

# Introduction to Embedded Systems

\*Content taken from HP Educational Services, Advanced Embedded Course

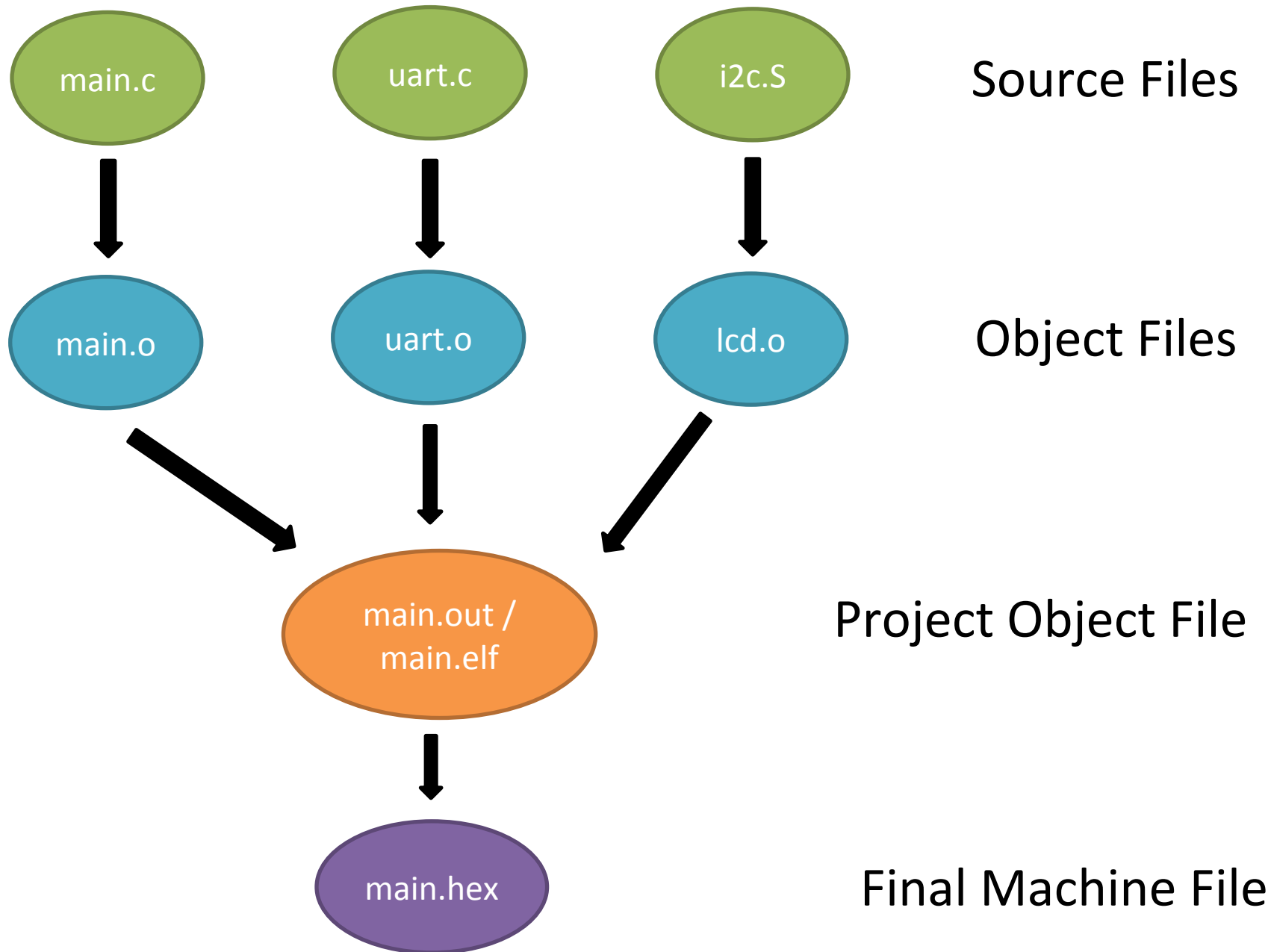
# Basics

- What is a microcontroller ? uC vs uP ?
- CMOS-TTL voltage level
- Clock ? RAM ? FLASH ? EEPROM ? Registers ?
- 8 bit / 16 bit / 32 bit ?
- Why AVR ?

# Tool-Chain

Bunch of utilities which contains following,

- Compiler  $.c \rightarrow .o$
- Assembler  $.S / .asm \rightarrow .o$
- Linker  $.o \rightarrow .out / .elf$
- Object Translator  $.elf/.out \rightarrow .hex$
- Programmer  $.hex \rightarrow \text{flash of uC}$
- Debugger For real-time debugging via JTAG
- Simulator For simulating



# Examples

- AVRGCC / WinAVR
- CVAVR
- Bascom

# Using AVRGCC

Install WinAVR on your system.

