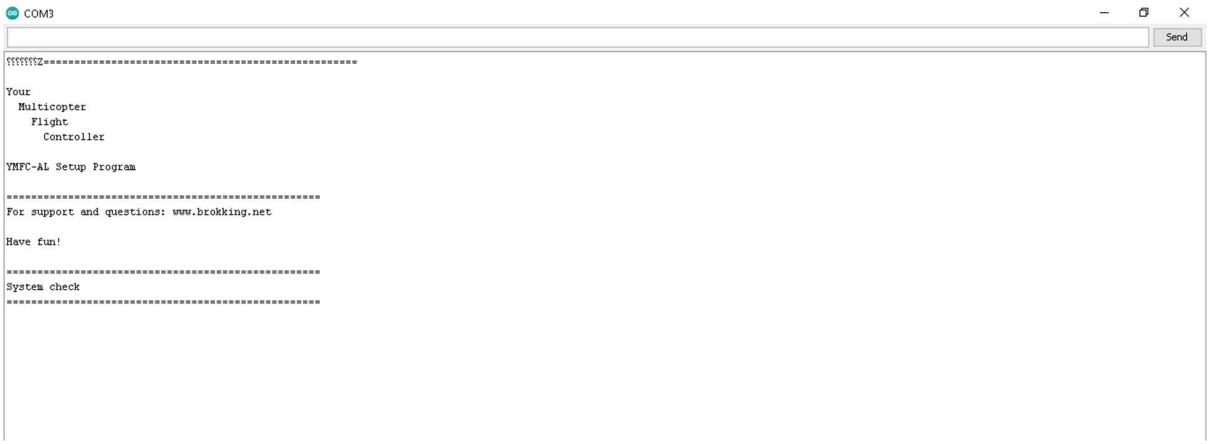


Disconnect Drone from PC and connect it again .

After It open the YMFC_AL_calibrate_code.ino if Arduino IDE

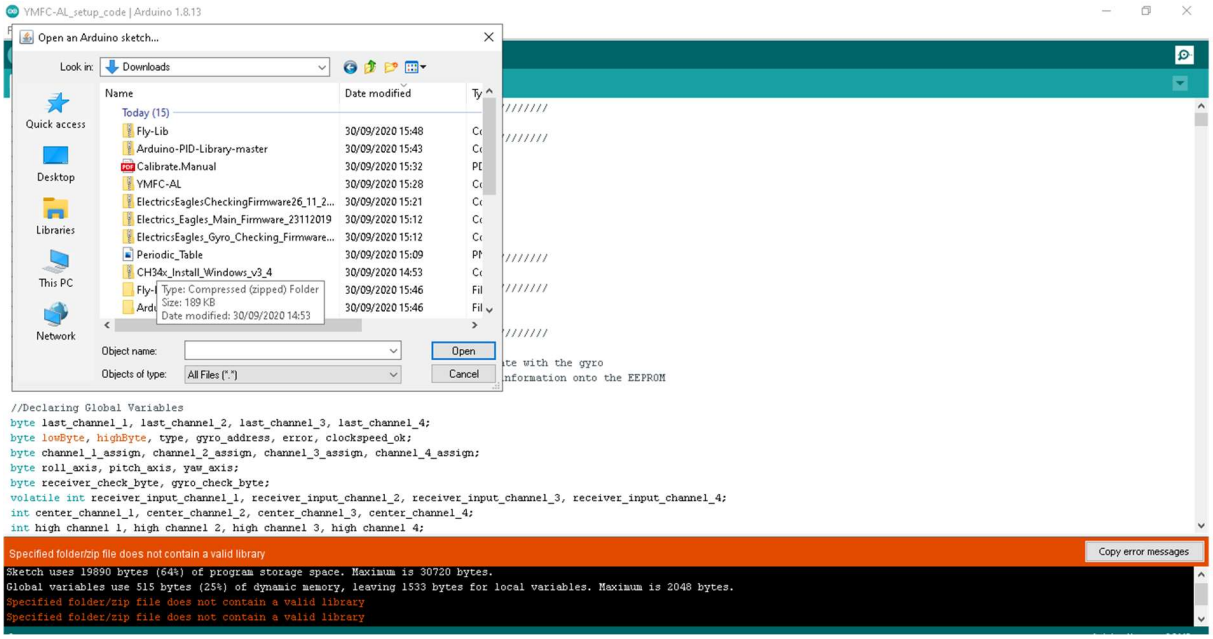
And also press Ctrl+U for flash drone.

