Obtional Assessment -2

$$x[n] = \begin{cases} \left(\frac{1}{3}\right)^n \cos\left(\frac{\pi}{4}n\right) & n < 0 \\ 0 & n > 0 \end{cases}$$

$$\therefore x[z] = \sum_{n=-\infty}^{\infty} x[n] \cdot z^{-n}$$

$$= \sum_{n=-\infty}^{\infty} \left(\frac{1}{3}\right)^n \cos\left(\frac{\pi}{4}n\right) \cdot z^{-n}$$

$$= \left(\frac{1}{2}\right) \sum_{n=-\infty}^{0} \left(\frac{1}{3}\right)^{n} e^{j\frac{\pi}{4}n} z^{-n} + \left(\frac{1}{2}\right) \sum_{n=-\infty}^{0} \left(\frac{1}{3}\right)^{n} e^{j\frac{\pi}{4}n} z^{-n}$$

$$=\left(\frac{1}{2}\right)\sum_{n=0}^{\infty}\left(\frac{1}{3}\right)^{-n}e^{-j\frac{\pi}{4}n}z^{n}+\left(\frac{1}{2}\right)\sum_{n=0}^{\infty}\left(\frac{1}{3}\right)^{-n}e^{j\frac{\pi}{4}n}z^{n}$$

$$= \left(\frac{1}{2}\right) \frac{1}{1 - 3 \cdot e^{-j\pi/4}Z} + \left(\frac{1}{2}\right) \frac{1}{1 - 3 \cdot e^{j\pi/4}Z}$$

→ (3 POINTS)

... ROC:
$$|z| < \frac{1}{3}$$

→ (0.5 POINTS)

. The poles wie at
$$Z = \frac{1}{3}e^{j\pi/4}$$
 4 $Z = \frac{1}{3}e^{j\pi/4}$ $\rightarrow (0.5 POINTS)$

$$x[n] = 2^{51[n]}$$

$$x[n] = 2^{n \cdot u[n]}$$

$$x[n] = \begin{cases} 1, & n < 0 \\ 2^n, & n \ge 0 \end{cases}$$

$$= u[-n-1] + 2^n u[n]$$
 (1)

$$2^{n} u[n] = \frac{1}{1-2z^{-1}}$$
, ROC: $|z| > 2$

$$u[-n-1] = \frac{-1}{1-z^{-1}}$$
, ROC; $|z| < 1$

Now, by egr 1),

$$x[n] = u[-n-1] + 2^n u[n]$$

$$ROC: |z| < 1$$

$$ROC: |z| > 2$$

Thesie is no common Roc foot x[n]. Hence X(z) not exist here. -> (2 POINTS) MINIST "

SOL(3): (a) Given causal LTI system 'S'-

$$\frac{d^{3}y(+)}{dt^{3}} + (1+\alpha)\frac{d^{2}y(t)}{dt^{2}} + \alpha(1+\alpha)\frac{dy(t)}{dt} + \alpha^{2}y(t) = \alpha(t)$$

Taking the Laplace townsform of both sides of the given differential equation, we obtain —

$$S^{3}Y(S) + (1+\alpha)S^{2}Y(S) + \alpha(1+\alpha)SY(S) + \alpha^{2}Y(S) = X(S)$$

$$\begin{cases} as we know - \frac{d^n f(t)}{dt^n} \Longrightarrow s^n F(s) & \text{Biloteral} \\ & Laplace Totans. \end{cases}$$

$$\left[S^{3} + (1+\alpha)S^{2} + \alpha(1+\alpha)S + \alpha^{2}\right]Y(S) = X(S)$$

The sie for i.e.,
$$H(s) = \frac{Y(s)}{X(s)} = \frac{1}{s^3 + (1+\alpha)s^2 + \alpha(1+\alpha)s + \alpha^2}$$

Given that
$$-g(t) = \frac{dh(t)}{dt} + h(t)$$

Taking the Laplace townsform of both sides of the given differential equation, we obtain—

$$G_1(s) = (s+1) \cdot H(s)$$

$$G_1(S) = \frac{(S+1)}{S^3 + (1+\alpha)S^2 + \alpha(1+\alpha)S + \alpha^2}$$

$$G_{1}(s) = \frac{(s+1)}{(s^{2}+\alpha s+\alpha^{2})}$$

$$G_1(s) = \frac{1}{(s^2 + \alpha s + \alpha^2)}$$

... G(s) has poles at $\alpha(-\frac{1}{2}+j\frac{\sqrt{3}}{2})$ $\alpha(-\frac{1}{2}-j\frac{\sqrt{3}}{2})$.