Open CMD Prompt type : `avr-gcc --help`

See the manual for more details

# Sample Code (main.c)

```
#include <avr/io.h>
// we are not defining which
microcontroller is this !

int main (void) {

    DDRA    = 0xFF;
    PORTA   = 0xF0;
}
```

# 1. Compiling

```
avr-gcc -c -mmcu=atmega128 main.c
```

This will create main.o



## 2. Linking

Used when we have multiple source files (.c)

```
avr-gcc -mmcu=atmega128 main.o -o main.out
```

This will generate final object code for the project: main.out

### 3. Object Copy

```
avr-objcopy -O ihex main.out main.hex
```

This will generate Final Intel machine file ready to be loaded to Flash of the microcontroller.

## 4. Programmer (AVR-dude)

Command line programmer

In CMD Prompt type : avrdude for displaying options

```
avrdude -p atmega128 -P com4 -c jtagmkl -U  
flash:w:main.hex
```

# Makefiles...

To reduce the number of steps involved in complete process.

Read the Makefile Manual for more details.

# First Makefile

Create a file in the project folder WITHOUT any extension with following name : Makefile

Write Following code

`main:`

```
avr-gcc main.c -mmcu=atmega128 -c  
avr-gcc -mmcu=atmega128 main.o -o main.out  
avr-objcopy -O ihex main.out main.hex
```

`program:`

```
avrdude -p atmega128 -P com4 -c jtagmkI -U flash:w:  
main.hex
```

# Using Makefile

Type following on CMD Prompt:

make main : will execute commands on label  
'main'

make program : will execute commands on label  
'program'

# Completing Makefile

PROJ = main

# Name of project without extension

SRC = main.c lcd.c uart.c

# List all Source Files here.

CC = avr-gcc

#Compiler used

MCU = atmega128

#Microcontroller used

main:

\$(CC) \$(SRC) -mmcu=\$(MCU) -c

\$(CC) -mmcu=\$(MCU) \*.o -o \$(PROJ).out

avr-objcopy -O ihex \$(PROJ).out \$(PROJ).hex

program:

avrdude -p \$(MCU) -P com4 -c jtagmkl -U flash:w:\$(PROJ).hex

clean:

rm \*.o \*.out \*.hex

# Auto Generated Makefile

Use Mfile generator from WinAVR. Edit following lines,

- Line 44 : MCU = atmega128
- Line 65 : F\_CPU = 8000000
- Line 73 : TARGET = main
- Line 83 : SRC = \$(TARGET).c uart.c lcd.c
- Line 97 : ASRC = i2cmaster.S
- Line 276 : AVRDUDE\_PROGRAMMER = jtagmkl
- Line 279 : AVRDUDE\_PORT = com4



# IDE : Integrated Development Environment

- AVR Studio : backend AVRGCC

All tools are inbuilt.

# C Review

# Macros

**#define** Label Replacement

Function through Macros

**#define** add(x,y) (x)+(y)

# Binary Operators

Operation	Operator Symbol in C	Operation Mode
AND	&	Binary
OR		Binary
XOR	^	Binary
1's Complement	~	Unary
Left Shift	<<	Binary
Right Shift	>>	Binary

# Shift Operators

Right Shift : >>

Left Shift : <<

# Bit operations on Registers

## Setting a bit

Use the bitwise OR operator (|) to set a bit.

$\text{REGA} |= 1 \ll x$

## Clearing a bit

Use the bitwise AND operator (&) to clear a bit.