After it open the Serial Monitor and follow the calibrate instructions on screen calibrate drone .

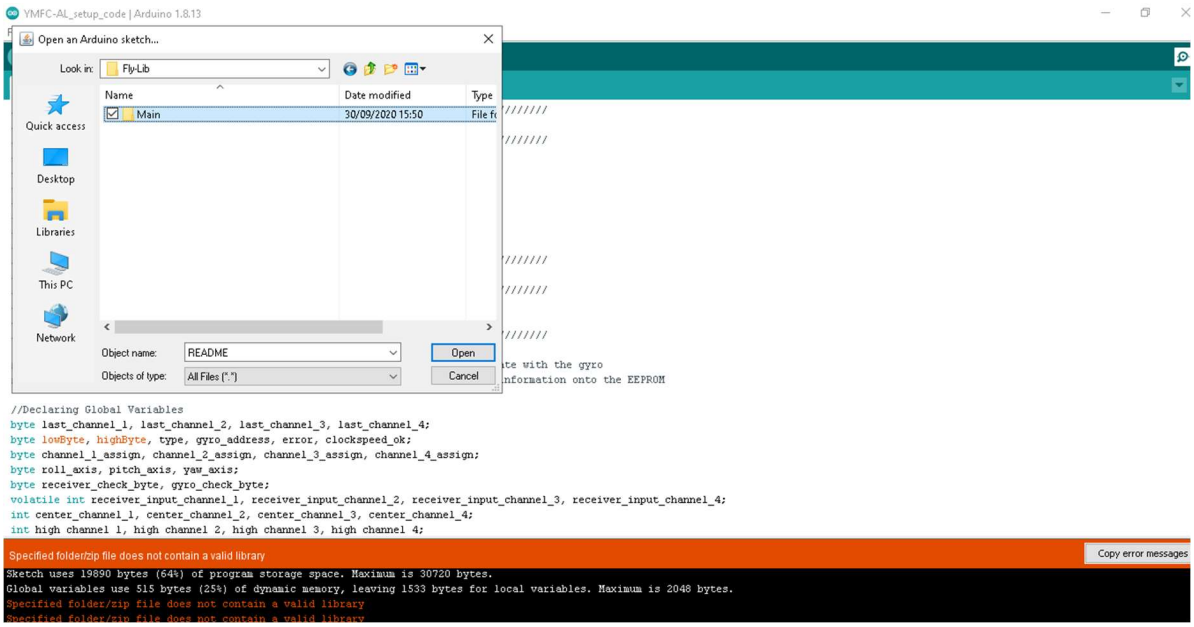


After it open / downland Fly-Lib.zip and unpack it.

After it open Arduino IDE File -> Open and select path to ino file


YMFC-AL_setup_code | Arduino 1.8.13
Open an Arduino sketch...
Look in: Downloads
Quick access
Desktop
Libraries
This PC
Network
Name
Date modified
Today (15)
Fly-Lib 30/09/2020 15:48
Arduino-PID-Library-master 30/09/2020 15:43
Calibrate.Manual 30/09/2020 15:32
YMFC-AL 30/09/2020 15:28
ElectricsEaglesCheckingFirmware26_11_2... 30/09/2020 15:21
Electrics_Eagles_Main_Firmware_23112019 30/09/2020 15:12
ElectricsEagles_Gyro_Checking_Firmware... 30/09/2020 15:12
Periodic_Table 30/09/2020 15:09
CH34x_Install_Windows_v3_4 30/09/2020 14:53
Type: Compressed (zipped) Folder
Size: 189 KB
Date modified: 30/09/2020 14:53
30/09/2020 15:46
30/09/2020 15:46
Object name:
Objects of type: All Files (*.*)
Open
Cancel
//Declaring Global Variables
byte last_channel_1, last_channel_2, last_channel_3, last_channel_4;
byte lowByte, highByte, type, gyro_address, error, clockspeed_ok;
byte channel_1_assign, channel_2_assign, channel_3_assign, channel_4_assign;
byte roll_axis, pitch_axis, yaw_axis;
byte receiver_check_byte, gyro_check_byte;
volatile int receiver_input_channel_1, receiver_input_channel_2, receiver_input_channel_3, receiver_input_channel_4;
int center_channel_1, center_channel_2, center_channel_3, center_channel_4;
int high_channel_1, high_channel_2, high_channel_3, high_channel_4;
Specified folder/zip file does not contain a valid library
Copy error messages
Sketch uses 19890 bytes (64%) of program storage space. Maximum is 30720 bytes.
Global variables use 515 bytes (25%) of dynamic memory, leaving 1533 bytes for local variables. Maximum is 2048 bytes.
Specified folder/zip file does not contain a valid library
Specified folder/zip file does not contain a valid library