Therefore, G(s) has 2. Poles. \rightarrow (1.5 Points)

(b) By eqⁿ(1),

$$H(s) = \frac{1}{(s+1)(s^2 + \alpha s + \alpha^2)}$$

Therefore, H(s) has poles at
$$-1$$
, $\alpha(-\frac{1}{2}+j\frac{\sqrt{3}}{2})$ and $\alpha(-\frac{1}{2}-j\frac{\sqrt{3}}{2})$.

The given system is causal LTI system. Foot stability of causal system, poles of Tolansfell function H(s) should lies in Left Hand Side of 8-plane. (For stability, Roc includes imaginary axis in s-plane). For this to be true Re{s} < 0

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$$\left(-\frac{\alpha}{2}\right) < 0$$

Sol.(4): Given that
$$x[n] = (\frac{1}{2})^{n} \cos \left[\frac{\pi}{2}(n-1)\right] \Longrightarrow x(e^{j\omega})$$

$$\therefore x(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] \cdot e^{-j\omega n}$$

$$= \sum_{n=-\infty}^{\infty} (\frac{1}{2})^{n} \cos \left[\frac{\pi}{2}(n-1)\right] \cdot e^{-j\omega n}$$

$$=$$

$$\begin{split} \therefore X_{2}(e^{j\omega}) &= \sum_{N=0}^{\infty} \frac{1}{2} \frac{1}{N} \cos \left[\frac{\pi}{e}(n-1)\right] \cdot e^{-j\omega n} \\ &= \sum_{N=0}^{\infty} \frac{1}{2} \frac{1}{N} \cdot \frac{j\pi_{0}(n-1)}{e} + \frac{-j\pi_{0}(n-1)}{2} \cdot e^{-j\omega n} \\ &= \frac{1}{2} \left\{ \sum_{N=0}^{\infty} \frac{1}{2} \frac{1}{N} \cdot e^{j\frac{\pi}{e}(n-1)} - j\omega n + \sum_{N=0}^{\infty} \frac{1}{2} \frac{1}{N} \cdot e^{-j\frac{\pi}{e}(n-1)} - j\omega n \right\} \\ &= \frac{1}{2} \left\{ \frac{e^{j\pi/e}}{1 - \left(\frac{1}{2}\right) \cdot e^{j\pi/e} e^{-j\omega}} + \frac{e^{j\pi/e}}{1 - \left(\frac{1}{2}\right) \cdot e^{j\pi/e} e^{-j\omega}} \right\} \\ &= \frac{1}{2} \left\{ \frac{e^{j\pi/e}}{1 - \left(\frac{1}{2}\right) \cdot e^{j\pi/e} e^{-j\omega}} + \frac{e^{j\pi/e}}{1 - \left(\frac{1}{2}\right) \cdot e^{j\pi/e} e^{-j\omega}} \right\} \\ &= \frac{1}{2} \left\{ \frac{e^{j\pi/e}}{1 - \left(\frac{1}{2}\right) \cdot e^{j\pi/e} e^{-j\omega}} + \frac{e^{j\pi/e}}{1 - \left(\frac{1}{2}\right) \cdot e^{j\pi/e} e^{-j\omega}} \right\} \\ &+ \frac{1}{2} \left\{ \frac{e^{-j\pi/e}}{1 - \left(\frac{1}{2}\right) e^{j\pi/e} e^{-j\omega}} + \frac{e^{j\pi/e}}{1 - \left(\frac{1}{2}\right) \cdot e^{-j\pi/e} e^{-j\omega}} \right\} \\ &- \cos(\pi/e) \end{split}$$