$\text{REGA} \&= \sim(1 \ll x)$

# Bit operations on Registers

## **Toggling a bit**

The XOR operator (^) can be used to toggle a bit.

```
REGA ^= 1 << x;
```

## **Checking/Reading a bit**

```
bit = REGA & (1 << x);
```

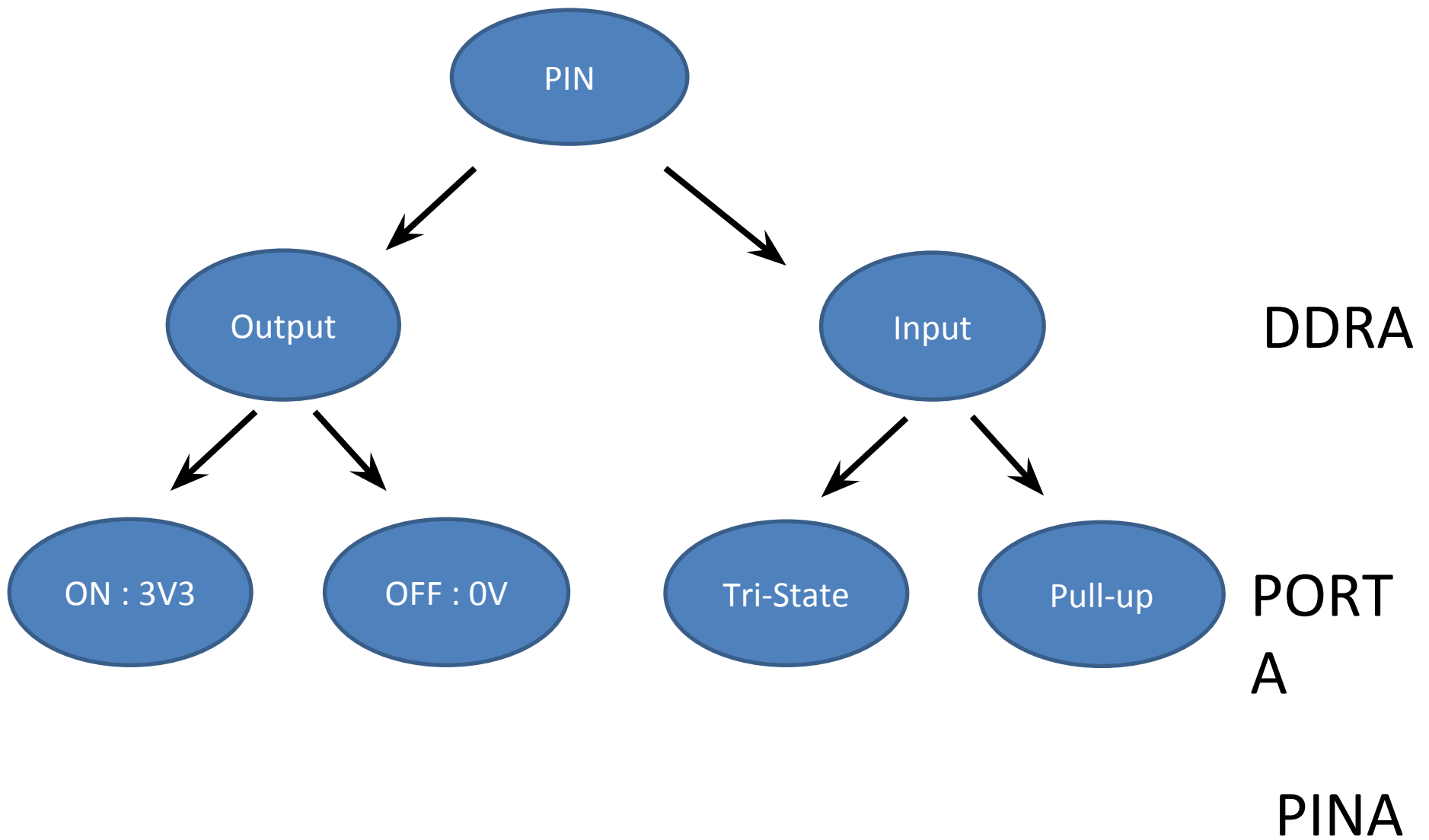
AVR GPIO



# 3 Registers

8 bit registers mapped to GPIO pins.

- PORTX
- PINX
- DDRX



# Port Registers

Port registers allow for lower-level and faster manipulation of the i/o pins of the microcontroller on an Arduino board. The chips used on the Arduino board (the ATmega8 and ATmega168) have three ports:

- B (digital pin 8 to 13)
- C (analog input pins)
- D (digital pins 0 to 7)

# Port Registers Conti...

- **PORTD** maps to Arduino digital pins 0 to 7
- **PORTB** maps to Arduino digital pins 8 to 13  
The two high bits (6 & 7) map to the crystal pins and are not usable
- **PORTC** maps to Arduino analog pins 0 to 5.  
Pins 6 & 7 are only accessible on the Arduino Mini

# ATmega168/328-Arduino Pin Mapping

## Atmega168 Pin Mapping

### Arduino function

reset	(PCINT14/RESET) PC6	1
digital pin 0 (RX)	(PCINT16/RXD) PD0	2
digital pin 1 (TX)	(PCINT17/TXD) PD1	3
digital pin 2	(PCINT18/INT0) PD2	4
digital pin 3 (PWM)	(PCINT19/OC2B/INT1) PD3	5
digital pin 4	(PCINT20/XCK/T0) PD4	6
VCC	VCC	7
GND	GND	8
crystal	(PCINT6/XTAL1/TOSC1) PB6	9
crystal	(PCINT7/XTAL2/TOSC2) PB7	10
digital pin 5 (PWM)	(PCINT21/OC0B/T1) PD5	11
digital pin 6 (PWM)	(PCINT22/OC0A/AIN0) PD6	12
digital pin 7	(PCINT23/AIN1) PD7	13
digital pin 8	(PCINT0/CLKO/ICP1) PB0	14

### Arduino function

28	PC5 (ADC5/SCL/PCINT13)	analog input 5
27	PC4 (ADC4/SDA/PCINT12)	analog input 4
26	PC3 (ADC3/PCINT11)	analog input 3
25	PC2 (ADC2/PCINT10)	analog input 2
24	PC1 (ADC1/PCINT9)	analog input 1
23	PC0 (ADC0/PCINT8)	analog input 0
22	GND	GND
21	AREF	analog reference
20	AVCC	VCC
19	PB5 (SCK/PCINT5)	digital pin 13
18	PB4 (MISO/PCINT4)	digital pin 12
17	PB3 (MOSI/OC2A/PCINT3)	digital pin 11(PWM)
16	PB2 (SS/OC1B/PCINT2)	digital pin 10 (PWM)
15	PB1 (OC1A/PCINT1)	digital pin 9 (PWM)

Digital Pins 11, 12 & 13 are used by the ICSP header for MOSI, MISO, SCK connections (Atmega168 pins 17, 18 & 19). Avoid low-impedance loads on these pins when using the ICSP header.

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