And


YMFC-AL_setup_code | Arduino 1.8.13
Open an Arduino sketch...
Look in: Fly-Lib
Quick access
Desktop
Libraries
This PC
Network
Name
Date modified
Type
Main 30/09/2020 15:50
Object name: README
Objects of type: All Files (*.*)
Open
Cancel
//Declaring Global Variables
byte last_channel_1, last_channel_2, last_channel_3, last_channel_4;
byte lowByte, highByte, type, gyro_address, error, clockspeed_ok;
byte channel_1_assign, channel_2_assign, channel_3_assign, channel_4_assign;
byte roll_axis, pitch_axis, yaw_axis;
byte receiver_check_byte, gyro_check_byte;
volatile int receiver_input_channel_1, receiver_input_channel_2, receiver_input_channel_3, receiver_input_channel_4;
int center_channel_1, center_channel_2, center_channel_3, center_channel_4;
int high_channel_1, high_channel_2, high_channel_3, high_channel_4;
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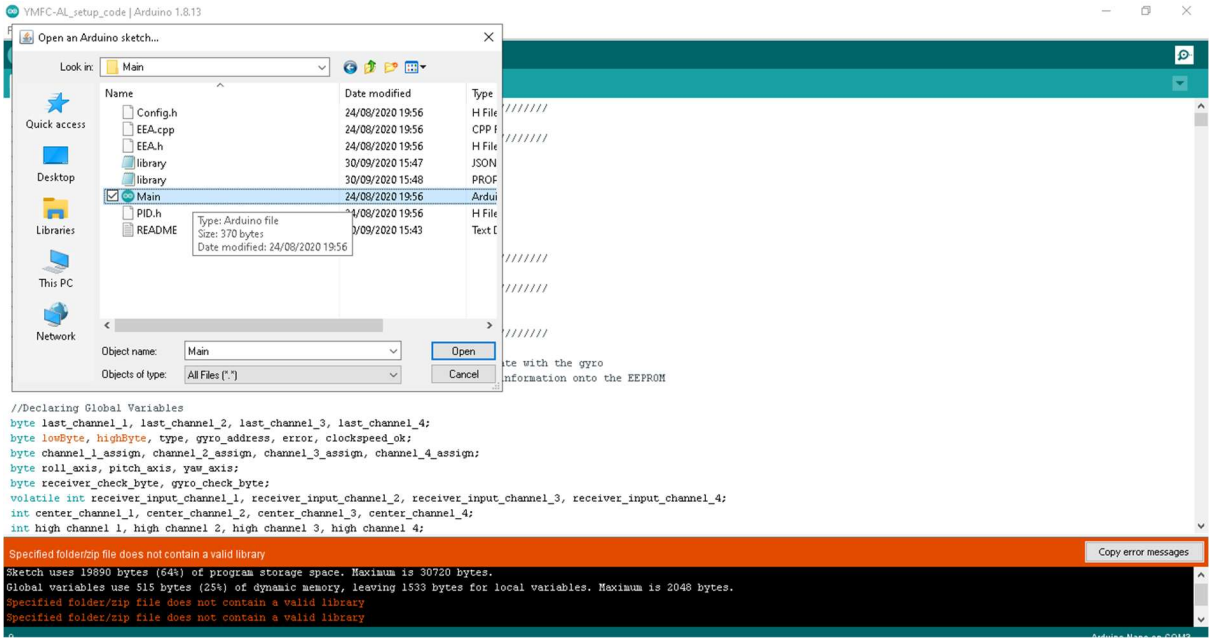

And press Open

After It last time press Ctrl + U to upload code to Drone controller.

And enjoy flights.